(Working Title) Appendix: Task Switching Replication Cognitive Control under varying Posture

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Abstract

Appendix of all figures, tables and materials generated by the project. Not all figures and tables may be used in final document, so can refer to this document for details of data analysis, visualizations, summary tables and other products of this project.

Appendix

Tables

Some text here.

Figures

Table 1: Summary of experiment participants results. Number of samples, and the average head and torso displacement during experiment are shown.

part	date	samples	head	torso
1	2021-11-10 10:21	47313	2.9716	3.7108
2	2021-11-10 11:15	56914	1.5779	3.9911
3	2021-11-10 12:20	45214	2.3325	3.5064
4	2021-11-10 13:18	43433	8.3482	10.8110
5	2021-11-10 14:22	43511	2.1401	2.8497
6	2021-11-10 15:12	35283	1.9824	3.5356
7	2021-11-11 15:07	46522	2.5832	2.6806
8	2021-11-11 16:36	75436	3.7156	4.4358
9	2021-11-12 10:09	51769	2.9460	3.6241
10	2021-11-12 11:10	46269	2.3017	2.6263
11	2021-11-12 12:35	41928	2.3433	2.1368
12	2021-11-12 13:50	43413	2.8110	3.4173
13	2021-11-15 09:58	41690	2.2234	3.9255
14	2021-11-15 11:14	43444	1.7378	2.9976
16	2021-11-15 15:40	44641	1.6500	2.2349
17	2021-11-16 09:56	42725	2.6281	3.2190
18	2021-11-16 11:06	47743	1.7233	3.8136

Table 2: Fit of logistic regression model with response (correct or incorrect) as the dependent variable, and average torso joint movement leading up to the response as the independent variable.

Dep. Variable:	correc	rrectValue No. Observations:		6514				
Model:	Lo	Logit		Residua	als:	6512		
Method:	MLE		\mathbf{Df}	Model:		1		
Date:	Tue, 16	Tue, 16 Nov 2021		eudo R-	squ.:	0.0006210		
Time:		20:56	Log	Log-Likelihood:			-2119.8	
converged:	T_1	rue	${ m LL}\cdot$	LL-Null:			-2121.1	
	c	oef	std err	${f z}$	$\mathbf{P} {>} \left \mathbf{z} \right $	[0.025]	0.975]	
const	2.	2793	0.066	34.651	0.000	2.150	2.408	
jointTorsoDisplacement		.0008	0.000	-1.688	0.091	-0.002	0.000	

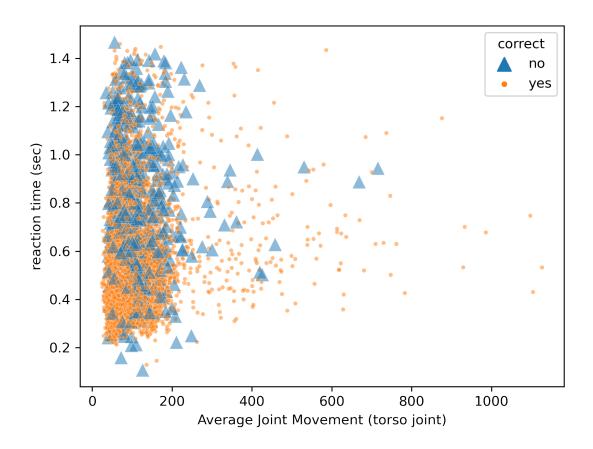


Figure 1: Reaction time of participants plotted as a function of average joint movement (displacement) captured from Kinect tracking sensor. Correct and incorrect responses are indicated by marker color and shape.

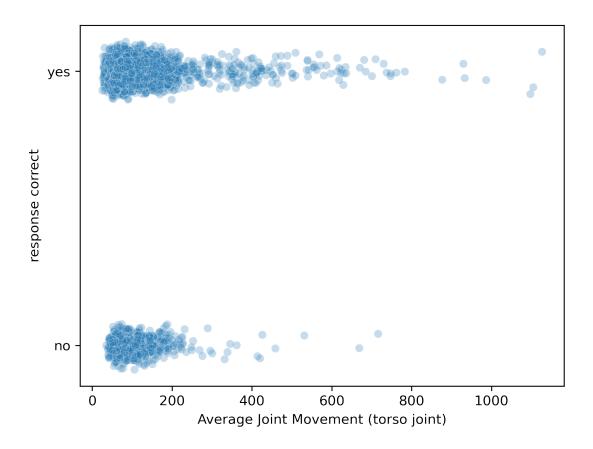


Figure 2: Response (correct or incorrect) as a function of average joint movement (displacement) captured from Kinect tracking sensor.