

"Open Source Macroeconomics Laboratory Boot Camp Dynamic Stochastic General Equilibrium Modeling"

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Outline

- 1 Introduction
- 2 A Generalized DSGE Model
- 3 Our Baseline Model
- 4 Steady State
- 5 Solution Methods

Definition of General Equilibrium

Definition

A *competitive equilibrium* is a set of allocations, $\{x_i\}_{i=1}^I$, and prices, $\{p_i\}_{i=1}^I$, for each factor of production and consumable such that:

- 1 households optimize utility,
- 2 firms optimize profits,
- 3 the government meets its budget constraints, and
- 4 all factor and goods markets clear

Walras' Law

Walras Law - If an economy has N markets and $N - 1$ of those markets are in equilibrium, then the remaining market must also be in equilibrium.

DGE and DSGE models

- 1 DGE - Dynamic General Equilibrium
- 2 DSGE - Dynamic Stochastic General Equilibrium

Captivating Dynamic Fan Videos

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Household's Problem

$$\begin{aligned}
 & \max_{\{x_{it}, k_{t+1}\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \beta^t E_t \{ u(\{x_{it}\}_{i=1}^I) \} \\
 \text{s.t. } & \sum_{i=1}^I p_{it} x_{it} + \sum_{j=1}^J (1 + r_{jt} - \delta_j) k_{jt} - k_{j,t+1} = 0 \quad \forall t \quad (1)
 \end{aligned}$$

Household's Problem

$$V(\{k_{jt}\}; \theta_t) = \max_{\{x_{it}\}, \{k_{j,t+1}\}} u(\{x_{it}\}) + \beta E_t \{ V(\{k_{j,t+1}\}, \theta_{t+1}) \}$$

$$\text{s.t.} \quad \sum_{i=1}^I p_{it} x_{it} + \sum_{j=1}^J (1 + r_{jt} - \delta_j) k_{jt} - k_{j,t+1} = 0 \quad (2)$$

Household's Problem Solution

$$u_{x_i}(\{x_{it}\}_{i=1}^I) + \lambda_t p_{it} = 0 \quad \forall i \quad (3)$$

$$- \lambda_t + \beta E_t \{ V_{k_j}(\{k_{j,t+1}\}, \theta_{t+1}) \} = 0 \quad \forall j \quad (4)$$

The condition on each λ_t recovers the budget constraint.

Envelope condition:

$$V_{k_j}(\{k_t\}; \theta_t) = \lambda_t(1 + r_{jt} - \delta_j) \quad \forall j \quad (5)$$

Euler Equations

Euler equations:

$$\lambda_t = \beta E_t \{ \lambda_{t+1} (1 + r_{j,t+1} - \delta_j) \} \quad \forall j \quad (6)$$

or

$$\frac{u_{x_i}(\{x_{it}\}_{i=1}^I)}{p_{it}} = \beta E_t \left\{ \frac{u_{x_i}(\{x_{i,t+1}\}_{i=1}^I)}{p_{i,t+1}} (1 + r_{j,t+1} - \delta) \right\} \quad \forall i, j \quad (7)$$

Firm's Problem

$$\max_{\{K_{jt}\}, \{X_{it}\}} \Pi_t = \sum_{i=1}^I P_{it} X_{it} - \sum_{j=1}^J R_{jt} K_{jt} \text{ s.t. } F(\{X_{it}\}, \{K_{jt}\}, \{z_{nt}\}) = 0$$

Maximization yields the following first-order conditions:

$$P_{it} + \Lambda_t F_{Xi}(\{X_{it}\}, \{K_{jt}\}, \{z_{nt}\}) = 0 \quad \forall i \quad (8)$$

$$-R_{jt} + \Lambda_t F_{Kj}(\{X_{it}\}, \{K_{jt}\}, \{z_{nt}\}) = 0 \quad \forall j \quad (9)$$

$$F(\{X_{it}\}, \{K_{jt}\}, \{z_{nt}\}) = 0 \quad (10)$$

Adding-Up and Market Clearing

Market clearing conditions for period are given by:

$$x_{it} = X_{it} \quad \forall i \quad (11)$$

$$k_{jt} = K_{jt} \quad \forall j \quad (12)$$

We also must impose equivalences between the prices faced by households and those faced by firms to prevent infinite arbitrage opportunities.

$$p_{it} = P_{it} \quad \forall i \quad (13)$$

$$r_{jt} = R_{jt} \quad \forall j \quad (14)$$

Exogenous Laws of Motion

Finally, we need to specify a stochastic process for the technology shocks. Let Z_t denote the vector of $\{z_{nt}\}$'s each period.

$$Z_t = (I - P)\bar{Z} + PZ_{t-1} + H_t; \quad H_t \sim \text{i.i.d.}(0, \Sigma) \quad (15)$$

where P is a square matrix of VAR coefficients, H_t is a vector of random variables, and Σ is a variance/covariance matrix.

Equilibrium

Categorize Variables

$$\begin{aligned} X_t &= \{k_{j,t-1}\}_{j=1}^J \\ Y_t &= \left\{ \{x_{it}, p_{it}\}_{i=1}^I, \{r_{jt}\}_{j=1}^J \right\} \\ Z_t &= \{z_{nt}\}_{n=1}^N \end{aligned} \tag{16}$$

Our goal is to find a policy function, Φ , that maps the values of the current state into the values for the endogenous state variables next period.

$$X_{t+1} = \Phi(X_t, Z_t) \quad (17)$$

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Household's Problem

$$V(k_t; \theta_t) = \max_{\ell_t, k_{t+1}} u(c_t, \ell_t) + \beta E_t \{ V(k_{t+1}, \theta_{t+1}) \} \quad (18)$$

$$\text{s.t. } (1 - \tau) [w_t \ell_t + (r_t - \delta) k_t] + k_t + T_t = c_t + k_{t+1} \quad (19)$$

We can dispense with the Lagrangian if we rewrite (19) as

$$c_t = (1 - \tau) [w_t \ell_t + (r_t - \delta)k_t] + k_t + T_t - k_{t+1} \quad (20)$$

and substitute it into the utility function of (18).

The first order conditons from the problem are:

$$u_\ell(c_t, \ell_t) + u_c(c_t, \ell_t) w_t (1 - \tau) = 0 \quad (21)$$

$$- u_c(c_t, \ell_t) + \beta E_t \{ V_k(k_{t+1}, \theta_{t+1}) \} = 0 \quad (22)$$

The envelope condition is :

$$V_k(k_t; \theta_t) = u_c(c_t, \ell_t) [(r_t - \delta)(1 - \tau) + 1] \quad (23)$$

Combining (22) and (23) and rearranging terms gives us the intertemporal Euler equation.

$$u_c(c_t, \ell_t) = \beta E_t \{ u_c(c_{t+1}, \ell_{t+1}) [(r_{t+1} - \delta)(1 - \tau) + 1] \} \quad (24)$$

Rewriting (21) gives the a consumption-leisure Euler equation.

$$-u_\ell(c_t, \ell_t) = u_c(c_t, \ell_t) w_t (1 - \tau) \quad (25)$$

Firm's Problem

$$\max_{K_t, L_t} \Pi_t = f(K_t, L_t, z_t) - W_t L_t - R_t K_t$$

where K_t and L_t are capital and labor hired, R_t and W_t are the factor prices, and $f(\cdot)$ is the production function.

It yields the following first-order conditions:

$$R_t = f_K(K_t, L_t, z_t) \quad (26)$$

$$W_t = f_L(K_t, L_t, z_t) \quad (27)$$

Government

The government collects distortionary taxes and refunds these to the households lump-sum:

$$\tau [w_t \ell_t + (r_t - \delta)k_t] = T_t \quad (28)$$

Adding-Up and Market Clearing

Market clearing is:

$$\ell_t = L_t \quad (29)$$

$$k_t = K_t \quad (30)$$

Price equivalences are:

$$w_t = W_t \quad (31)$$

$$r_t = R_t \quad (32)$$

Exogenous Laws of Motion

The stochastic process for the technology is:

$$z_t = (1 - \rho_z)\bar{z} + \rho_z z_{t-1} + \epsilon_t^z; \quad \epsilon_t^z \sim \text{i.i.d.}(0, \sigma_z^2) \quad (33)$$

The Equilibrium

The dynamic equilibrium for the model is defined by (20) and (24) – (33), a system of eleven equations in eleven unknowns. We can simplify this, however, by using (31) and (32) as definitions to eliminate the variables W_t and R_t . Similarly, (29) and (30) eliminate L_t and K_t . This leaves us with seven equations in seven unknowns, $\{c_t, k_t, \ell_t, w_t, r_t, T_t \text{ \& } z_t\}$.

The equations are:

$$c_t = (1 - \tau) [w_t \ell_t + (r_t - \delta) k_t] + k_t + T_t - k_{t+1} \quad (34)$$

$$u_c(c_t, \ell_t) = \beta E_t \{ u_c(c_{t+1}, \ell_{t+1}) [(r_{t+1} - \delta)(1 - \tau) + 1] \} \quad (35)$$

$$- u_\ell(c_t, \ell_t) = u_c(c_t, \ell_t) w_t (1 - \tau) \quad (36)$$

$$r_t = f_K(k_t, \ell_t, z_t) \quad (37)$$

$$w_t = f_L(k_t, \ell_t, z_t) \quad (38)$$

$$\tau [w_t \ell_t + (r_t - \delta) k_t] = T_t \quad (39)$$

$$z_t = (1 - \rho_z) \bar{z} + \rho_z z_{t-1} + \epsilon_t^z; \quad \epsilon_t^z \sim \text{i.i.d.}(0, \sigma_z^2) \quad (40)$$

The state of the economy is defined by z_t and k_{t-1} . All other variables are jump variables. This gives us the following classifications:

$$\begin{aligned}X_t &= \{k_{t-1}\} \\Y_t &= \{c_t, \ell_t, w_t, r_t, T_t\} \\Z_t &= \{z_t\}\end{aligned}\tag{41}$$

Our goal is the policy function:

$$X_{t+1} = \Phi(X_t, Z_t)\tag{42}$$

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The Solow Model

A familiar example is the simple Solow growth model. In this model households save a constant portion of their income, savings and investment are equal and capital accumulates with depreciation.

$$\begin{aligned} S_t &= sY_t & Y_t &= K_t^\alpha L_t^{1-\alpha} \\ L_t &= \bar{L} = 1 & S_t &= I_t \\ I_t &= K_{t+1} - (1 - \delta)K_t \end{aligned}$$

Iterative substitution yields the following policy function:

$$K_{t+1} = (1 - \delta)K_t + sK_t^\alpha \quad (43)$$

The solution for \bar{K} is:

$$\bar{K} = \left(\frac{se^{(1-\alpha)\bar{z}}}{\delta} \right)^{\frac{1}{1-\alpha}} \quad (44)$$

Brock and Mirman's Model

Households solve the following dynamic program.

$$V(K_t, z_t) = \max_{K_{t+1}} \ln(e^{z_t} K_t^\alpha - K_{t+1}) + \beta E_t \{ V(K_{t+1}, z_{t+1}) \} \quad (45)$$

The associated Euler equation is:

$$\frac{1}{e^{z_t} K_t^\alpha - K_{t+1}} = \beta E_t \left\{ \frac{\alpha e^{z_{t+1}} K_{t+1}^{\alpha-1}}{e^{z_{t+1}} K_{t+1}^\alpha - K_{t+2}} \right\} \quad (46)$$

The law of motion for z is:

$$z_{t+1} = \rho z_t + \varepsilon_t; \quad \varepsilon_t \sim i.i.d(0, \sigma^2) \quad (47)$$

Brock and Mirman's Model

You be we asked in an exercise at the end of this chapter to verify that the policy function takes the following form:

$$K_{t+1} = Ae^{z_t} K_t^\alpha \quad (48)$$

You will need to find the value of A as a function of the model's parameters.

The steady state value of K is defined by using (48) with $K_t = K_{t+1}$ and $z_t = 0$.

$$\bar{K} = A^{\frac{1}{1-\alpha}} \quad (49)$$

Steady State of the Baseline Model

To find the steady state in our DSGE model we need to proceed similarly and replace the time-period-specific values of $\{c_t, k_t, \ell_t, w_t, r_t, \tau_t \text{ \& } z_t\}$ with their steady state values as below:

$$\bar{c} = (1 - \tau) [\bar{w}\bar{\ell} + (\bar{r} - \delta)\bar{k}] + \bar{T} \quad (50)$$

$$u_c(\bar{c}, \bar{\ell}) = \beta E_t \{ u_c(\bar{c}, \bar{\ell}) [(\bar{r} - \delta)(1 - \tau) + 1] \} \quad (51)$$

$$- u_\ell(\bar{c}, \bar{\ell}) = u_c(\bar{c}, \bar{\ell}) \bar{w} (1 - \tau) \quad (52)$$

$$\bar{r} = f_K(\bar{k}, \bar{\ell}, \bar{z}) \quad (53)$$

$$\bar{w} = f_L(\bar{k}, \bar{\ell}, \bar{z}) \quad (54)$$

$$\tau [\bar{w}\bar{\ell} + (\bar{r} - \delta)\bar{k}] = \bar{T} \quad (55)$$

Additional Issues

GDP is given by:

$$y_t = f(k_t, \ell_t, z_t) \quad (56)$$

Investment is given by:

$$i_t = k_{t+1} - (1 - \delta)k_t \quad (57)$$

In addition, while r_t is the rental rate on capital, it is not the same as the real interest rate that would be offered on financial assets. The closest analog is the *user cost of capital*, which is defined as:

$$u_t = r_t - \delta \quad (58)$$

Outline

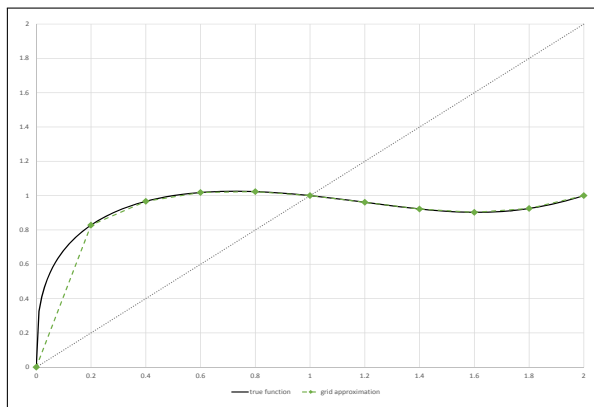
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Solution Methods

- discrete grid approximations
- spline function approximations
- linear-quadratic approximations objective functions and constraints
- log-linearization of the characterizing equations
- higher-order approximation of the characterizing equations

Grid Method

Figure: **Grid Approximation to the True Policy Function**



Polynomial Methods

Figure: **Polynomial Approximations to the True Policy Function**

