**Encoder1Cnt=62**

**93.94**

**RobotCommand.ExpectWheelSpeed1=-25.00**

**EncoderData.MeasuredWheelSpeed1=93.94**

**pwmoutput1=-685**

**RobotCommand.ExpectWheelSpeed2=25.00**

**EncoderData.MeasuredWheelSpeed2=-96.97**

**pwmoutput2=699**

**RobotCommand.ExpectWheelSpeed3=-25.00**

**EncoderData.MeasuredWheelSpeed3=-21.21**

**pwmoutput3=-56**

**RobotCommand.ExpectWheelSpeed4=25.00**

**EncoderData.MeasuredWheelSpeed4=25.76**

**pwmoutput4=38**

**pwm[0]=-255**