

## 4 : Artificial Neural Network, Backpropagation and testing

```
import numpy as np

...
    each sample in dataset has
...
    # [ hours_of_sleeping, hours_of_studying, marks_obtained_in_a_test ]

dataset = [ [2, 9, 92],
             [1, 5, 86],
             [3, 6, 89]
            ]
```

### Preparing inputs and outputs

```
# Forming inputs and outputs for the Neural Network

inputs = [ sample[:-1]      for sample in dataset ]
outputs = [ [ sample[-1] ]  for sample in dataset ]

    # Notice : extra big brackets for generating column array, highly critical if it is ignored

# converting normal arrays to numpy float arrays,

inputs = np.array(inputs, dtype=float)
outputs = np.array(outputs, dtype=float)

# Normalizing by max divide, The inputs and outputs should be in range [0, 1]

inputs = inputs/np.amax(inputs, axis=0)    # input has 2 columns, dividing each column with maximum of respective column
outputs = outputs/100                      # since max test score is 100
```

### Defining necessary functions

```
#activation function

def sigmoid(s):

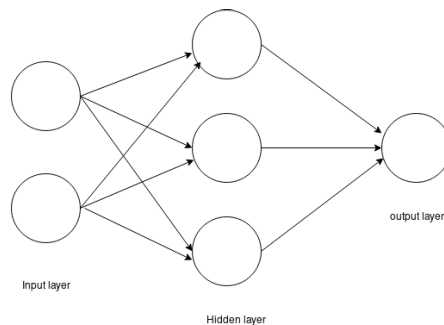
    return 1/(1 + np.exp( -s ) )
```

```
#dervivative of activation function which is necessary for backtracking

def sigmoid_derivative(s):

    return s * (1 - s)
```

### static single hidden layered Neural Net class without biases



```

class Neural_Network(object):

    def __init__(self, inputs, outputs):

        # Initialization
        self.inputs = inputs
        self.outputs = outputs

        #-----

        # Parameters
        self.input_size = len(inputs[0])
        self.output_size = 1
        self.hidden_size = 3          # number of neurons in hidden layer

        #-----

        # random weights for first layer and second layer'

        self.weights1 = np.random.randn(self.input_size, self.hidden_size)    # (3x2) weight matrix from input to hidden layer
        self.weights2 = np.random.randn(self.hidden_size, self.output_size)    # (3x1) weight matrix from hidden to output layer

    def forward(self, inputs):

        ''' forward propogation '''

        #+++++

        self.z1 = np.dot(inputs, self.weights1)    # dot product of input layer and first set of 3x2 weights
        self.z2 = sigmoid(self.z1)                # activation function applied on previous output

        #+-----+

        self.z3 = np.dot(self.z2, self.weights2)    # dot product of hidden layer and second set of 3x1 weights
        obtained_output = sigmoid(self.z3)          # final activation function

        #+++++

        return obtained_output

    def backward(self, obtained_output):

        ''' backward propgate through the network '''

        # error in output
        output_error = self.outputs - obtained_output

        # applying derivative of sigmoid to obtained outputs
        output_delta = output_error * sigmoid_derivative(obtained_output)

        '''-----'''

        # z2 error: hidden layer weights contribribution to output error
        z2_error = output_delta.dot( self.weights2.transpose() )

        # applying derivative of sigmoid to z2 error
        z2_delta = z2_error * sigmoid_derivative(self.z2)

        '''-----'''

        #-----#
        # updating weights, wj -> wj + n * delta(wj)    #
        #                                     n, learning rate    #
        #-----#

        # adjusting first set (input --> hidden) weights
        self.weights1 = self.weights1 + (0.5 * self.inputs.T.dot(z2_delta) )    #.T stands for transpose

        # adjusting second set (hidden --> output) weights
        self.weights2 = self.weights2 + (0.5 * self.z2.T.dot(output_delta) )

    def train(self):

        ''' training the network'''

        obtained_output = self.forward(self.inputs)
        self.backward(obtained_output)

```

## Creating a neural net and training it

```
net = Neural_Network(inputs, outputs)

for i in range(20):           # the more you train, the less error you obtain untill it overfits

    loss = np.mean( np.square(outputs - net.forward(inputs)))    # mean sum squared loss
    print ("Epoch-> ", i, " Loss:", loss)
    net.train()
```

```
Epoch-> 0 Loss: 0.07274521673240818
Epoch-> 1 Loss: 0.0585782542249422
Epoch-> 2 Loss: 0.047897611723800394
Epoch-> 3 Loss: 0.039725730089891075
Epoch-> 4 Loss: 0.03337521083036012
Epoch-> 5 Loss: 0.028364553631714123
Epoch-> 6 Loss: 0.0243542932035502
Epoch-> 7 Loss: 0.021102324867346034
Epoch-> 8 Loss: 0.018433588767724624
Epoch-> 9 Loss: 0.01621966047452225
Epoch-> 10 Loss: 0.014364967246628403
Epoch-> 11 Loss: 0.01279739659922404
Epoch-> 12 Loss: 0.011461822793107186
Epoch-> 13 Loss: 0.01031558692703971
Epoch-> 14 Loss: 0.009325299066303581
Epoch-> 15 Loss: 0.008464545890300382
Epoch-> 16 Loss: 0.007712226436721825
Epoch-> 17 Loss: 0.007051329051034897
Epoch-> 18 Loss: 0.006468022117193933
Epoch-> 19 Loss: 0.005950970628860717
```

## Prediction

```
test = np.array( [ [2, 5], [1, 9], [2, 3] ], dtype=float)    # same as preparing inputs
test = test/np.amax(test, axis=0)

print("Input: ", test, sep='\n\n')                            # Normalized input
```

Input:

```
[[1.      0.55555556]
 [0.5     1.      ]
 [1.      0.33333333]]
```

```
output_of_test = net.forward(test) * 100

print("Predicted Output", output_of_test, sep='\n\n')        # predicted marks for each sample
```

Predicted Output

```
[[86.19906654]
 [79.93228323]
 [86.8421938  ]]
```