Mehdi Nouni

Experience

Robotics Software Intern

July 2024 – Sept. 2024

Technozor

Centre Urbain Nord, Tunis, Tunisia

- Developed the entire code for all sensors and actuators for a miniature submarine.
- Implemented MQTT for real-time transmission over Wi-Fi with an ESP-32 to visualize it through Grafana.

Keywords: Python, C, C++, ESP-32, Arduino, UART, Grafana, MQTT, Computer Vision

Industrial Automation Intern

June 2023 – July 2023

AS2E Automation

Soukra, Ariana, Tunisia

- Simulated industrial robotic arms FANUC, Denso for pick-and-place tasks.
- Worked with FANUC Roboguide and Denso Wincaps III for simulation environments.

Keywords: Proprietary Programming Languages, Reverse Kinematics

Personal Projects

Chess Playing Robot Arm:

May, 2024 - June, 2024

- Developed an image processing program with OpenCV2 to provide information to Stockfish, a chess engine.
- Established UART between Arduino and the computer using Python.
- Implemented reverse kinematics using a linear programming algorithm, SLQP.

Keywords: Python, C, C++, Arduino, UART, Computer Vision, Reverse Kinematics

Autonomous Differential Drive Robot EUROBOT 2023

Sept. 2022 - May 2023

- Programmed PID controllers and algorithms for reverse kinematics and odometry.
- Deployed ROS on Ubuntu to establish communication between the Raspberry Pi and STM32.
- Implemented obstacle avoidance algorithms using input data from an RPLIDAR.

Keywords: Python, C, C++, STM32, Arduino, ROS, PID, Obstacle Avoidance, Ubuntu

Education

Engineering Degree in Industrial IT and Automation

Sept. 2020 - Sept. 2025 (expected)

Tunis, Tunisia

National Institute of Applied Science and Technology

Skills and Tools

• Programming Languages: Python, C++,

Java

• Operating Systems: Windows.

Linux

• Familiar Hardware: STM32, Arduino, ESP32, Raspberry Pi

• Developer Tools: Visual Studio Code Git & Github • Robotics: ROS, PID, Control Theory, Applied Mathematics • Misc Tools and Sofwares: Grafana, MQTT OpenCV, Pytorch

Languages

English:Fluent French:Fluent Arabic:Native Language

Extracurricular Activities

AeRobotix INSAT Sept. 2021 – Sept. 2024

• Member: Participated in tournaments in the first year gain experience with robotics.

• Member of an EUROBOT 2023 Team

Problem-Solving Group Member

Sept. 2018 – Sept. 2019

• Member: Spent a year working with an instructor and other peers, gaining problem solving skills in the process.