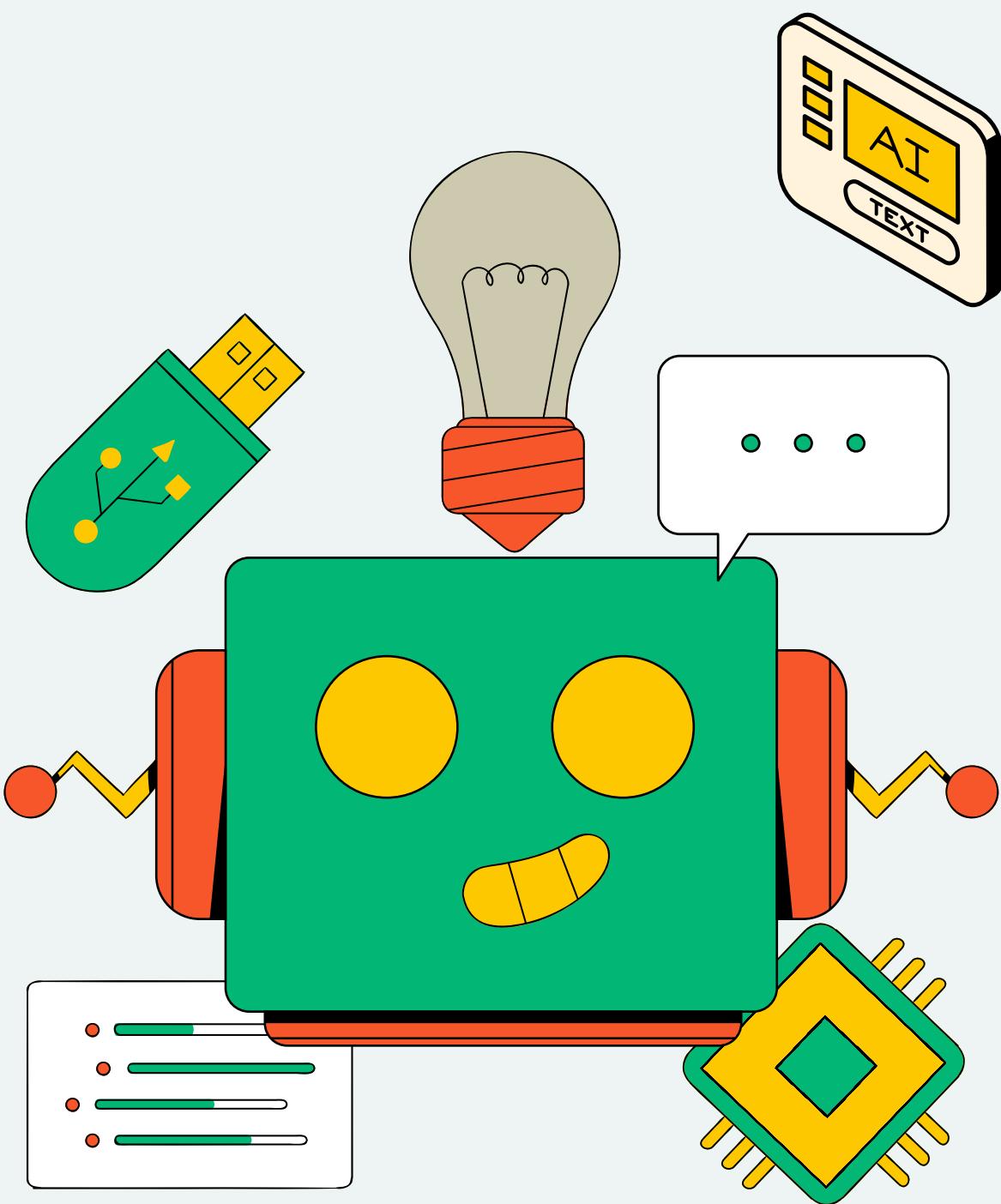




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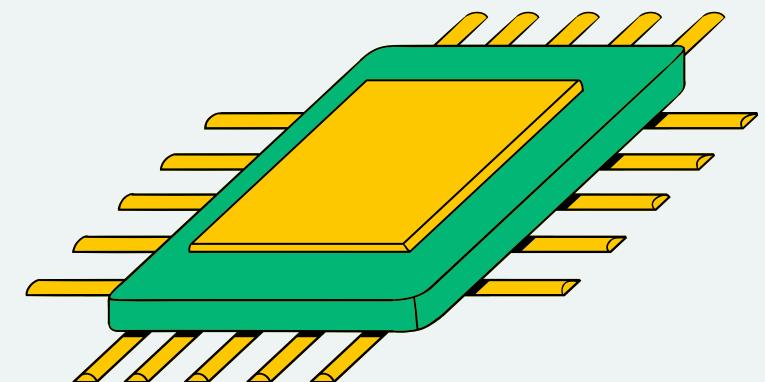


LITERATURE REVIEW THESIS

PRESENTATION

PRESENTED BY:

GAGAN DESHAD





PRESENTATION OUTLINE

- Introduction
- Deep Lab Cut
- Behavioural Papers
- Models
- YoloV8n
- MobileNet-SSD
- EfficientNet-BO
- YOLOX+BoT-SORT-Slim
- VGG+CNN
- VGG+CNN+LSTM
- R-CNN + NAS
- Acceleration based-ACT4Behav



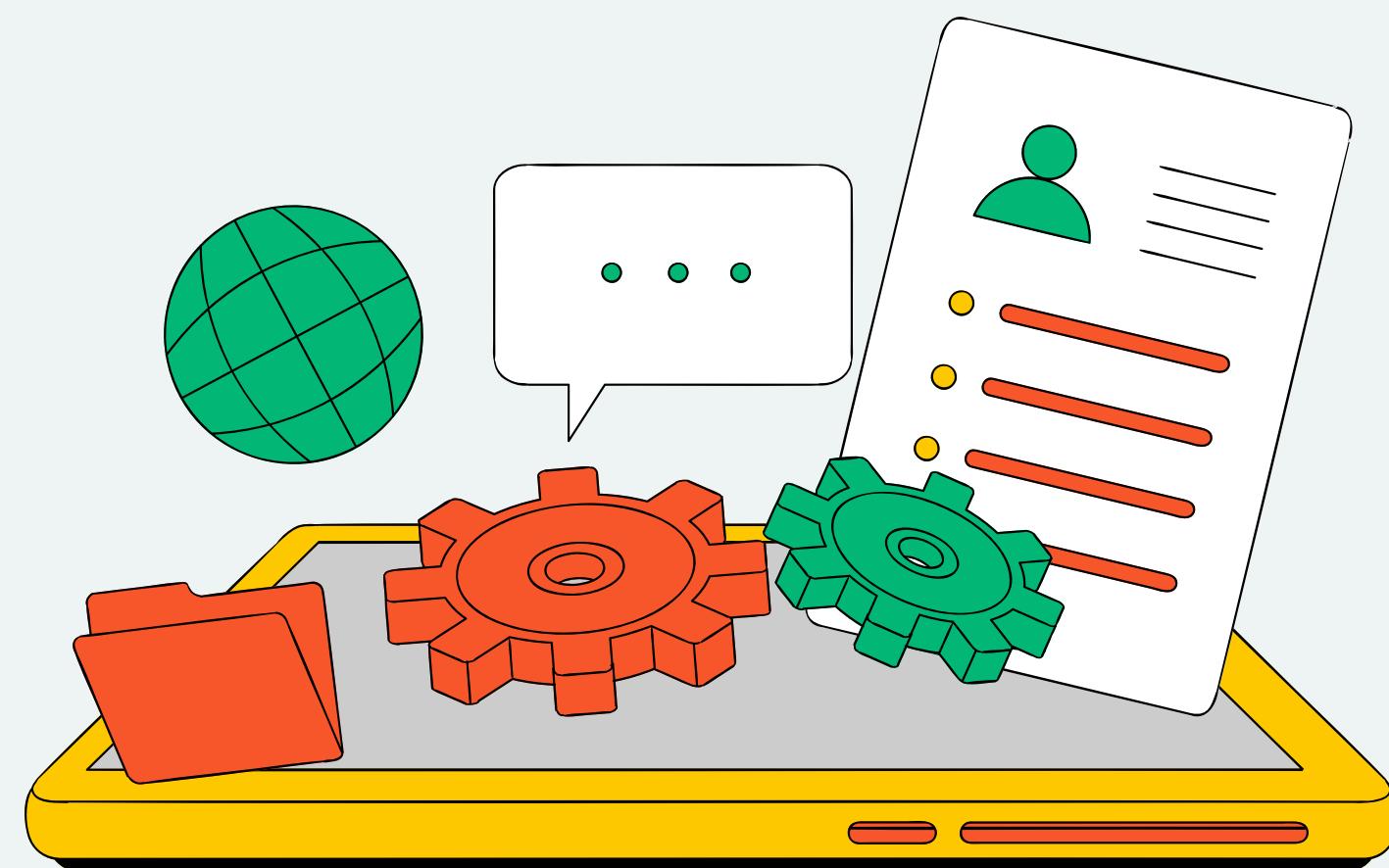


TYPES OF DETECTION?

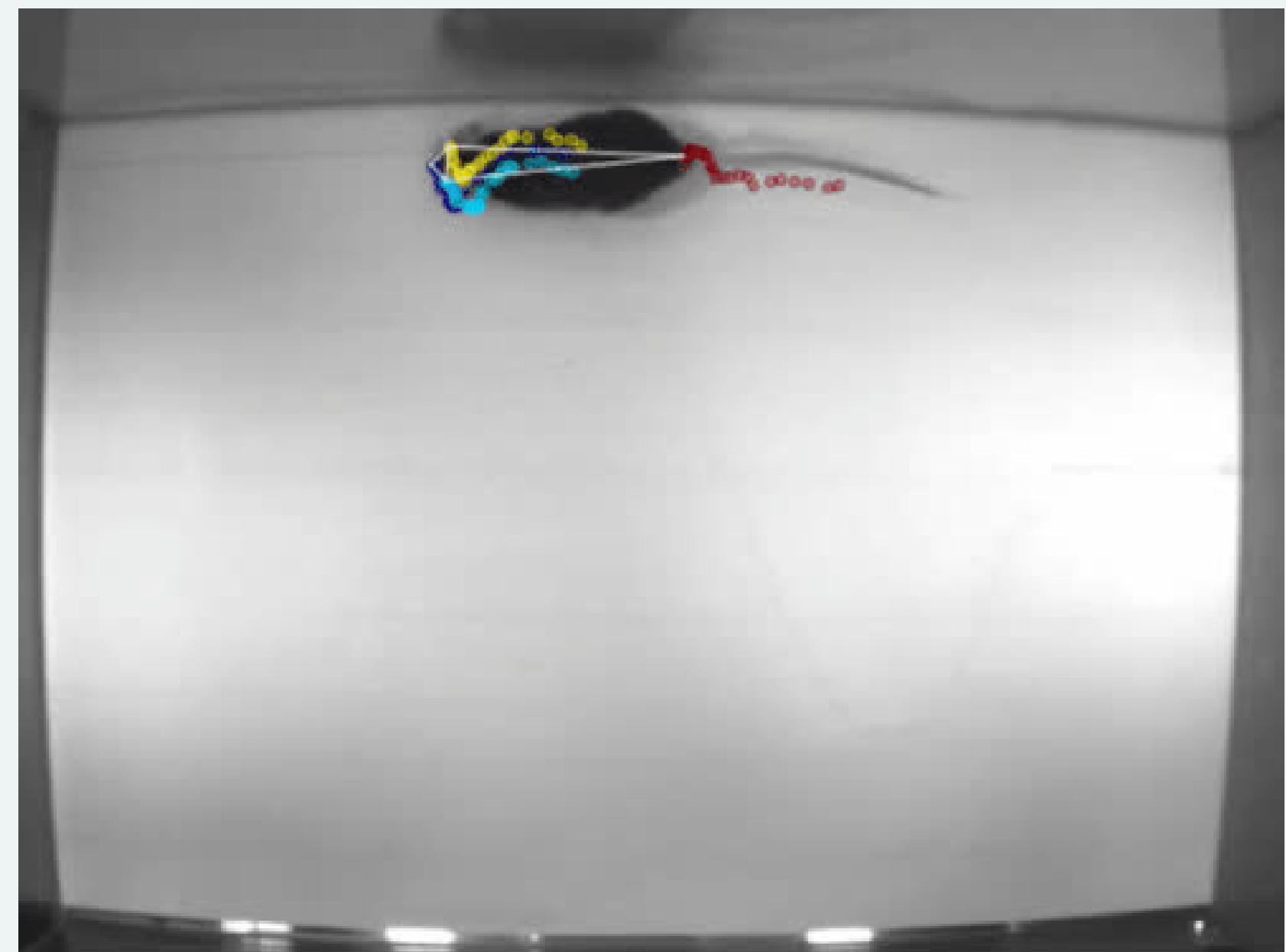
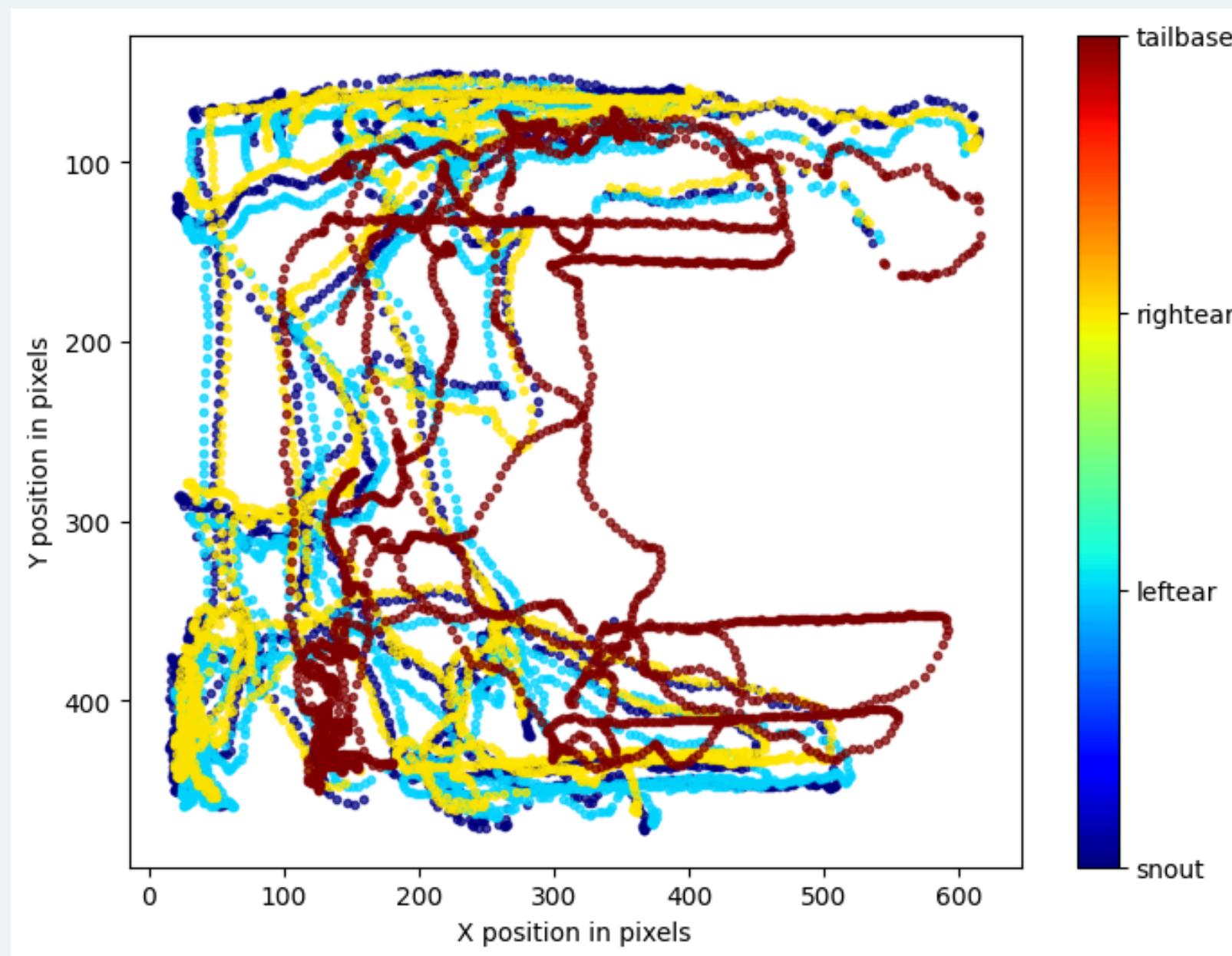
Weight Detection

Posture

Behaviour

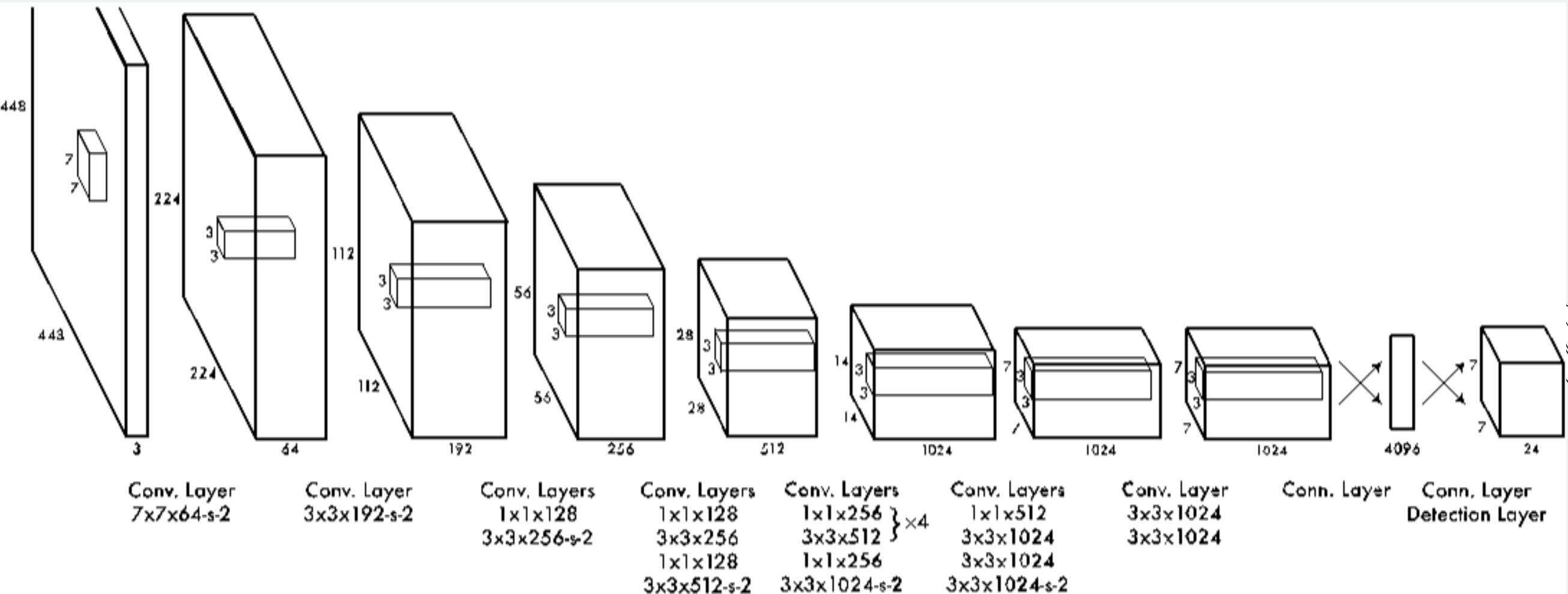


DEEP LAB CUT





YOLOV8n

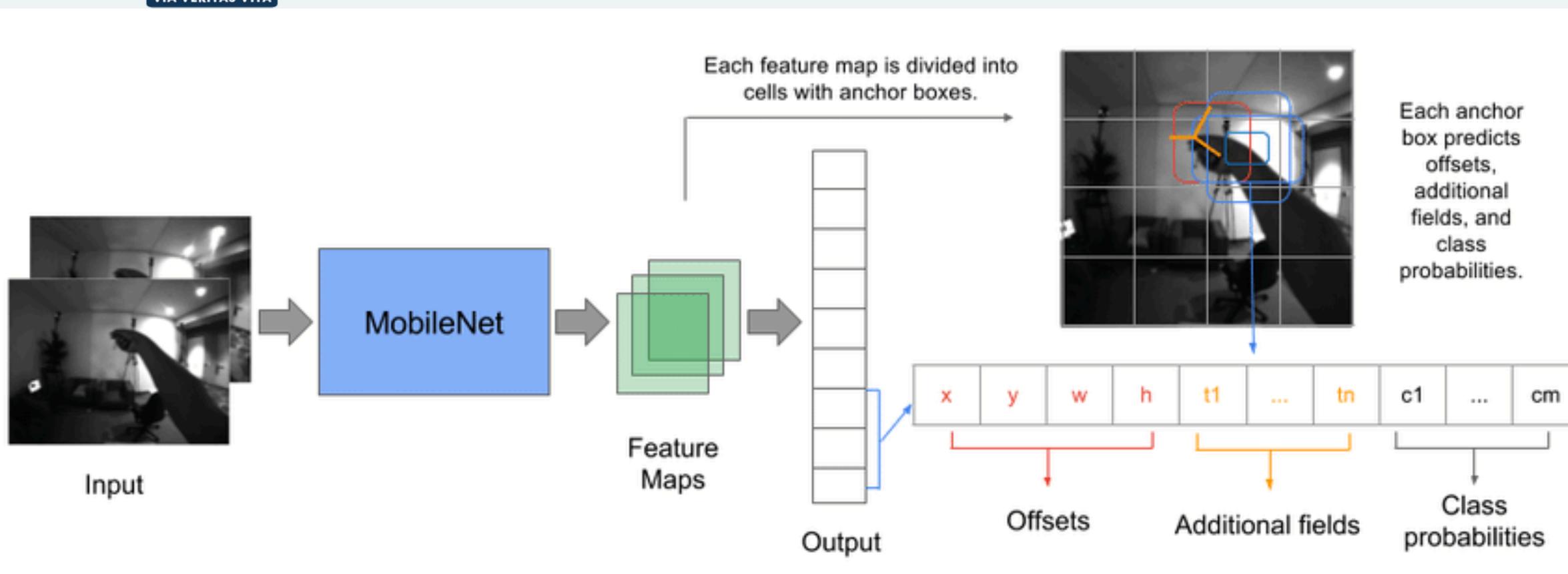


- One-stage detector: Processes the entire image in one pass.
- Real-time performance: Very fast and suitable for applications like video surveillance or robotics.
- Single neural network: Directly predicts bounding boxes and class probabilities.





MOBILENET-SSD



- One-stage detector: Uses the SSD (Single Shot Detector) framework.
- Backbone: MobileNet – a lightweight CNN optimized for mobile and edge devices.
- Efficiency: Designed for low-latency and low-power devices.





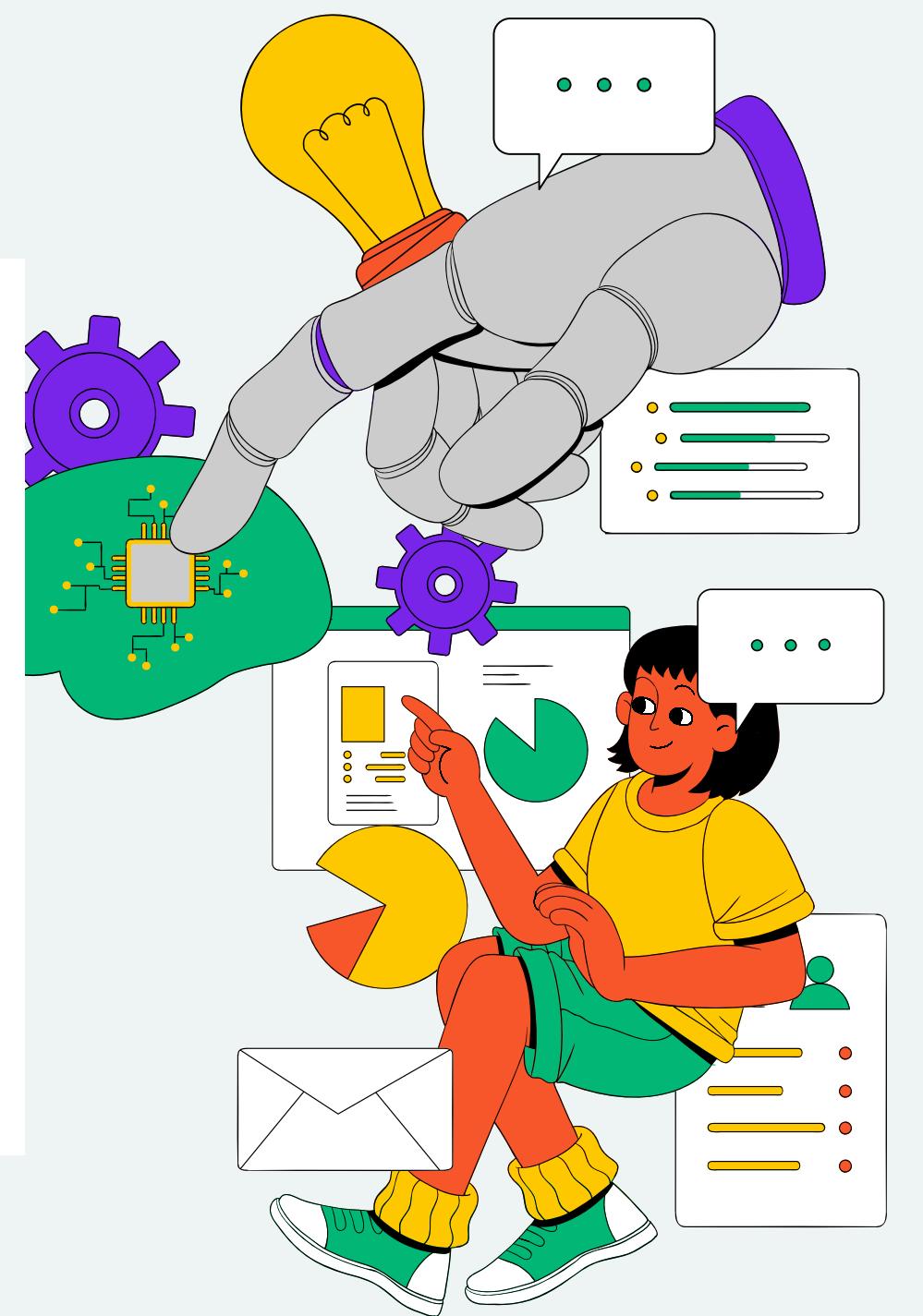
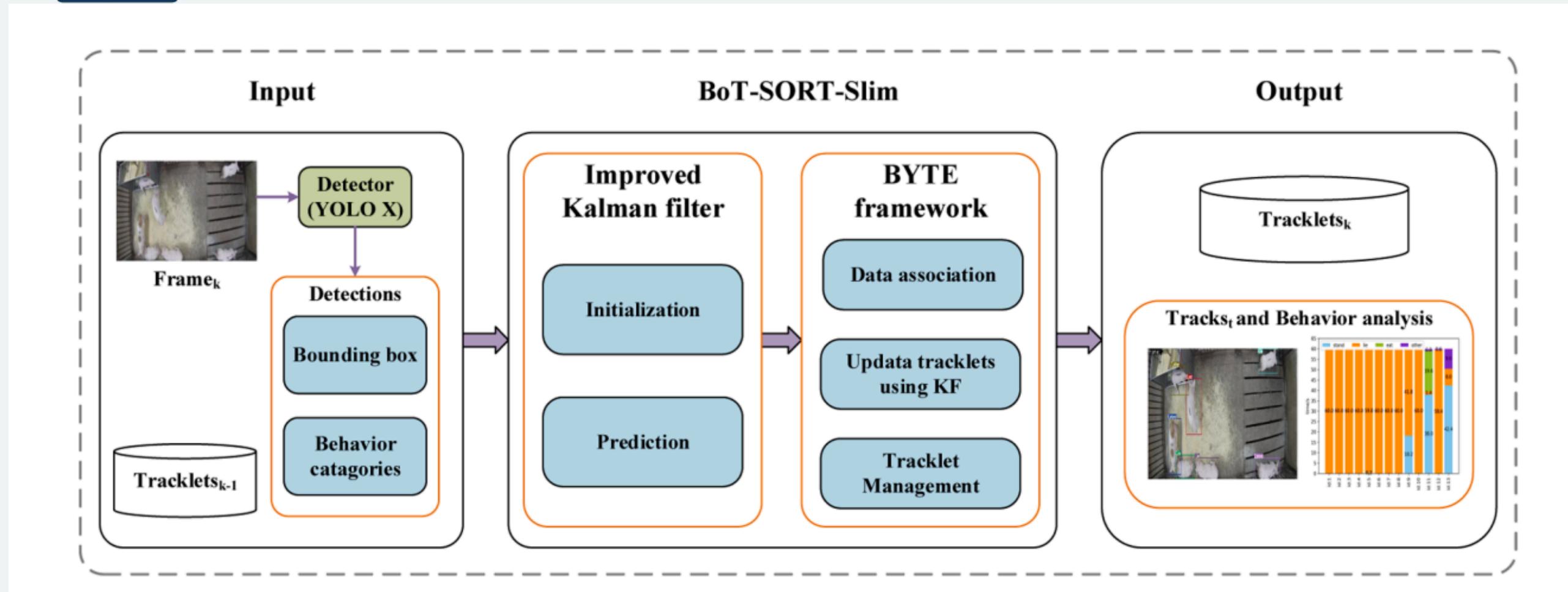
EFFICIENTNET-BO



- Key idea: Uses a compound scaling method to balance network depth, width, and resolution for better efficiency.
- Architecture: Based on Mobile Inverted Bottleneck Convolution (MBConv) blocks, like in MobileNetV2.
- Baseline model: EfficientNet-BO is the smallest and fastest model in the EfficientNet family. 

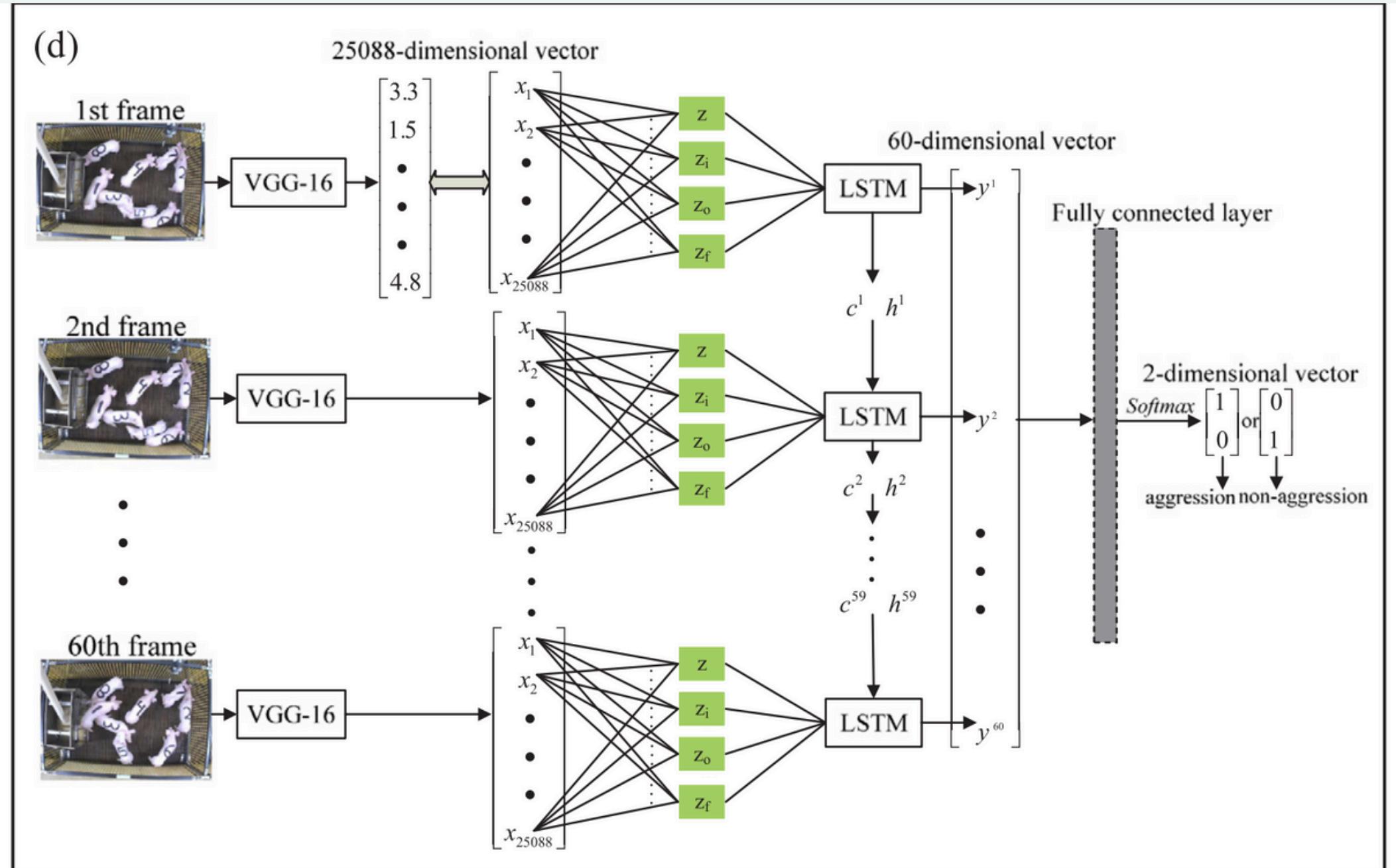


YOLOH+BOT-SORT-SLIM



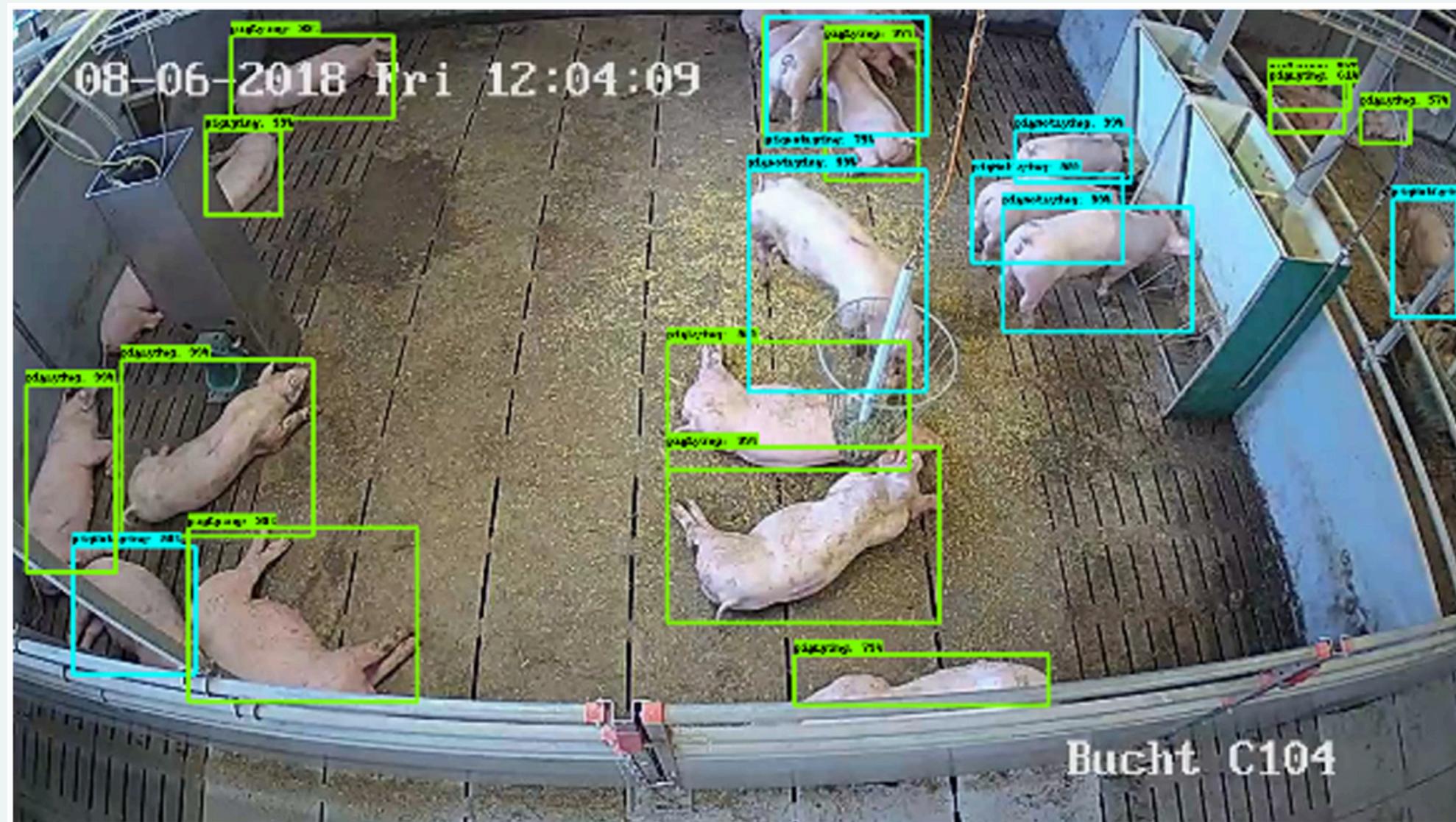


VGG+CNN+LSTM

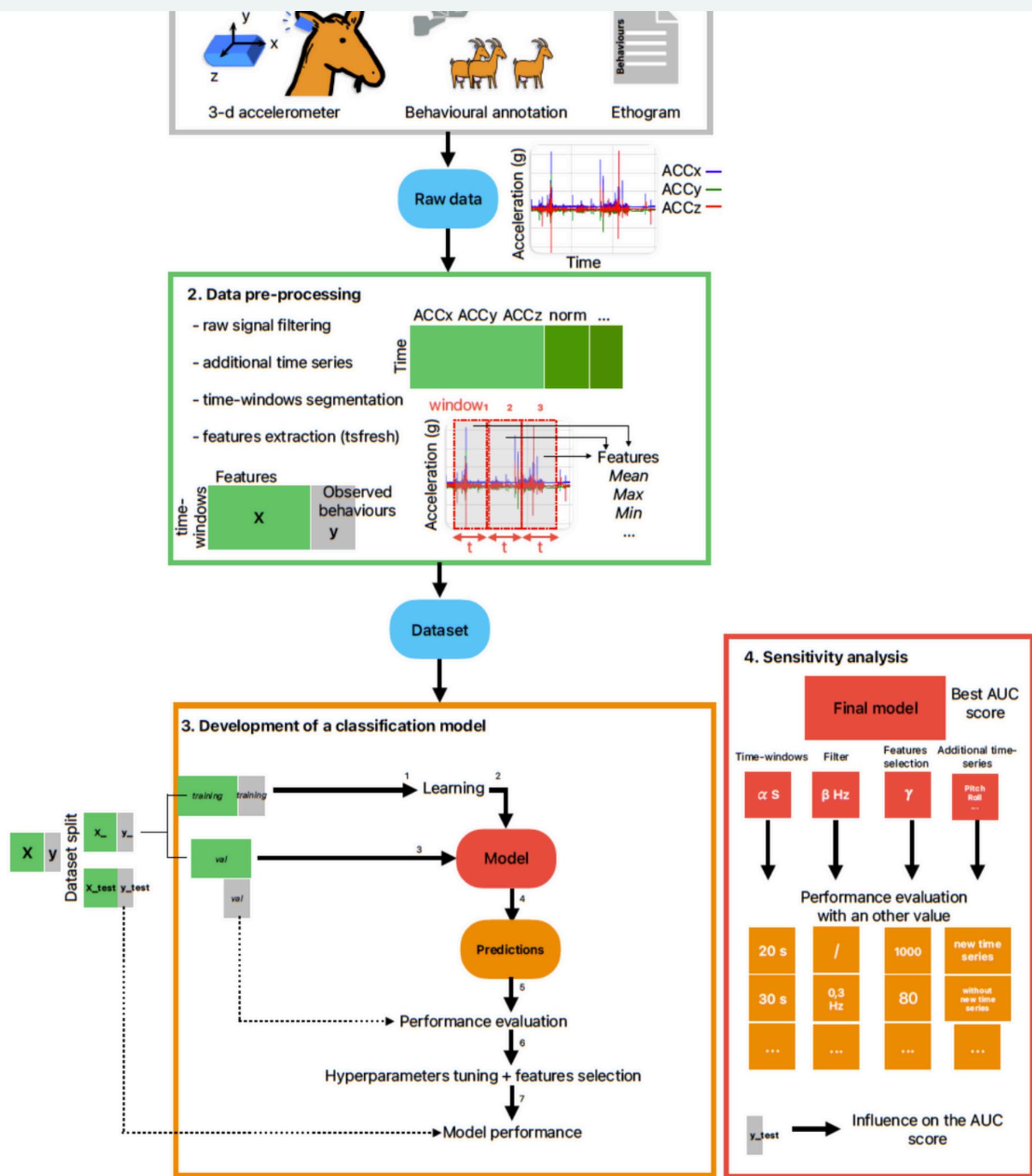




R-CNN + NAS

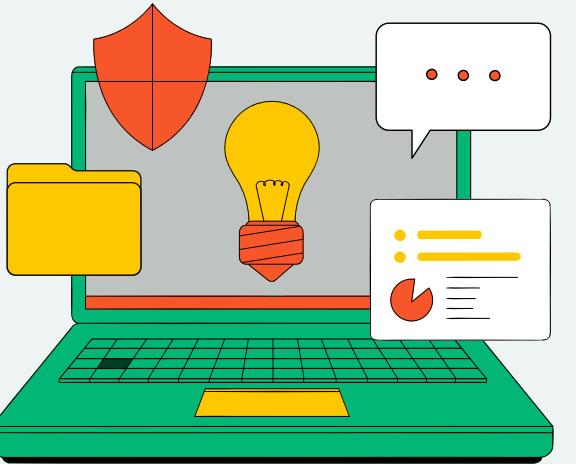


ACCELEROMETER BASED

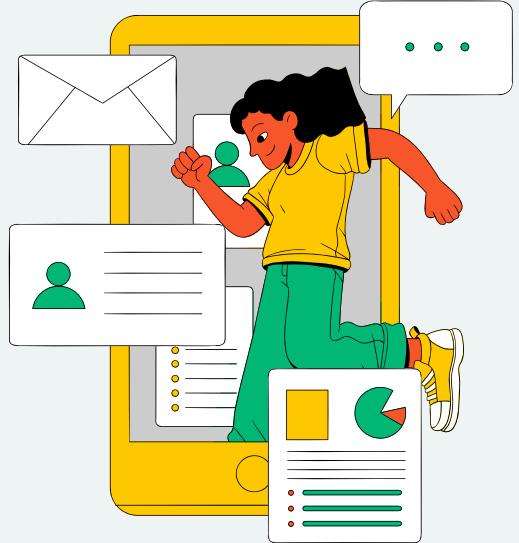


RESOURCE PAGE

[Yolo Bot Slim](#)



[YOLOv8n, MobileNetSSD, and EfficientNet-BO](#)



[RCNN NAS for position](#)



[VGG16 + Stacked CNN](#)

[Accelerometer Data Pipeline](#)

[Deep Lab CUT](#)