

Introduction to Machine Learning

Introduction to Machine Learning

Amo G. Tong

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Lecture 5 Supervised Learning

- Naïve Bayes Classifier
- Readings: Mitchell Ch 6.9-6.10; Murphy Ch 3.5
- Some materials are courtesy of Vibhava Gogate and Tom Mitchell.
- All pictures belong to their creators.

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Supervised Learning

- Given some training examples $\langle x, f(x) \rangle$ and an unknown function f .
- Find a good approximation of f .

- Step 1. Select the features of x to be used.
- Step 2. Select a hypothesis space H : a set of candidate functions to approximate f .
- Step 3. Select a measure to evaluate the functions in H .
- Step 4. Use a machine learning algorithm to find the best function in H according to your measure.

- **Bayesian Learning: the most probable classification**
- **Naïve Bayes Classifier: additional assumption.**

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Optimal Bayes Classifier

- Instance space X : each $x \in X$ is characterized by attributes (x_1, \dots, x_k)
- Classifications V .

Sky	Water	Forecast	EnjoySport
Sunny	Warm	Same	Yes

- Underlying truth: a distribution $\Pr[x, v]$ over (x, v) .

Most probable classification = $\operatorname{argmax}_{v \in V} \Pr[v|x]$

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Optimal Bayes Classifier

- Settings: learn a function $X \rightarrow V$
- Instance space X : each $x \in X$ is characterized by attributes (x_1, \dots, x_k)
- Classifications V .

Sky	Water	Forecast	EnjoySport
Sunny	Warm	Same	Yes

$$\operatorname{argmax}_{v \in V} \Pr[v|x] = \operatorname{argmax}_{v \in V} \sum_{h \in H \text{ and } h(x)=v} \Pr[h]$$

The probability that x is classified as v .
e.g.
 $x = (\text{Sunny}, \text{Warm}, \text{Same})$
 $\Pr[\text{yes}|x]$ is the probability that x is classified as yes.

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Optimal Bayes Classifier

- Settings: learn a function $X \rightarrow V$
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- Classifications V .

Sky	Water	Forecast	EnjoySport
Sunny	Warm	Same	Yes

$$\operatorname{argmax}_{v \in V} \Pr[v|x] = \operatorname{argmax}_{v \in V} \sum_{h \in H \text{ and } h(x)=v} \Pr[h]$$

The distribution over H . This is hard to compute.
We need to estimate $\Pr[h]$ by $\Pr[h|D]$ for each h in H .
The example in Lec 4 is very simple.

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Optimal Bayes Classifier

- Settings: learn a function $X \rightarrow V$
- Instance space X : each $x \in X$ is characterized by attributes (x_1, \dots, x_k)
- Classifications V .

Sky	Water	Forecast	EnjoySport
Sunny	Warm	Same	Yes

$$\operatorname{argmax}_{v \in V} \Pr[v|x] = \operatorname{argmax}_{v \in V} \sum_{h \in H \text{ and } h(x)=v} \Pr[h]$$

Can we compute this directly?
Let us try it. (next page)

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Naïve Bayes Classifier

$$\Pr[v|x] = \frac{\Pr[x|v] \Pr[v]}{\Pr[x]} \quad \text{Bayes theorem.}$$

$$\operatorname{argmax} \Pr[v|x] = \operatorname{argmax} \Pr[x|v] \Pr[v] = \operatorname{argmax} \Pr[x_1, x_2, \dots, x_k | v] \Pr[v]$$

$$x = (x_1, \dots, x_k)$$

Sky	EnjoySport
Sunny	Yes
Sunny	No
Rainy	No
Rain	Yes
Sunny	No

Can you classify a new instance (Sunny)?

$$\Pr[\text{Sunny}|\text{yes}, D] \Pr[\text{yes}|D] = \frac{1}{2} * \frac{2}{5}$$

$$\Pr[\text{Sunny}|\text{no}, D] \Pr[\text{no}|D] = \frac{2}{3} * \frac{3}{5}$$

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Naïve Bayes Classifier

$$\Pr[v|x] = \frac{\Pr[x|v] \Pr[v]}{\Pr[x]} \quad \text{Bayes theorem.}$$

$$\operatorname{argmax} \Pr[v|x] = \operatorname{argmax} \Pr[x|v] \Pr[v] = \operatorname{argmax} \Pr[x_1, x_2, \dots, x_k | v] \Pr[v]$$
$$x = (x_1, \dots, x_k)$$

Suppose x_i and y are binary.
There are totally $\Theta(2^k)$ different parameters (instance, classification).

A lot of data needed.

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Naïve Bayes Classifier

Pr[v|x] = Pr[x|v] Pr[v] / Pr[x] Bayes theorem.

argmax Pr[v|x] = argmax Pr[x|v] Pr[v] = argmax Pr[x1, x2, ..., xk | v] Pr[v]
x = (x1, ..., xk)

Suppose xi and y are binary.
There are totally O(2^k) different parameters (instance, classification).

Table with 4 columns: Sky, Water, Forecast, EnjoySport. Rows include Sunny, Warm, Same, Yes; Sunny, Warm, Same, No; Rainy, Warm, Change, No; Sunny, Cool, Change, Yes; Sunny, Cool, Same, no.

A lot of data needed.

Can you classify a new instance (Sunny, Warm, Change)?
Pr[Sunny, Warm, Change|yes, D]=0
Pr[Sunny, Warm, Change|no, D]=0

Naïve Bayes Classifier

argmax Pr[v|x] = argmax Pr[x|v] Pr[v] = argmax Pr[x1, x2, ..., xk | v] Pr[v]
x = (x1, ..., xk)

Suppose xi and y are binary.
There are totally O(2^k) different parameters (instance, classification).

Naïve Bayes Assumption: given the classification v, the attributes are independent.

Pr[x1, x2 | v] = Pr[x1 | v] Pr[x2 | v]

Naïve Bayes Classifier

Naïve Bayes Assumption: given the classification v, the attributes are independent.

Pr[x1, x2 | v] = Pr[x1 | v] Pr[x2 | v]

Table with 4 columns: Sky, Water, Forecast, EnjoySport. Row: Sunny, Warm, Same, Yes.

Table with 4 columns: Sky, Water, Forecast, EnjoySport. Rows include Sunny, Warm, Same, Yes; Sunny, Warm, Same, No; Rainy, Warm, Change, No; Sunny, Cool, Change, Yes; Sunny, Cool, Same, no.

Can you classify a new instance (Sunny, Warm, Change)?

Pr[Sunny, Warm, Change|yes]
= Pr[Sunny|yes] * Pr[Warm|yes] * Pr[Change|yes]

Naïve Bayes Classifier

argmax Pr[v|x] = argmax Pr[x|v] Pr[v]
= argmax Pr[x1, x2, ..., xk | v] Pr[v]

Naïve Bayes Assumption: given the classification v, the attributes are independent.

Pr[x1, x2 | v] = Pr[x1 | v] Pr[x2 | v]

argmax Pr[x1, x2, ..., xk | v] Pr[v] = argmax [Pr[xi | v] Pr[v]

Naïve Bayes Classifier: argmax [Pr[xi | v] Pr[v]

How many parameters now? O(k)

Naïve Bayes Classifier

argmax Pr[x1, x2, ..., xk | v] Pr[v] = argmax [Pr[xi | v] Pr[v]

Naïve Bayes Classifier: argmax [Pr[xi | v] Pr[v]

Can you classify a new instance (Sunny, Warm, Change)?

Pr[Sunny|yes] * Pr[Warm|yes] * Pr[Change|yes] * Pr[yes]

Pr[Sunny|no] * Pr[Warm|no] * Pr[Change|no] * Pr[no]

Naïve Bayes Classifier

Naïve Bayes Classifier: argmax [Pr[xi | v] Pr[v]

For a new instance (x1, ..., xk) and each v in V.

Estimate Pr[xi | v] and Pr[v] for each xi and v by data D.

MLE of Pr[v] and Pr[xi | v]
Bernoulli Point Estimation.

Cclass=v: set of instances with classification v in D.

Cxi=xi: set of instances with xi as the i-th attribute.

Pr[v]_MLE = |Cclass=v| / |D|
Pr[xi | v]_MLE = |Cclass=v intersect Cxi=xi| / |Cclass=v|

Naïve Bayes Classifier

Naïve Bayes Classifier: argmax [Pr[xi | v] Pr[v]

Pr[v] = |Cclass=v| / |D|, Pr[xi | v] = |Cclass=v intersect Cxi=xi| / |Cclass=v|

Table with 4 columns: Sky, Water, Forecast, EnjoySport. Rows include Sunny, Warm, Same, Yes; Sunny, Warm, Same, No; Rainy, Warm, Change, No; Sunny, Cool, Change, Yes; Sunny, Cool, Same, no.

How to classify (Sunny, Warm, Change)?

Pr[yes]=2/5,
Pr[Sunny|yes] = 2/2,
Pr[Warm|yes] = 1/2
Pr[Change|yes] = 1/2

Pr[no]=3/5,
Pr[Sunny|no] = 2/3,
Pr[Warm|no] = 2/3
Pr[Change|no] = 1/3

Text Classification: Rumor or not Rumor

Article: a sequence of words.

- X -> V
- X: all possible articles
- V={rumor, not rumor}
- D: some labeled articles

x= 'I have a red apple and a blue apple'

v_opt = argmax Pr[x | v] Pr[v]

Text Classification: Rumor or not Rumor

Text Classification. Rumor or not Rumor??

Article x: a sequence of words.

x= 'I have a red apple and a blue apple'

v_opt = argmax Pr[x | v] Pr[v]

There are so many sequences of words.

- An article usually has more than 1000 words.
- More than 10,000 common words.
- That is 10,000^1000 = 10^4000
- Atoms in universe: 10^80
- Hm..
- We need some assumption/simplification.

Text Classification: Rumor or not Rumor

- Text Classification. Rumor or not Rumor??

- Article x : a sequence of words. (L : length)

$$\operatorname{argmax}_v \Pr[x|v] \Pr[v]$$

$x = \text{'I have a red apple and a blue apple'}$

- Naïve Bayes Assumption: the positions are independent given the class.

$$\operatorname{argmax}_v \prod_{i=1}^L \Pr[X_i = x_i|v] \Pr[v]$$

- $\Pr[X_i = x_i|v]$ the probability of observing x_i in the i -th position.

$$I \mid have \mid a \mid red \mid apple \mid and \mid a \mid blue \mid apple$$

Remarks

- What if part of the new instance is never observed?

- Let us use ‘smoothing’.

$$\Pr[x_i|v]_{MLE} = \frac{|C_{class=v} \cap C_{X_i=x_i}| + mp}{|C_{class=v}| + m}$$
- m-estimate
- m is a constant and p is the prior estimate of x_i over possible values. If no prior estimate, set $p = 1/k$ where k is the number of possible values of the attribute.
- Pretend you have m extra instances of class v and mp of them have x_i as the attribute value.

Remarks

- Naïve Bayes Assumption: the attributes are conditionally independent.

- What if the assumption is not true?

$$\Pr[x_1, x_2, \dots, x_k|v] \Pr[v] \neq \prod \Pr[x_i|v]$$

- This assumption may not be true, but this approximate performs good.
- A plausible reason: Only need the probability of the correct class to be the largest!
- E.g.
- Truth: $\Pr[f(x) = 1] = 0.99$ and $\Pr[f(x) = 0] = 0.01$. Very likely $f(x) = 1$
- Your estimate: $\Pr[f(x) = 1] = 0.51$ and $\Pr[f(x) = 0] = 0.49$. You say $f(x) = 1$.

Text Classification: Rumor or not Rumor

- $\Pr[X_i = x_i|v]$ the probability of observing x_i in the i -th position.
- How to compute $\Pr[X_i = x_i|v]$?

- Positions have the same distribution over the word.
- $\Pr[X_i = \text{apple}|v] = \Pr[X_j = \text{apple}|v]$
- $\Pr[X_i = \text{apple}|v]$ the probability that the i -th position is ‘apple’.

- $\Pr[x_i|v]$ can be computed by $\frac{\text{Count}(x_i, v)}{\sum_{x \in X} \text{Count}(x, v)}$ where X is the set of all distinct words, and $\text{count}(x, v)$ is number of the times word x appears in documents of class v .

Remarks

- What if part of the new instance is never observed?

- Suppose you have $x = (x_1, cool, x_3)$ but no training instance has Water=Cool.

$$\Pr[x_i|v]_{MLE} = \frac{|C_{class=v} \cap C_{X_i=x_i}| + mp}{|C_{class=v}| + m}$$

{cool, warm}

Sky	Water	Forecast	EnjoySport
Sunny	Warm	Same	Yes
Sunny	Warm	Same	No
Rainy	Warm	Change	No
Sunny	Warm	Change	Yes

Remarks

- Naïve Bayes Assumption: the attributes are conditionally independent.

- The effect of this assumption:

- (a) the hypothesis space is restricted to those satisfy this assumption.
- (b) it requires less data (low variance).

$$\Pr[x_1, x_2, \dots, x_k|v] \Pr[x_i|v]$$

(Sky=Sunny, Temperature=Warm, Normal, Strong, Warm, Same)=Yes

- (c) Naïve Bayes classifier finds the most probable classification within this hypothesis.
- If the assumption is true, Naïve Bayes is the optimal classifier.

Remarks

- What if part of the new instance is never observed?

- Suppose you have $x = (x_1, cool, x_3)$ but no training instance has Water=Cool.
- We will have $\prod \Pr[x_i|yes] \Pr[yes] = \prod \Pr[x_i|no] \Pr[no] = 0$ regardless of other attributes of x .

$$\Pr[x_i|v]_{MLE} = \frac{|C_{Y=v} \cap C_{X_i=x_i}|}{|C_{Y=v}|}$$

- This is not reasonable.

Sky	Water	Forecast	EnjoySport
Sunny	Warm	Same	Yes
Sunny	Warm	Same	No
Rainy	Warm	Change	No
Sunny	Warm	Change	Yes

Example

- A text classification example (from Dan Jurafsky)

	Doc	Words	Class
Training	1	Chinese Beijing Chinese	c
	2	Chinese Chinese Shanghai	c
	3	Chinese Macao	c
	4	Tokyo Japan Chinese	j
Test	5	Chinese Chinese Chinese Tokyo Japan	?

- We use m-estimate where (m=number of distinct word) and (p=1/m).
- m=6, p=1/6

$\Pr[j]=1/4$
 $\Pr[c]=3/4$

$\Pr[\text{Chinese}|j]=(1+1)/(3+6)=2/9$
 $\Pr[\text{Tokyo}|j]=(1+1)/(3+6)=2/9$
 $\Pr[\text{Japan}|j]=(1+1)/(3+6)=2/9$
- $\Pr[j|x] = \left(\frac{1}{4}\right) * \left(\frac{2}{9}\right)^3 * \left(\frac{2}{9}\right) * \left(\frac{2}{9}\right) \approx 0.0001$
- $\Pr[c|x] = \left(\frac{3}{4}\right) * \left(\frac{2}{9}\right)^3 * \left(\frac{1}{14}\right) * \left(\frac{1}{14}\right) \approx 0.0003$

$\Pr[\text{Chinese}|c]=(5+1)/(8+6)=3/7$
 $\Pr[\text{Tokyo}|c]=(0+1)/(8+6)=1/14$
 $\Pr[\text{Japan}|c]=(0+1)/(8+6)=1/14$

Dealing with Small Numbers

- A practical issue: $\prod \Pr[x_i|v]$

- We are multiplying lots of small numbers: underflow.

- $0.5^{57} = 7 E - 18$
- $\Pr[j|x] = \left(\frac{1}{4}\right) * \left(\frac{2}{9}\right)^3 * \left(\frac{2}{9}\right) * \left(\frac{2}{9}\right) \approx 0.0001$
- $\Pr[c|x] = \left(\frac{3}{4}\right) * \left(\frac{2}{9}\right)^3 * \left(\frac{1}{14}\right) * \left(\frac{1}{14}\right) \approx 0.0003$

- Solution: use log and add.
- $a * b = e^{\ln a + \ln b}$
- Keep the log form.

Gaussian Naïve Bayes

- Continuous features

Sky	Water	Forecast	EnjoySport
Sunny	Warm	Same	Yes

Sky	Water	Forecast	EnjoySport
0.2	0.5	0.7	Yes

argmax_v \prod_{i=1}^k Pr[X_i = x_i | v] Pr[v]

- Pr[v]_{MLE} can be computed in the same way.

Pr[Sky = sunny | yes]_{MLE} = \frac{yes \wedge sunny}{yes}

Pr[Sky = 0.2 | yes]_{MLE} = ??

Generally, assume a distribution over the domain of Sky.

- Discrete domain {sunny, cloudy}
- Continuous domain R.

- Assume that Pr[Sky = x | yes] follows a particular distribution.

Gaussian Naïve Bayes

- Continuous features

Sky	Water	Forecast	EnjoySport
0.2	0.5	0.7	Yes

- Assume Pr[Sky = x | yes] follows a particular distribution.
- Naïve Bayes + Gaussian
- X_i: the i-th attribute, v_k the k-th classification.

- Assume Pr[X_i = x_i | v_k] follows N(\mu_{i,k}, \sigma_{i,k}^2)

Pr[X_i = x | v_k] = \frac{1}{\sigma_{i,k} \sqrt{2\pi}} e^{-\frac{(x_i - \mu_{i,k})^2}{2\sigma_{i,k}^2}}

Point estimation:
Learn \mu_{i,k}, \sigma_{i,k}^2 from data

Gaussian Naïve Bayes

- Continuous features

- X_i: the i-th attribute, v_k the k-th class.
- Assume Pr[X_i = x_i | v_k] follows N(\mu_{i,k}, \sigma_{i,k}^2)

Sometimes we assume:
The variance is
Independent of class \sigma_{i,k}^2 = \sigma_i^2
Independent of attribute \sigma_{i,k}^2 = \sigma_k^2
Independent of both \sigma_{i,k}^2 = \sigma^2

Pr[X_i = x | v_k] = \frac{1}{\sigma_{i,k} \sqrt{2\pi}} e^{-\frac{(x_i - \mu_{i,k})^2}{2\sigma_{i,k}^2}}

Point estimation:
Learn \mu_{i,k}, \sigma_{i,k}^2 from data

Gaussian Naïve Bayes

- Continuous features

Pr[X_i = x_i | v_k] = \frac{1}{\sigma_{i,k} \sqrt{2\pi}} e^{-\frac{(x_i - \mu_{i,k})^2}{2\sigma_{i,k}^2}}

u_{i,k}^{MLE} = \frac{\sum_{x \in class_k} x_i}{|class_k|}

\sigma_{i,k}^2_{MLE} = \frac{\sum_{x \in class_k} (x_i - \mu_{i,k}^{MLE})^2}{|class_k|}

class_k: the set of examples of class k.

Recap: how to learn a Gaussian.

Unbiased:
\sigma_{i,k}^2_{MLE} = \frac{\sum_{x \in class_k} (x_i - \mu_{i,k})^2}{|class_k| - 1}

Summary

- Naïve Bayes Classifier

argmax Pr[v | x]

= argmax Pr[x | v] Pr[v]

= argmax \prod Pr[x_i | v] Pr[v]

Assume a form for them.
Estimate it by data.

Summary

- Bayes optimal classifier
 - Review
- Naïve Bayes Classifier
 - What is the assumption? Why we need it?
 - When the attributes are discrete
 - How to estimate the parameters?
 - m-estimate
 - When the attributes are continuous
 - Gaussian naïve Bayes.
 - How to estimate the parameters?

Sky	Water	Forecast	EnjoySport
Sunny	Warm	Same	Yes

- Text classification

x = 'I have a red apple and a blue apple'

Group Discussion

- A text classification example (from Dan Jurafsky)

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Pr[Chinese | j]=(1+1)/(3+6)=2/9
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Pr[Japan | j]=(1+1)/(3+6)=2/9

- Pr[j | x] = (\frac{1}{4}) * (\frac{2}{9})^3 * (\frac{2}{9}) * (\frac{2}{9}) \approx 0.0001
- Pr[c | x] = (\frac{3}{4}) * (\frac{2}{9})^3 * (\frac{1}{14}) * (\frac{1}{14}) \approx 0.0003
- y = (Japan, Macao, Macao)

Pr[Chinese | c]=(5+1)/(8+6)=3/7
Pr[Tokyo | c]=(0+1)/(8+6)=1/14
Pr[Japan | c]=(0+1)/(8+6)=1/14