

MATH 1530: ABSTRACT ALGEBRA

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Notes for Abstract Algebra

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1 Introduction to groups

1.1 Preliminary definitions

Definition 1.1.1: A **set** is “a collection of elements,” e.g., the integers $\mathbb{Z} = \{\dots, -2, -1, 0, 1, 2, \dots\}$, the real numbers \mathbb{R} , and the rational numbers \mathbb{Q} (fractions). Note that we use $\mathbb{Z}_{\geq 0} = \{0, 1, 2, \dots\}$ to refer to the nonnegative integers.

Definition 1.1.2: If A, B are sets, define the **Cartesian product** as

$$A \times B = \{(a, b) \mid a \in A, b \in B\}$$

We can abbreviate $A^2 = A \times A$. Similarly, if A_1, \dots, A_n are sets, then

$$A_1 \times \dots \times A_n = \{(a_1, \dots, a_n) \mid a_1 \in A_1, \dots, a_n \in A_n\}$$

Let $A^n = A \times \dots \times A$ (n times).

Definition 1.1.3: A **function** $f : A \rightarrow B$, or a **map**, is an association of an element $f(a) \in B$ to every element $a \in A$. We call A the **domain** of f , and B the **codomain** of f . Furthermore, the **range** or **image** of f is

$$\{f(a) : a \in A\}$$

Example 1: Let $f : \mathbb{Z} \rightarrow \mathbb{Z}$ be given by $x \mapsto 2x$.¹ The codomain and domain are both \mathbb{Z} , while the image is

$$\{b \in \mathbb{Z} : b = 2a \text{ for some } a \in \mathbb{Z}\}$$

which is the set of even numbers.

Definition 1.1.4: A **binary operation** on a given set G is a function $* : G \times G \rightarrow G$. For example, integer addition $(+ : \mathbb{Z} \times \mathbb{Z} \rightarrow \mathbb{Z})$ is a binary operation.

¹The symbol \mapsto means “maps to.”

1.2 What is a group?

Definition 1.2.1: A **group** is a set G together with a binary operation $*$: $G \times G \rightarrow G$ such that the following hold:

- (1) “Associativity”: for $a, b, c \in G$, $(a * b) * c = a * (b * c)$.
- (2) “Existence of the identity”: there is an element $e \in G$ such that for all $g \in G$, $e * g = g$ and $g * e = g$.
- (3) “Existence of inverses”: for every $g \in G$, there is an element that we’ll call $g^{-1} \in G$ such that $g * g^{-1} = g^{-1} * g = e$, where e is an identity element of G .

Theorem 1.2.2

$(\mathbb{Z}, +)$ forms a group.^a

^aWe write the ordered pair $(\mathbb{Z}, +)$ to represent the integers along with the binary operation of addition.

Proof. Indeed, we check that $(\mathbb{Z}, +)$ satisfies the three axioms of being a group:

- (1) For associativity, we note that $(a + b) + c = a + (b + c)$ for all $a, b, c \in \mathbb{Z}$.
- (2) For existence of the identity, $0 \in \mathbb{Z}$ satisfies $0 + a = a + 0 = a$ for all $a \in \mathbb{Z}$.
- (3) For existence of inverses, consider some $a \in \mathbb{Z}$. Then assert that $-a \in \mathbb{Z}$ satisfies $a + (-a) = (-a) + a = 0$.

Thus, we have shown that $(\mathbb{Z}, +)$ is a group. \square

Definition 1.2.3: Let $(G, *)$ be a group. Then G is a **commutative** or **abelian** group if $a * b = b * a$ for all $a, b \in G$.

For example, \mathbb{Z} , \mathbb{R} , and \mathbb{Q} with addition are all **commutative groups**. However, below is an example of a non-commutative group.

Example 2: Not all groups are commutative. Let G be the symmetries of a can (cylinder) C which are physically possible, i.e., the rigid motions preserving the can. These are called the orientation-preserving isometries of \mathbb{R}^3 . More precisely, we can define the set of symmetries

$$\text{Sym}(C) = \{A : \mathbb{R} \rightarrow \mathbb{R} : \det(A) = 1, A(C) = C\}$$

where A is an linear transformation which is an isometry. Put this together with the binary operation of composition \circ , and this forms a group.

However, these motions are not commutative. That is, flipping the can and then rotating it is distinct from rotating the can and then flipping it.

Theorem 1.2.4

Every group has a unique identity element.

1.3 The group $\mathbb{Z}/n\mathbb{Z}$

Definition 1.3.1: Let A be a nonempty set. Then a **relation** on A is a subset $R \subseteq A \times A$, which is written $a \sim b$ if and only if $(a, b) \in R$.

Definition 1.3.2: A relation R is an **equivalence relation** if it satisfies the following three properties:

- (1) “**Reflexivity**”: $a \sim a$ for all $a \in A$.
- (2) “**Symmetry**”: if $a \sim b$, then $b \sim a$ for all $a, b \in A$.
- (3) “**Transitivity**”: if $a \sim b$ and $b \sim c$, then $a \sim c$ for all $a, b, c \in A$.

Let $f : A \rightarrow D$ be a function. Given $a, b \in A$, we’ll say $a \sim b$ if and only if $f(a) = f(b)$. This is an equivalence relation; moreover, all equivalence relations can be written in this form.

Example 3: Consider the set $A = \{\text{students in Math 1530}\}$. For any two students $a, b \in A$, say $a \sim b$ if and only if a has the same birthday as b . This is an equivalence relation, so we can relate this to the above form as follows. Let $D = \{\text{Jan 1}, \dots, \text{Dec 31}\}$ be the set of possible birthdays, and $f : A \rightarrow D$ be a function mapping students to their birthdays.

Definition 1.3.3: Let \sim be an equivalence relation on A . Then we say

$$\bar{a} = \{b \in A : a \sim b\}$$

is an **equivalence class** of a . The equivalence classes of A partition it into non-overlapping groups covering all of A .

Let $n \in \mathbb{Z}$. Say $n \mid a$ (pronounced “ n divides a ”) if $a = kn$ for some $k \in \mathbb{Z}$. Now define a relation \equiv_n on \mathbb{Z} by $a \equiv_n b$ if $n \mid (a - b)$. We call this relation “congruent modulo n .” To prove that \equiv_n is an equivalence relation on \mathbb{Z} , we must show the following:

- (1) $a \equiv_n a$ for all $a \in \mathbb{Z}$.
- (2) $a \equiv_n b$ implies $b \equiv_n a$ for all $a, b \in \mathbb{Z}$.
- (3) $a \equiv_n b$ and $b \equiv_n c$ implies $a \equiv_n c$ for all $a, b, c \in \mathbb{Z}$.

Proof. Indeed, we will show that \equiv_n satisfies the three axioms of equivalence relations:

- (1) For reflexivity, $a - a = 0$ and $n \mid 0$.
- (2) For symmetry, $a \equiv_n b \implies n \mid (a - b) \implies a - b = kn$ for some $k \in \mathbb{Z}$. We want to show that $b \equiv_n a$, i.e., $b - a = ln$ for some $l \in \mathbb{Z}$. We may take $l = (-k)$.
- (3) For transitivity, there exists $k, l \in \mathbb{Z}$ such that $a - b = kn$ and $b - c = ln$. Then, adding these equations gives $a - c = (k + l)n$. Since $(k + l) \in \mathbb{Z}$, we conclude $n \mid (a - c) \implies a \equiv_n c$.

□

Definition 1.3.4: $\mathbb{Z}/n\mathbb{Z}$ is the set of equivalence classes modulo n , i.e., equivalence classes with respect to the equivalence relation \equiv_n .

For example, $\mathbb{Z}/5\mathbb{Z} = \{\bar{0}, \bar{1}, \bar{2}, \bar{3}, \bar{4}\}$. The choice of “captains” is not important, so we could alternatively write this as $\mathbb{Z}/5\mathbb{Z} = \{\bar{10}, \bar{-4}, \bar{2}, \bar{8}, \bar{24}\}$.

Definition 1.3.5: We define the binary operation of addition $+$: $\mathbb{Z}/n\mathbb{Z} \times \mathbb{Z}/n\mathbb{Z} \rightarrow \mathbb{Z}/n\mathbb{Z}$ as follows: $\bar{a} + \bar{b} = \overline{a + b}$ for all $\bar{a}, \bar{b} \in \mathbb{Z}/n\mathbb{Z}$.

Lemma 1.3.6

Addition on $\mathbb{Z}/n\mathbb{Z}$ is well-defined, as stated above.

Proof. Given $a_1, a_2 \in \mathbb{Z}$ such that $\bar{a}_1 = \bar{a}_2$ and $b_1, b_2 \in \mathbb{Z}$ such that $\bar{b}_1 = \bar{b}_2$, we want to show that $\overline{a_1 + b_1} = \overline{a_2 + b_2}$. Indeed, $a_1 - a_2 = kn$ and $b_1 - b_2 = ln$ for $k, l \in \mathbb{Z}$. Adding these equations gives

$$(a_1 + b_1) - (a_2 + b_2) = (k + l)n$$

so that $\overline{a_1 + b_1} = \overline{a_2 + b_2}$ since $(k + l) \in \mathbb{Z}$. □

Theorem 1.3.7

$(\mathbb{Z}/n\mathbb{Z}, +)$ is a group.

Proof. Again, we check the three group axioms:

(1) We have

$$\begin{aligned} \bar{a} + (\bar{b} + \bar{c}) &= \bar{a} + \overline{b + c} \\ &= \overline{a + (b + c)} \\ &= \overline{(a + b) + c} \\ &= \overline{a + b} + \bar{c} \\ &= (\bar{a} + \bar{b}) + \bar{c} \end{aligned}$$

by associativity of addition.

(2) We have $\bar{0} + \bar{a} = \bar{a} + \bar{0} = \bar{a}$ for all $a \in \mathbb{Z}/n\mathbb{Z}$.

(3) We have $-\bar{a} + \bar{a} = \bar{a} + (-\bar{a}) = \bar{0}$ for all $a \in \mathbb{Z}/n\mathbb{Z}$. □

Definition 1.3.8: We define the binary operation of multiplication \cdot : $\mathbb{Z}/n\mathbb{Z} \times \mathbb{Z}/n\mathbb{Z} \rightarrow \mathbb{Z}/n\mathbb{Z}$ as follows: $\bar{a} \cdot \bar{b} = \overline{ab}$ for all $\bar{a}, \bar{b} \in \mathbb{Z}/n\mathbb{Z}$.

Theorem 1.3.9

Multiplication on $\mathbb{Z}/n\mathbb{Z}$ is well-defined, as defined above.

1.3.1 The multiplicative group $(\mathbb{Z}/n\mathbb{Z})^\times$

However, $(\mathbb{Z}/n\mathbb{Z}, \cdot)$ is not a group unless $n = 1$, as inverses may not exist. Indeed, $\bar{1}$ is an identity, but $\bar{0} \cdot a = \bar{1}$ has no solution, i.e., there is no multiplicative inverse for $\bar{0}$. Now, let:

$$(\mathbb{Z}/n\mathbb{Z})^\times = \{\bar{a} \in \mathbb{Z}/n\mathbb{Z} : \bar{a} \cdot \bar{c} = \bar{1} \text{ for some } \bar{c} \in \mathbb{Z}/n\mathbb{Z}\}$$

We call this set “the multiplicative units of $\mathbb{Z}/n\mathbb{Z}$.”

Example 4: Given $n = 4$, we say $(\mathbb{Z}/4\mathbb{Z})^\times = \{\bar{1}, \bar{3}\}$. In particular, $\bar{1} \cdot \bar{1} = \bar{1}$ and $\bar{3} \cdot \bar{3} = \bar{1}$.

Theorem 1.3.10

$(\mathbb{Z}/n\mathbb{Z})^\times, \cdot$ is a group.

Proof. Given $\bar{a}, \bar{c} \in (\mathbb{Z}/n\mathbb{Z})^\times$, we must show that $\bar{a} \cdot \bar{c} \in (\mathbb{Z}/n\mathbb{Z})^\times$. First, we will show that \cdot defines a binary operation on $(\mathbb{Z}/n\mathbb{Z})^\times$, i.e., $(\mathbb{Z}/n\mathbb{Z})^\times$ is closed under multiplication. Indeed, $\bar{a} \cdot \bar{b} = \bar{1}$ and $\bar{c} \cdot \bar{d} = \bar{1}$ for some $\bar{b}, \bar{d} \in \mathbb{Z}/n\mathbb{Z}$. Multiplying these equations gives:

$$\begin{aligned} \bar{1} &= (\bar{a} \cdot \bar{b})(\bar{c} \cdot \bar{d}) \\ &= (\bar{a} \cdot \bar{c})(\bar{b} \cdot \bar{d}) \end{aligned}$$

In addition, associativity holds as in $\mathbb{Z}/n\mathbb{Z}$. There is an identity element, namely $\bar{1}$, and inverses exist as in $\mathbb{Z}/n\mathbb{Z}$ based on the definition of $(\mathbb{Z}/n\mathbb{Z})^\times$. \square

Theorem 1.3.11

$(\mathbb{Z}/n\mathbb{Z})^\times = \{\bar{a} : a \in \mathbb{Z}, (a, n) = 1\}$

1.3.2 Applications of arithmetic in $\mathbb{Z}/n\mathbb{Z}$

Example 5: What is the last digit of 2^{50} ? To calculate this, work in $\mathbb{Z}/10\mathbb{Z}$:

$$\begin{aligned} \bar{2} \cdot \bar{2} &= \bar{4} \\ \bar{2} \cdot \bar{2} \cdot \bar{2} &= \bar{8} \\ \bar{2} \cdot \bar{2} \cdot \bar{2} \cdot \bar{2} &= \bar{6} \\ \bar{2} \cdot \bar{2} \cdot \bar{2} \cdot \bar{2} \cdot \bar{2} &= \bar{2} \end{aligned}$$

and so on. Hence this cycles through $(\bar{2}, \bar{4}, \bar{8}, \bar{6})$ as demonstrated above. We can use this pattern to see the last digit is $\boxed{4}$. Alternatively, since $\bar{2}^5 = \bar{2}$:

$$\begin{aligned} \bar{2}^{50} &= (\bar{2}^5)^{10} \\ &= \bar{2}^{10} \\ &= \bar{2}^5 \cdot \bar{2}^5 \\ &= \bar{2} \cdot \bar{2} = \bar{4} \end{aligned}$$

1.4 Some general theorems about groups

Lemma 1.4.1

Let $(G, *)$ be a group. Then G has a unique identity element.

Proof. Let $e, f \in G$ be identity elements. Then:

$$e = e * f \text{ (since } f \text{ is an identity element)}$$

$$e * f = f \text{ (since } e \text{ is an identity element)}$$

Therefore $e = f$ and there is exactly one identity element. \square

Lemma 1.4.2

Let $(G, *)$ be a group. Then G has a unique inverse.

Proof. Given $a \in G$, suppose that $b, c \in G$ are inverses of a . Then:

$$e = a * b \text{ (since } b \text{ inverse of } a)$$

$$c * e = c * a * b$$

$$c = b \text{ (since } c \text{ inverse of } a)$$

Since $b = c$, every element of a group must have a unique inverse. \square

Lemma 1.4.3

Let $(G, *)$ be a group. Then $(a * b)^{-1} = (b^{-1}) * (a^{-1})$ for all $a, b \in G$.

Proof. We need to check that $(a * b) * ((b^{-1}) * (a^{-1})) = e$ is the identity element. This is left as an exercise to the reader. \square

Lemma 1.4.4

Let $(G, *)$ be a group. For any $a_1, \dots, a_n \in G$, $a_1 * \dots * a_n$ has a well-defined value, i.e., is independent of bracketing.

Theorem 1.4.5

Given $(G, *)$ a group and $a, b \in G$, the equation $ax = b$ has a unique solution.

1.5 The order of a group

Definition 1.5.1: Let $(G, *)$ be a group. The **order of a group** G denoted $|G|$ is the number of elements. If G is infinite, say $|G| = \infty$.

Definition 1.5.2: Let $(G, *)$ be a group. The **order of an element** $a \in G$ is the smallest $n \in \mathbb{Z}_{>0}$ such that $a^n = e$.

Example 6: The symmetries of a can $Sym(C)$ has order $|Sym(C)| = \infty$, but it has elements of finite order. For instance, the identity has order $|e| = 1$. A rotation by 180° has order 2, a rotation by 120° has order 3, and so on. In fact, for any order $n \in \mathbb{Q}$, a rotation by $2\pi/n$ has order n .

1.6 A brief interlude on functions

Definition 1.6.1: Let $f : A \rightarrow C$ be a function on sets. Then f is **injective** (one-to-one) if given any two elements $a, b \in A$, then $f(a) = f(b) \implies a = b$.^a

^aThe contrapositive, $a \neq b \implies f(a) \neq f(b)$ is equivalent.

Definition 1.6.2: Let $f : A \rightarrow C$ be a function on sets. Then f is **surjective** (onto) if for all $c \in C$, there exists $a \in A$ with $f(a) = c$.

Definition 1.6.3: A function is **bijective** if it is both injective and surjective.

Given a function $f : A \rightarrow C$ between finite sets A and C , then we write $|A|$ to denote the number of elements (i.e., the **cardinality**) of A . Then, we can say:

1. f injective $\implies |A| \leq |C|$
2. f surjective $\implies |A| \geq |C|$
3. f bijective $\implies |A| = |C|$

1.7 Dihedral groups

Definition 1.7.1: The **dihedral group**, denoted D_{2n} , is the group of rigid motions of a regular n -gon. The group operation is composition.

The $2n$ subscript in the name for the dihedral group refers to the order of the group. We can rotate the n -gon by integer multiples of $2\pi/n$, and we can “flip” the n -gon in \mathbb{R}^3 . These combinations of rotations and flips are specifically the $2n$ elements of the dihedral group.

More rigorously, we can label the vertices of an n -gon $\{1, \dots, n\}$ in clockwise order. A rigid motion of the n -gon can be recorded as a bijection

$$\sigma : \{1, \dots, n\} \rightarrow \{1, \dots, n\}$$

i.e., a permutation of $\{1, \dots, n\}$. Therefore, $\sigma(j)$ records the new position of vertex j . We claim that the map of sets

$$D_{2n} \rightarrow \{\text{bijections from } \{1, \dots, n\} \rightarrow \{1, \dots, n\}\}$$

is injective. The intuition here is that the rigid motions of the n -gon are a subset of the possible permutations. Now, note that D_{2n} has at least $2n$ elements (as shown above).

Theorem 1.7.2

$|D_{2n}| = 2n$ (i.e., D_{2n} is the dihedral group of order $2n$)

Proof. We know that $|D_{2n}| \geq 2n$, so we want to show $|D_{2n}| \leq 2n$. Define a map:

$$\begin{aligned} D_{2n} &\rightarrow \{(1, 2), \dots, (n-1, n), (n, 1), (2, 1), \dots, (n, n-1), (1, n)\} \\ \sigma &\mapsto (\sigma(1), \sigma(2)) \end{aligned}$$

where the target has cardinality $2n$. This map is injective, since any two adjacent elements uniquely define a rigid motion of the n -gon. Thus, $|D_{2n}| \leq 2n$. \square

1.7.1 Explicit description of D_{2n}

Label an n -gon $\{1, \dots, n\}$ on its vertices. Let r be clockwise rotation by $2\pi/n$, and let s be a reflection about the central line bisecting the angle at vertex 1. Note that:

- $1, \dots, r^{n-1} \in D_{2n}$ are distinct rotations.
- s is distinct from $1, \dots, r^{n-1}$.
- $s, sr, sr^2, \dots, sr^{n-1} \in D_{2n}$ are all distinct.

Theorem 1.7.3

$D_{2n} = \{1, \dots, r^{n-1}, s, \dots, sr^{n-1}\}$

Proof. We need only show that

$$r^i \neq sr^j \text{ for any } i, j \in \{1, \dots, n-1\}$$

Indeed, $r^{i-j} \neq s$. \square

Furthermore, $rs = sr^{-1}$, i.e., rotating and reflecting is the same as reflecting and rotating by the same amount in the opposite direction.

Given these observations, we now know how to multiply in D_{2n} . For example, we can multiply the rigid motions (sr^6) and (sr^9) on an arbitrary regular n -gon:

$$\begin{aligned} (sr^6)(sr^9) &= s(r^6s)r^9 \\ &= s(r^5sr^{-1})r^9 \\ &= s(sr^{-6})r^9 \\ &= r^3 \end{aligned}$$

Alternatively, we can define D_{2n} in terms of generators and relations as follows:

$$D_{2n} = \langle r, s \mid r^n = 1, s^2 = 1, rs = sr^{-1} \rangle$$

In particular, any relation on elements of D_{2n} can be obtained from the given relations.

1.8 Symmetric groups

Definition 1.8.1: Let X be a non-empty set, and let S_X be the permutations of X . When $X = [n] := \{1, \dots, n\}$, we write $S_n = S_{\{1, \dots, n\}}$. Then S_X is a group under composition, where $f * g = g \circ f$.

Example 7: $S_3 = \{\{1, 2, 3\}, \{1, 3, 2\}, \{2, 1, 3\}, \{2, 3, 1\}, \{3, 1, 2\}, \{3, 2, 1\}\}$.

Lemma 1.8.2

A map $f : A \rightarrow C$ is a bijection if and only if there exists a function $g : C \rightarrow A$ such that $f \circ g = \text{id}_C$ and $g \circ f = \text{id}_A$.

Theorem 1.8.3

The order $|S_n| = n!$, i.e., the factorial of n .

Proof. To choose a permutation of $\{1, \dots, n\}$, we can choose any of n mappings for 1, $n-1$ remaining mappings for 2, and so on. Since there is no “overlap,” this is an injective function. Furthermore, since this is injective and the domain and range have the same number of elements, it is also a bijection. \square

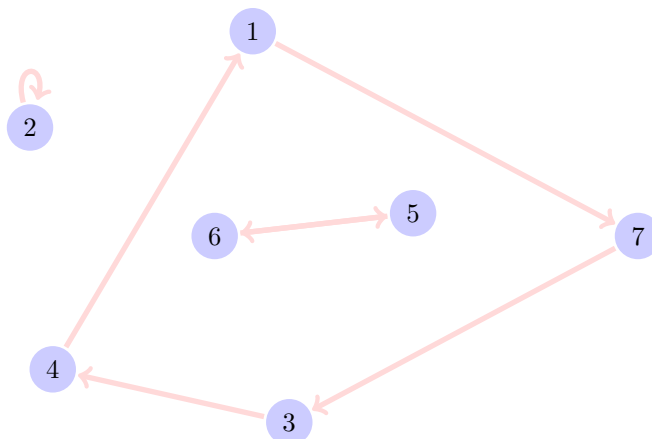
1.8.1 Cycle notation for permutations

Let $\sigma \in S_n$. Using the two-line notation style for permutations, we can write:

$$\sigma = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 \\ 7 & 2 & 4 & 1 & 6 & 5 & 3 \end{pmatrix}$$

This maps $1 \mapsto 7$, $2 \mapsto 2$, and so on. Alternatively, it can be represented with a directed graph, as in the following example:

Example 8: Given $\sigma = \{7, 2, 4, 1, 6, 5, 3\}$, the corresponding directed graph is as follows:



The above directed graph can be divided into three disjoint cycles $\sigma = (1734)(56)(2)$, or just $\sigma = (1734)(56)$.² More generally, we'll claim that any such permutation must produce a graph of disjoint cycles. This notation allows us to calculate inverses and powers:

- **Inverses** - $\sigma^{-1} = (4371)(65)$, which is calculated by going in the reverse direction
- **Powers** - $\sigma^2 = (13)(47)(5)(6) = (13)(47)$, where we count every other element of each cycle. To calculate σ^n , count every n th element.

Theorem 1.8.4

Let $\sigma \in S_n$. Then, draw an arrow from i to $\sigma(i)$ for each $i \in \{1, \dots, n\}$. The resulting directed graph is a collection of disjoint cycles.

Theorem 1.8.5

In general, for $\sigma \in S_n$, $|\sigma|$ is the least common multiple of all cycle lengths in the cycle decomposition of σ .

Definition 1.8.6: Say that $\sigma \in S_n$ is an ***m-cycle*** if its cycle notation has just one cycle of length m (and all other cycles length 1).

We can also use this notation to calculate products (i.e., composition) of permutations. For example, consider the case of $(154)(23) \circ (12345)$:³ since $1 \mapsto 2$ in (12345) and then $2 \mapsto 3$ in $(154)(23)$, it must be the case that $1 \mapsto 3$ in their composition. This general principle can be applied repeatedly to calculate that

$$\begin{aligned}(154)(23) \circ (12345) &= (13)(2)(4)(5) = (13) \\ (1734) \circ (56) &= (1734)(56)\end{aligned}$$

²It is a convention to remove 1-element cycles from the notation, just as a convenience. The order of these cycles is not important, and σ could equivalently be written as $\sigma = (65)(3417)$, or one of many other possible combinations.

³ $\sigma \circ \tau$ means first τ , then σ

where in the second example, composition is nothing more than concatenation since the two permutations are non-overlapping. Such disjoint cycles always commute, but not all permutations commute. For example, $(12) \circ (13) = (132)$ but $(13) \circ (12) = (123)$.

Theorem 1.8.7

S_n is nonabelian for $n \geq 3$.

1.9 Homomorphisms and isomorphisms

1.9.1 Motivation

Consider the following groups:

1. $(\mathbb{Z}/2\mathbb{Z}, +) = \{\bar{0}, \bar{1}\}$

- $\bar{0} + \bar{0} = \bar{0}$
- $\bar{0} + \bar{1} = \bar{1}$
- $\bar{1} + \bar{0} = \bar{1}$
- $\bar{1} + \bar{1} = \bar{0}$

2. $S_2 = \{\text{id}, (12)\}$, with \circ :

- $\text{id} \circ \text{id} = \text{id}$
- $\text{id} \circ (12) = (12)$
- $(12) \circ \text{id} = (12)$
- $(12) \circ (12) = \text{id}$

3. A group $(P, +)$ with elements $P = \{\text{even}, \text{odd}\}$, with $+$ given by:

- $\text{even} + \text{even} = \text{even}$
- $\text{even} + \text{odd} = \text{odd}$
- $\text{odd} + \text{even} = \text{odd}$
- $\text{odd} + \text{odd} = \text{even}$

Are these groups all the same? Not exactly (they have different elements), but they are all *isomorphic*. This is described formally in the next section.

1.9.2 Formal definitions and theorems

Definition 1.9.1: A **homomorphism** of groups $(G, *)$ and (H, \cdot) is a map $\phi : G \rightarrow H$ such that for all $g, g' \in G$, $\phi(g) \cdot \phi(g') = \phi(g * g')$. Equivalently, for all $a, b, c \in G$, if $a * b = c$, then also $\phi(a) \cdot \phi(b) = \phi(c)$.

Example 9: Given groups G and H , there is always a homomorphism

$$\begin{aligned} \phi : G &\rightarrow H \\ g &\mapsto e \text{ (identity in } h) \end{aligned}$$

Then ϕ is a homomorphism since $\phi(g_1) \cdot \phi(g_2) = \phi(g_1 g_2) = \phi(e)$.

Definition 1.9.2: Let $(G, *)$ and (H, \cdot) be groups. An **isomorphism** is a map $\phi : G \rightarrow H$ such that the following are true:

- ϕ is a bijection.
- for all $g, g' \in G$, $\phi(g) \cdot \phi(g') = \phi(g * g')$.

In this case, we say that $G \cong H$. An isomorphism is a bijective homomorphism.

Example 10: Here are some examples of isomorphisms:

- $G \cong G$ via identity map.
- Consider the exponential function $\exp : \mathbb{R} \rightarrow \mathbb{R}_{>0}$ bijection taking addition to multiplication: $e^{x+y} = e^x e^y$. This yields the isomorphism $(\mathbb{R}, +) \cong (\mathbb{R}_{>0}, \cdot)$.

Theorem 1.9.3

If $G \cong H$ and G is abelian, then H is abelian.

Lemma 1.9.4

Let $\phi : G \rightarrow H$ be a homomorphism. Then $\phi(e_G) = e_H$.

Proof. Indeed, $\phi(e_G) = \phi(e_G e_G) = \phi(e_G) \phi(e_G)$. Given $x \in H$ a group, $x \cdot x = x$ if and only if x is the identity. Thus $\phi(e_G) = e_H$. \square

Lemma 1.9.5

Let $\phi : G \rightarrow H$ be a homomorphism. Then for all $a \in G$, $\phi(a^{-1}) = \phi(a)^{-1}$.

Proof. Given $a \in G$, $\phi(e_G) = \phi(a \cdot a^{-1}) = \phi(a) \phi(a^{-1}) = e_H$ by the previous lemma. Therefore, $\phi(a^{-1}) = \phi(a)^{-1}$. \square

1.9.3 Homomorphisms of \mathbb{Z}

Let H be any group. What are the homomorphisms $\mathbb{Z} \rightarrow H$? We claim that given $b \in H$, there is a unique homomorphism $\phi : \mathbb{Z} \rightarrow H$ with $\phi(1) = b$. This means that a homomorphism $\mathbb{Z} \rightarrow H$ exists and is uniquely determined by the element it sends 1 to.

Theorem 1.9.6

Let H be any group. Then given an element $b \in H$, there exists a unique homomorphism ϕ from the additive group $(\mathbb{Z}, +)$ to H such that $\phi(1) = b$.

Proof. For uniqueness, if $\phi : \mathbb{Z} \rightarrow H$ with $\phi(1) = b$, then $\phi(1+1) = \phi(1)\phi(1) = b^2$. Continuing in this way, $\phi(1+\dots+1) = \phi(1)\dots\phi(1) = b^n$. Furthermore, $\phi(0) = e_H$ and $\phi(-1) = b^{-1}$; as before, $\phi(-n) = b^{-n}$. Thus $\phi(n) = b^n$ for all $n \in \mathbb{Z}$. For existence, we'll show that the following is a homomorphism:

$$\begin{aligned}\phi : \mathbb{Z} &\rightarrow H \\ n &\mapsto b^n\end{aligned}$$

Indeed, given $x, y \in \mathbb{Z}$, then $\phi(x)\phi(y) = b^x b^y = b^{x+y} = \phi(x+y)$ as desired. \square

2 Subgroups and generators

2.1 Subgroups

Definition 2.1.1: Let G be a group. A subset $H \subseteq G$ is a **subgroup** of G if:

- $H \neq \emptyset$
- Given $g_1, g_2 \in H$, then $g_1 g_2 \in H$.
- Given $g \in H$, $g^{-1} \in H$.

Equivalently, the operator on G restricts to an operation on H , and H is a group with respect to this. Write $H \leq G$ if this is true.

Example 11: Here are some examples of subgroups (and non-subgroups):

1. The additive group $2\mathbb{Z} = \{\dots, -2, 0, 2, \dots\}$ is a subgroup of \mathbb{Z} ; this holds for any $n\mathbb{Z}$.
2. $\mathbb{Z}_{\geq 0} = \{0, 1, 2, \dots\} \subseteq \mathbb{Z}$ is not a subgroup since additive inverses do not exist.
3. For any group G , G and the trivial subgroup e_G are always groups.

Lemma 2.1.2: Subgroup Criterion

Given a group G , say $H \subseteq G$ for some nonempty subset H . Then H is a subgroup if for all $x, y \in H$, $xy^{-1} \in H$.

Definition 2.1.3: Let G be a group. We define the **center** of G as

$$Z(G) = \{g \in G : gx = xg \text{ for all } x \in G\}$$

If G is abelian, then $Z(G) = G$ and conversely $Z(G) = G \implies G$ is abelian.

Theorem 2.1.4

The center of a group is always a subgroup, i.e., $Z(G) \leq G$ for any G .

Proof. Given $x, y \in Z(G)$, we want to show that $xy^{-1} \in Z(G)$. Namely, given $z \in G$, we want $(xy^{-1})z = z(xy^{-1})$. Indeed, since x, y commute with all members of G :

$$\begin{aligned}
 (xy^{-1})z &= x(y^{-1}z) \\
 &= (y^{-1}z)x \\
 &= (z^{-1}y)^{-1}x \\
 &= (yz^{-1})^{-1}x \\
 &= (zy^{-1})x \\
 &= z(y^{-1}x) \\
 &= z(xy^{-1})
 \end{aligned}$$

as desired. Hence, the center of a group is always a subgroup. \square

2.2 Generators

Definition 2.2.1: Let G be a group, and let $S \subseteq G$ be any subset. Then the subgroup **generated by** S , denoted $\langle S \rangle$, is the collection of all (finite) products^a of elements in S and their inverses in G . If $\langle S \rangle = G$, we say S **generates** G .

^aWe say e is the product of exactly 0 elements.

Example 12: In \mathbb{Z} , $\langle 1 \rangle = \mathbb{Z}$. Furthermore, $\langle 3, 4 \rangle = \mathbb{Z}$ since $4 - 3 = 1$, which has already been shown to generate \mathbb{Z} . However, $\langle 2 \rangle = 2\mathbb{Z}$ does not generate \mathbb{Z} . Notice that $\langle a, b \rangle = \mathbb{Z}$ if and only if a, b are relatively prime.

Theorem 2.2.2

The generated set $\langle S \rangle$ is a subgroup.

Theorem 2.2.3

The subgroup $\langle S \rangle$ is the smallest subgroup of G containing S .^a

^aThat is, for any subgroup $H \leq G$ such that $S \subseteq H$, then $\langle S \rangle \subseteq H$.

Proof. Indeed, given a subgroup $H \leq G$ with $S \subseteq H$, then H must contain all products of elements in S as well as inverses. Hence, $\langle S \rangle \subseteq H$. \square

2.2.1 Properties of \mathbb{Z}

Recall that $\mathbb{Z} = \{\dots, -2, -1, 0, 1, 2, \dots\}$ is generated by a single element $\langle 1 \rangle$:

- **Well-ordering principle** - Every nonempty subset of $\mathbb{Z}_{>0}$ has a least element.
- For $a, b \in \mathbb{Z}$, say $a \mid b$ (“ a divides b ”) if $b = ac$ for some $c \in \mathbb{Z}$.

- Given $a, b \in \mathbb{Z} - \{0\}$, there exists a unique integer $d \geq 1$ (called the **greatest common divisor**) such that:
 - $d \mid a$ and $d \mid b$
 - if $e \in \mathbb{Z}$ such that $e \mid a$ and $e \mid b$, then $e \mid d$

We notate this as $d = \gcd(a, b) = (a, b)$.

- Given $a, b \in \mathbb{Z} - \{0\}$, there exists a unique integer $l \geq 1$ (called the **least common multiple**) such that:
 - $a \mid l$ and $b \mid l$
 - if $m \in \mathbb{Z}$ such that $a \mid m$ and $b \mid m$, then $l \mid m$

We notate this as $l = \text{lcm}(a, b) = [a, b]$.

Theorem 2.2.4

Given $a, b \in \mathbb{Z}$, the product $a \cdot b = (a, b) \cdot [a, b]$.

- **Division algorithm** - Given $a, b \in \mathbb{Z} - \{0\}$, there exists unique $q, r \in \mathbb{Z}$ such that $a = bq + r$ and $0 \leq r < b$.
- **Euclidean algorithm** - repeated use of the division algorithm can be used to compute the greatest common denominator. For example:

$$39 = 2(15) + 9$$

$$15 = 1(9) + 6$$

$$9 = 1(6) + 3$$

$$6 = 2(3) + 0$$

so we conclude that the greatest common denominator $(39, 15) = 3$.

Theorem 2.2.5

Given $a, b \in \mathbb{Z} - \{0\}$, compute the following steps:

$$\begin{array}{ll}
 a = q_0 b + r_0 & 0 \leq r_0 < b \\
 b = q_1 r_0 + r_1 & 0 \leq r_1 < r_0 \\
 r_0 = q_2 r_1 + r_2 & 0 \leq r_2 < r_1 \\
 \vdots & \vdots \\
 r_{k-2} = q_k r_{k-1} + r_k & 0 \leq r_k < r_{k-1} \\
 r_{k-1} = q_{k+1} r_k + 0 &
 \end{array}$$

We make the following three claims about this algorithm:

1. The algorithm terminates.
2. $r_k = ma + nb$ for some $m, n \in \mathbb{Z}$
3. $r_k = (a, b)$

Proof. Indeed, we'll show the three claims:

1. Suppose for the sake of contradiction that the algorithm doesn't terminate. Then the sequence $r_0 > r_1 > r_2 > \cdots > 0$ has no least element, violating the well-ordering principle.
2. Working backwards along the Euclidean algorithm:

$$\begin{aligned} r_k &= r_{k-2} - q_k r_{k-1} \\ &= r_{k-2} - q_k(r_{k-3} - q_{k-1} r_{k-2}) \\ &\quad \vdots \\ &= am + bn \end{aligned}$$

where we reach the final form by iterating substitution until the beginning of the algorithm.^a

3. Note $r_k \mid r_{k-1}$ by the last equation. Also, $r_k \mid r_{k-2}$ by the second-to-last equation. Iterating this process, we get $r \mid a$ and $r \mid b$. It remains to show that if $s \in \mathbb{Z}$, $s \mid a$, and $s \mid b$, then $s \mid r$. Indeed, $s \mid a$ and $s \mid b \implies s \mid (am + bn)$ for $m, n \in \mathbb{Z}$, so $s \mid r$ by (2). □

^aAs an aside, we can use this to write 3 as a linear combination of 39 and 15:

$$\begin{aligned} 3 &= 9 - 1(6) \\ &= 9 - 1(15 - 9) \\ &= 2(9) - 1(15) \\ &= 2(39 - 2 \cdot 15) - 1(15) \end{aligned}$$

This gives us $3 = 2 \cdot 39 - 5 \cdot 15$ as desired.

2.2.2 Cyclic groups

Definition 2.2.6: A group G is **cyclic** if it can be generated by a single element, i.e., $G = \langle x \rangle$ for some $x \in G$. Then $G = \{x^n : n \in \mathbb{Z}\}$.

Here are some examples of cyclic groups (and non-cyclic groups):

- $\mathbb{Z} = \langle 1 \rangle = \langle -1 \rangle$ is a cyclic group.
- $\mathbb{Z}/n\mathbb{Z} = \langle \bar{1} \rangle$ is also a cyclic group.
- \mathbb{R}/\mathbb{Z} is not a cyclic group. However, a dense cover can be generated by an irrational number. That is, for example, any element in \mathbb{R}/\mathbb{Z} is arbitrarily close to but not confined in $\langle \pi \rangle$.
- D_{2n} is not cyclic.
- Fix $n \geq 1$. Then $\{z \in \mathbb{C} : z^n = 1\}$ under multiplication is a cyclic group.
- There are no uncountable cyclic groups.

Lemma 2.2.7

If $H = \langle x \rangle$, then $|H| = |x|$ (i.e., if $|x| = \infty$, then $|H| = \infty$)

Proof. First, consider the case that $|x| = n$ is finite. Then we claim that

$$H = \{1, x, \dots, x^{n-1}\}$$

and these are all distinct. If instead $x^a = x^b$ for some $x \leq a < b < n$, then $1 = x^{b-a}$, contradicting $|x| = n$. To show that H does indeed equal this set,^a we need to show that $H \supseteq \{1, x, \dots, x^{n-1}\}$ (the reverse direction is by definition). Indeed, given $x^t \in H$ for some $t \in \mathbb{Z}$, then by the division algorithm $t = qn + r$ for some $0 \leq r < n$. Then:

$$x^t = x^{qn+r} = x^{nq}x^r \in \{1, \dots, x^n\}$$

Now, suppose $|x|$ infinite. Then, we'll claim $\{\dots, x^{-1}, 1, x, x^2, \dots\}$ are all distinct. Indeed, if $x^a = x^b$ for $a < b$, then $x^{b-a} = 1$ is a contradiction. \square

^aIn general, to show that any two sets A and E are equal, it is standard to show that $A \subseteq E$ and $E \subseteq A$.

Lemma 2.2.8

Let G be any group, and $x \in G$. If $x^m = 1$ and $x^n = 1$, then $x^{(m,n)} = 1$.

Proof. Let $d = (m, n)$. Note that $d = am + bn$ for $a, b \in \mathbb{Z}$. Then $x^d = x^{am}x^{bn} = 1$. \square

Lemma 2.2.9

If $x^m = 1$, then $(|x|) \mid m$.

Proof. Let $n = |x|$. We want to show that $n \mid m$. If $m = 0$, then indeed $n \mid m$. Otherwise, let $d = (m, n)$. Then by the previous lemma, $x^d = 1$ so $d \geq n$; hence $d = n$. \square

Theorem 2.2.10

Let $G = \langle x \rangle = \{x^k : k \in \mathbb{Z}\}$. Then the following are true:

1. Let $|G| = n$. Then the map

$$\begin{aligned} \varphi : G &\rightarrow \mathbb{Z}/n\mathbb{Z} \\ x^k &\mapsto \bar{k} \end{aligned}$$

is well-defined and an isomorphism.

2. Let $|G| = \infty$. Then the map

$$\begin{aligned} \varphi : G &\rightarrow \mathbb{Z} \\ x^k &\mapsto k \end{aligned}$$

is well-defined and an isomorphism.

This is equivalent to saying that every cyclic group is isomorphic to \mathbb{Z} or some $\mathbb{Z}/n\mathbb{Z}$.

Proof. Let $H = \{\dots, x^{-2}, x^{-1}, 1, x, x^2, \dots\}$. Either every element in H is distinct, or some $x^i = x^j$ for $i \neq j$, which will result in a cyclic pattern. We'll prove the theorem by considering these two cases in turn:

1. ($|G| = n$) We claim that there exists $n \geq 1$ such that $x^n = 1$. Indeed, if $a < b$ with $x^a = x^b$ then $1 = x^{b-a}$. Now, choose the smallest n with this property. We'll define the following map

$$\begin{aligned}\varphi : H &\rightarrow \mathbb{Z}/n\mathbb{Z} \\ x^a &\mapsto \bar{a}\end{aligned}$$

and claim that it is an isomorphism. To show this is well defined: given $x^a = x^b$, we'll show that $\bar{a} = \bar{b}$. Assume so, and let $x^{b-a} = 1$ where we posit $b-a > 0$ without loss of generality. Then $x^{(n, b-a)} = 1$ (since the $\gcd(c, d)$ is a linear combination of integers c and d). Therefore, $n \leq (n, b-a)$, so $n \mid b-a$, and finally $\bar{a} = \bar{b}$. To show that φ is a homomorphism, consider the following derivation:

$$\begin{aligned}\varphi(x^k \cdot x^l) &= \varphi(x^{k+l}) \\ &= \overline{k+l} \\ &= \bar{k} + \bar{l} \\ &= \varphi(x^k) \cdot \varphi(x^l)\end{aligned}$$

Next, we'll claim that φ is clearly a surjection of sets of order n . Finally, to show injectivity: given a, b with $\bar{a} = \bar{b}$, we want to show that $x^a = x^b$. Indeed, $n \mid b-a$, so $x^a = x^b$ by our choice of n .

2. ($|G| = \infty$) We claim that the following map

$$\begin{aligned}\varphi : H &\rightarrow \mathbb{Z} \\ x^a &\mapsto a\end{aligned}$$

is an isomorphism. Indeed, $\varphi(x^a x^b) = \varphi(x^a) + \varphi(x^b)$, so this is a homomorphism. Since there is a unique x^a for each $a \in \mathbb{Z}$, this map is surjective. Similarly, since $x^a \neq x^b$ where $a \neq b$, then this map is injective as well. Hence φ is a bijection and a homomorphism and therefore an isomorphism. □

Example 13: What are the cyclic subgroups of $\mathbb{Z}/12\mathbb{Z}$? We can check each of the twelve elements, and see what subgroups they generate and if they are unique:

- $\langle x^1 \rangle = \langle x^5 \rangle = \langle x^7 \rangle = \langle x^{11} \rangle$
 - $\langle x^2 \rangle = \langle x^{10} \rangle$
 - $\langle x^3 \rangle = \langle x^9 \rangle$
 - $\langle x^4 \rangle = \langle x^8 \rangle$
 - $\langle 1 \rangle$
-

Theorem 2.2.11

Every subgroup of a cyclic subgroup is cyclic.

Proof. Let $G = \langle x \rangle$ be a cyclic group, and $H \leq G$ a subgroup. Now, consider the smallest $n \geq 1$ such that $x^n \in H$. Then we claim $H = \langle x^n \rangle$. We'll show this in two parts:

- It follows that $\langle x^n \rangle \subseteq H$ since H is a subgroup closed under the group operation.
- To show $H \subseteq \langle x^n \rangle$, consider an element $x^a \in H$. Then $x^{(a,n)} \in H \implies n \mid a$, so then $x^a \in \langle x^n \rangle$.

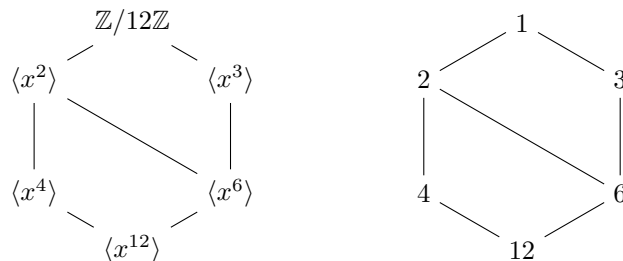
Since the sets are subsets of each other, it must be the case that $H = \langle x^n \rangle$. \square

Theorem 2.2.12

Let $H = \langle x \rangle$ be a cyclic group of order n . Then x^a generates H if and only if $(a, n) = 1$

2.3 Lattices of subgroups

Let G be a group, and say G is finite. The lattice of subgroups is a diagram of all subgroups of G : if $H < K$ is a proper subgroup and there are no subgroups properly between them,⁴ draw a line connecting H to K . For example, consider the diagram for $\mathbb{Z}/12\mathbb{Z} \cong H = \langle x : x^2 = 1 \rangle$.



For any $\mathbb{Z}/n\mathbb{Z}$, the graph of lattices is dual to the lattice of divisors of n , which is shown to the right for $n = 12$ in the above figure.

Theorem 2.3.1

If $H < K$ is a proper subgroup, and if $x \in K - H$ and $\langle H \cup \{x\} \rangle = K$, then there are no subgroups properly between H and K .

⁴We say a subgroup X is properly between two groups $H < K$ if H is a proper subgroup of X and X is a proper subgroup of K .

3 Group actions

Definition 3.0.1: A **group action** F of a group (G, \times) on a set A is a function $F : G \times A \rightarrow A$ satisfying two axioms:^a

- For all $g_1, g_2 \in G$, $a \in A$, then $F(g_2, F(g_1, a)) = F(g_2 g_1, a)$.
- For all $a \in A$, $F(e_G, a) = a$ where e_G is the identity element in G .

^aThe function application will be $F(g, a)$ for $g \in G$ and $a \in A$. The textbook (Dummit and Foote) writes $g \cdot a$ as notation for $F(g, a)$.

Example 14: Here are some examples of group actions:

1. Let $G = (\mathbb{R} - \{0\}, \times)$ be a multiplicative group, and let $A = \mathbb{R}^3$. Define the group action F to be scalar multiplication as follows:

$$F(r, (x, y, z)) = (rx, ry, rz)$$

Why is this a group action? We'll check that the two axioms hold. Indeed, the functions compose, i.e., for $r, s \in G$, then $F(r, F(s, (x, y, z))) = (rsx, rsy, rsz)$.⁵ Furthermore, $F(1, (x, y, z)) = (1x, 1y, 1z) = (x, y, z)$ as desired.

2. Let $G = S_n$ be the group of permutations on n elements. Then, let $A = \{1, 2, \dots, n\}$. Define $F : S_n \times A \rightarrow A$ by $F(\sigma, j) = \sigma(j)$. This is also a group action.
3. Let $G = \left\{ \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \right\}$ under matrix multiplication be the group of rotation matrices in the Euclidean two-dimensional plane. For brevity, we'll write $R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$. This is a group because:

- (a) *Inverses* - for any rotation $R(\theta)$, take $R(-\theta)$.
- (b) *Identity* - let the identity $R(0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$.
- (c) *Closure* - for any $R(\alpha)$ and $R(\beta)$, $R(\alpha)R(\beta) = R(\alpha + \beta)$.

Furthermore, this group inherits associativity from matrix multiplication.

3.1 Geometric rotations as group actions

Consider a geometric figure as a subset $S \subseteq \mathbb{R}^2$ in the real plane.

Definition 3.1.1: Given a set X , the **power set** $P(X)$ is defined to be the collection of all subsets of X .

Let $X = \{1, 2, \dots, n\}$. Then $P(X)$ has 2^n elements, because for each element of X , it can either be included or not be included in a given subset of X . For example, we have $\{1, 2\} \in P(X)$, $\emptyset \in P(X)$, and so on.

⁵Using the textbook notation, we can write $r \cdot (s \cdot (x, y, z)) = (rs) \cdot (x, y, z)$.

Now, let's define a group action on the power set. Define $F : G \times P(\mathbb{R}^2) \rightarrow P(\mathbb{R}^2)$ by $F(M, S) = M(S)$ where M is the rotation matrix $M \in G$ and S is our geometric figure in \mathbb{R}^2 . Note that $M(S) = \{Ms \in \mathbb{R}^2 : s \in S\}$.

To see what this looks like, let $R(\frac{\pi}{2}) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$. This will rotate $S \subseteq \mathbb{R}^2$ counterclockwise by $\pi/2$. Exercise: check that this is a group action.

3.2 Permutations and group actions

Theorem 3.2.1

Let a group G act on a set A via the group action F . Then, define σ_g by $a \mapsto F(g, a)$. We claim that this σ_g is a permutation in S_A .

Proof. We need to show that $\sigma_g : A \rightarrow A$ is both injective and surjective. Indeed, to show injectivity, take any $a_1, a_2 \in A$. Suppose $\sigma_g(a_1) = \sigma_g(a_2)$. Then:

$$\begin{aligned} a_1 &= e \cdot a_1 \\ &= (g^{-1}g) \cdot a_1 \\ &= g^{-1} \cdot (g \cdot a_1) \\ &= g^{-1} \cdot (g \cdot a_2) \\ &= (g^{-1}g) \cdot a_2 \\ &= a_2 \end{aligned}$$

This is sufficient to show injectivity, since $\sigma_g(a_1) = \sigma_g(a_2) \implies a_1 = a_2$. Next up, we'll show surjectivity. Take any element $a \in A$; then, we want to find $a' \in A$ such that $\sigma_g(a') = a$. Consider $g^{-1} \cdot a \in A$; then $g \cdot (g^{-1}a) = (gg^{-1}) \cdot a = a$. Thus, σ_g as defined above is both surjective and injective, and therefore bijective. Woohoo! \square

You can find some of the algebraic structure of G in S_A ; specifically, the homomorphism is preserved. This is defined formally in the following theorem. Note that this does not necessarily preserve injectivity.

Theorem 3.2.2

Let (G, \times) act on a set A , such that the group action is defined as follows:

$$\begin{aligned} \varphi : G &\rightarrow S_A \\ g &\mapsto \sigma_g \end{aligned}$$

where σ_g is defined as in Theorem 3.2. Then φ is a homomorphism.

Proof. Consider any two elements $g_1, g_2 \in G$. We need to check that $\varphi(g_1)\varphi(g_2) = \varphi(g_1g_2)$. Indeed, for any $a \in A$, we have

$$\begin{aligned}\sigma_{g_1}\sigma_{g_2}(a) &= \sigma_{g_1}(\sigma_{g_2}(a)) \\ &= g_1 \cdot (g_2 \cdot a) \\ &= (g_1g_2) \cdot a \\ &= \sigma_{g_1g_2}(a)\end{aligned}$$

Thus $\varphi(g_1)\varphi(g_2) = \varphi(g_1g_2)$ as desired. \square

4 Quotient groups

4.1 Preliminary definitions

Definition 4.1.1: The **image** of φ is $\text{im}(\varphi) = \{\varphi(g) : g \in G\}$.

Definition 4.1.2: The **kernel** of φ is $\ker(\varphi) = \{g \in G : \varphi(g) = 1_H\}$.

Theorem 4.1.3

Let $\varphi : G \rightarrow H$ be a group homomorphism. Then $\ker(\varphi) \leq G$ is a subgroup.

Proof. Note that $\varphi(1_G) = \varphi(1_H)$, so $1_G \in \ker(\varphi)$. Now, given $x, y \in \ker(\varphi)$, check that $xy^{-1} \in \ker(\varphi)$ by the subgroup criterion. Indeed, since φ is a homomorphism, $\varphi(xy^{-1}) = \varphi(x)\varphi(y)^{-1} = 1_H(1_H)^{-1} = 1_H$. \square

Theorem 4.1.4

Let $\varphi : G \rightarrow H$ be a group homomorphism. Then $\text{im}(\varphi) \leq H$ is a subgroup.

Definition 4.1.5: Let $\varphi : G \rightarrow H$ be a homomorphism. Then given $h \in \text{im}(\varphi)$, we say the **fiber** over h is

$$\varphi_h = \{g \in G : \varphi(g) = h\}$$

For example, $\varphi_{1_H} = \ker(\varphi)$. The fibers of φ partition G , i.e., every element of G is in exactly one fiber. We'll see this again with left and right cosets of a subgroup.

Definition 4.1.6: Let $\varphi : G \rightarrow H$ be a group homomorphism. Then define $G/\ker(\varphi)$ to have elements as the fibers of φ . Then we define $\varphi_h \cdot \varphi_{h'} = \varphi_{hh'}$ to be the group operation.

Note that $G/\ker(\varphi) \cong \text{im}(\varphi)$.

Definition 4.1.7: Let H be any subgroup of G . Then the **left cosets** of H are subsets of the form $gH = \{gh : h \in H\}$. The **right cosets** of H are subsets of the form $Hg = \{hg : h \in H\}$.

Further, remark that $H = 1H$ is a left coset, but it's the only left coset that's a subgroup because it is the only one containing the identity element $1 \in G$. Similarly, $H = H1$ is the only right coset that is a subgroup.

Example 15: Let $G = D_8$ be the group of symmetries of a square with the following eight elements: $\{1, r, r^2, r^3, s, sr, sr^2, sr^3\}$. Furthermore, let $H = \{1, r, r^2, r^3\}$ be the subgroup of rotations. The left cosets are as follows:

- $H = \{1, r, r^2, r^3\}$
- $rH = \{r, r^2, r^3, 1\}$
- $r^2H = \{r^2, r^3, 1, r\}$
- $r^3H = \{r^3, 1, r, r^2\}$
- $sH = \{s, sr, sr^2, sr^3\}$
- $srH = \{sr, sr^2, sr^3, s\}$
- $sr^2H = \{sr^2, sr^3, s, sr\}$
- $sr^3H = \{sr^3, s, sr, sr^2\}$

Of these left cosets, only two (H and sH) are distinct. Note that the left cosets of H partition G , since every element of G is contained in exactly one of H and sH .

Theorem 4.1.8

The left cosets of H partition G .^a

^aThe right cosets behave similarly, but there is no guarantee that the partitions are the same.

Proof. Given $g \in G$, note that $g = g1 \in gH$, so every element of G appears in at least one left coset of H . Now, we need to show that these cosets are disjoint. To prove this, suppose $g \in g'H$. Then, it suffices to show that $gH = g'H$. Indeed, let $g = g'h'$ for some $h' \in H$. Then:

$$\begin{aligned} gH &= \{gh : h \in H\} \\ &= \{g'h'h : h \in H\} \\ &= g'H \quad (\text{since } h'H = H \text{ by closure and inverses}) \end{aligned}$$

Therefore, the left cosets of H are indeed distinct. □

Theorem 4.1.9

Let $\varphi : G \rightarrow H$ be a homomorphism. For $g \in G$, let $h = \varphi(g)$. Then:

$$\varphi_h = gK = Kg$$

where $K = \ker(\varphi)$.

Lemma 4.1.10

Given a subgroup $H \leq G$, there is a bijection from $H \rightarrow gH$ for any $g \in G$.^a

^aSimilarly for the right coset Hg .

Proof. Consider the following map (not necessarily a homomorphism):

$$\begin{aligned} f : H &\rightarrow gH \\ h &\mapsto gh \end{aligned}$$

Indeed, f is a bijection from H to gH as defined above. \square

Corollary 4.1.11

Let G be a finite group, with subgroup $H \leq G$. Then $|H|$ divides $|G|$.

Proof. G is partitioned into cosets H, g_2H, \dots, g_kH for some g_2, \dots, g_k . We write

$$\begin{aligned} |G| &= |H| + |g_2H| + \dots + |g_kH| \\ &= |H| + \dots + |H| \\ &= k|H| \end{aligned}$$

so indeed the order of G is a multiple of $|H|$. \square

Definition 4.1.12: A subgroup N of G is **normal** if $gN = Ng$ for all $g \in G$.

Example 16: If G abelian, then any subgroup of G is normal. However, is the reverse statement true? No, consider $H = \{1, r, r^2, r^3\} \leq D_8$ as discussed in Example 15. H is normal in G , but we know that $G = D_8$ is not abelian since $rs \neq sr$, for example.

To see an example of a non-normal subgroup, consider $H' = \langle s \rangle = \{1, s\} \leq D_8$. The left and right cosets of H' are as follows:

- | | |
|---------------------------|---------------------------|
| • $H' = \{1, s\}$ | • $H' = \{1, s\}$ |
| • $rH' = \{r, sr^3\}$ | • $H'r = \{r, sr\}$ |
| • $r^2H' = \{r^2, sr^2\}$ | • $H'r^2 = \{r^2, sr^2\}$ |
| • $r^3H' = \{r^3, sr\}$ | • $H'r^3 = \{r^3, sr^3\}$ |

Indeed, these left and right cosets are not the same, so H' is not a normal subgroup of G .

4.2 Conjugacy

Definition 4.2.1: An **automorphism** of G is an isomorphism $G \rightarrow G$.

Definition 4.2.2: Let G be a group with element $g \in G$. Then **conjugation** by g is the following automorphism:

$$\begin{aligned}\varphi : G &\rightarrow G \\ x &\mapsto gxg^{-1}\end{aligned}$$

Proof. We'll show that φ (conjugation) is indeed an isomorphism in three steps:

- i. To show that φ is a homomorphism:

$$\begin{aligned}\varphi(xy) &= gxyg^{-1} \\ &= gxg^{-1}gyg^{-1} \\ &= \varphi(x)\varphi(y)\end{aligned}$$

- ii. To show that φ is injective, take $x, y \in G$ such that $gxg^{-1} = gyg^{-1}$. Then we have $x = y$ as desired.
- iii. To show that φ is surjective, let $y \in G$, and note $\varphi(g^{-1}yg) = g(g^{-1}yg)g^{-1} = y$. □

Definition 4.2.3: Two elements $x, y \in G$ are **conjugates** if $y = gxg^{-1}$ for some $g \in G$.

Theorem 4.2.4

Conjugacy is an equivalence relation on G .

Proof. By the definition of equivalence relations:

- i. **Reflexive** - $g = 1g1^{-1}$ for all $g \in G$.
- ii. **Symmetric** - say $y = gxg^{-1}$. Then $g^{-1}yg = x$, so this relation is symmetric.
- iii. **Transitive** - say $y = gxg^{-1}$ and $z = hyh^{-1}$ for some $g, h \in G$. Then $z = h(gxg^{-1})h^{-1} = (hg)x(hg)^{-1}$ as desired. □

Definition 4.2.5: Let G be a group. The **conjugacy classes** of G are the equivalence classes under the relation of conjugacy.

Example 17: For example, consider the conjugacy classes of D_8 :

- $\{1\}$ as the identity
- $\{r^2\}$ since $sr^2s^{-1} = r^2ss^{-1} = r^2$

- $\{r, r^3\}$ since $srs^{-1} = r^3ss^{-1} = r^3$
- $\{s, sr^2\}$ by similar reasoning
- $\{sr, sr^3\}$ by similar reasoning

Theorem 4.2.6

Let $N \leq G$ be a subgroup. Then N is normal if and only if $gNg^{-1} = N$ for all $g \in G$, where we define $gNg^{-1} := \{gng^{-1} : n \in N\}$.

Proof. Let $N \leq G$. Then by definition, N is normal iff $gN = Ng$ for all $g \in G$. Multiplying by g^{-1} on both sides gives $gNg^{-1} = N$ as desired. \square

Equivalently, $N \leq G$ is normal iff it is a union of conjugacy classes. We can see this by examining unions of the conjugacy classes of D_8 as defined in Example 17.