▶ Pitch for Vg (L8-70kts) Ground Reference Maneuver Maneuver Memory Items "APAMCO" (call out) ▶ Pitch (slowlv) to an at-► Altitude titude that induces a ▶ Power stall (call out) and wait ► Airspeed ► Mixture ► Recover ► Clearing Turns: two 90° • Reduce AOA. the drift turns (left & right) • Full power and slow-► Outside Reference flight recovery Slow Flight Stall: Power On ► A: completed >1500 AGL ► A: completed >1500 AGL ▶P: bottom of the green ▶P: bottom of the green; ► A: normal as required for target ►M: full rich airspeed ► C & O ► A: LOkts ► Landing config flow ►M: full rich ▶ Pitch & trim for 55-60kts ► (& 0) ► Add power when roll in ► Simultaneously increase ► Turns gently (<=15° bank) pitch (slowly) and apply ► Recover ("go-round"): 65-100% power • Full power & flaps 20° ► Stay coordinated with rud-• Pos∙ rate & LOkts der to avoid spin • Flaps 10° (clear from ▶Pitch (slowly) to an atobstacle) titude that induces a • Flaps up (safe altitude stall (call out) and wait & 65kts) ► Recover: Steep Turns Reduce AOA. ► A: completed >1500 AGL • Full power ▶P: bottom of the green; Emergency Descent as required for target ► "TTTCC" airspeed • Trim for Vq (┕Გ-70kts) ► A: <Va Turn (make necessary ► M: no change shallow/steep turns to ► C & O stay over the chosen ► Establish 45° bank ► Add power when roll in area) Troubleshoot (checklist) ▶ Use horizon to maintain Communicate VS., check and maintain Commit to landing altitude and airspeed ▶ Glide to the chosen area ▶ Roll out in advance to ▶ First circle: avoid overshooting establish visual/sink Stall: Power Off rate reference for later ► A: completed >1500 AGL turns ▶ P: no change finalize the descent ► A: normal strategy ►M: full rich ► Stay above the chosen ► C & O area by circling ▶ Power to idle (>=1000 RPM ► Aim for 1000AGL on the for safety) final downwind ▶ Dump all flaps when air-► Land on the "runwav" speed permits

Turn Around a Point

- ▶ Find a reliable point
- ► Start from the downwind ► Use a shallower/steeper bank angle to correct for
- ► Stay coordinated throughout the maneuver ► Make a 360° circle and
- focus on outside