

# COMP 64101

## Reasoning and Learning under Uncertainty

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### Lecture 3 - Part 3



*I know it's [Tuesday]. It's a good day for math!*

*–Inspired by Max Mintz, UPenn.*

- Intro (§9.1)
- Belief propagation on chains (§9.2)
- Belief propagation on trees (§9.3)
- More goodies on this (§9.4 – 9.7)

**Nota bene:** Section numbers refer to [Murphy \(2023\)](#).

# 9.1 Introduction

## Message passing algorithms

- For PGMs with a *sparse* graph structure.
- Leverage the CI properties encoded by the graph to perform efficient posterior inference: computing marginals, mode(s), sampling etc.
- Based on the principle of **dynamic programming** (DP):
  - Find global solution by finding local solutions to sub-problems.
  - Combine local optima to get global optima.
- Implementation idea:
  - Maintain probability distributions (beliefs) on the value of each node.
  - Update these beliefs given evidence from some part of the graph.
  - Pass beliefs on a node (or clique) to neighbouring nodes (or cliques).
- Note: messages to be passed are nothing else than the beliefs.
- These algorithms are a.k.a. **belief propagation** (BP) algorithms.

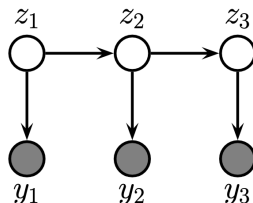
**To do:** Look up and learn more about the principle of DP.

## 9.2 Belief propagation on chains

- Easy start: Graph structure is a 1D chain.
- The idea of a Markov chain could be helpful to some extent, but the graph structure might not look exactly like a classical Markov chain.
- Keep in mind that there are hidden variables and observed variables.
- Further simplifications:
  - Directed PGMs.
  - Hidden variables are discrete.
- Methods extend to continuous latent variables, Undirected PGMs.

## 9.2.1 Hidden Markov Models (HMMs)

- Variables:
  - $\mathbf{z}_t$  are **hidden** (a.k.a. **latent**),
  - $\mathbf{y}_t$  are **observations** or **outputs**.
- HMMs are latent variable sequence models.

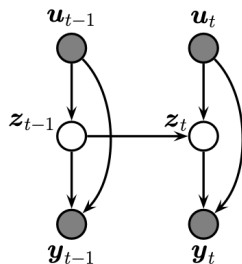


- CI properties given by the chain-structured graph (see figure).
- Joint distribution:

$$p(\mathbf{y}_{1:T}, \mathbf{z}_{1:T}) = \left[ p(\mathbf{z}_1) \prod_{t=2}^T p(\mathbf{z}_t | \mathbf{z}_{t-1}) \right] \left[ \prod_{t=1}^T p(\mathbf{y}_t | \mathbf{z}_t) \right]$$

# Compare: General setting of State Space Models (SSMs)

- Variables:
  - $\mathbf{z}_t$  are **hidden** (a.k.a. **latent**),
  - $\mathbf{y}_t$  are **observations** or **outputs**,
  - $\mathbf{u}_t$  are **optional inputs**.
- “Latent variable sequence models.”



- CI properties given by the chain-structured graph (see figure).
- Joint distribution:

$$p(\mathbf{y}_{1:T}, \mathbf{z}_{1:T} | \mathbf{u}_{1:T}) = \left[ p(\mathbf{z}_1 | \mathbf{u}_1) \prod_{t=2}^T p(\mathbf{z}_t | \mathbf{z}_{t-1}, \mathbf{u}_t) \right] \left[ \prod_{t=1}^T p(\mathbf{y}_t | \mathbf{z}_t, \mathbf{u}_t) \right]$$

## 9.2.1.1 Example: casino HMM

- **To do:** Read this example ([Murphy \(2023\)](#), pp. 402 - 403).

## 9.2.1.2 Posterior inference

- Posterior inference on the hidden states.
- Goal: Compute  $p(\mathbf{z}_t | \mathbf{y}_{1:T})$  for  $t = 1, \dots, T$ .
- Note: Computation given on whole stream of observations  $\mathbf{y}_{1:T}$
- This is an instance of smoothing!
- Forwards Filtering Backwards Smoothing (FFBS).



## 9.2.1.2 Posterior inference (cont'd)

- Case of discrete hidden variables:

$$\begin{aligned} p(\mathbf{z}_t = j | \mathbf{y}_{1:T}) &= p(\mathbf{z}_t = j | \mathbf{y}_{1:t} \mathbf{y}_{t+1:T}) \\ &= p(\mathbf{z}_t = j, \mathbf{y}_{t+1:T} | \mathbf{y}_{1:t}) / p(\mathbf{y}_{t+1:T} | \mathbf{y}_{1:t}) \\ &\propto p(\mathbf{z}_t = j, \mathbf{y}_{t+1:T} | \mathbf{y}_{1:t}) \\ &= p(\mathbf{z}_t = j | \mathbf{y}_{1:t}) p(\mathbf{y}_{t+1:T} | \mathbf{z}_t = j, \mathbf{y}_{1:t}) \\ &= p(\mathbf{z}_t = j | \mathbf{y}_{1:t}) p(\mathbf{y}_{t+1:T} | \mathbf{z}_t = j) \end{aligned}$$

- Idea: Compute the factors separately, then combine.
  - Forwards pass: Compute  $p(\mathbf{z}_t = j | \mathbf{y}_{1:t})$ .
  - Backwards pass: Compute  $p(\mathbf{y}_{t+1:T} | \mathbf{z}_t = j)$ .
- **Food for thought:** What if continuous hidden variables?

- 9.2.2 The forwards algorithm
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 403 - 404).
- 9.2.3 The forwards-backwards algorithm
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 404 - 407).
    - 9.2.3.1 Backwards recursion
    - 9.2.3.2 Example
    - 9.2.3.3 Two-slice smoothed marginals
    - 9.2.3.4 Numerically stable implementation
- 9.2.4 Forwards filtering backwards smoothing
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 407 - 408).
- 9.2.5 Time and space complexity
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 408 - 409).

- 9.2.6 The Viterbi algorithm
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 409 - 412).
    - 9.2.6.1 Forwards pass
    - 9.2.6.2 Backwards pass
    - 9.2.6.3 Example
    - 9.2.6.4 Time and space complexity
    - 9.2.6.5 N-best list
- 9.2.7 Forwards filtering backwards sampling
  - **To do:** Read about this ([Murphy \(2023\)](#), p. 412).

## 9.3 Belief propagation on trees

- Trees are special kinds of graph structures.
- Message passing algorithms, extended to trees.
- Build on ideas from:
  - Algorithms for HMMs (§ 9.2.3)
  - Algorithms for Kalman smoothing (§ 8.2.3)

- 9.3.1 Directed vs undirected trees
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 412 - 414).
- 9.3.2 Sum-product algorithm
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 414 - 415).
- 9.3.3 Max-product algorithm
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 415 - 417).
    - 9.3.3.1 Connection between MMM and MAP
    - 9.3.3.2 Connection between MPM and MAP
    - 9.3.3.3 Connection between MPE and MAP

# More goodies on BP on trees

- 9.4 Loopy belief propagation
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 417 - 428).
- 9.5 The variable elimination (VE) algorithm
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 428 - 434).
- 9.6 The junction tree algorithm (JTA)
  - **To do:** Read about this ([Murphy \(2023\)](#), p. 434).
- 9.7 Inference as optimization
  - **To do:** Read about this ([Murphy \(2023\)](#), pp. 435 - 437).

Kevin P. Murphy. *Probabilistic Machine Learning: Advanced Topics*. MIT Press, 2023. URL <http://probml.github.io/book2>.