

# Brushless Flycore Wiring Setup

## Bill of Materials

0.96" OLED - <https://www.amazon.com/gp/product/B09C5K91H7/>

Rotary (chose one)

20mm Encoder: <https://www.amazon.com/gp/product/B07DM2YMT4/>

15mm Encoder: <https://www.amazon.com/dp/B07D3D64X7/>

Trigger Switch: <https://www.amazon.com/gp/product/B00MFRMFS6/>

47UF Capacitor (if using the Mjolnir Board PCB):

[https://www.amazon.com/gp/product/B0BQ59XWNR/ref=ppx\\_yo\\_dt\\_b\\_search\\_asin\\_title?ie=UTF8&th=1](https://www.amazon.com/gp/product/B0BQ59XWNR/ref=ppx_yo_dt_b_search_asin_title?ie=UTF8&th=1)

Currently used motors: iFlight Xing2 1404 4600KV

<https://www.racedayquads.com/products/iflight-xing2-1404-4600kv-micro-motor>

ESC: any blheli32 ESCs (ones I use:

<https://www.racedayquads.com/products/spedix-gs35-35a-individual-esc-2-6s-dshot1200?variant=4258743123979> )

Arduino Nano3

Neutron Solenoid

1 Mjolnir Board

## Wire Lengths

Encoder Wires - 4x 8 inches 22g

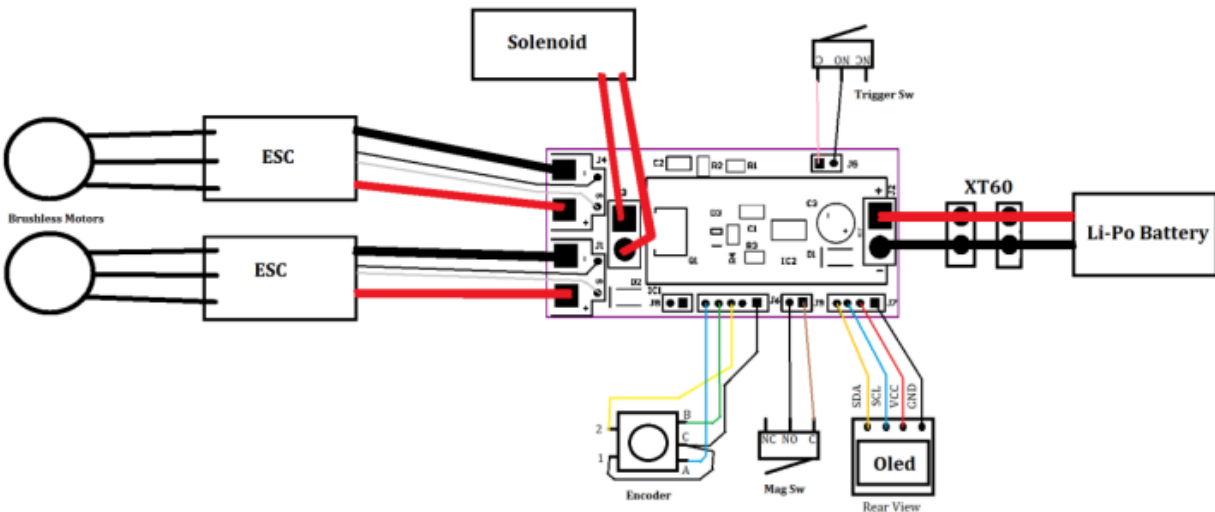
OLED Wires - 4x 8inches 22g

Trigger Switch - 2x 12inch 22g

Power (Pistol Mode) - 17in x2

# Overview

## Mjolnir PCB Setup

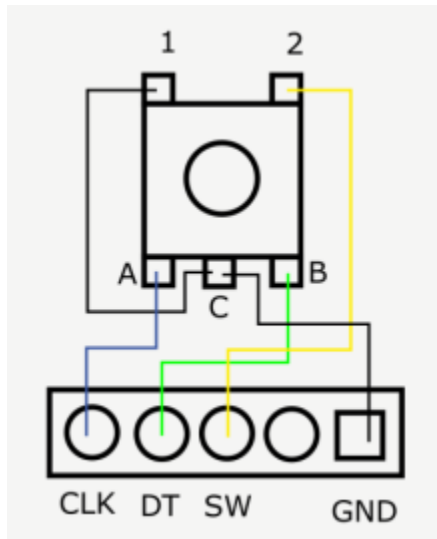


Arduino is mounted with 15-pin break aways on PCB

Trigger, Encoder, ESC Signal and 0.96" OLED utilizes JST-XH 2.56mm connectors with 22g wire

Solenoid, Power and ESC Power uses XT-30 connectors with 20g wire

## KY-22 Rotary (without PCB) Encoder Diagram



Encoder facing front

Ground Wire Connects to Tabs 1 and C

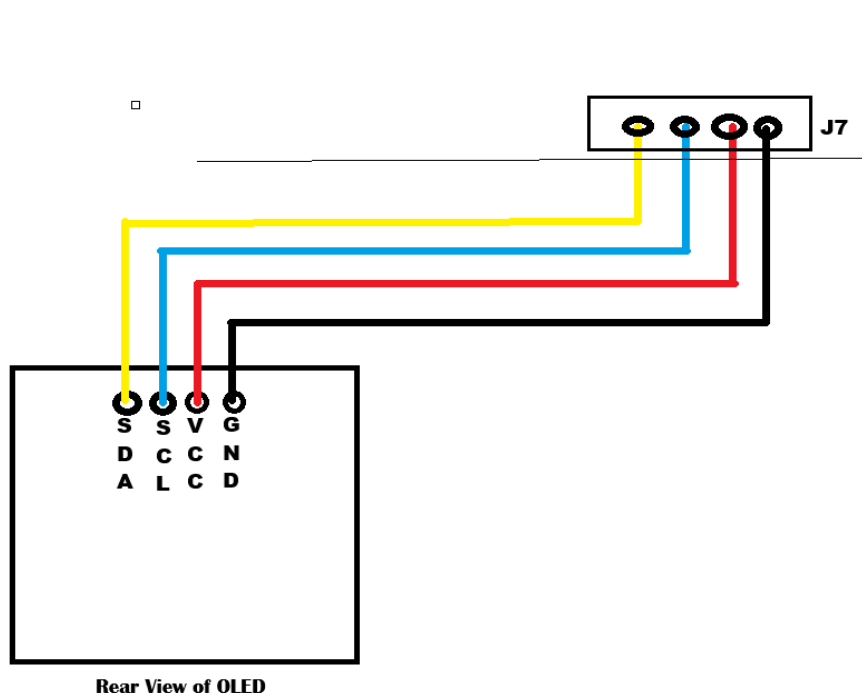
**SW Wire** connects to **Tab 2**

**DT Wire** connects to **Tab B**

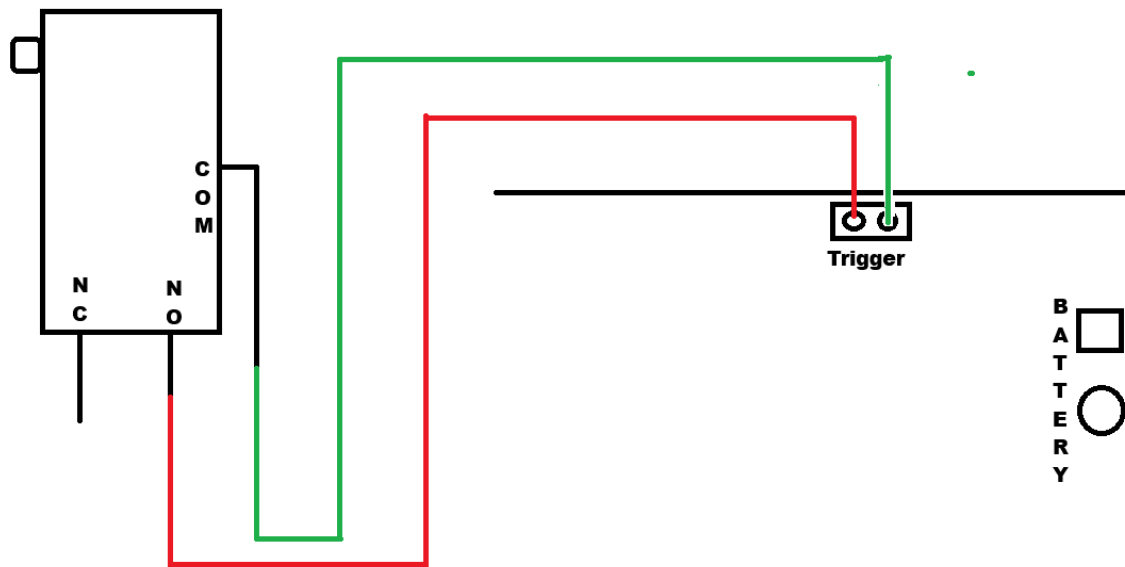
**CLK Wire** connects to **Tab A**

## O.96" OLED Screen

Wires from OLED screen connects to sections J7 (4 pin) of PCB. This is the only 4-Pin JST Connector on the PCB.



# Trigger



Wire from the NO (Normally Open) and Comm to the 2-pin Trigger port.