

Process Management:-

nice
setgid
getgid

chdir
setpgid
getrgid

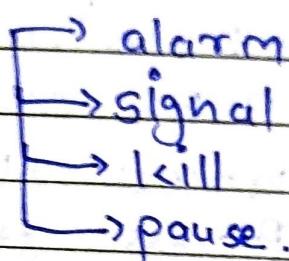
wait
getpgid
getuid

fork
getppid
getruid

exec
setuid

exit

signals



24) C/C++ methods/functions use sig.

Process:- is a program in execution.

Multiple instances of the same program are different processes.

Process memory image contains 3 components (context, data, program code) in 2 different address spaces:-

1. User Address Space:-

→ An executable program code.

→ Associated data needed by program.

2. Kernel Address Space:-

→ Execution context needed by OS to manage the process (PID, CPU registers, CPU time, stack, open files, signals).

Process Control Block (PCB) :-

- Every Process will maintain its own PCB in system process table array or linked list.
- Context / kernel address Space will PCB stack of processes.
- PCB contains:
 - Process ID, Parent Process ID
 - Process state
 - CPU State: CPU register contents, PSW (Process Status Word).
 - Priority and other scheduling info.
 - Pointers to different memory areas.
 - Open file information.
 - Signals and signal handlers info.
 - Various accounting info like CPU time etc.
 - Many other OS specific fields.

Operations on Process:-

1. Process Creation:-

- Data structures like PCB will initialize & set up.
- Initial resources allocate.
- Ready Queue add process.
- ↳ que of processes which are ready to run.

2. Process Scheduling:-

CPU will allot process to process & process run start.

Process Termination:

- Process को remove करती है।
- Resources को reclaim करती है।
- exit status तथा किसी data को
- कि किंवदं parent process को pass करती है।
- signal करती है कि Parent process के
interruption inform करती है।

Events that lead to Process Creation.

1. System boot :- bg process or daemons
 start होते हैं।

e.g. init bg की कार्यों को
 interactive mode में।

Sys of supervisor से किंवदं processes
 की functionality provide करती है।

2. User Request :- CLI shell या cmd run
 करते हैं या App run करते हैं या
 click करते हैं।

3. A process can spawn another
 i.e. child process using fork() e.g.
 servers can create new process
 for each client req.

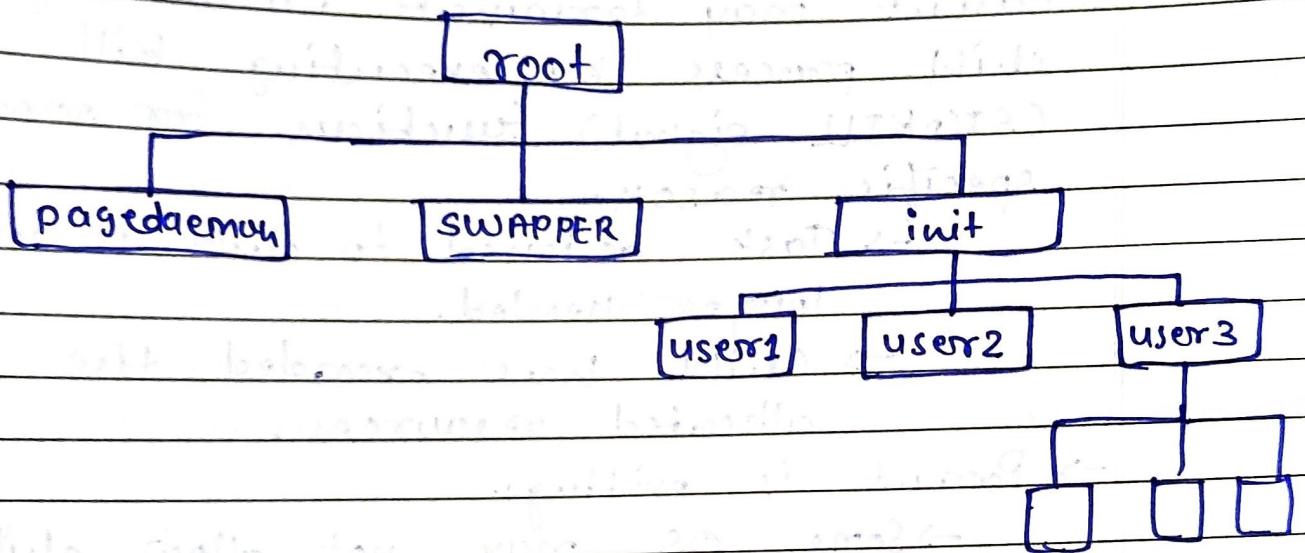
Stages of Linux Boot Process.

1. BIOS :- Basic Input Output System
 - performs system integrity checks, search boot loaders on cd-rom or disk, and executes MBR boot loader.
2. MBR :- Master Boot Record :-
 - Available in 1st sector of bootable disk, executes GRUB boot loader.
3. GRUB :- Grand Unified Bootloader.
 - multiple Kernel images
 - GRUB will use & will select kernel & execute it.
4. Kernel : root file system is mounted.
 - init is executed.
 - ↳ First program to run.
5. init : executes run level programs depending on runlevel.
6. Run level → Run level programs executed from etc/rc.d/rc*.d
 - 0 → System halt ; no activity, the system can be safely powered down.
 - 1 → Single user, rarely used.
 - 2 → Multiple users, no NFS (network filesystem); also used rarely.
 - IMP. ↳ 3 → Multiple users, command line interface the std run level for most Linux based server hardware.
 - 4 → user definable.

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- 5 → Multiple users, GUI, std multi systems.
 For most Linux-based desktop
- 6 → Reboot; used when restarting the system.

Process Tree on UNIX System:



Pagedaemon → responsible for virtual page management.

Swapper → scheduler, kernel daemon →
 moves whole processes b/w main memory and virtual memory
 as a part of VMS system.

init → first process after the kernel is loaded.

init → root of all user processes.
 ↳ user Address Space.

Events leading to Process termination:-

- Process executes last statement and asks OS to terminate it using exit() function.
- Process encounters fatal errors like divide by Zero, I/O error, memory allocation errors etc.
- Parent may terminate execution of child process by executing kill (SIGKILL signal) function for some specific reason.
 - Task assigned to child is no longer needed.
 - Child has exceeded the allocated resources.
- Parent is exiting.
 - Some OS may not allow child to continue if parent terminates.

Process Relation b/w Parent and Child ~~Resource~~ Processes .

- Resource sharing possibilities.
 - Parent and children share all resources.
 - Children share subset of parents resources.
 - Parent and child share no resources.

- Execution Possibilities:
 - Parent and children execute concurrently.
- Memory address space possibilities:
 - Address space of child duplicate of parent.
 - Child has a new program loaded into it.

Process Management System Call:

1. pid_t getpid(void);
 - get process ID.
 - Returns process ID of calling process.
2. pid_t getppid(void);
 - get parent's process ID.
 - returns parent process ID of calling process.
3. pid_t fork(void); IMP
 - Create child process by duplicating memory of parent process.
 - child gets copy of data space.
 - Now uses Copy-On-Write (cow)
 - Returns 0 in child, process ID of child in parent, -1 on error.

4. pid_t vfork (void);

→ Now Absolute.

→ Earlier fork() used to copy a complete memory of parent to child so vfork was used as optimized method.

→ returns 0 in child, process ID of child in parent,
-1 on error.

5. void exit (int);

→ terminated the process.

→ Parent process will receive the success value passed as int.

6. pid_t wait (int *status);

→ wait for child process to terminate.

→ Returns PID of child that terminated and status indicates returned status.

7. int exec (const char pathname,
const char *args, ...).

→ replaces current process memory with new process to be executed in pathname.

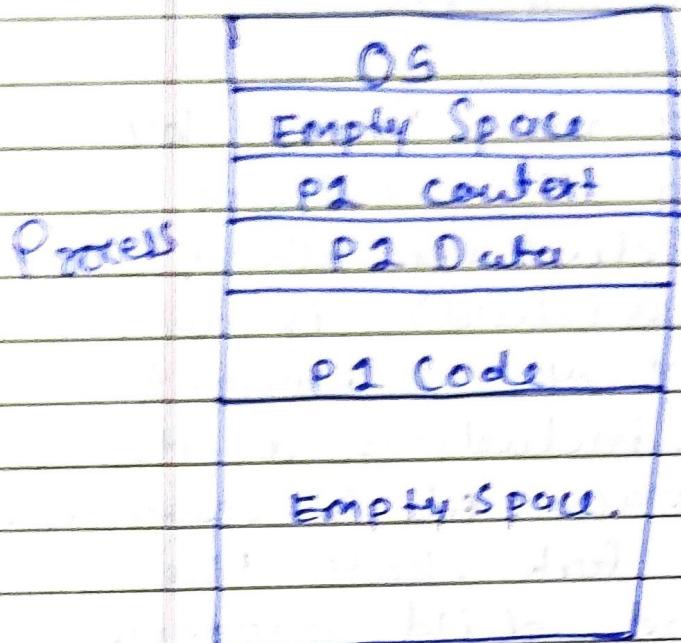
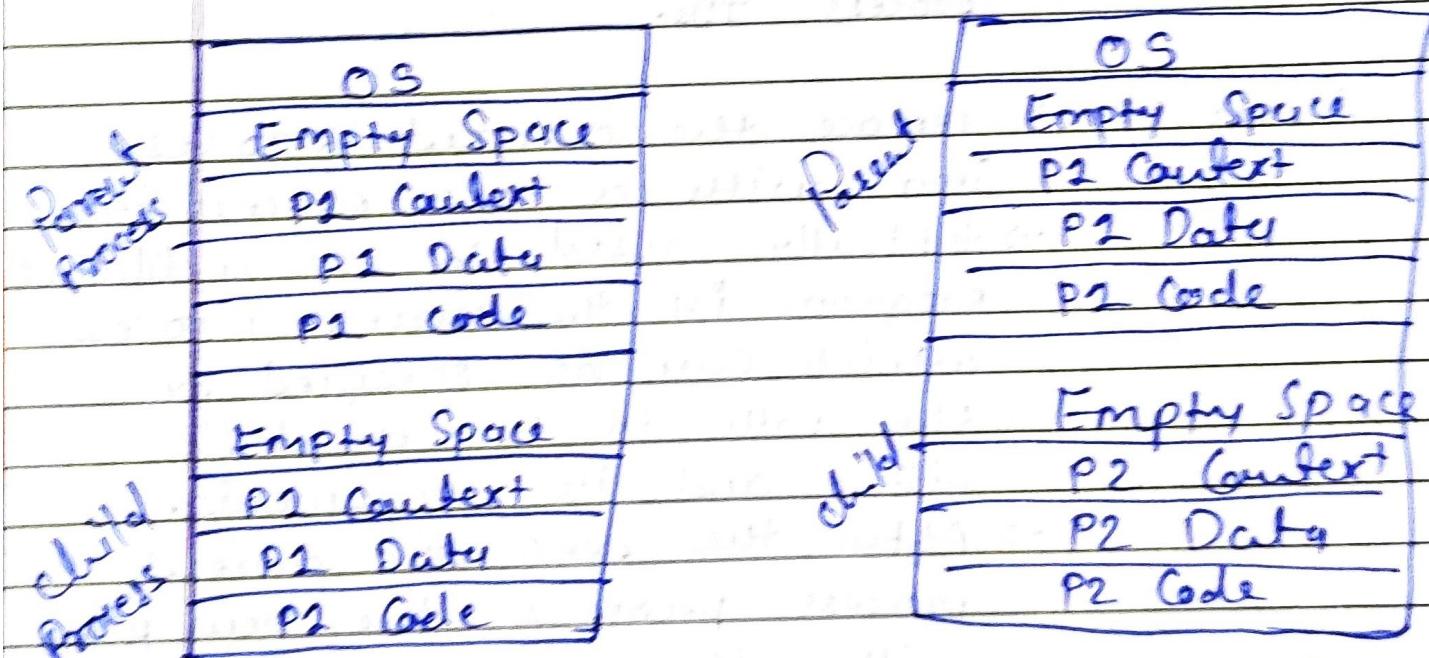
→ return -1 on error and no return on success.

IMP

→ Difference b/w fork() & exec():

1. fork() → create a new process by duplicating the calling process. ~~forking child~~ is an exact copy of the parent process, including all its memory space, files, & resources.
→ After the fork, both the parent and child processes run independently of each other, with their own unique process IDs.

2. exec() → replace the current process img. with a new process img.
→ typically used to run a different program in the current process, which can be specified by the path to the executable file and its arguments.
→ After the exec, the current process becomes the new pg, with its own new set of memory space, files, and other system resources.

`pid = fork()``exec(program-name)``close the
child Process.``Replace child
image.`

Process

States:

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Idle → fork() changes as it executes.

Runnable → create self. e.g. runnable

Running → waiting for CPU to start running. process is current running

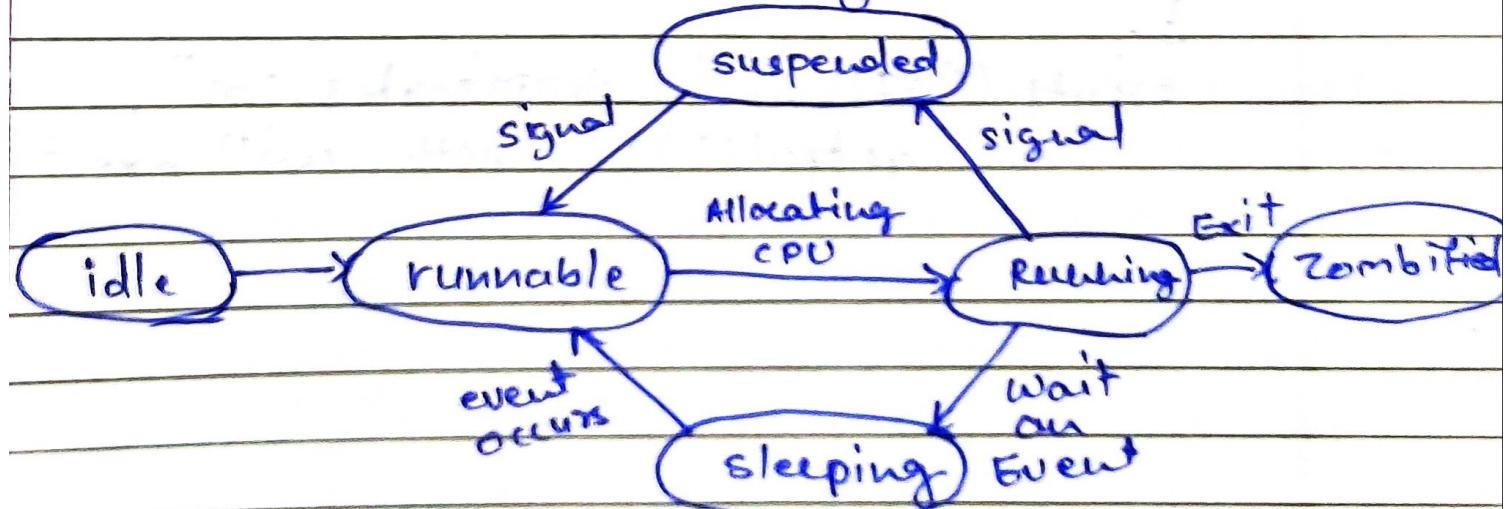
Sleeping → process is waiting for an event to occur. e.g. If process has executed

read() system calls, it will go in sleep until I/O req is complete.

Suspended → process has been "frozen" by signal such as SIGSTOP, it will resume when SIGCONT signal received. e.g. Ctrl + z suspend

Zombified → all the processes of foreground

process has terminated but job. has not yet returned its exit code to its parent. The process remains in zombie state until parent accepts return code using wait() syscall.



→ System Calls fork(), getpid(), getppid().

main()

{

int pid;

printf("I'm the org process with PID %d
and PPID %d", getpid(), getppid());
pid = fork(); // Duplicate child and parent
continue from here.

if (pid != 0) // pid != 0 must be parent

{

printf("I'm the org process with
PID %d and PPID %d", getpid(),
getppid());

printf("my child's pid is %d", pid);

{

else // child

{

printf("I'm the child process with
PID %d and PPID %d.\n",
getpid(), getppid());

{

printf("PID %d terminates.\n",
getpid()); // both will exec this.

Parent and Child Process Variable Scope

→ before fork → there is only one process so only one copy of variable.

→ Immediately after fork, two copies of the variables are created.

(one for parent and other for child).

After fork any changes to the variable is done in the local copy

of the respective process, hence the other process variable value will be different.

How many total processes will be created?

int main()

{

fork();

fork();

fork();

}

→ Total 8 process.

$$2^n$$

→ Orphan Process:- If parent process does not wait for child and it first terminates leaving child process orphan.

→ orphan processes are adopted by init process which started the parent (ie. parent of parent).

Call `wait()` to avoid orphans.

zombie process:- process that finished running, but it's parent process has not yet read its exit status.

→ If the parent process does not call `wait()` and `waitpid()` to read exit status, child become zombie and if parent dies it become orphan.

Race Conditions:- a type of programming error that can occur when multiple processes access a shared resource or data structure concurrently, and the outcome of the program depends on the order in which the processes execute.

Eg. If two processes simultaneously try to update the same var or file, the result may depend on the order in which the update occurs.

If the processes or threads does not synchronize their access to the shared resource, result may lead to bug.

Additional status info from wait()

childpid = wait (&wstatus);

→ returns the exit status from child which can further be inspected using these macros.

WIFEXITED (wstatus) → returns true if child terminated normally.

WEXITSTATUS (wstatus) → returns exit status (least significant 8 bits).

WIFSIGNALED (wstatus) → returns true if child process was terminated by a signal.

~~WTERMSIG (wstatus)~~ → returns the no. of signal.

WCOREDUMP (wstatus) → returns true if child produced a core dump.

WIFSTOPPED (wstatus) → returns true if child was stopped by a signal.

WSTOPSIG (wstatus) → returns the signal no. which caused child to stop.

WIFCONTINUED (wstatus) → returns true if child was resumed with SIGCONT signal.

exec() family of system calls:-

When a process executes an "exec()" system call, its PID and PPID no.s stay the same - only the code that the process is executing changes.

```
int exec(const char* path, const char*  
        arg0, const char* argv, NULL);  
int execv(const char* path, const char*  
        argv[]);  
int execvp(const char* path, const char*  
        arg0, const char* argv, NULL);  
int execvp(const char* path, const  
        char* argv[]);
```

These calls replaces the calling process's code, data and stack with those of the executable whose pathname is stored in path.

~~exec()~~ & execvp():-

use the \$ PATH environment var to find path.

→ If exe not found → returns -1.
otherwise replace code and starts to execute new code.

exec() & execv()

- invoke the exec with the string arguments pointed to by argv[1] through argv[n].
- arg0 must be the name of the executable file itself and ~~exec~~ the list of arguments must be null terminated.

execve() & execvp():

- invoke the executable with the string arguments pointed to by argv[1] to argv[n], whose argv[n+1] is null.
- argument must be ~~point~~ the name of the executable file itself.

→ Master-Slave Implementation:

Master accepts 2 values from CLT.

Set of 2 values to be passed to each child process i.e. argv[1] to argv[2]

pass to child 1, 3-4 to 2 so on.

Creates as many child processes as required i.e. n/2.

Reads the value returned using read() call using _WEXITSTATUS macro.

`exec()` & `execpc()` :-

- invoke the exe with the string arguments pointed to by `arg1` through `argn`.
- `arg0` must be the name of the executable file itself, and ~~the~~ the list of arguments must be null terminated.

`execv()` & `execvp()` :-

- invoke the executable with the string arguments pointed to by `argv[1]` to `argv[n]`, where `argv[n+1]` is null.
- `arg0` must be ~~point~~ the name of the executable file itself.

> Master-Slave Implementation:-

Master accepts n values from CLI.
Set of 2 Values to be passed to each child process i.e. `argv[1]` & `argv[2]`
pass to child 1, 3-4 to 2 so on.
For as many child processes as required ie. $n/2$.

Reads the value returned using `exit()` call using `NEXISTSTATUS` macro.

child process accepts the 2 CLI args
performs required processing.
Returns the result back as exit
status using `exit()` system call.

`system()`

- int `system(const char* command);`
- implemented using `fork()`, `exec()`
and `waitpid()`
- used to execute the command
passed as parameters.
eg., `system("ls -l");`
runs `ls -l` command.

→ How to get additional information
about process which is running.

when a process starts it creates
a directory with process ID under
`/proc` for per process info.

1. check PID using `ps` command.
`proc$ ps -aux`

2. Now change the dir to `/proc/pid`
and list the content `ls -l`.
[↓]
2123 etc.

most files with its content is described here.

cmdline → commandline Arguments.
cpu → current and last cpu in which it was executed.

cwd → link to the current working directory.

environ → values of environment variables.

exe → link to the executable of this process.

fdl → Directory which contains all the file descriptors.

mem → memory held by this process.

stat → Process status.

memoryinfo → info about memory.

comm & /task/{tid}/comm → Common content info about the parent task and each of the child task eg. on web browser there may be multiple windows each of which is child task.

/fdl info / fdr → info about opened file