Complete search - Backtracking

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References

The contents of this document are taken mainly from the follow sources:

- Rina Dechter and Daniel Frost, Backtrackging algorithms for constraint satisfaction problems
- Pter van Beek, Chapter 4 Backtracking Search Algorithms

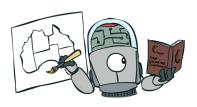
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Constraint satisfaction problems (CSPs)

- A special subset of search problems.
- State is defined by variables X_i with values from a domain D (sometimes D depends on i)
- Goal test is a set of constraints specifying allowable combinations of values for subsets of variables





Constraint satisfaction problems (CSPs)

Definition

A constraint satisfaction problem (CSP) is a tuple (X,D,C) where:

- $X = \{x_1, x_2, \dots, x_n\}$ is the set of variables.
- $D = \{d_1, d_2, \dots, d_n\}$ is the set of domains.
- $C = \{c_1, c_2, \dots, c_n\}$ is a set of constraints.

For example, $x, y, z \in \{0, 1\}, x + y = z$ is a CSP where:

- Variables are: x, y, z
- Domains are: $d_x = d_y = d_z = \{0, 1\}$
- There is a single constraint: x + y = z

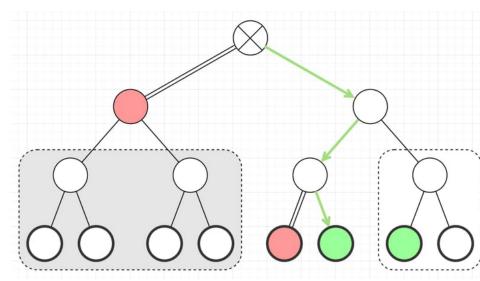


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Brute-force Approach

- Brute-force is a simple and naive algorithmic approach to solving problems that involves exhaustively checking all possible solutions.
- It is typically used when the problem size is small and the search space is manageable.
- It can also be used in combination with other techniques, such as pruning or heuristics, to improve their efficiency and effectiveness.

Complete Search - Backtracking



Complete Search - Backtracking

- The basic idea behind backtracking is to recursively build a partial solution by making choices from a set of available options, and then backtrack if the solution fails to satisfy the constraints.
- The algorithm explores the search space depth-first, which means that
 it goes as far as possible along each branch of the search tree before
 backtracking to the previous decision point and exploring another
 branch.
- if a node in the search tree does not lead to a solution, it is considered a deadend and its subtree can be pruned.

Complete Search - Backtracking

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CSP-BACKTRACKING(PartialAssignment a)

If a is complete then return a

X <- select an unassigned variable

D <- select an ordering for the domain of X

For each value v in D do

If v is consistent with a then

Add (X = v) to a

result <- CSP-BACKTRACKING(a)

If result <> failure then return result

Remove (X = v) from a

Return failure
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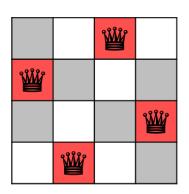
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N-queens problem

The N-Queens problem is a classic problem in computer science and mathematics that involves placing N chess queens on an N \times N chessboard such that no two queens attack each other.





Knapsack

The Knapsack problem involves packing a knapsack with items of different weights and values. The goal is to maximize the value of the items in the knapsack while keeping the total weight of the knapsack below a certain limit.



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Benefits and Drawbacks of Backtracking

Benefits

- Backtracking is a more intelligent and efficient way of searching through large solution spaces than brute-force;
- Backtracking problems are very intuitive to code;

Drawbacks

- In the worst case where all possible solutions must be explored, Backtracking has the same worst-case time & space complexity as Brute-force;
- Backtracking is complete but not guaranteed to find optimal solution, or just sub-optimal;

Improvements to backtracking

- Backtracking usually suffers from thrashing, namely, rediscovering the same inconsistencies and the same partial successes during search.
- Efficient cures for such behavior in all cases are unlikely, since the problem is NP-hard.



Filtering



Ordering

