

# Complete search - Backtracking

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The contents of this document are taken mainly from the follow sources:

- Rina Dechter and Daniel Frost, Backtrackging algorithms for constraint satisfaction problems
- Pter van Beek, Chapter 4 - Backtracking Search Algorithms

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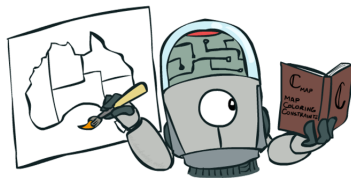
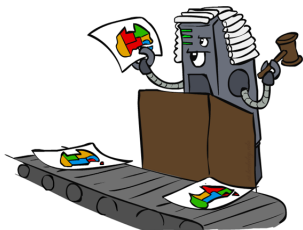
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# Constraint satisfaction problems (CSPs)

- A special subset of search problems.
- State is defined by **variables**  $X_i$  with values from a **domain**  $D$  (sometimes  $D$  depends on  $i$ )
- Goal test is a **set of constraints** specifying allowable combinations of values for subsets of variables



# Constraint satisfaction problems (CSPs)

## Definition

A constraint satisfaction problem (CSP) is a tuple  $(X, D, C)$  where:

- $X = \{x_1, x_2, \dots, x_n\}$  is the set of variables.
- $D = \{d_1, d_2, \dots, d_n\}$  is the set of domains.
- $C = \{c_1, c_2, \dots, c_n\}$  is a set of constraints.

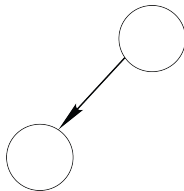
For example,  $x, y, z \in \{0, 1\}, x + y = z$  is a CSP where:

- Variables are:  $x, y, z$
- Domains are:  $d_x = d_y = d_z = \{0, 1\}$
- There is a single constraint:  $x + y = z$

# Brute-force Approach

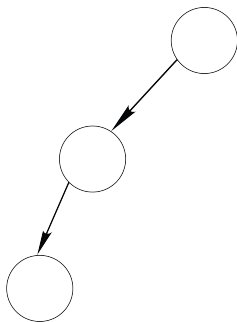
- Brute-force is a simple and naive algorithmic approach to solving problems that involves exhaustively checking all possible solutions.
- It is typically used when the problem size is small and the search space is manageable.
- It can also be used in combination with other techniques, such as pruning or heuristics, to improve their efficiency and effectiveness.

# Complete Search - Backtracking

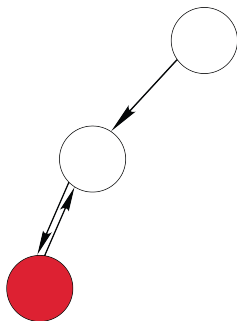




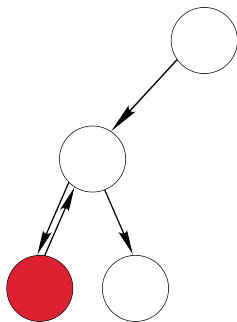
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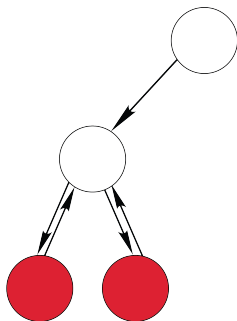
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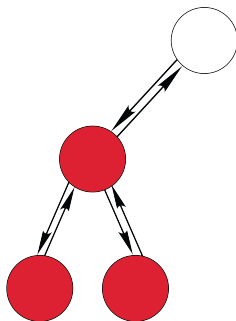
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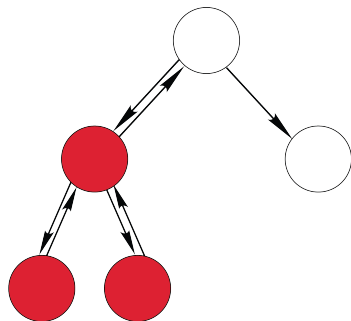
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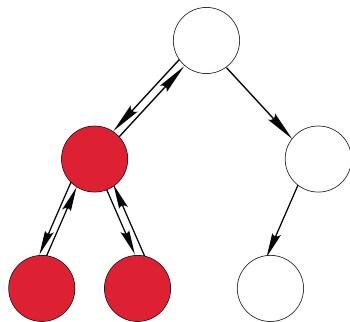
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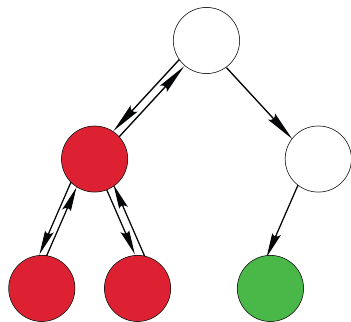
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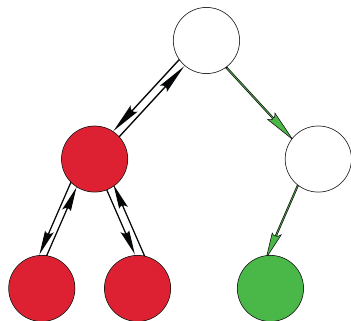


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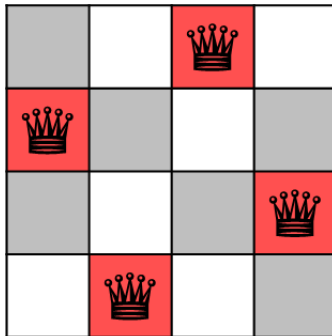
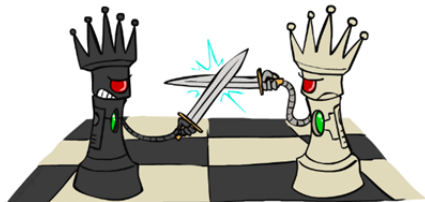
- The basic idea behind backtracking is to recursively build a partial solution by making choices from a set of available options, and then backtrack if the solution fails to satisfy the constraints.
- The algorithm explores the search space depth-first, which means that it goes as far as possible along each branch of the search tree before backtracking to the previous decision point and exploring another branch.
- if a node in the search tree does not lead to a solution, it is considered a deadend and its subtree can be pruned.

# Complete Search - Backtracking

```
CSP-BACKTRACKING(PartialAssignment a)
  If a is complete then return a
  X <- select an unassigned variable
  D <- select an ordering for the domain of X
  For each value v in D do
    If v is consistent with a then
      Add (X = v) to a
      result <- CSP-BACKTRACKING(a)
      If result <> failure then return result
      Remove (X = v) from a
  Return failure
```

# N-queens problem

The N-Queens problem is a classic problem in computer science and mathematics that involves placing N chess queens on an  $N \times N$  chessboard such that no two queens attack each other.



# Knapsack

The Knapsack problem involves packing a knapsack with items of different weights and values. The goal is to maximize the value of the items in the knapsack while keeping the total weight of the knapsack below a certain limit.

