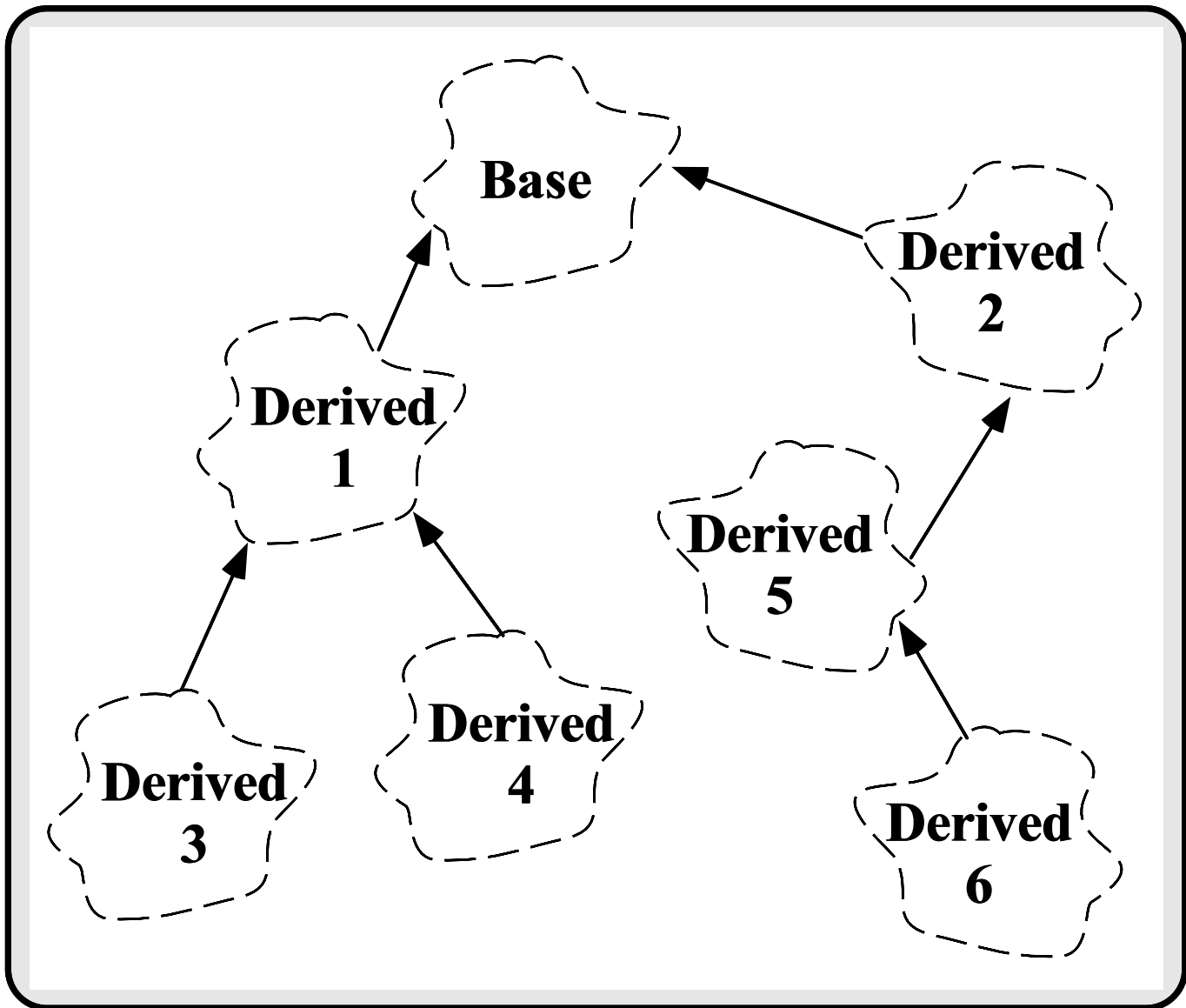


Inheritance Overview

- A type (called a *subclass* or *derived* type) can inherit the characteristics of another type(s) (called a *superclass* or *base type*)
 - The term *subclass* is equivalent to *derived type*
- A derived type acts just like the base type, except for an explicit list of:
 1. *Specializations*
 - Change implementations *without* changing the base class interface
 - * Most useful when combined with dynamic binding
 2. *Generalizations/Extensions*
 - Add new operations or data to derived classes

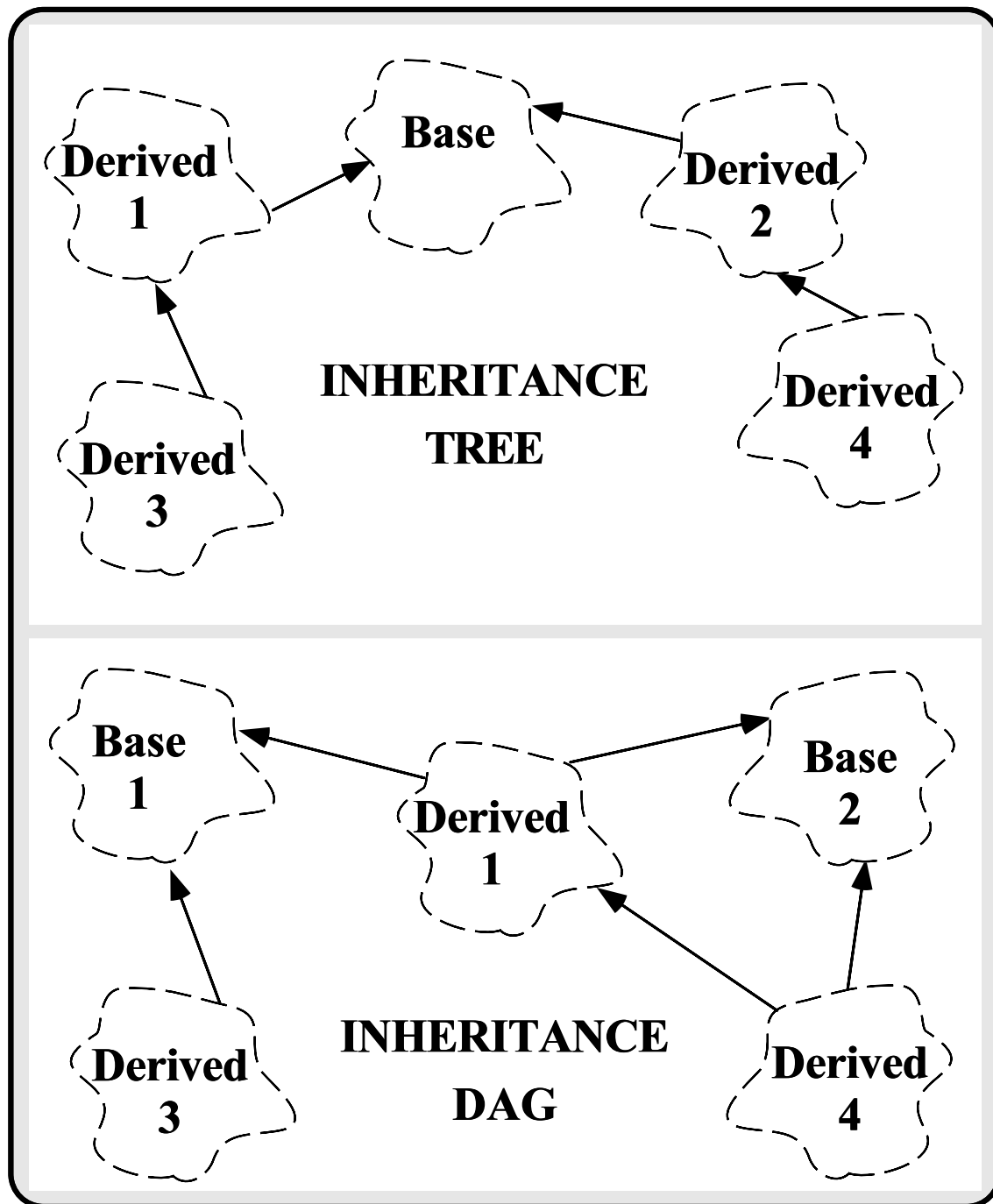
Visualizing Inheritance



Types of Inheritance

- Inheritance comes in two forms, depending on number of *parents* a subclass has
 1. *Single Inheritance* (SI)
 - Only one parent per derived class
 - Form an inheritance “tree”
 - SI requires a small amount of run-time overhead when used with dynamic binding
 - e.g., Smalltalk, Simula, Object Pascal
 2. *Multiple Inheritance* (MI)
 - More than one parent per derived class
 - Forms an inheritance “Directed Acyclic Graph” (DAG)
 - Compared with SI, MI adds additional run-time overhead (also involving dynamic binding)
 - e.g., C++, Eiffel, Flavors (a LISP dialect)

Inheritance Trees vs. Inheritance DAGs



Inheritance Benefits

1. *Increase reuse and software quality*

- Programmers reuse the base classes instead of writing new classes
 - Integrates *black-box* and *white-box* reuse by allowing extensibility and modification without changing existing code
- Using well-tested base classes helps reduce bugs in applications that use them
- Reduce object code size

2. *Enhance extensibility and comprehensibility*

- Helps support more flexible and extensible architectures (along with dynamic binding)
 - *i.e.*, supports the open/closed principle
- Often useful for modeling and classifying hierarchically-related domains

Inheritance Liabilities

1. May create deep and/or wide hierarchies that are hard to understand and navigate without class browser tools
2. May decrease performance slightly
 - *i.e.*, when combined with *multiple inheritance* and *dynamic binding*
3. Without dynamic binding, inheritance has only limited utility
 - Likewise, dynamic binding is almost totally useless without inheritance
4. Brittle hierarchies, which may impose dependencies upon ancestor names

Inheritance in C++

- Deriving a class involves an extension to the C++ class declaration syntax
- The class head is modified to allow a *derivation list* consisting of base classes
- *e.g.*,

```
class Foo { /* ... };  
class Bar : public Foo { /* ... };  
class Foo : public Foo, public Bar { /* ... };
```

Key Properties of C++

Inheritance

- The base/derived class relationship is explicitly recognized in C++ by predefined standard conversions
 - *i.e.*, a pointer to a derived class may always be assigned to a pointer to a base class that was inherited *publically*
 - * But not vice versa...
- When combined with dynamic binding, this special relationship between inherited class types promotes a type-secure, *polymorphic* style of programming
 - *i.e.*, the programmer need not know the actual type of a class at compile-time
 - Note, C++ is not truly polymorphic
 - * *i.e.*, operations are not applicable to objects that don't contain definitions of these operations at some point in their inheritance hierarchy

Simple Screen Class

- The following code is used as the base class:

```
class Screen {  
public:  
    Screen (int = 8, int = 40, char = ' ');  
    ~Screen (void);  
    short height (void) const { return this->height_; }  
    short width (void) const { return this->width_; }  
    void height (short h) { this->height_ = h; }  
    void width (short w) { this->width_ = w; }  
    Screen &forward (void);  
    Screen &up (void);  
    Screen &down (void);  
    Screen &home (void);  
    Screen &bottom (void);  
    Screen &display (void);  
    Screen &copy (const Screen &);  
    // ...  
private:  
    short height_, width_;  
    char *screen_, *cur_pos_;  
};
```

Subclassing from Screen

- `class Screen` can be a public base class of `class Window`
- *e.g.*,

```
class Window : public Screen {  
public:  
    Window (const Point &, int rows = 24,  
            int columns = 80,  
            char default_char = ' ');  
    void set_foreground_color (Color &);  
    void set_background_color (Color &);  
    void resize (int height, int width);  
    // ...  
private:  
    Point center_;  
    Color foreground_;  
    Color background_;  
    // ...  
};
```

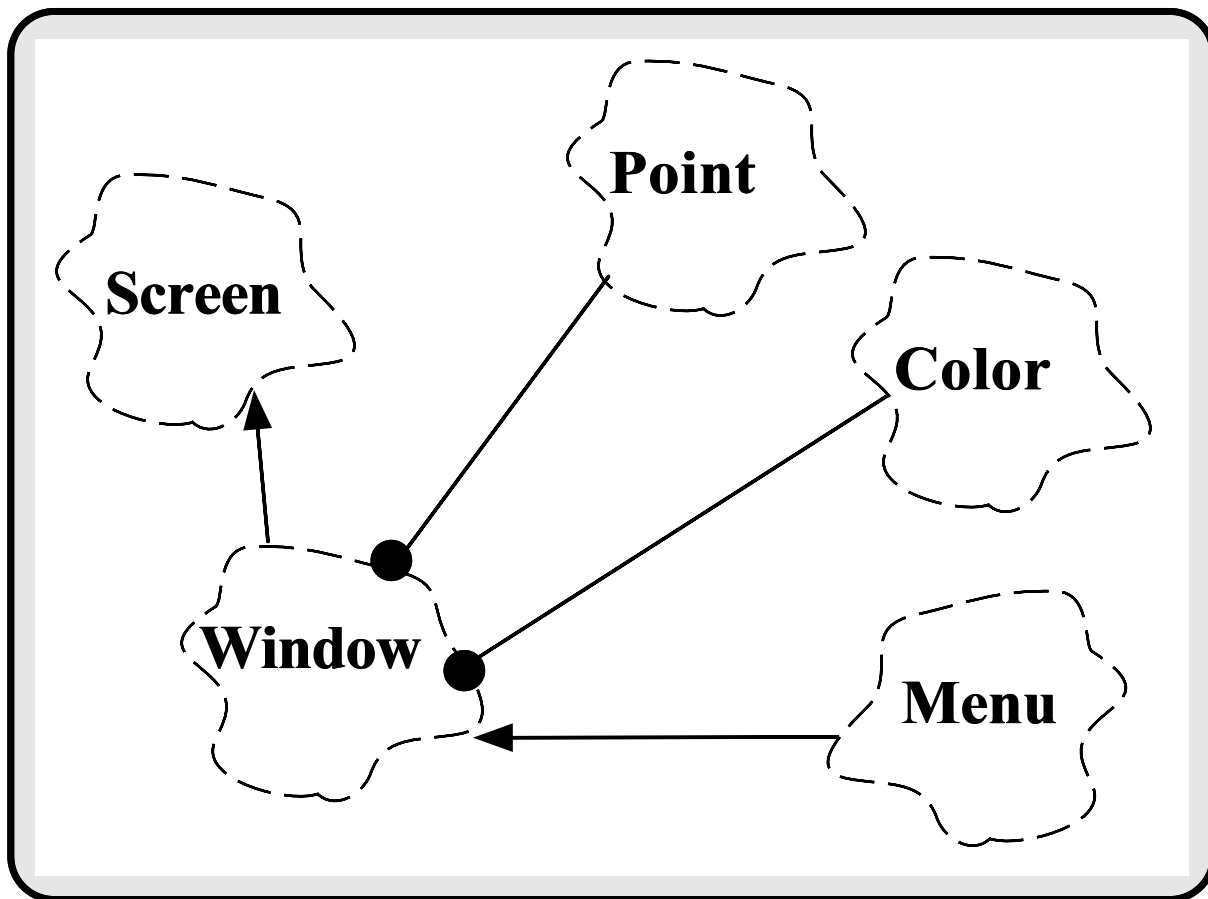
Multiple Levels of Derivation

- A derived class can itself form the basis for further derivation, e.g.,

```
class Menu : public Window {  
public:  
    void set_label (const char *l);  
    Menu (const Point &, int rows = 24,  
        int columns = 80,  
        char default_char = ' ');  
    // ...  
private:  
    char *label_;  
    // ...  
};
```

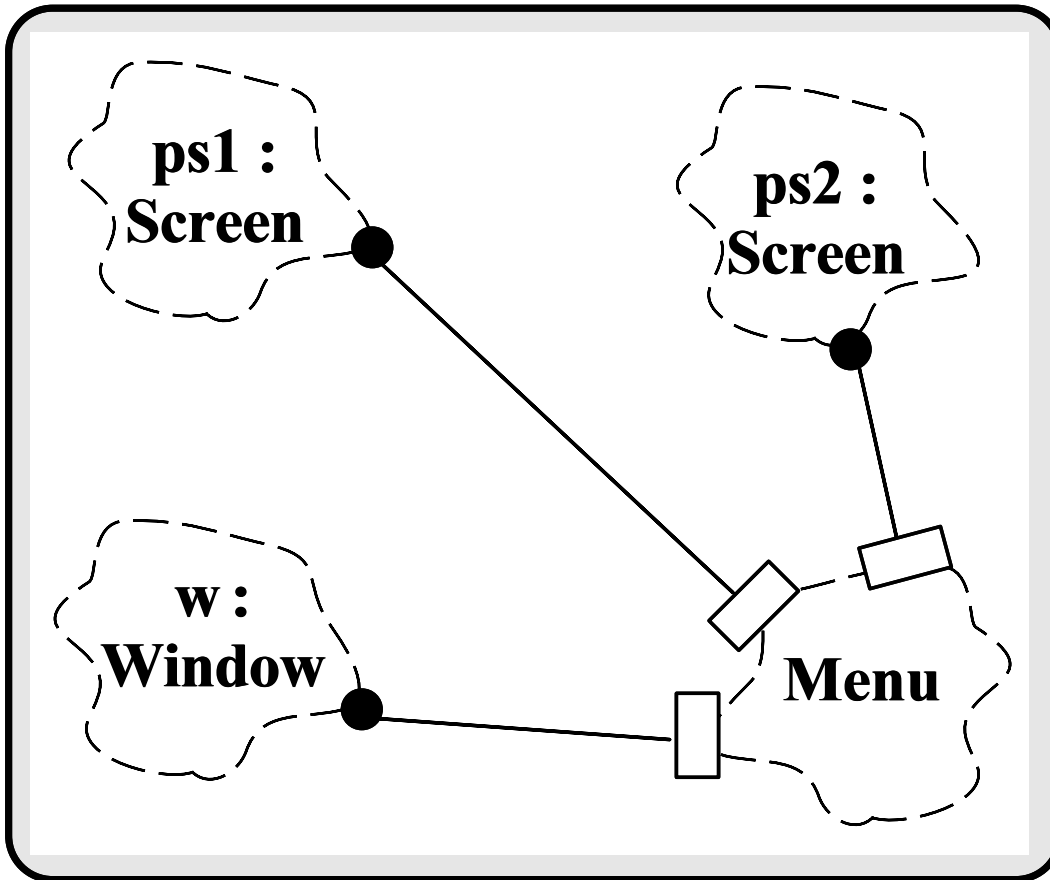
- `class Menu` inherits data and methods from both `Window` and `Screen`
 - i.e., `sizeof (Menu) >= sizeof (Window) >= sizeof (Screen)`

The Screen Inheritance Hierarchy



- Screen/Window/Menu hierarchy

Variations on a Screen...



- A pointer to a derived class can be assigned to a pointer to any of its *public* base classes without requiring an explicit cast:

```
Menu m; Window &w = m; Screen *ps1 = &w;  
Screen *ps2 = &m;
```

Using the Screen Hierarchy

- *e.g.*,

```
class Screen { public: virtual void dump (ostream &); = 0 }
class Window : public Screen {
    public: virtual void dump (ostream &);
};
class Menu : public Window {
    public: virtual void dump (ostream &);
};
// stand-alone function
void dump_image (Screen *s, ostream &o) {
    // Some processing omitted
    s->dump (o);
    // (*s->vp[1]) (s, o));
}
```

```
Screen s; Window w; Menu m;
Bit_Vector bv;
```

```
// OK: Window is a kind of Screen
dump_image (&w, cout);
// OK: Menu is a kind of Screen
dump_image (&m, cout);
// OK: argument types match exactly
dump_image (&s, cout);
// Error: Bit_Vector is not a kind of Screen!
dump_image (&bv, cout);
```

Using Inheritance for Specialization

- A derived class *specializes* a base class by adding new, more specific *state variables* and *methods*
 - Method use the same interface, even though they are implemented differently
 - * *i.e.*, “overridden”
 - Note, there is an important distinction between *overriding*, *hiding*, and *overloading*...
- A variant of this is used in the *template method* pattern
 - *i.e.*, behavior of the base class relies on functionality supplied by the derived class
 - This is directly supported in C++ via *abstract base classes* and *pure virtual functions*

Specialization Example

- Inheritance may be used to obtain the features of one data type in another closely related data type
- For example, class Date represents an arbitrary Date:

```
class Date {  
public:  
    Date (int m, int d, int y);  
    virtual void print (ostream &s) const;  
    // ...  
private:  
    int month_, day_, year_;  
};
```

- Class Birthday derives from Date, adding a name field representing the person's birthday, e.g.,

```
class Birthday : public Date {  
public:  
    Birthday (const char *n, int m, int d, int y)  
        : Date (m, d, y), person_ (strdup (n)) {}  
    ~Birthday (void) { free (person_); }  
    virtual void print (ostream &s) const;  
    // ...  
private:  
    const char *person_;  
};
```


Implementation and Use-case

- Birthday::print could print the person's name as well as the date, *e.g.*,

```
void Birthday::print (ostream &s) const {  
    s << this->person_ << " was born on ";  
    Date::print (s);  
    s << "\n";  
}
```

- *e.g.*,

```
const Date july_4th (7, 4, 1993);  
Birthday my_birthday ("Douglas C. Schmidt", 7, 18, 1962);
```

```
july_4th.print (cerr);  
// july 4th, 1993  
my_birthday.print (cout);  
// Douglas C. Schmidt was born on july 18th, 1962
```

```
Date *dp = &my_birthday;  
dp->print (cerr);  
// ??? what gets printed ???  
// (*dp->vp[1])(dp, cerr);
```

Alternatives to Specialization

- Note that we could also use *object composition* instead of *inheritance* for this example, e.g.,

```
class Birthday {  
public  
    Birthday (char *n, int m, int d, int y):  
        date_ (m, d, y), person_ (n) {}  
    // same as before  
private:  
    Date date_;  
    char *person_;  
};
```

- However, in this case we would not be able to utilize the dynamic binding facilities for base classes and derived classes

– e.g.,

```
Date *dp = &my_birthday;  
// ERROR, Birthday is not a subclass of date!
```

- While this does not necessarily affect reusability, it does affect extensibility...

Using Inheritance for Extension/Generalization

- Derived classes add *state variables* and/or *operations* to the *properties* and *operations* associated with the base class
 - Note, the interface is generally widened!
 - Data member and method access privileges may also be modified
- Extension/generalization is often used to facilitate reuse of *implementations*, rather than *interface*
 - However, it is not always necessary or correct to export interfaces from a base class to derived classes

Extension/Generalization

Example

- Using `class Vector` as a private base class for derived class `Stack`

```
class Stack : private Vector { /* ... */ };
```

- In this case, `Vector`'s `operator[]` may be reused as an implementation for the `Stack` `push` and `pop` methods
 - Note that using private inheritance ensures that `operator[]` does not show up in the interface for class `Stack`!
- Often, a better approach in this case is to use a composition/Has-A rather than a descendant/Is-A relationship...

Vector Interface

- Using class `Vector` as a base class for a derived class such as class `Checked_Vector` or class `Ada_Vector`
 - One can define a `Vector` class that implements an unchecked, uninitialized array of elements of type `T`
- e.g., `/* File Vector.h (incomplete wrt initialization and assignment) */`

`// Bare-bones implementation, fast but not safe`

`template <class T>`

`class Vector {`

`public:`

`Vector (size_t s);`

`~Vector (void);`

`size_t size (void) const;`

`T &operator[] (size_t index);`

`private:`

`T *buf_;`

`size_t size_;`

`};`

Vector Implementation

- *e.g.*,

```
template <class T>
```

```
Vector<T>::Vector (size_t s): size_ (s), buf_ (new T[s]) {}
```

```
template <class T>
```

```
Vector<T>::~~Vector (void) { delete [] this->buf_; }
```

```
template <class T> size_t
```

```
Vector<T>::size (void) const { return this->size_; }
```

```
template <class T> T &
```

```
Vector<T>::operator[] (size_t i) { return this->buf_[i]; }
```

```
int main (void) {
```

```
    Vector<int> v (10);
```

```
    v[6] = v[5] + 4; // oops, no initial values
```

```
    int i = v[v.size ()]; // oops, out of range!
```

```
    // destructor automatically called
```

```
}
```

Benefits of Inheritance

- Inheritance enables modification and/or extension of ADTs *without changing the original source code*
 - e.g., someone may want a variation on the basic Vector abstraction:
 1. A vector whose bounds are checked on every reference
 2. Allow vectors to have lower bounds other than 0
 3. Other vector variants are possible too...
 - * e.g., automatically-resizing vectors, initialized vectors, etc.
- This is done by defining new derived classes that inherit the characteristics of the Vector base class
 - Note that inheritance also allows code to be shared

Checked_Vector Interface

- The following is a subclass of Vector that allows run-time range checking:
- /* File Checked-Vector.h (incomplete wrt initialization and assignment) */

```
struct RANGE_ERROR {  
    "range_error" (size_t index);  
    // ...  
};  
template <class T>  
class Checked_Vector : public Vector<T> {  
public:  
    Checked_Vector (size_t s);  
    T &operator[] (size_t i) throw (RANGE_ERROR);  
    // Vector::size () inherited from base class Vector.  
protected:  
    bool in_range (size_t i) const;  
private:  
    typedef Vector<T> inherited;  
};
```


Implementation of Checked_Vector

- *e.g.*,

```
template <class T> bool  
Checked_Vector<T>::in_range (size_t i) const {  
    return i < this->size ();  
}
```

```
template <class T>  
Checked_Vector<T>::Checked_Vector (size_t s)  
    : inherited (s) {}
```

```
template <class T> T &  
Checked_Vector<T>::operator[] (size_t i)  
    throw (RANGE_ERROR)  
{  
    if (this->in_range (i))  
        return (*(inherited *) this)[i];  
        // return BASE::operator[] (i);  
    else  
        throw RANGE_ERROR (i);  
}
```

Checked_Vector Use-case

- *e.g.*,

```
#include "Checked_Vector.h"
```

```
typedef Checked_Vector<int> CV_INT;
```

```
int foo (int size)
{
    try
    {
        CV_INT cv (size);
        int i = cv[cv.size ()]; // Error detected!
                                // exception raised...
        // Call base class destructor
    }
    catch (RANGE_ERROR)
    { /* ... */ }
}
```

Design Tip

- Note, dealing with parent and base classes
 - It is often useful to write derived classes that do not encode the names of their direct parent class or base class in any of the method bodies
 - Here's one way to do this systematically:

```
class Base {  
  public:  
    int foo (void);  
};  
class Derived_1 : public Base {  
  typedef Base inherited;  
  public:  
    int foo (void) { inherited::foo (); }  
};  
class Derived_2 : public Derived_1 {  
  typedef Derived_1 inherited;  
  public:  
    int foo (void) {  
      inherited::foo ();  
    }  
};
```

- This scheme obviously doesn't work as transparently for multiple inheritance...

Ada_Vector Interface

- The following is an Ada Vector example, where we can have array bounds start at something other than zero
- */* File ada_vector.h (still incomplete wrt initialization and assignment....) */*

```
#include "vector.h"  
// Ada Vectors are also range checked!  
template <class T>  
class Ada_Vector : private Checked_Vector<T> {  
public:  
    Ada_Vector (size_t l, size_t h);  
    T &operator ()(size_t i) throw (RANGE_ERROR)  
    inherited::size; // explicitly extend visibility  
private:  
    typedef Checked_Vector<T> inherited;  
    size_t lo_bnd_  
};
```

Ada_Vector Implementation

- e.g., class Ada_Vector (cont'd)

```
template <class T>
```

```
Ada_Vector<T>::Ada_Vector (size_t lo, size_t hi)  
    : inherited (hi - lo + 1), lo_bnd_ (lo) {}
```

```
template <class T> T &
```

```
Ada_Vector<T>::operator ()(size_t i)
```

```
    throw (RANGE_ERROR) {
```

```
        if (this->in_range (i - this->lo_bnd_))
```

```
            return Vector<T>::operator [] (i - this->lo_bnd_);
```

```
            // or Vector<T> &self = *(Vector<T> *) this;
```

```
            // self[i - this->lo_bnd_];
```

```
        else
```

```
            throw RANGE_ERROR (i);
```

```
    }
```

Ada_Vector Use-case

- Example Ada Vector Usage (File main.C)

```
#include <iostream.h>
#include <stdlib.h>
#include "ada_vector.h"

int main (int argc, char *argv[]) {
    try {
        size_t lower = ::atoi (argv[1]);
        size_t upper = ::atoi (argv[2]);
        Ada_Vector<int> ada_vec (lower, upper);

        ada_vec (lower) = 0;

        for (size_t i = lower + 1; i <= ada_vec.size (); i++)
            ada_vec (i) = ada_vec (i - 1) + 1;

        // Run-time error, index out of range
        ada_vec (upper + 1) = 100;

        // Vector destructor called when
        // ada_vec goes out of scope
    }
    catch (RANGE_ERROR) { /* ... */ }
}
```

Memory Layout

- Memory layouts in derived classes are created by concatenating memory from the base class(es)

– e.g., // from the cfront-generated .c file

```
struct Vector {  
    T *buf__6Vector;  
    size_t size__6Vector;  
};  
struct Checked_Vector {  
    T *buf__6Vector;  
    size_t size__6Vector;  
};  
struct Ada_Vector {  
    T *buf__6Vector; // Vector  
    size_t size__6Vector; // part  
    size_t lo_bnd__10Ada_Vector; // Ada_Vector  
};
```

- The derived class constructor calls the base constructor in the “base initialization section,” i.e.,

```
Ada_Vector<T>::Ada_Vector (size_t lo, size_t hi)  
    : inherited (hi - lo + 1), lo_bnd_ (lo) {}
```

Base Class Constructor

- Constructors are called from the “bottom up”
- Destructors are called from the “top down”
- *e.g.*,

```
/* Vector constructor */
struct Vector *
__ct__6VectorFi (struct Vector *__0this, size_t __0s) {
    if (__0this || (__0this =
        __nw__FUi (sizeof (struct Vector))))
        ((__0this->size__6Vector = __0s),
        (__0this->buf__6Vector =
            __nw__FUi ((sizeof (int)) * __0s)));
    return __0this;
}
```


Derived Class Constructors

- *e.g.*,

```
/* Checked_Vector constructor */
struct Checked_Vector *__ct__14Checked_VectorFi (
    struct Checked_Vector *__0this, size_t __0s) {
    if (__0this || (__0this =
        __nw__FUi (sizeof (struct Checked_Vector))))
        __0this = __ct__6VectorFi (__0this, __0s);
    return __0this;
}

/* Ada_Vector constructor */
struct Ada_Vector *__ct__10Ada_VectorFiT1 (
    struct Ada_Vector *__0this, size_t __0lo, size_t __0hi) {
    if (__0this || (__0this =
        __nw__FUi (sizeof (struct Ada_Vector))))
        if (((__0this = __ct__14Checked_VectorFi (__0this,
            __0hi - __0lo + 1))))
            __0this->lo_bnd__10Ada_Vector = __0lo;
    return __0this;
}
```

Destructor

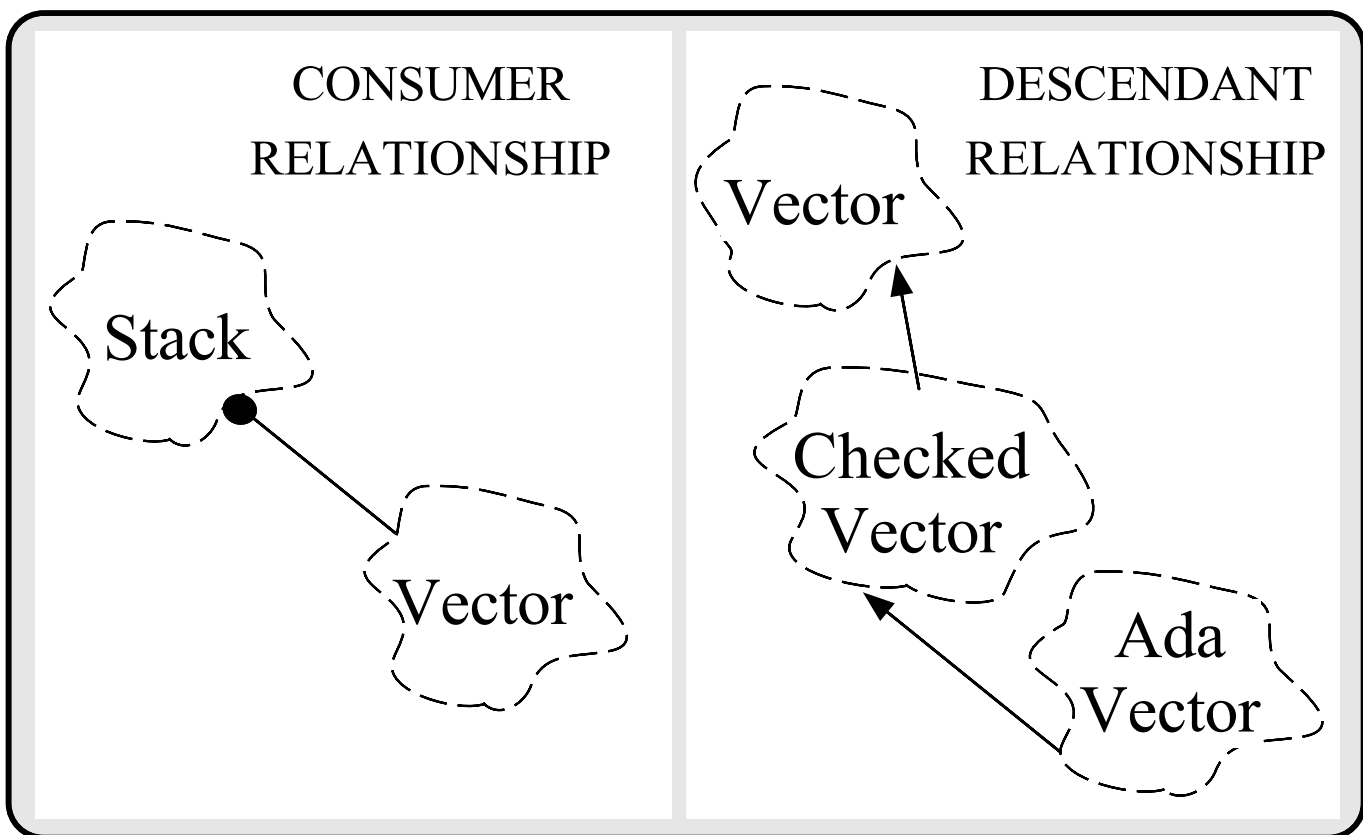
- Note, destructors, constructors, and assignment operators are *not* inherited
- However, they may be called automatically were necessary, e.g.,

```
char __dt__6VectorFv (  
    struct Vector *__0this, int __0__free) {  
    if (__0this) {  
        __dl__FPv ((char *) __0this->buf__6Vector);  
        if (__0this)  
            if (__0__free & 1)  
                __dl__FPv ((char *) __0this);  
    }  
}
```

Describing Relationships Between Classes

- *Consumer/Composition/Aggregation*
 - A class is a consumer of another class when it makes use of the other class's services, as defined in its interface
 - * For example, a Stack implementation could rely on an array for its implementation and thus be a consumer of the Array class
 - Consumers are used to describe a *Has-A* relationship
- *Descendant/Inheritance/Specialization*
 - A class is a descendant of one or more other classes when it is designed as an extension or specialization of these classes. This is the notion of inheritance
 - Descendants are used to describe an *Is-A* relationship

Has-A vs. Is-A Relationships



Interface vs. Implementation

Inheritance

- Class inheritance can be used in two primary ways:
 1. *Interface inheritance*: a method of creating a subtype of an existing class for purposes of setting up dynamic binding, *e.g.*,
 - Circle is a subclass of Shape (*i.e.*, *Is-A* relation)
 - A Birthday is a subclass of Date
 2. *Implementation inheritance*: a method of reusing an implementation to create a new class type
 - *e.g.*, a **class** Stack that inherits from **class** Vector. A Stack is not really a subtype or specialization of Vector
 - In this case, inheritance makes implementation easier, since there is no need to rewrite and debug existing code.
 - * This is called “using inheritance for reuse”
 - * *i.e.*, a pseudo-*Has-A* relation

The Dangers of Implementation Inheritance

- Using inheritance for reuse may sometimes be a dangerous misuse of the technique

- Operations that are valid for the base type may not apply to the derived type at all

- * *e.g.*, performing an subscript operation on a stack is a meaningless and potentially harmful operation

```
class Stack : public Vector {  
    // ...  
};  
Stack s;  
s[10] = 20; // could be big trouble!
```

- In C++, the use of a **private** base class minimizes the dangers

- * *i.e.*, if a class is derived “private,” it is illegal to assign the address of a derived object to a pointer to a base object

- On the other hand, a consumer/Has-A relation might be more appropriate...

Private vs Public vs Protected

Derivation

- Access control specifiers (*i.e.*, **public**, **private**, **protected**) are also meaningful in the context of inheritance
- In the following examples:
 - `<....>` represents actual (omitted) code
 - `[....]` is implicit
- Note, all the examples work for both data members and methods

Public Derivation

- *e.g.*,

```
class A {  
  public:  
    <public A>  
  protected:  
    <protected A>  
  private:  
    <private A>  
};
```

```
class B : public A {  
  public:  
    [public A]  
    <public B>  
  protected:  
    [protected A]  
    <protected B>  
  private:  
    <private B>  
};
```


Private Derivation

- *e.g.*,

```
class A {  
  public:  
    <public A>  
  private:  
    <private A>  
  protected:  
    <protected A>  
};
```

```
class B : private A { // also class B : A  
  public:  
    <public B>  
  protected:  
    <protected B>  
  private:  
    [public A]  
    [protected A]  
    <private B>  
};
```

Protected Derivation

- *e.g.*,

```
class A {  
  public:  
    <public A>  
  protected:  
    <protected A>  
  private:  
    <private A>  
};
```

```
class B : protected A {  
  public:  
    <public B>  
  protected:  
    [protected A]  
    [public A]  
    <protected B>  
  private:  
    <private B>  
};
```

Summary of Access Rights

- The following table describes the access rights of inherited methods
 - The vertical axis represents the access rights of the methods of base class
 - The horizontal access represents the mode of inheritance

| | | INHERITANCE ACCESS | | | |
|--|--|-----------------------|-----------|---------|------------|
| | | public | protected | private | restricted |
| M A E C M C B E E S R S | M A E C M C B E E S R S | public | pub | pro | pri |
| | | protected | pro | pro | pri |
| | | private | n/a | n/a | n/a |
| | | | | | |

- Note that the resulting access is always the most restrictive of the two

Other Uses of Access Control Specifiers

- Selectively redefine visibility of individual methods from base classes that are derived *privately*

```
class A {  
public:  
    int f ();  
    int g_;  
    ...  
private:  
    int p_;  
};
```

```
class B : private A {  
public:  
    A::f; // Make public  
protected:  
    A::g_; // Make protected  
};
```

Common Errors with Access Control Specifiers

- It is an error to “increase” the access of an inherited method in a derived class

– e.g., you may not say:

```
class B : private A {  
    // nor protected nor public!  
    public:  
        A::p_; // ERROR!  
};
```

- It is also an error to derive *publically* and then try to selectively decrease the visibility of base class methods in the derived class

– e.g., you may not say:

```
class B : public A {  
    private:  
        A::f; // ERROR!  
};
```

General Rules for Access Control

Specifiers

- Private methods of the base class are not accessible to a derived class (unless the derived class is a **friend** of the base class)
- If the subclass is derived *publically* then:
 1. Public methods of the base class are accessible to the derived class
 2. Protected methods of the base class are accessible to derived classes and friends only

Caveats

- Using protected methods weakens the data hiding mechanism since changes to the base class implementation might affect all derived classes. *e.g.*,

```
class Vector {  
  public:  
    //...  
  protected:  
    // allow derived classes direct access  
    T *buf_;  
    size_t size_;  
};  
class Ada_Vector : public Vector {  
  public:  
    T &operator() (size_t i) {  
      return this->buf_[i];  
    }  
    // Note the strong dependency on the name buf_  
};
```

- However, performance and design reasons may dictate use of the protected access control specifier
 - Note, inline functions often reduces the need for these efficiency hacks...

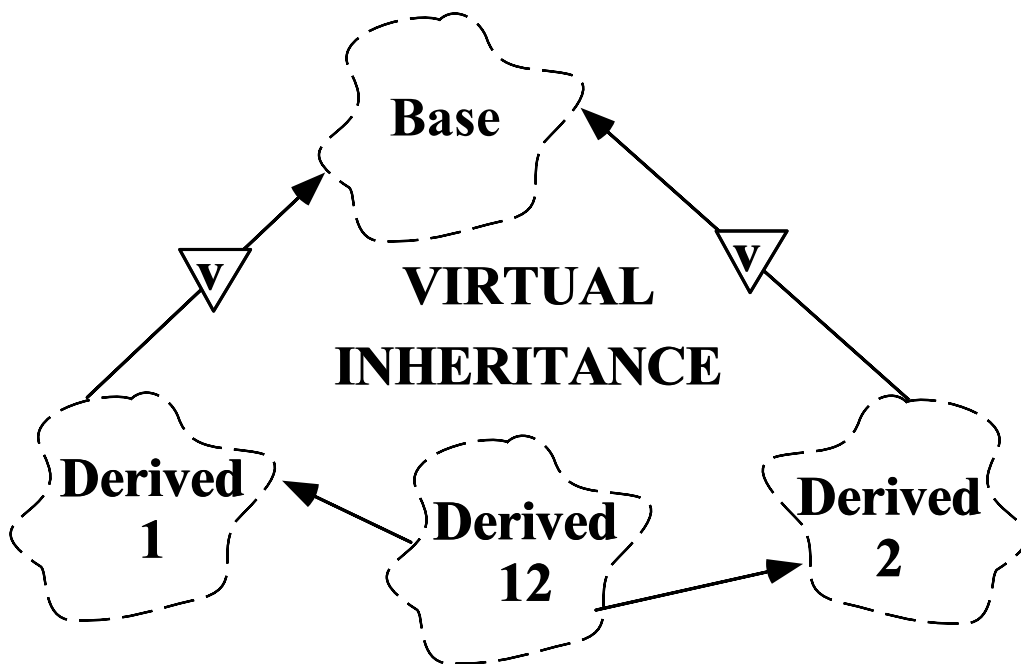
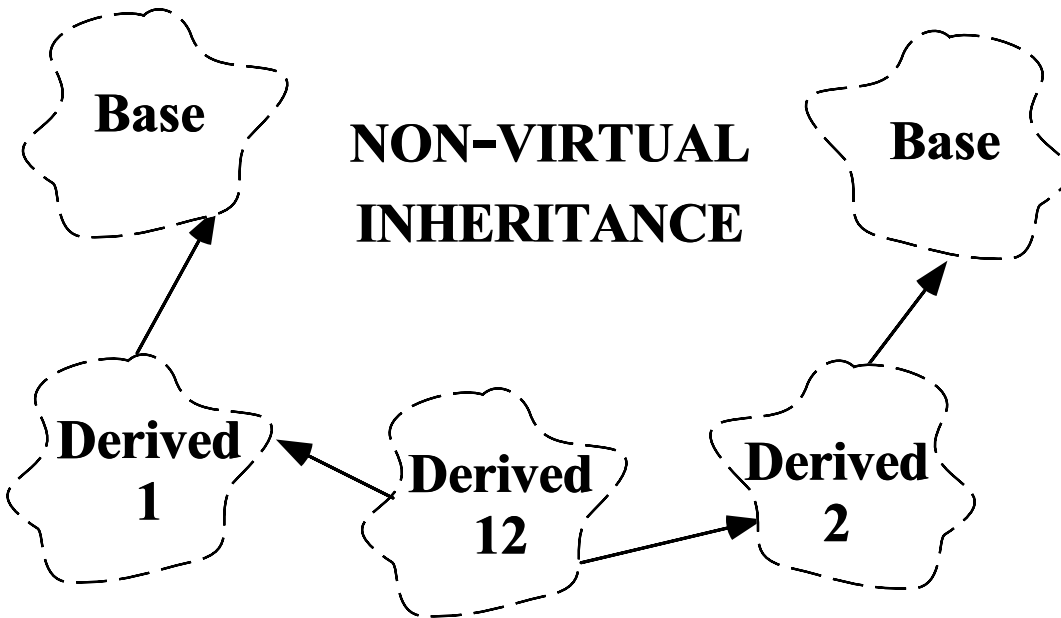
Overview of Multiple Inheritance in C++

- C++ allows *multiple inheritance*
 - *i.e.*, a class can be simultaneously derived from two or more base classes
 - *e.g.*,

```
class X { /* .... */ };  
class Y : public X { /* .... */ };  
class Z : public X { /* .... */ };  
class YZ : public Y, public Z { /* .... */ };
```

- Derived classes Y, Z, and YZ inherit the data members and methods from their respective base classes

Multiple Inheritance Illustrated



Liabilities of Multiple Inheritance

- A base class may legally appear only once in a derivation list, *e.g.*,
 - `class Two_Vector : public Vector, public Vector // ERROR!`
- However, a base class may appear multiple times within a derivation hierarchy
 - *e.g.*, `class YZ` contains two instances of `class X`
- This leads to two problems with multiple inheritance:
 1. It gives rise to a form of method and data member ambiguity
 - Explicitly qualified names and additional methods are used to resolve this
 2. It also may cause unnecessary duplication of storage
 - “Virtual base classes” are used to resolve this

Motivation for Virtual Base Classes

- Consider a user who wants an `Init_Checked_Vector`:

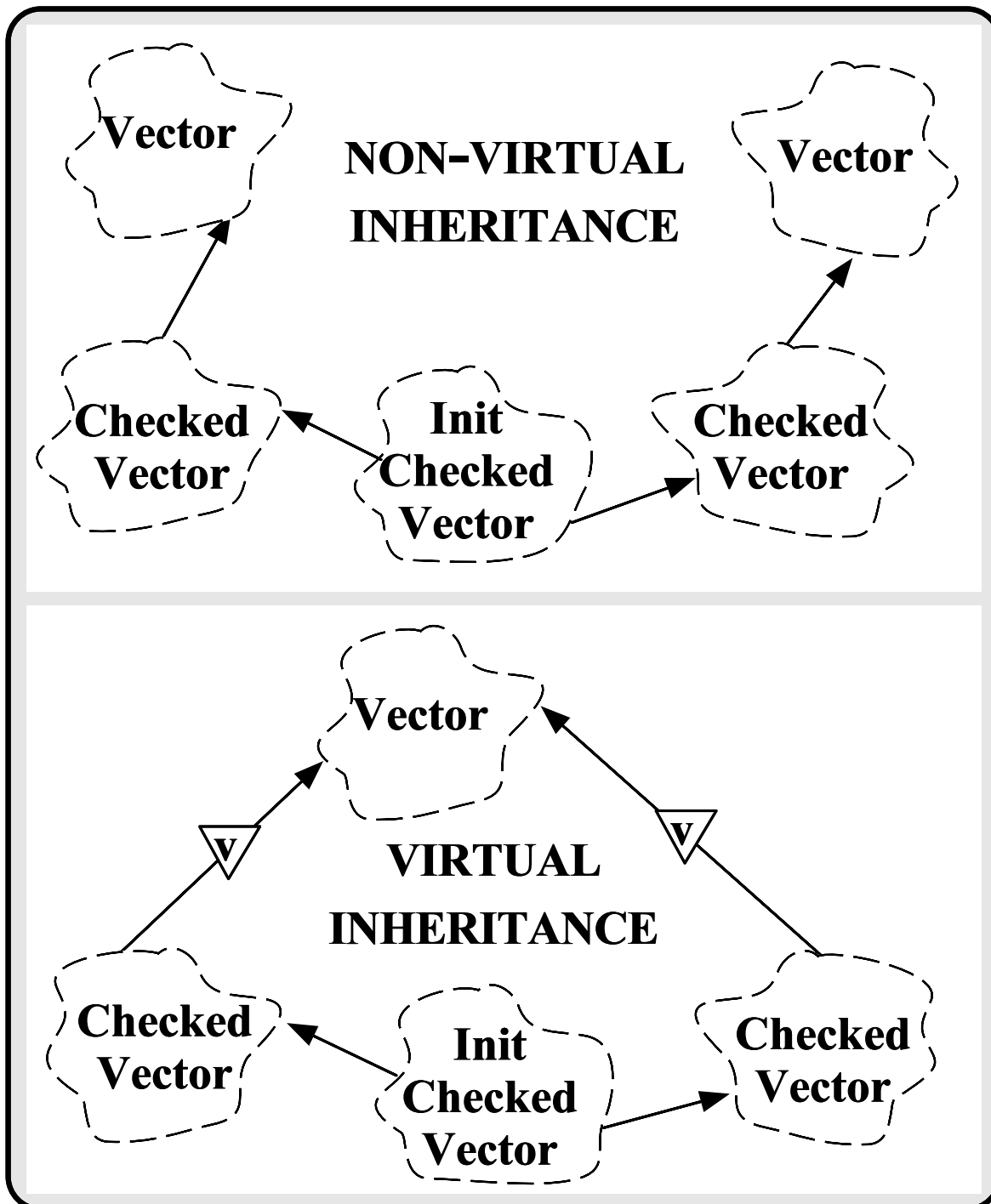
```
class Checked_Vector : public virtual Vector
{ /* .... */ };
class Init_Vector : public virtual Vector
{ /* .... */ };
class Init_Checked_Vector :
    public Checked_Vector, public Init_Vector
{ /* .... */ };
```

- In this example, the **virtual** keyword, when applied to a base class, causes `Init_Checked_Vector` to get one `Vector` base class instead of two

Overview of Virtual Base Classes

- Virtual base classes allow class designers to specify that a base class will be shared among derived classes
 - No matter how often a virtual base class may occur in a derivation hierarchy, only “one” shared instance is generated when an object is instantiated
 - * Under the hood, pointers are used in derived classes that contain virtual base classes
- Understanding and using virtual base classes correctly is a non-trivial task since you must plan in advance
 - Also, you must be aware when initializing sub-classes objects...
- However, virtual base classes are used to implement the client and server side of many implementations of CORBA distributed objects

Virtual Base Classes Illustrated



Initializing Virtual Base Classes

- With C++ you must choose one of two methods to make constructors work correctly for virtual base classes:

1. You need to either supply a constructor in a virtual base class that takes no arguments (or has default arguments), *e.g.*,

`Vector::Vector (size_t size = 100); // has problems...`

2. Or, you must make sure the *most derived class* calls the constructor for the virtual base class in its *base initialization section*, *e.g.*,

```
Init_Checked_Vector (size_t size, const T &init):  
    Vector (size), Check_Vector (size),  
    Init_Vector (size, init)
```

Vector Interface Revised

- The following example illustrates templates, multiple inheritance, and virtual base classes in C++

```
#include <iostream.h>
#include <assert.h>
// A simple-minded Vector base class,
// no range checking, no initialization.
template <class T>
class Vector
{
public:
    Vector (size_t s): size_ (s), buf_ (new T[s]) {}
    T &operator[] (size_t i) { return this->buf_[i]; }
    size_t size (void) const { return this->size_; }
private:
    size_t size_;
    T *buf_;
};
```

Init_Vector Interface

- A simple extension to the Vector base class, that enables automagical vector initialization

```
template <class T>
class Init_Vector : public virtual Vector<T>
{
public:
    Init_Vector (size_t size, const T &init)
        : Vector<T> (size)
    {
        for (size_t i = 0; i < this->size (); i++)
            (*this)[i] = init;
    }
    // Inherits subscripting operator and size().
};
```


Checked_Vector Interface

- A simple extension to the Vector base class that provides range checked subscripting

```
template <class T>
class Checked_Vector : public virtual Vector<T>
{
public:
    Checked_Vector (size_t size): Vector<T> (size) {}
    T &operator[] (size_t i) throw (RANGE_ERROR) {
        if (this->in_range (i))
            return (*(inherited *) this)[i];
        else throw RANGE_ERROR (i);
    }
    // Inherits inherited::size.
private:
    typedef Vector<T> inherited;

    bool in_range (size_t i) const {
        return i < this->size ();
    }
};
```

Init_Checked_Vector Interface and Driver

- A simple multiple inheritance example that provides for both an initialized *and* range checked Vector

```
template <class T>
class Init_Checked_Vector :
    public Checked_Vector<T>, public Init_Vector<T> {
public:
    Init_Checked_Vector (size_t size, const T &init):
        Vector<T> (size),
        Init_Vector<T> (size, init),
        Checked_Vector<T> (size) {}
    // Inherits Checked_Vector::operator[]
};
```

- Driver program

```
int main (int argc, char *argv[]) {
    try {
        size_t size = ::atoi (argv[1]);
        size_t init = ::atoi (argv[2]);
        Init_Checked_Vector<int> v (size, init);
        cout << "vector size = " << v.size ()
              << ", vector contents = ";

        for (size_t i = 0; i < v.size (); i++)
            cout << v[i];

        cout << "\n" << ++v[v.size () - 1] << "\n";
    }
    catch (RANGE_ERROR) { /* ... */ }
}
```

Multiple Inheritance Ambiguity

- Consider the following:

```
struct Base_1 { int foo (void); /* .... */ };
struct Base_2 { int foo (void); /* .... */ };
struct Derived : Base_1, Base_2 { /* .... */ };
int main (void) {
    Derived d;
    d.foo (); // Error, ambiguous call to foo ()
}
```

- There are two ways to fix this problem:

1. Explicitly qualify the call, by prefixing it with the name of the intended base class using the scope resolution operator, *e.g.*,

```
d.Base_1::foo (); // or d.Base_2::foo ()
```

2. Add a new method foo to class Derived (similar to Eiffel's renaming concept) *e.g.*,

```
struct Derived : Base_1, Base_2 {
    int foo (void) {
        Base_1::foo (); // either, both
        Base_2::foo (); // or neither
    }
};
```