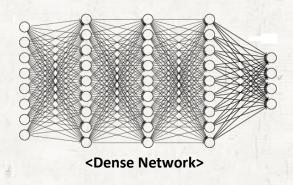
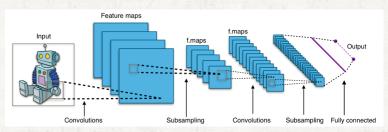
Convolutional Neural Networks

Convolutional Neural Network

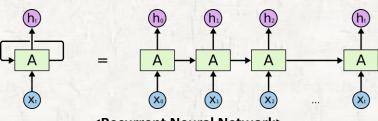
- Type of Deep Neural Network
 - Dense Network (=Fully-connected Neural Network)
 - Convolutional Neural Network
 - Recurrent Neural Network

• • • • •





<Convolutional Neural Network>



<Recurrent Neural Network>

Convolutional Neural Network

- What is the Convolutional Neural Network?
 - Consists of Convolution, Pooling layers

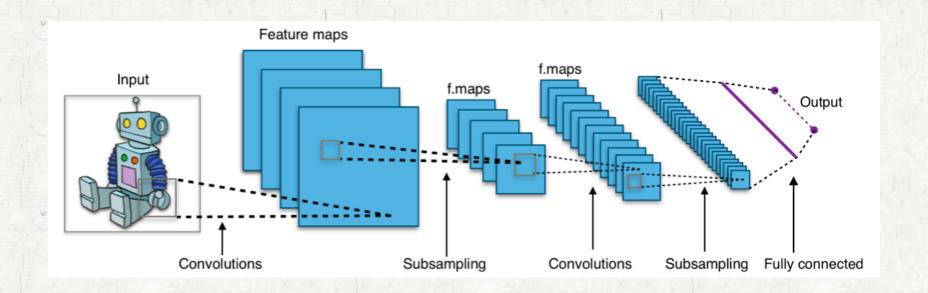


Image data

How to perceive on computer

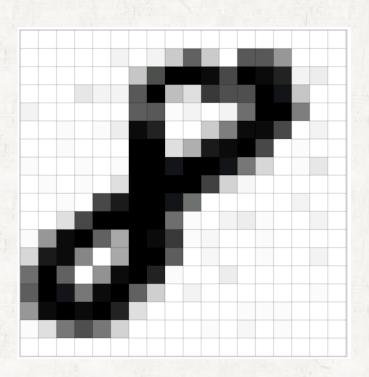
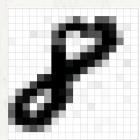


Image data

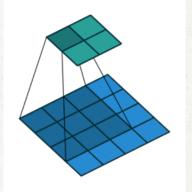
- How to perceive on computer
 - DNN(Dense Neural network)



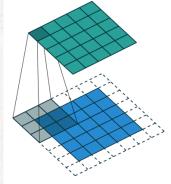
CNN(Convolutional Neural network)

Convolution

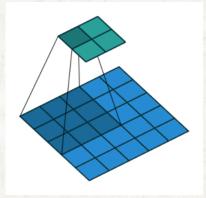
Summary (1)



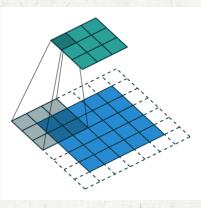
Padding=0, Strides=1



Padding=1, Strides=1



Padding=0, Strides=2

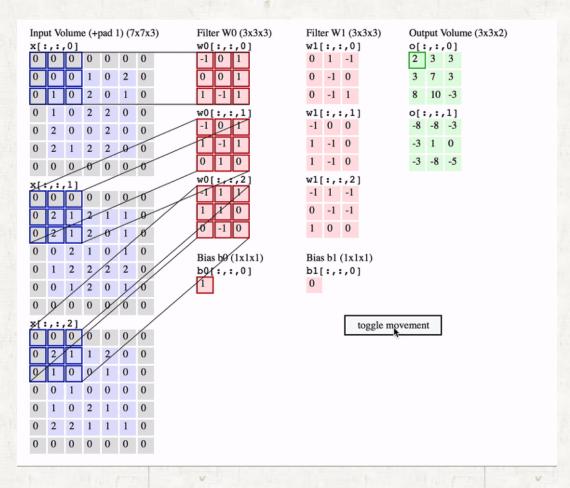


Padding=1, Strides=2

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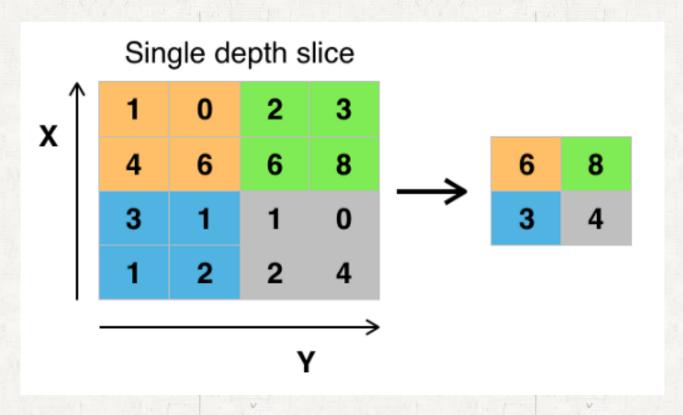
Convolution

Summary (2)



Pooling

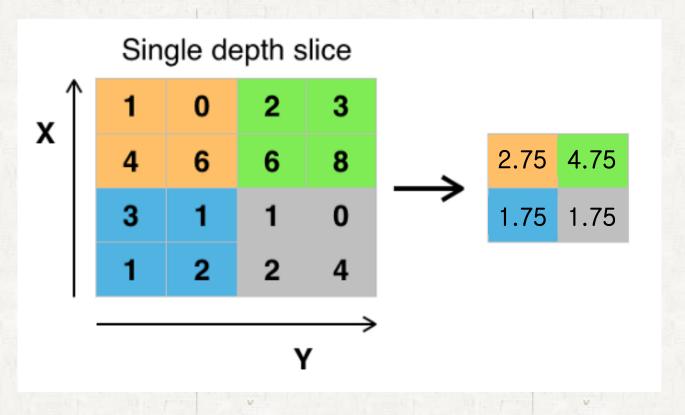
- Summary (1)
 - MAX pooling
 - Sride=2, Kernel_size=2



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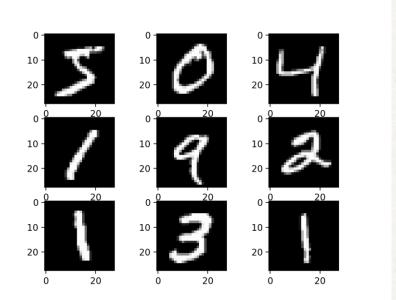
Pooling

- Summary (2)
 - Average pooling
 - Sride=2, Kernel_size=2

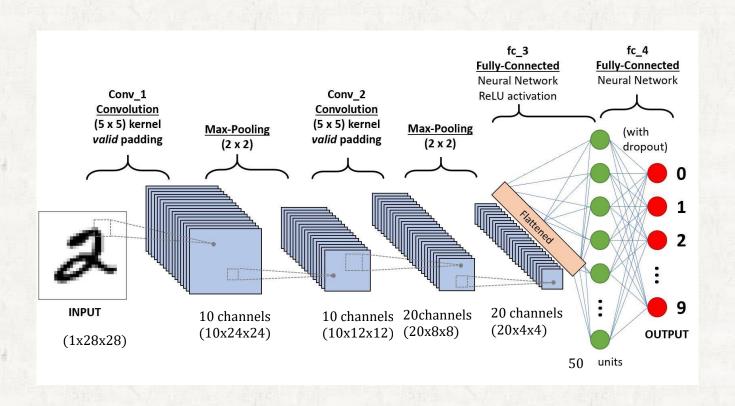


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- MNIST Dataset
 - MNIST is handwritten digit images
 - It contains training set of 60,000 examples and a test set of 10,000 examples
 - Each example is a 28x28 grayscale image, associated with a label from 10 classes.



CNN Architecture



Preparation

```
import torch
import torch.nn as nn
import torch.optim as optim
import torch.nn.functional as F
from torchvision import transforms, datasets

USE_CUDA = torch.cuda.is_available()
DEVICE = torch.device("cuda" if USE_CUDA else "cpu")
```

- USE_CUDA = torch.cuda.is_available()DEVICE = torch.device("cuda" if USE_CUDA else "cpu")
 - Select device to use (GPU or CPU)
 - If GPU can be used, use GPU
 - else, use CPU

Setup data

```
transform = transforms.Compose([
    transforms.ToTensor(),
    transforms.Normalize(mean=(0.5,), std=(0.1,))
])
trainset = datasets.MNIST(
    root='./.data/',
                                       train-images-idx3-ubyte.gz
                                                                     train-labels-idx1-ubyte.gz
                                       GZ 파일
                                                                     GZ 파일
    train=True,
                                       9.45MB
                                                                     28.2KB
    download=False,
    transform=transform
testset = datasets.MNIST(
    root='./.data/',
                                       t10k-images-idx3-ubyte.gz
                                                                    t10k-labels-idx1-ubyte.gz
    train=False,
                                       GZ 파일
                                                                    GZ 파일
    download=False,
                                                                    4.43KB
    transform=transform
```

Transforms: Normalize data

Setup for mini-batch

```
BATCH_SIZE = 64

train_loader = torch.utils.data.DataLoader(
    dataset=trainset,
    batch_size=BATCH_SIZE,
    shuffle=True,
)
test_loader = torch.utils.data.DataLoader(
    dataset=testset,
    batch_size=BATCH_SIZE,
    shuffle=True,
)
```

- Divide by each batch of data
- Data Shuffling

Setup Network

```
class Net(nn.Module):
   def init (self):
        super(Net, self). init ()
        self.conv1 = nn.Conv2d(1, 10, kernel_size=5)
        self.conv2 = nn.Conv2d(10, 20, kernel_size=5)
        self.fc1 = nn.Linear(320, 50)
        self.fc2 = nn.Linear(50, 10)
   def forward(self, x):
       x = F.relu(F.max pool2d(self.conv1(x), 2))
       x = F.relu(F.max pool2d(self.conv2(x), 2))
       x = x.view(-1, 320)
       x = F.relu(self.fc1(x))
       x = F.dropout(x, training=self.training)
       x = self.fc2(x)
       return F.log softmax(x, dim=1)
```

- nn.Linear(x, y) = x_dim -> y_dim (node)
- nn.Conv2d(x, y) = x_dim -> y_dim (channel)

Model and Optimizer

```
model = Net().to(DEVICE)
optimizer = optim.SGD(model.parameters(), lr=0.01)
```

- Net.to(DEVICE)
 - .to(): function sends the parameters of the model to the specified location.
 - DEVICE = GPU or CPU (defined it before)
- Stochastic Gradient Descent (SGD)
 - Parameters to learn
 - Learning rate Hyper Parameter

Setup for training

```
def train(model, train loader, optimizer, epoch):
   model.train()
    for batch idx, (data, target) in enumerate(train loader):
        data, target = data.to(DEVICE), target.to(DEVICE)
        optimizer.zero grad()
        output = model(data)
        loss = F.cross entropy(output, target)
        loss.backward()
        optimizer.step()
        if batch idx % 200 == 0:
            print('Train Epoch: {} [{}/{} ({:.0f}%)]\tLoss:
{:.6f}'.format(
                epoch, batch_idx * len(data),
len(train loader.dataset),
                100. * batch_idx / len(train_loader), loss.item()))
```

Setup for evaluation

```
def evaluate(model, test loader):
   model.eval()
   test loss = 0
    correct = 0
   with torch.no grad():
        for data, target in test loader:
            data, target = data.to(DEVICE), target.to(DEVICE)
            output = model(data)
            test loss += F.cross entropy(output, target,
                                         reduction='sum').item()
            pred = output.max(1, keepdim=True)[1]
            correct += pred.eq(target.view as(pred)).sum().item()
   test loss /= len(test loader.dataset)
    test accuracy = 100. * correct / len(test loader.dataset)
    return test loss, test accuracy
```

• Run!

```
[10] Test Loss: 0.4043, Accuracy: 96.98%
[20] Test Loss: 0.3592, Accuracy: 97.22%
[30] Test Loss: 0.3326, Accuracy: 98.47%
```

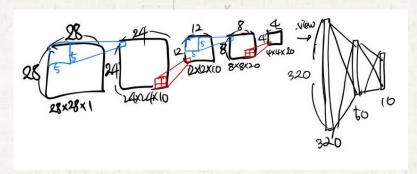
Convolution Layer

```
class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        self.conv1 = nn.Conv2d(1, 10, kernel_size=5)
        self.conv2 = nn.Conv2d(10, 20, kernel_size=5)
        self.fc1 = nn.Linear(320, 50)
        self.fc2 = nn.Linear(50, 10)
```

Conv2d

- Filter: 5x5x10, 5x5x20
- Default: Strides: 1, Padding: 0

$$out = \frac{\ln + 2P - f}{s} + 1$$



Add Convolution and Pooling Layer

○ CNN의 channel, kernel size, stride, padding 을 변경해서 자신만의 CNN 구조를 만들어보자!

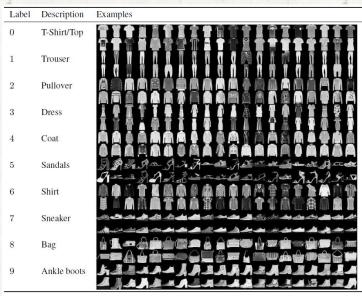
```
class Net(nn.Module):
    def __init__(self):
        super(Net, self).__init__()
        self.conv1 = nn.Conv2d(1, 10, kernel_size=5, stride=1, padding=0)
        self.conv2 = nn.Conv2d(10, 20, kernel_size=5, stride=1, padding=0)
        self.fc1 = nn.Linear(???, ???)
        self.fc2 = nn.Linear(???, 10)
```

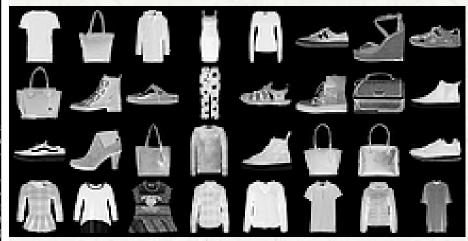
Add Dropout and Batch Normalization

♥ Convolution Dropout, Batch Normalization 을 추가하여 성 능을 비교해보자!

Fahsion MNIST

- Fashion MNIST Dataset
 - Fashion-MNIST is a dataset of Zalando's article images
 - It contains training set of 60,000 examples and a test set of 10,000 examples
 - Each example is a 28x28 grayscale image, associated with a label from 10 classes.





Cifar-10

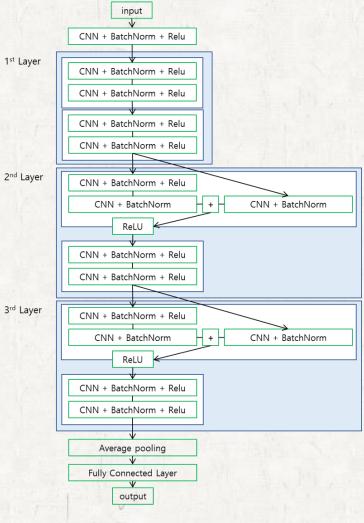
- Cifar-10 Dataset
 - Subsets of the 80 million tiny images dataset that is commonly used for training various image processing systems and machine learning
 - It consists of 60,000 32x32 color images in 10 classes, with 6,000 images per class. There are 50,000 training images and 10,000 test images.



<Sample images from Cifar-10 dataset>

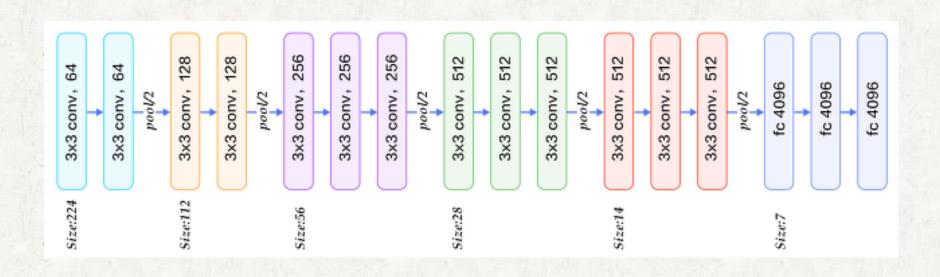
Try to make ResNet





Try to make VGG Net

VGG Network



Pytorch Net

nn.Sequential()

```
class Net(nn.Module):
   def __init__(self):
        super(Net, self). init ()
        self.conv1 = nn.Sequential(
            nn.Conv2d(1, 10, kernel size=5),
            nn.MaxPool2d(kernel_size=2, stride=2),
            nn.ReLU(),
            nn.Dropout2d(0.5),
        self.conv2 = nn.Sequential(
            nn.Conv2d(10, 20, kernel_size=5),
            nn.MaxPool2d(kernel size=2, stride=2),
            nn.ReLU(),
            nn.Dropout2d(0.5),
        self.fc = nn.Sequential(
            nn.Linear(320, 50),
            nn.ReLU(),
            nn.Dropout(0.5),
            nn.Linear(50, 10),
   def forward(self, x):
        x = self.conv1(x)
        x = self.conv2(x)
        x = x.view(-1, 320)
        x = self.fc(x)
        return F.log_softmax(x, dim=1)
```

```
class Net(nn.Module):
    def init (self):
        super(Net, self).__init__()
        self.conv1 = make_Sequential(
                      1, 10, 5, 2, 2, 0.5)
        self.conv2 = make Sequential(
                      10, 20, 5, 2, 2, 0.5)
        self.fc = nn.Sequential(
            nn.Linear(320, 50),
            nn.ReLU(),
            nn.Dropout(0.5),
            nn.Linear(50, 10),
    def forward(self, x):
        x = self.conv1(x)
        x = self.conv2(x)
        x = x.view(-1, 320)
        x = self.fc(x)
        return F.log softmax(x, dim=1)
def make_Sequential(in_ch, out_ch,
               conv_k, pool_k, pool_s, dropout_p):
    return nn.Sequential(
        nn.Conv2d(in ch, out ch,
                          kernel size=conv k),
        nn.MaxPool2d(kernel_size=pool_k,
                              stride=pool s),
        nn.ReLU(),
        nn.Dropout2d(dropout p),
```