## Lecture2 作业

1,假设训练样本集为D =  $\{(\mathbf{x}_1, y_1) = ((3,3)^T, 1), (\mathbf{x}_2, y_2) = ((4,3)^T, 1), (\mathbf{x}_3, y_3) = ((1,1)^T, -1)\}$ ,使用感知器算法设计分类面,并判断测试样本 $\mathbf{x} = (0,1)^T$ 属于哪个类别。

解:

样本增广后为: 
$$\vec{x}_1 = (1,3,3)^T$$
,  $y_1 = 1$ ,  $\vec{x}_2 = (1,4,3)^T$ ,  $y_2 = 1$ ,  $\vec{x}_3 = (1,1,1)^T$ ,  $y_3 = -1$ 

初始化权重:  $\vec{w}^{(0)} = (0,0,0)^T$ 

$$sign\left(\vec{w}^{(0)T}\vec{x}_1\right) = 0 \neq y_1, \quad \therefore \quad \vec{w}^{(1)} = \vec{w}^{(0)} + y_1\vec{x}_1 = (1,3,3)^T,$$

$$sign(\vec{w}^{(1)T}\vec{x}_2) = 1 = y_2, \quad \therefore \quad \vec{w}^{(2)} = \vec{w}^{(1)} = (1,3,3)^T$$

$$sign\left(\vec{w}^{(2)T}\vec{x}_3\right) = 1 \neq y_3, \quad \therefore \quad \vec{w}^{(3)} = \vec{w}^{(2)} + y_3\vec{x}_3 = (0,2,2)^T$$

$$sign\left(\vec{w}^{(3)T}\vec{x}_1\right) = 1 = y_1, \quad \therefore \quad \vec{w}^{(4)} = \vec{w}^{(3)} = (0,2,2)^T$$

$$sign\left(\vec{w}^{(4)T}\vec{x}_2\right) = 1 = y_2, \quad \therefore \quad \vec{w}^{(5)} = \vec{w}^{(4)} = (0,2,2)^T$$

$$sign\left(\vec{w}^{(5)T}\vec{x}_{3}\right) = 1 \neq y_{3}, \quad \therefore \quad \vec{w}^{(6)} = \vec{w}^{(5)} + y_{3}\vec{x}_{3} = (-1,1,1)^{T}$$

$$sign\left(\vec{w}^{(6)T}\vec{x}_1\right) = 1 = y_1, \quad \therefore \quad \vec{w}^{(7)} = \vec{w}^{(6)} = (-1,1,1)^T$$

$$sign(\vec{w}^{(7)T}\vec{x}_2) = 1 = y_2, \quad \therefore \quad \vec{w}^{(8)} = \vec{w}^{(7)} = (-1,1,1)^T$$

$$sign(\vec{w}^{(8)T}\vec{x}_3) = 1 \neq y_3, \quad \therefore \quad \vec{w}^{(9)} = \vec{w}^{(8)} + y_3\vec{x}_3 = (-2,0,0)^T$$

$$sign\left(\vec{w}^{(9)T}\vec{x}_1\right) = -1 \neq y_1, \quad \therefore \quad \vec{w}^{(10)} = \vec{w}^{(9)} + y_1\vec{x}_1 = (-1,3,3)^T$$

$$sign\left(\vec{w}^{(10)T}\vec{x}_2\right) = 1 = y_2, \quad \therefore \quad \vec{w}^{(11)} = \vec{w}^{(10)} = (-1,3,3)^T$$

$$sign\left(\vec{w}^{(11)T}\vec{x}_3\right) = 1 \neq y_3, \quad \therefore \quad \vec{w}^{(12)} = \vec{w}^{(11)} + y_3\vec{x}_3 = (-2,2,2)^T$$

常样本进行增广,
$$\vec{\mathbf{x}} = (1,0,1)^T$$
,
$$sign(\vec{\mathbf{w}}^T\vec{\mathbf{x}}) = sign((-3,1,1)(1,0,1)^T = -1, \quad \therefore \quad \vec{\mathbf{x}} \in -1 \not\simeq$$

- 2,对于感知器算法(PLA),假设第 t 次迭代时,选择的是第 n 个样本:  $sign(\mathbf{w}^T\mathbf{x}_n) \neq y_n$ , $\mathbf{w}_{t+1} \leftarrow \mathbf{w}_t + y_n\mathbf{x}_n$ ,下述那个式子正确?
  - (a)  $\mathbf{w}_{t+1}^T \mathbf{x}_n = y_n$
  - (b)  $\operatorname{sign}(\mathbf{w}_{t+1}^T \mathbf{x}_n) = y_n$
- $(c) y_n \mathbf{w}_{t+1}^T \mathbf{x}_n \ge y_n \mathbf{w}_t^T \mathbf{x}_n$
- (d)  $y_n \mathbf{w}_{t+1}^T \mathbf{x}_n < y_n \mathbf{w}_t^T \mathbf{x}_n$
- 3, 证明: 针对线性可分训练样本集,PLA 算法中,当 $\mathbf{W}_0 = \mathbf{0}$ ,在对分错样本进行了 T 次纠正后,下式成立:  $\frac{\mathbf{w}_f^T}{\|\mathbf{w}_f\|} \frac{\mathbf{w}_T}{\|\mathbf{w}_T\|} \ge \sqrt{T} \cdot constant$ 证明: 由于

$$egin{aligned} oldsymbol{W}_f^T oldsymbol{W}_{t+1} &= oldsymbol{W}_f^T oldsymbol{W}_t + y_n(t) oldsymbol{X}_n(t) \ &\geqslant oldsymbol{W}_f^T oldsymbol{W}_t + \min_n y_n(t) oldsymbol{W}_f^T oldsymbol{X}_n(t) \end{aligned}$$

且有 $W_0 = 0$ ,故有 $\boldsymbol{W}_f^T \boldsymbol{W}_T \ge T \cdot \min_n y_n \boldsymbol{W}_f^T \boldsymbol{X}_n$ ;

又由于

$$egin{aligned} \| oldsymbol{W}_{t+1} \|^2 &= \| oldsymbol{W}_t + y_n(t) oldsymbol{X}_n(t) \|^2 \ &= \| oldsymbol{W}_t \|^2 + 2 y_n(t) oldsymbol{W}_t^T oldsymbol{X}_n(t) + \| y_n(t) oldsymbol{X}_n(t) \|^2 \ &\leqslant \| oldsymbol{W}_t \|^2 + 0 + \| y_n(t) oldsymbol{X}_n(t) \|^2 \ &\leqslant \| oldsymbol{W}_t \|^2 + \max \| oldsymbol{X}_n(t) \|^2 \end{aligned}$$

故有 $\|\boldsymbol{W}_T\| \leqslant \sqrt{T \cdot \max_n \|\boldsymbol{X}_n\|^2}$ ;

综上所述,有

$$egin{aligned} egin{aligned} oldsymbol{W}_f^T oldsymbol{W}_T & oldsymbol{W}_T^T oldsymbol{W}_T & oldsymbol{W}_T oldsymbol{W}_T & oldsymbol{W}_T & oldsymbol{W}_T & oldsymbol{W}_T oldsymbol{W}_N \ & oldsymbol{W}_f \| oldsymbol{W}_T \|$$

4,针对线性可分训练样本集,PLA 算法中,假设对分错样本进行了 T 次纠正后得到的分类面不再出现错分状况,定义:  $\mathbf{R}^2 = \max \|\mathbf{x}_n\|^2$ ,

$$\rho = \min_{n} y_n \frac{\mathbf{w}_f^T}{\|\mathbf{W}_f\|} \mathbf{x}_n, \quad$$
试证明:  $\mathbf{T} \leq \frac{\mathbf{R}^2}{\rho^2}$ 

证明:

$$egin{aligned} & rac{oldsymbol{W}_f^T oldsymbol{W}_T}{\|oldsymbol{W}_f^T \| oldsymbol{W}_T \| \|oldsymbol{W}_T \| \| oldsymbol{W}_T \| \| oldsym$$

$$egin{aligned} \sqrt{T} &\leqslant rac{R}{
ho} \cdot rac{oldsymbol{W}_f^T oldsymbol{W}_T}{\|oldsymbol{W}_f\| \|oldsymbol{W}_T\|} \ &= rac{R}{
ho} \cdot \cos \langle oldsymbol{W}_f, oldsymbol{W}_T 
angle \ &\leqslant rac{R}{
ho} \end{aligned}$$

因此有

$$T \leqslant \frac{R^2}{
ho^2}$$

5, 假 设 训 练 样 本 集 为 D =  $\{(\vec{x}_1, y_1) = ((0.2, 0.7)^T, 1), (\vec{x}_2, y_2) = ((0.3, 0.3)^T, 1), (\vec{x}_3, y_3) = ((0.4, 0.5)^T, 1), (\vec{x}_4, y_4) = ((0.6, 0.5)^T, 1), (\vec{x}_5, y_5) = ((0.1, 0.4)^T, 1), (\vec{x}_6, y_6) = ((0.4, 0.6)^T, -1), (\vec{x}_7, y_7) = ((0.6, 0.2)^T, -1), (\vec{x}_8, y_8) = ((0.7, 0.4)^T, -1), (\vec{x}_9, y_9) = ((0.8, 0.6)^T, -1), (\vec{x}_{10}, y_{10}) = ((0.7, 0.5)^T, -1)\}$ ,用 Pocket 算法设计分类面。(可借助编程实现,迭代次数最多 10 次,需提交每次迭代的结果)解:略