Multimedia (Lab 02)

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Summary

• In previous lab, you have installed Visual C++ and OpneCV library in your computer.

- In this lab, continue to the basic practice.
 - Load an image and display it on your screen.
 - Also, you will learn about simple pixel transforms in images.

[Lab01-2] cont'd

- Load an image (using cv::imread)
- Create a named OpenCV window (using cv::namedWindow)
- Display an image in the OpenCV window (using cv::imshow)

http://docs.opencv.org/3.2.0/db/deb/tutorial_display_i mage.html

```
#include <opency2/core/core.hpp>
#include <opency2/imgcodecs.hpp>
#include <opency2/highgui/highgui.hpp>
#include <iostream>
#include <string>
using namespace cv;
using namespace std;
int main( int argc, char** argv )
    string imageName("../data/HappyFish.jpg"); // by default
    if(argc > 1)
        imageName = argv[1];
    Mat image;
    image = imread(imageName.c_str(), IMREAD_COLOR); // Read the file
    if( image.empty() )
                                             // Check for invalid input
        cout << "Could not open or find the image" << std::endl;
        return -1;
    namedWindow( "Display window", WINDOW_AUTOSI左 ); // Create a window for display.
    imshow( "Display window", image );
                                                   // Show our image inside it.
    waitKev(0); // Wait for a kevstroke in the window
    return 0;
```

[Lab02-1]

- A general image processing operator is a function that takes one or more input images and produces an output image.
- Simple pixel transform: We will learn how to change our image appearance.
 - Load an image (using cv::imread)
 - Change its contrast and brightness of an image
 - $g(x) = \alpha * f(x) + \beta$
 - The parameters $\alpha>0$ and β are often called the *gain* and *bias* parameters; sometimes these parameters are said to control *contrast* and *brightness* respectively.
 - Display the result image in an OpenCV window (using <u>cv::imshow</u>)

Example results

• using α =2.2 and β =50



Some useful function

Saturation Arithmetic

- OpenCV deals a lot with image pixels that are often encoded in a compact, **8- or 16-bit per channel**, form and thus have a limited value range.
- Furthermore, certain operations on images, like color space conversions, brightness/contrast adjustments, sharpening, complex interpolation can **produce values out of the available range**.
- If you just store the lowest 8 (16) bits of the result, this results in visual artifacts and may affect a further image analysis.
- To solve this problem, the so-called *saturation* arithmetics is used.
- For example, to store r, the result of an operation, to an 8-bit image, you find the nearest value within the 0..255 range:
 - $I(x,y)=\min(\max(r),0),255)$

1 | Lat<uchar>(y, x) = saturate_cast<uchar>(r);

- To access each element of an image matrix, use
 - .at<data type>(y, x)
 - For example, in case of gray image
 - Mat gray_img(Size(1920, 1080), CV_8UC1);
 - int value = gray_img.at<uchar>(100, 200);
 - In case of color image
 - Mat color_img(Size(1920, 1080), CV8UC3);
 - int blue = $color_img.at < Vec3b > (y, x)[0]$;
 - int green = color_img.at<Vec3b>(y, x)[1];
 - int red = $color_img.at < Vec3b > (y, x)[2];$

Useful Tip for Debug

- Image Watch: viewing in-memory images in the Visual Studio debugger
 - Author: Wolf Kienzle
 - You will learn how to visualize OpenCV matrices and images within Visual Studio 2012.

[Lab02-2]

- Linear blending of two images
 - Load two images (using cv::imread)
 - Do linear blending of the two images
 - $dst(x,y) = \alpha * src_1(x,y) + \beta * src_2(x,y)$
 - where $\beta = 1 \alpha$.
 - cv::addWeighted(src1, α , src2, β , γ , dst)
 - Display the result image in an OpenCV window (using cv::imshow)
 - By varying α from $0 \rightarrow 1$ this operator can be used to perform a temporal cross-dissolve between two images

