

**Subject Name: EOS / Embedded Linux**

**Note : you need to read relevant documentation, as you attempt the assignment questions – in addition, you need to understand, before you can go, for implementation**

Note : you need to read the lecture notes | SRM | DATA-SHEET | TRM | samples | \*.txt files | relevant kernel documentation

Note : after reading the above and during the practicals, if you still have specific doubts, please write to [babu.krishnamurthy@yahoo.com](mailto:babu.krishnamurthy@yahoo.com)

### **Lab Assignment 2:**

- 1. Explain clearly, how additional UARTs of BeagleBone Black board can be enabled, by modifying the board's device tree sources/dts/dtsi - you need to understand the UARTs available on the board and modify the dts/dtsi, as per device tree rules and hw rules – test, modify, and verify , that the enabled UARTs are visible, in the /proc/device-tree/\* of the target kernel – also, verify, that the platform devices of the additional UARTs are visible, under /sys/bus/platform/devices/\* and /sys/bus/platform/drivers/ - explore the attributes and details – check, if they are correctly set-up, as required**
- 2. Enable I2C1 bus of the BeagleBone blackboard, by modifying the device tree of beaglebone black – modify, test, and verify, using /proc/device-tree/\* ,/sys/bus/platform/devices/\* and /sys/bus/platform/drivers/\* - in addition, based on pickit board pdf, i2c\_demo\_board.txt and other attached files, modify the device tree of the beaglebone black, for adding support, for i2c client devices – once added, you need test and verify, using /proc/device-tree/\* , /sys/bus/i2c/devices/\* , and /sys/bus/i2c/drivers/\***
- 3. Refer to ldd\_assignment5's pdfs, in emb\_linux\_3/ dump provided, during lectures. Refer to files, with file names starting, with char\_\* - Understand the working of the \*.c files – start with, char\_pc\_drv.c /char\_pc\_drv.h files – Build and test them on the target system of BeagleBone black – you need to use user-space files of char\_pseudo\_test.c / char\_pseudo\_test1.c – refer to pseudo\_class.c, for more comments on initializing a char device/driver**

4. Using the samples , from 3) and led\_ctrl.c , you need to export a set of char device , for accessing gpio pins , as per project requirements – you can mainly, use ioctl commands / ioctl() system call API and ioctl method of char driver to provide access to a set of gpio pins, as per project requirements

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