Presentation of expertise, field of study and research plan

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Examinee number: 5010 Mechanical Engineering, National Taiwan University

(Graduated in Jan. '23)

Content

- 1. Introduction
- 2. Resarch Expertise
- 3. Research Interest (field of study)
- 4. Research plan (Robotics & Al)



About me

- Currently a research student in Autonomous & Soft Robotics Laboratory
- BS studied in Mechanical Engineering (ME), GPA: 4.03/4.3 (last-60-credits)
- Presidential Award in '21 Fall (top 5% of the class in the semester)
- Exchange Student at 青山学院大学(duration: Sept. 2022-Jan. 2023)
- Team mentor of C.K. Robotics at Chien Kuo High School (for FRC competition)



My expertise

Major: Mechanical Design (CAD)

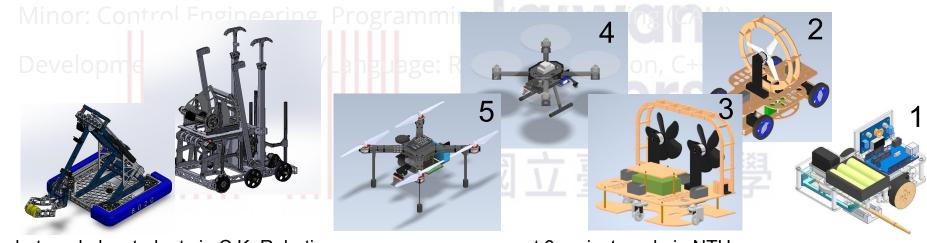
Design Software: SolloWorks, Autodesk Inventor Ton Cl

Minor: Control Engineering, Programming, Manufacturing (CAM)

My expertise - Robots Design

Major: Mechanical Design (CAD)

Design Software: SolidWorks, Autodesk Inventor



robot made by students in C.K. Robotics

past 3 project made in NTU

My expertise - Controlling Robots

Major: Mechanical Design (CAD)

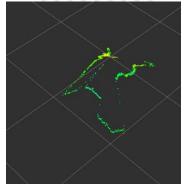
Design Software: SolloWorks, Autodesk Inventor



Robot for indoor mapping

Minor: Control Engineering, Programming

Development Environment/Programming Language: ROS, Linux, Python, C++



environment profile by LiDAR

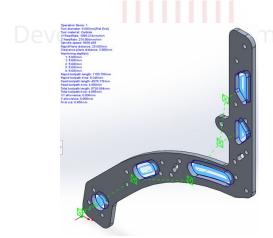


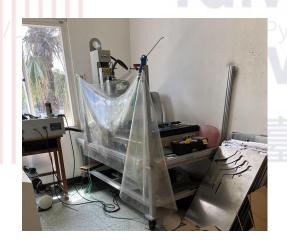
demo: https://drive.google.com/file/d/1hKtAE6LRW2CSUeNtEl2q9REkKdpO65h3/view?usp=drive_link

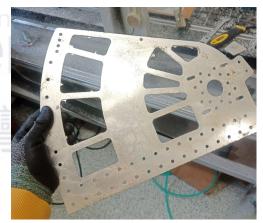
My expertise - Making Components of Robots

Design Software: SolidWorks, Autodesk Inventor

Minor: Control Engineering, Programming, Manufacturing (CAM)







after machining

Simulation for manufacturing in SW CAM

My expertise

Robots Design

Controlling Robots

Making Components of Robots

⇒ Robot is the intersection of my expertises

National Taiwan

Research Interest (field of study)

- Robotics
 - Quadruped Robots
 - Autonomous Driving
 - Humanoid
 - Drone (UAV)
- Others
 - Machine learning
 - Computer Vision (Object detection)

National Taiwan University

- Inspiration by https://reurl.cc/WGn8mx (MIT's Mini Cheetah)
- Instead of hand drafted the controllers, using learning based method
- Adaptive to different outdoor environment
- Scalable to application in Robotics field

University

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Thanks for your attention!