

Problem Statement 6:

AI-Driven Map Updates from Crowdsourced Data

Presented by Team Bundesliga

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Problem Statement

AI-Driven Map Update from Crowd-Sourced Data

Creating and maintaining a real-world digital map is challenging due to constant changes in the environment.

The goal is to develop an AI-first system that can automatically process raw geospatial data—like satellite images, GPS logs, and sensor data—to generate accurate, semantically rich, and up-to-date digital maps.

Manual map curation lacks scalability. With AI, there is a unique opportunity to transform map generation and updating into an intelligent, autonomous process.

Introduction

- Digital maps are built using complex pipelines: ingestion, extraction, enrichment, and rendering
- Traditional methods rely heavily on manual effort and rule-based systems
- These approaches limit scalability and speed of updates
- AI advancements (foundation models, computer vision, NLP) enable automation of the entire pipeline
- Our project uses generative AI and real-world data to create an intelligent map update prototype

Objectives

- To automate the process of updating digital maps using AI.
- To extract key map features (roads, buildings, signs) from raw data.
- To enrich map components with semantic information.
- To detect and correct inconsistencies or outdated information.
- To build a scalable and adaptable map-update pipeline.
- To demonstrate a working prototype using real-world APIs and models.

Our Approach

Data Acquisition

We use Google Maps APIs for map rendering and Google Street View imagery.

Feature Detection

YOLO (You Only Look Once) object detection model is used to identify elements such as vehicles, signboards, and buildings from street images.

Edge Detection

Using Python (Google Colab), we analyze and identify edges of components (e.g., road boundaries, infrastructure edges) for spatial structuring.

Integration

Combining data layers (API + AI models) into a unified representation for map updates.



Technologies Used

**Google
Colab
(Python)**

**End-to-end
implementation,
integration, and
visualization.**

**YOLO
(Object
Detection)**

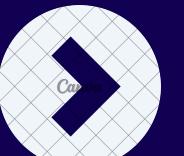
**Real-time
detection of map
objects like traffic
signs, cars,
pedestrians, etc**

**Google Maps
API & Street
View API**

**Used for map
integration,
street-level
imagery, and
positional
context.**

**OpenCV &
Edge
Detection
Algorithms**

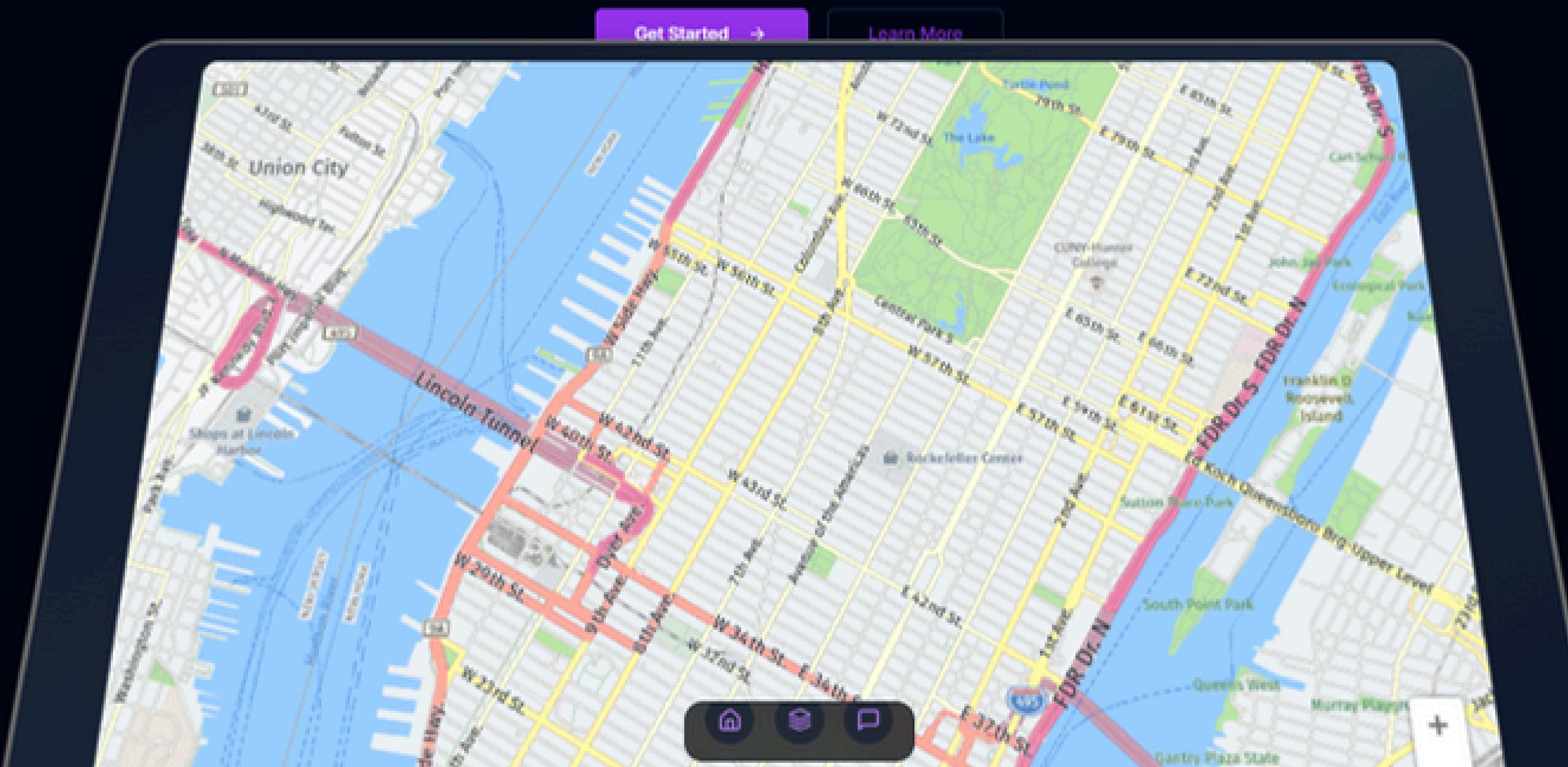
**For identifying
edges and spatial
boundaries in
map elements.**



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Web App

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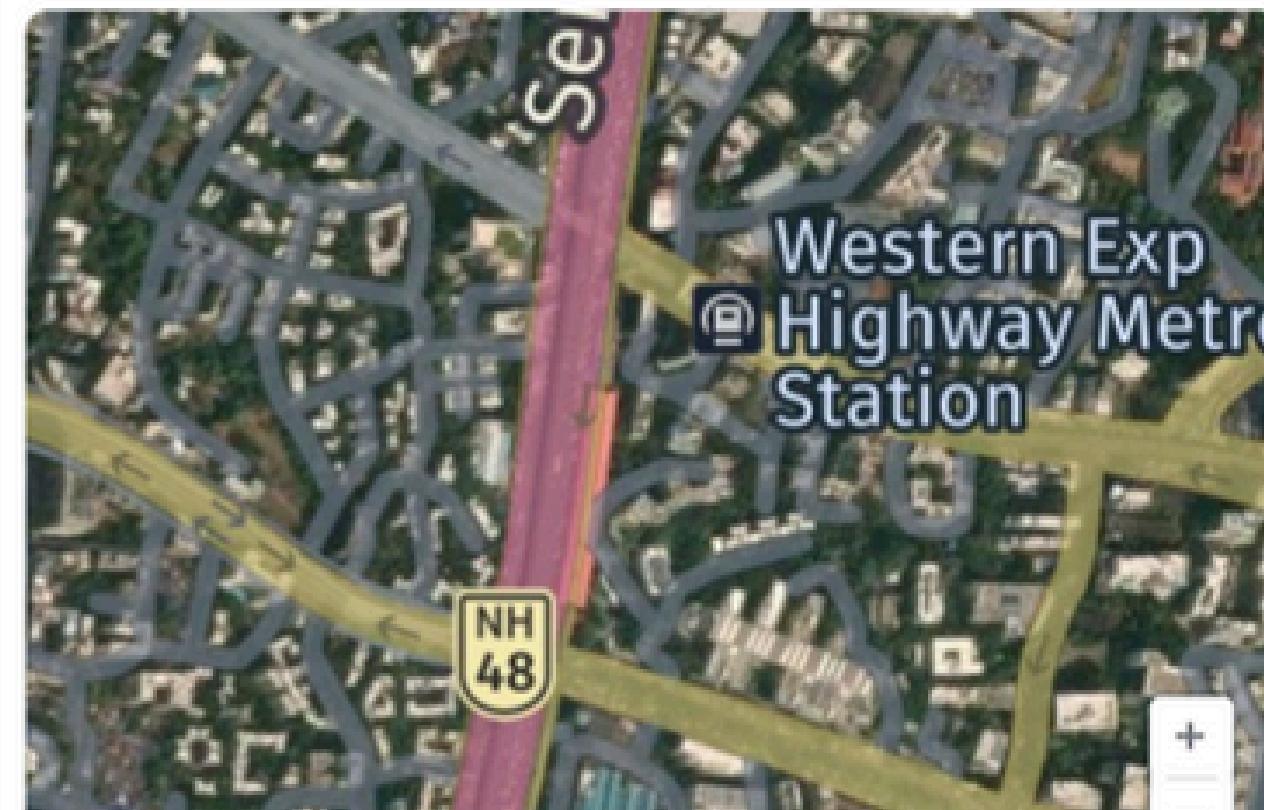
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Location Analysis

Enter a location to generate an AI-powered analysis with satellite imagery, street view, construction mapping, and environmental data.

[Analyze Location](#)[Aerial View](#)[Street View](#)

Andheri Flyover, Bima
NGR-Margdarshan,
Andheri East, Mumbai
400069, India

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Analysis Report

[Population](#)[Air Quality](#)[Road Development](#)

Population Statistics

Demographic data for Andheri Flyover, Bima NGR-Margdarshan, Andheri East, Mumbai 400069, India

Total Population

295,424

Population Density

4,142 /km²

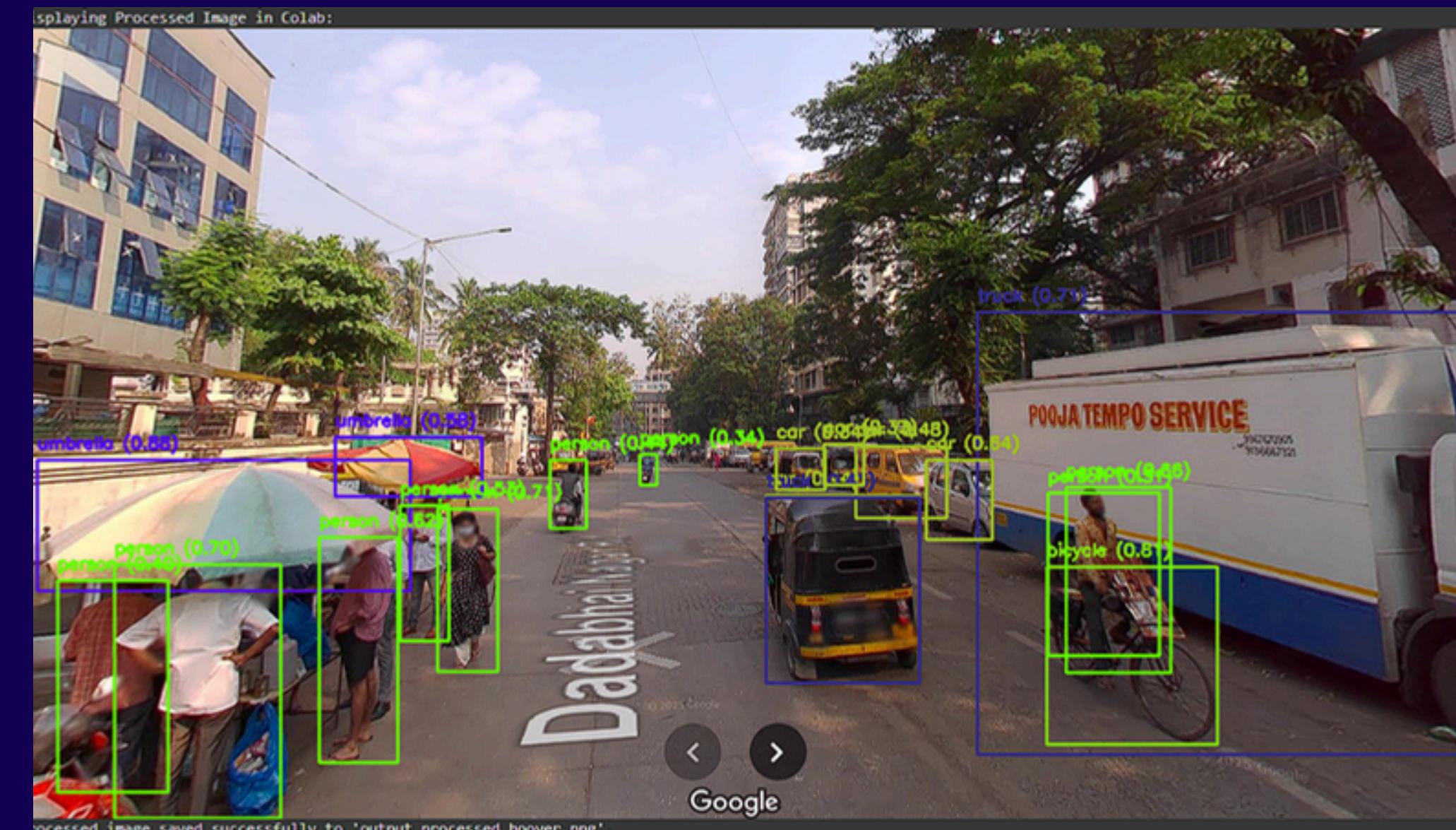
Annual Growth

1.5%

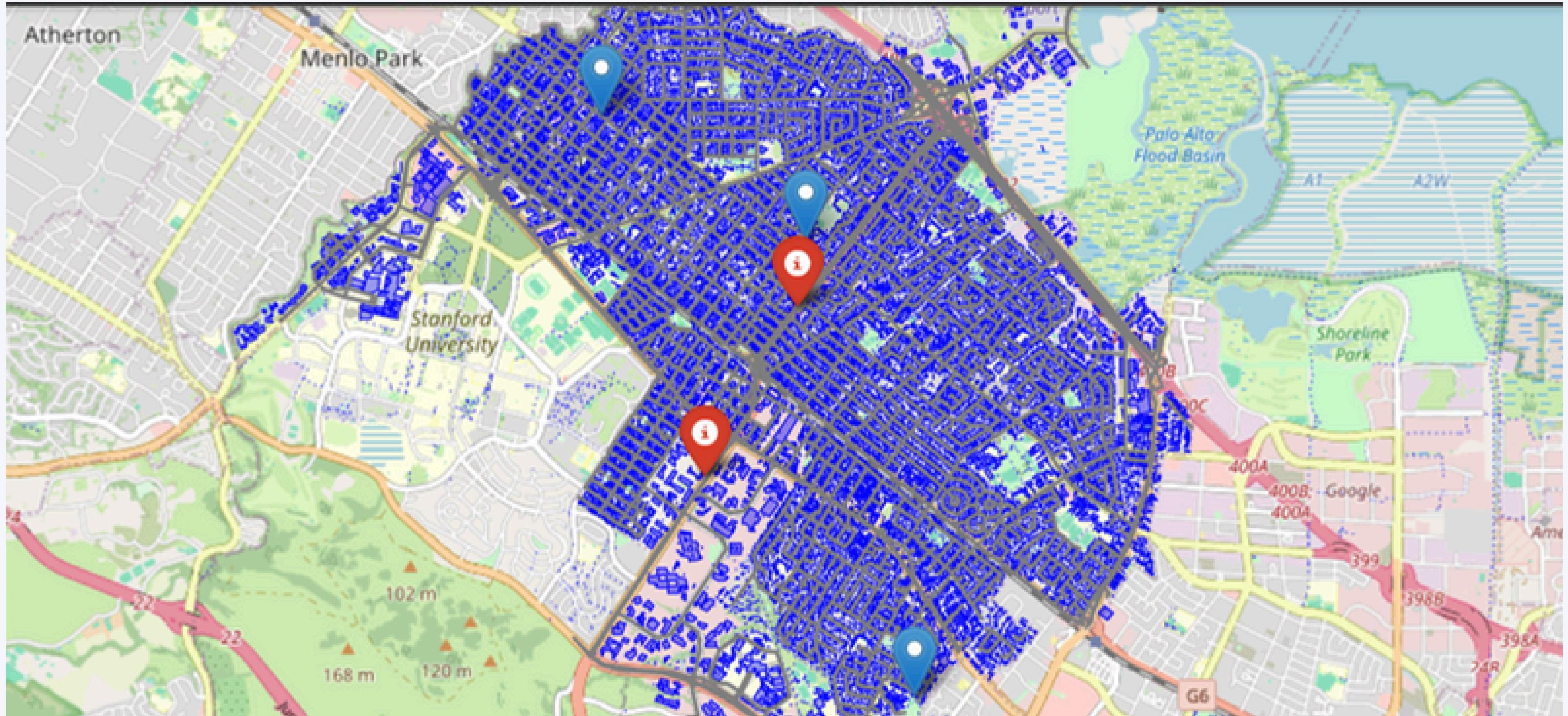
Population Insights

This area has a high population density with a steady growth rate. The demographic distribution suggests a younger population profile.

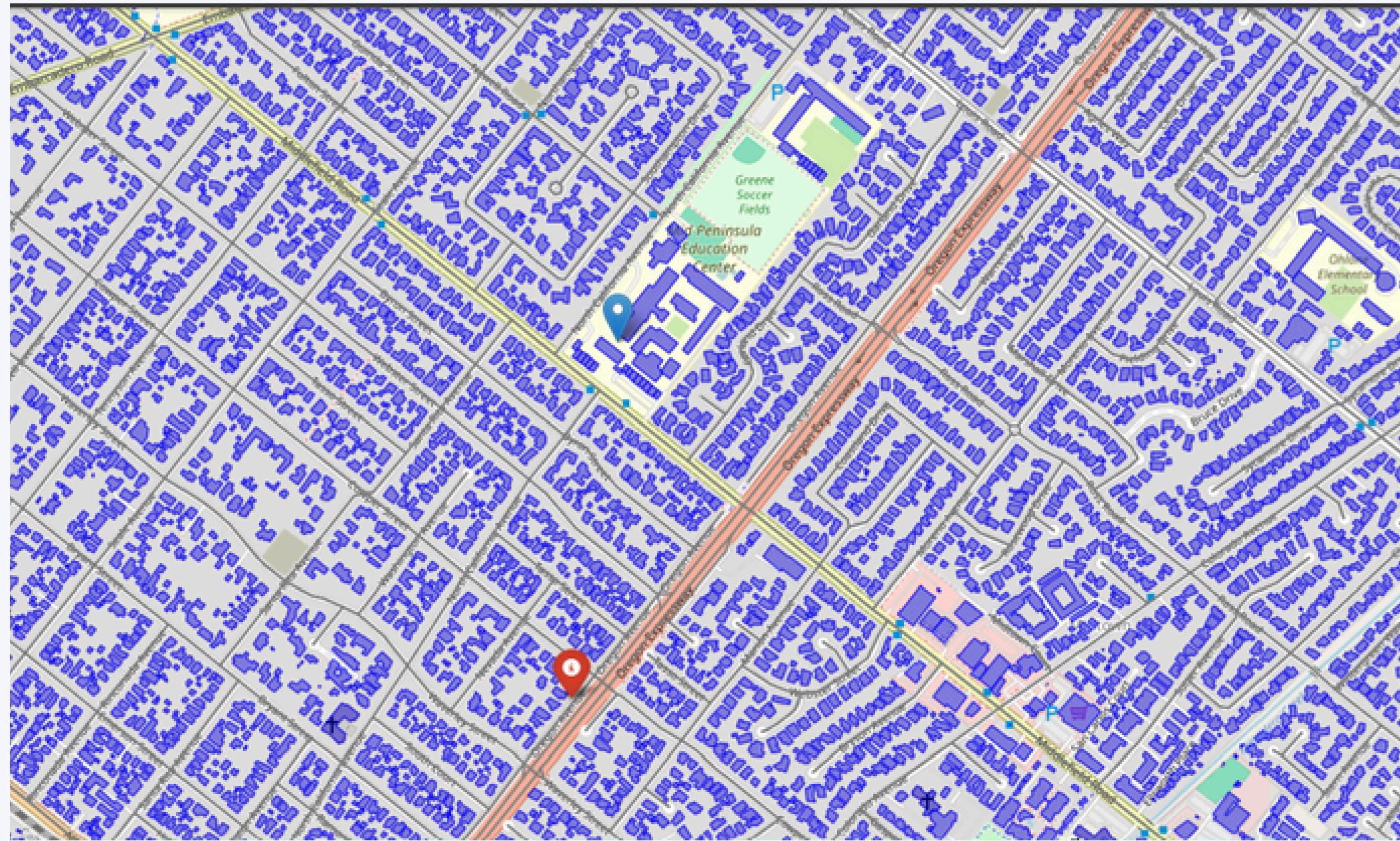
YOLO INTEGRATION



RESULTS AND MAP OUTCOMES



RESULTS AND MAP OUTCOMES



Results

- Successfully detected and labeled objects on real-world maps.
- Detected spatial boundaries for various map components.
- Demonstrated potential for real-time updates using crowd-sourced visuals.

Future Enhancements

- Integrate Lidar and GPS traces for higher spatial accuracy
- Expand YOLO object classes for richer feature detection
- Use NLP for place name tagging and POI classification
- Employ Generative AI to simulate new map data and fill in missing features
- Build a user feedback loop to validate and refine updates

Thank you