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Task # 1

$$\omega_n = 72$$

$$\zeta = 0.5$$

$$J=1$$

$$a = 1$$

$$TF_{\text{small F.B}} = \frac{\frac{K}{Js+a}}{1 + \frac{KK_f}{Js+a}} = \frac{K}{Js+a+KK_f}$$

$$TF_{\text{cascade}} = \frac{K}{Js+a+KK_f} \times \frac{1}{s} = \frac{K}{Js^2+(a+KK_f)s}$$

$$TF = \frac{\frac{K}{Js^2+(a+KK_f)s}}{1 + \frac{K}{Js^2+(a+KK_f)s}} = \frac{K}{Js^2+(a+KK_f)s+K}$$

$$\frac{K}{Js^2+(a+KK_f)s+K} = \frac{\omega_n^2}{s^2+2\zeta\omega_n s+\omega_n^2}$$

$$K = \omega_n^2 = 72^2 = 5184$$

$$a+KK_f = 2\zeta\omega_n$$

$$1+5184K_f = 2 \times 0.5 \times 72 \rightarrow K_f = \frac{72}{5184}$$

Task 2

$$G(s) = \frac{5184}{s^2+72s+8836} \times \frac{0.21}{s^2} = \frac{1088.64}{s^4+72s^3+5184s^2}$$

$$T.F = \frac{G}{1+GH} = \frac{\frac{1088.64}{s^4+72s^3+5184s^2}}{1+\frac{1088.64}{s^4+72s^3+5184s^2}} = \frac{1088.64}{s^4+72s^3+5184s^2+1088.64}$$

$$\text{Task 10}$$

$$t_r = \frac{\pi - \cos^{-1} \zeta}{\omega_n \sqrt{1 - \zeta^2}} = \frac{\pi - \cos^{-1} 0.5}{72 \sqrt{1 - 0.5^2}} = 0.0336 \text{ sec}$$

$$t_p = \frac{\pi}{\omega_n \sqrt{1 - \zeta^2}} = \frac{\pi}{72 \sqrt{1 - 0.5^2}} = 0.0564 \text{ sec}$$

$$t_s(2\%) = \frac{4}{\zeta \omega_n} = \frac{4}{0.5 \times 72} = \frac{1}{9} \text{ sec} \quad t_s(5\%) = \frac{3}{0.5 \times 72} = \frac{1}{12} \text{ sec}$$

$$M_p = e^{\frac{-\pi \zeta}{\sqrt{1 - \zeta^2}}} = e^{\frac{-\pi \times 0.5}{\sqrt{1 - 0.5^2}}} = 0.163 = 16.3\%$$

$$(3) e_{\text{ss ramp}} = \frac{1}{K_w}$$

$$K_v = \lim_{s \rightarrow 0} s G(s) H(s) = \lim_{s \rightarrow 0} s \times \frac{1088.64}{s^4 + 72s^3 + 5184s^2 + 1088.64} = \infty$$

$$e_{\text{ss ramp}} = \frac{1}{\infty} = 0$$

$$(4) \text{ Use PD controller } G_c(s) = K_p + K_d s$$

$$\text{Char eq'n: } 1 + G_c(s) G(s) H(s) = 0$$

$$1 + (K_p + K_d s) \times \frac{1088.64}{s^4 + 72s^3 + 5184s^2} = 0$$

$$s^4 + 72s^3 + 5184s^2 + 1088.64 K_d s + 1088.64 K_p = 0$$

$$a + b + 2\zeta \omega_n = 72$$

$$ab + (a+b)2\zeta \omega_n + \omega_n^2 = 5184$$

$$2\zeta \omega_n ab + (a+b)\omega_n^2 = 1088.64 K_d$$

$$ab \omega_n^2 = 1088.64 K_p$$

use conditions

$$M_p = e^{-\frac{\pi}{\sqrt{1-\zeta^2}}}$$

$$0.2 = e^{-\frac{\pi}{\sqrt{1-\zeta^2}}}$$

$$\zeta = 0.456$$

$$t_s (5\%) = \frac{3}{\zeta w_n}$$

$$2.5 = \frac{3}{0.456 w_n}$$

$$w_n = 2.63$$

Subs above (First 2 eqn.):

$$a + b + 2 \times 0.456 \times 2.63 = 72$$

$$a + b + 2.4 = 72$$

$$a + b = 69.6$$

$$ab + (69.6)(2.4) + (2.63)^2 = 5184$$

$$ab + 173.9569 = 5184$$

$$ab = 5010.0431$$

In last 2 eqn.:

$$2.4 \times 5010.0431 + 69.6 \times (2.63)^2 = 1088.64 K_d$$

$$K_d = 11.49$$

$$5010.0431 (2.63)^2 = 1088.64 K_p$$

$$K_p = 31.83$$

After tuning

$$K_p, K_v = \infty$$

$$e_{ramp} = 0$$

$$e_{step} = 0$$

$$K_a = \lim_{s \rightarrow 0} s^2 (31.83 + 18.6s) \times \frac{1088.64}{s^2(s^2 + 72s + 5184)}$$

$$K_a = 6.6843$$

$$e_{ss} = \frac{1}{K_a} = \frac{1}{6.6843} = 0.1496 = 14.96\%$$

Task 17

Lead :

$$G = \frac{1088.64}{s^2(s^2 + 72s + 5184)}, \quad \zeta = 0.456 \quad \& \quad \omega_n = 2.63$$

$$\text{closed loop poles : } -\zeta \omega_n \pm j \omega_n \sqrt{1 - \zeta^2} = -1.19928 \pm j 2.3406$$

$$G(s) \text{ at } s = -1.19928 \pm j 2.3406 = 0.63 \angle 123.91^\circ$$

$$\phi = 180 - 123.91 = 56.09^\circ$$

$$G_{\text{lead}} = \frac{K_c(s+1.35)}{(s+5.15)}$$

$$|G \times G_{\text{lead}}| = 1$$

$$\left| \frac{1088.64}{s^2(s^2 + 72s + 5184)} \times \frac{K_c(s+1.35)}{(s+5.15)} \right| = 1$$

$$@ s = -1.19928 \pm j 2.3406$$

$$1088.64 K_c (1.449 \times 10^5) = 1$$

$$K_c = \frac{1}{1088.64 (1.449 \times 10^5)} = 63.4$$

$$G_{\text{lead}} = \frac{63.4(s+1.35)}{s+5.15}$$

$$K_a^{\text{old}} = \lim_{s \rightarrow 0} s^2 G_{\text{lead}} GH = s^2 \times \frac{1088.64}{s^2(s^2 + 72s + 5184)} \times \frac{63.4(s+1.35)}{(s+5.15)} = 3.49$$

$$e_{ss} = \frac{1}{K_a^{\text{old}}} = \frac{1}{3.49} = 0.2865 = 28.65\%$$

Lag : (Decrease error to be within 1%)

$$K_a^{\text{new}} = 100$$

$$\beta = \frac{K_a^{\text{new}}}{K_a^{\text{old}}} = \frac{100}{3.49} = 28.653 \approx 29$$

$$\text{Assume } \frac{1}{T} = 0.029$$

$$\frac{1/T}{\beta} = \frac{0.029}{29} = 0.001$$

$$G_{\text{lag}} = \frac{(s + 0.029)}{s + 0.001}$$