

SMART WATER MANAGEMENT

Date	26-10-2023
Team ID	666
Team Name	Proj 223434 Team 2
Project Name	Smart Water Management

SOURCE CODE:

```
#define BLYNK_TEMPLATE_ID "TMPLlcLQu4bQ"  
#define BLYNK_TEMPLATE_NAME "water monitor"  
#define BLYNK_AUTH_TOKEN "OgvenxCWu9sG7-9deFGLFCLE4rWCGW7N"
```

```
char ssid[] = "Wokwi-GUEST";  
char pass[] = "";  
int emptyTankDistance = 150 ;  
int fullTankDistance = 40 ;  
int triggerPer = 10 ;  
#include <Adafruit_SSD1306.h>  
#include <WiFi.h>  
#include <WiFiClient.h>  
#include <BlynkSimpleEsp32.h>  
#include <AceButton.h>  
using namespace ace_button;
```

```
#define TRIGPIN 27  
#define ECHOPIN 26  
#define wifiLed 2  
#define BuzzerPin 13  
#define RelayPin 14  
#define ButtonPin1 12  
#define ButtonPin2 33
```

```
#define ButtonPin3 32
```

```
#define fullpin 25
```

```
#define VPIN_BUTTON_1 V1
```

```
#define VPIN_BUTTON_2 V2
```

```
#define VPIN_BUTTON_3 V3
```

```
#define VPIN_BUTTON_4 V4
```

```
#define VPIN_BUTTON_5 V5
```

```
#define SCREEN_WIDTH 128
```

```
#define SCREEN_HEIGHT 32
```

```
#define OLED_RESET -1
```

```
Adafruit_SSD1306 display(SCREEN_WIDTH, SCREEN_HEIGHT, &Wire,  
OLED_RESET);
```

```
float duration;
```

```
float distance;
```

```
int waterLevelPer;
```

```
bool toggleBuzzer = HIGH;
```

```
bool toggleRelay = false;
```

```
bool modeFlag = true;
```

```
bool conection = true;
```

```
String currMode;
```

```
char auth[] = BLYNK_AUTH_TOKEN;
```

```
ButtonConfig config1;
```

```
AceButton button1(&config1);
```

```
ButtonConfig config2;
```

```
AceButton button2(&config2);
```

```
ButtonConfig config3;
```

```
AceButton button3(&config3);
```

```
void handleEvent1(AceButton*, uint8_t, uint8_t);
```

```
void handleEvent2(AceButton*, uint8_t, uint8_t);
```

```
void handleEvent3(AceButton*, uint8_t, uint8_t);
```

```
BlynkTimer timer;
```

```
void checkBlynkStatus() {
```

```
    bool isconnected = Blynk.connected();
```

```
    if (isconnected == false) {
```

```
        digitalWrite(wifiLed, LOW);
```

```
        conection = true;
```

```
    }
```

```
    if (isconnected == true) {
```

```
        digitalWrite(wifiLed, HIGH);
```

```
        conection = false;
```

```
    }
```

```
}
```

```
BLYNK_WRITE(VPIN_BUTTON_3) {
```

```
    modeFlag = param.asInt();
```

```
    if(!modeFlag && toggleRelay){
```

```
        digitalWrite(RelayPin, LOW);
```

```
        toggleRelay = false;
```

```
    }
```

```

    controlBuzzer(500);
    currMode = modeFlag ? "AUTO" : "MANUAL";
}

BLYNK_WRITE(VPIN_BUTTON_4) {
    if(!modeFlag){
        toggleRelay = param.asInt();
        digitalWrite(RelayPin, toggleRelay);
        controlBuzzer(500);
    }
    else{
        Blynk.virtualWrite(VPIN_BUTTON_4, toggleRelay);
    }
}

BLYNK_WRITE(VPIN_BUTTON_5) {
    toggleBuzzer = param.asInt();
    digitalWrite(BuzzerPin, toggleBuzzer);
}

BLYNK_CONNECTED() {
    Blynk.syncVirtual(VPIN_BUTTON_1);
    Blynk.syncVirtual(VPIN_BUTTON_2);

    Blynk.virtualWrite(VPIN_BUTTON_3, modeFlag);
    Blynk.virtualWrite(VPIN_BUTTON_4, toggleRelay);
    Blynk.virtualWrite(VPIN_BUTTON_5, toggleBuzzer);
}

void displayData(){
    display.clearDisplay();

```

```

display.setTextSize(3);
display.setCursor(30,0);
display.print(waterLevelPer);
display.print(" ");
display.print("%");
display.setTextSize(1);
display.setCursor(0,25);
display.print(conection ? "OFFLINE" : "ONLINE");
display.setCursor(60,25);
display.print(currMode);
display.setCursor(110,25);
display.print(toggleRelay ? "! ON" : "OFF");
display.display();
}

```

```

void measureDistance(){

```

```

    digitalWrite(TRIGPIN, LOW);
    delayMicroseconds(2);

```

```

    digitalWrite(TRIGPIN, HIGH);
    delayMicroseconds(20);

```

```

    digitalWrite(TRIGPIN, LOW);

```

```

    duration = pulseIn(ECHOPIN, HIGH);

```

```

    distance = ((duration / 2) * 0.343)/10;

```

```

    if (distance > (fullTankDistance - 10) && distance < emptyTankDistance ){
        waterLevelPer = map((int)distance ,emptyTankDistance, fullTankDistance, 0, 100);
    }

```

```
Blynk.virtualWrite(VPIN_BUTTON_1, waterLevelPer);  
Blynk.virtualWrite(VPIN_BUTTON_2, (String(distance) + " cm"));
```

```
if (waterLevelPer < triggerPer){
```

```
  if(modeFlag){  
    if(!toggleRelay){  
      controlBuzzer(500);  
      digitalWrite(RelayPin, HIGH);  
      toggleRelay = true;  
      Blynk.virtualWrite(VPIN_BUTTON_4, toggleRelay);  
    }  
  }
```

```
  else{  
    if (toggleBuzzer == HIGH){  
      digitalWrite(BuzzerPin, HIGH);  
      Serial.println(" BuzzerPin high");  
    }  
  }  
}
```

```
if (distance < fullTankDistance){  
  digitalWrite(fullpin, HIGH);  
  if(modeFlag){  
    if(toggleRelay){  
      digitalWrite(RelayPin, LOW);  
  
      toggleRelay = false;  
      Blynk.virtualWrite(VPIN_BUTTON_4, toggleRelay);  
      controlBuzzer(500);
```

```

    }
}
else{
    if (toggleBuzzer == HIGH){
        digitalWrite(BuzzerPin, HIGH);
    }
}
}

if (distance > (fullTankDistance + 5) && waterLevelPer > (triggerPer + 5)){
    toggleBuzzer = HIGH;
    Blynk.virtualWrite(VPIN_BUTTON_5, toggleBuzzer);
    digitalWrite(BuzzerPin, LOW);
}
if (distance = fullTankDistance){
    Serial.println(" udh bang ");

}
}

displayData();
delay(100);
}

void controlBuzzer(int duration){
    digitalWrite(BuzzerPin, HIGH);
    Serial.println(" BuzzerPin HIT");
    delay(duration);
    digitalWrite(BuzzerPin, LOW);
}

void setup() {

```

```
Serial.begin(9600);
```

```
pinMode(ECHOPIN, INPUT);  
pinMode(TRIGPIN, OUTPUT);  
pinMode(wifiLed, OUTPUT);  
pinMode(RelayPin, OUTPUT);  
pinMode(BuzzerPin, OUTPUT);  
pinMode(fullpin, OUTPUT);
```

```
pinMode(ButtonPin1, INPUT_PULLUP);  
pinMode(ButtonPin2, INPUT_PULLUP);  
pinMode(ButtonPin3, INPUT_PULLUP);
```

```
digitalWrite(wifiLed, HIGH);  
digitalWrite(RelayPin, LOW);  
digitalWrite(BuzzerPin, LOW);
```

```
config1.setEventHandler(button1Handler);  
config2.setEventHandler(button2Handler);  
config3.setEventHandler(button3Handler);
```

```
button1.init(ButtonPin1);  
button2.init(ButtonPin2);  
button3.init(ButtonPin3);
```

```
currMode = modeFlag ? "AUTO" : "MANUAL";
```

```
if(!display.begin(SSD1306_SWITCHCAPVCC, 0x3C)) {  
    Serial.println(F("SSD1306 allocation failed"));  
    for(;;);  
}
```



```
delay(1000);  
display.setTextSize(1);  
display.setTextColor(WHITE);  
display.clearDisplay();
```

```
WiFi.begin(ssid, pass);  
timer.setInterval(2000L, checkBlynkStatus);  
timer.setInterval(1000L, measureDistance);  
Blynk.config(auth);  
delay(1000);
```

```
Blynk.virtualWrite(VPIN_BUTTON_3, modeFlag);  
Blynk.virtualWrite(VPIN_BUTTON_4, toggleRelay);  
Blynk.virtualWrite(VPIN_BUTTON_5, toggleBuzzer);
```

```
delay(500);  
}
```

```
void loop() {
```

```
Blynk.run();  
timer.run();
```

```
button1.check();  
button3.check();
```

```
if(!modeFlag){  
    button2.check();  
}
```

```
}
```

```
void button1Handler(AceButton* button, uint8_t eventType, uint8_t buttonState) {
```

```

Serial.println("EVENT1");
switch (eventType) {
  case AceButton::kEventReleased:
    if(modeFlag && toggleRelay){
      digitalWrite(RelayPin, LOW);
      toggleRelay = false;
      controlBuzzer(500);
    }
    modeFlag = !modeFlag;
    currMode = modeFlag ? "AUTO" : "MANUAL";
    Blynk.virtualWrite(VPIN_BUTTON_3, modeFlag);
    controlBuzzer(200);
    break;
}
}

```

```

void button2Handler(AceButton* button, uint8_t eventType, uint8_t buttonState) {
  Serial.println("EVENT2");
  switch (eventType) {
    case AceButton::kEventReleased:
      if(toggleRelay){
        digitalWrite(RelayPin, LOW);
        toggleRelay = false;
      }
      else{
        digitalWrite(RelayPin, HIGH);
        toggleRelay = true;
      }
      Blynk.virtualWrite(VPIN_BUTTON_4, toggleRelay);
      controlBuzzer(500);
      delay(1000);
    }
  }
}

```

```

        break;
    }
}

void button3Handler(AceButton* button, uint8_t eventType, uint8_t buttonState) {
    Serial.println("EVENT3");
    switch (eventType) {
        case AceButton::kEventReleased:
            digitalWrite(BuzzerPin, LOW);
            toggleBuzzer = LOW;
            Blynk.virtualWrite(VPIN_BUTTON_5, toggleBuzzer);
            break;
    }
}

```

Diagram. Json:

```

{
  "version": 1,
  "author": "Anonymous maker",
  "editor": "wokwi",
  "parts": [
    { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": 0, "left": 0, "attrs": {} },
    { "type": "board-ssd1306", "id": "oled1", "top": 127.94, "left": 144.23, "attrs": {} },
    {
      "type": "wokwi-pushbutton",
      "id": "btn1",
      "top": 210.09,
      "left": -82.64,
      "attrs": { "color": "green" }
    },
  ],
  {

```

```
"type": "wokwi-pushbutton",
"id": "btn2",
"top": 209.94,
"left": -165.82,
"attrs": { "color": "green" }
},
{
  "type": "wokwi-pushbutton",
  "id": "btn3",
  "top": 209.63,
  "left": -247.46,
  "attrs": { "color": "green" }
},
{
  "type": "wokwi-hc-sr04",
  "id": "ultrasonic1",
  "top": -98.88,
  "left": -265.69,
  "attrs": { "distance": "137" }
},
{
  "type": "wokwi-led",
  "id": "led1",
  "top": 74.72,
  "left": -383.66,
  "attrs": { "color": "yellow" }
},
{
  "type": "wokwi-led",
  "id": "led2",
  "top": 36.18,
```

```

    "left": -383.97,
    "attrs": { "color": "red" }
  },
  {
    "type": "wokwi-led",
    "id": "led3",
    "top": -4.65,
    "left": -383.35,
    "attrs": { "color": "blue" }
  }
],
"connections": [
  [ "esp:TX0", "$serialMonitor:RX", "", [] ],
  [ "esp:RX0", "$serialMonitor:TX", "", [] ],
  [ "oled1:GND", "esp:GND.1", "black", [ "v-12.55", "h-51.53", "v52.48" ] ],
  [ "oled1:VCC", "esp:3V3", "red", [ "v-21.39", "h-69.82", "v70.82" ] ],
  [ "oled1:SCL", "esp:D22", "green", [ "v0" ] ],
  [ "oled1:SDA", "esp:D21", "green", [ "v0" ] ],
  [ "ultrasonic1:GND", "esp:GND.2", "black", [ "v0" ] ],
  [ "ultrasonic1:VCC", "esp:VIN", "red", [ "v0" ] ],
  [ "btn3:2.r", "btn2:2.l", "green", [ "h0" ] ],
  [ "btn2:2.r", "btn1:2.l", "green", [ "h0" ] ],
  [ "btn1:2.r", "esp:GND.2", "black", [ "h10.68", "v-57.57", "h-17.06", "v-34.12" ] ],
  [ "btn1:1.l", "esp:D12", "orange", [ "h-1.3", "v-101.73" ] ],
  [ "esp:D33", "btn2:1.l", "green", [ "h-173.93", "v141.24" ] ],
  [ "btn3:1.l", "esp:D32", "green", [ "h-7.99", "v-158.4" ] ],
  [ "ultrasonic1:ECHO", "esp:D26", "blue", [ "v0" ] ],
  [ "ultrasonic1:TRIG", "esp:D27", "blue", [ "v0" ] ],
  [ "led3:C", "led2:C", "green", [ "v0" ] ],
  [ "led2:C", "led1:C", "green", [ "v0" ] ],
  [ "led1:A", "esp:D14", "green", [ "v0" ] ],

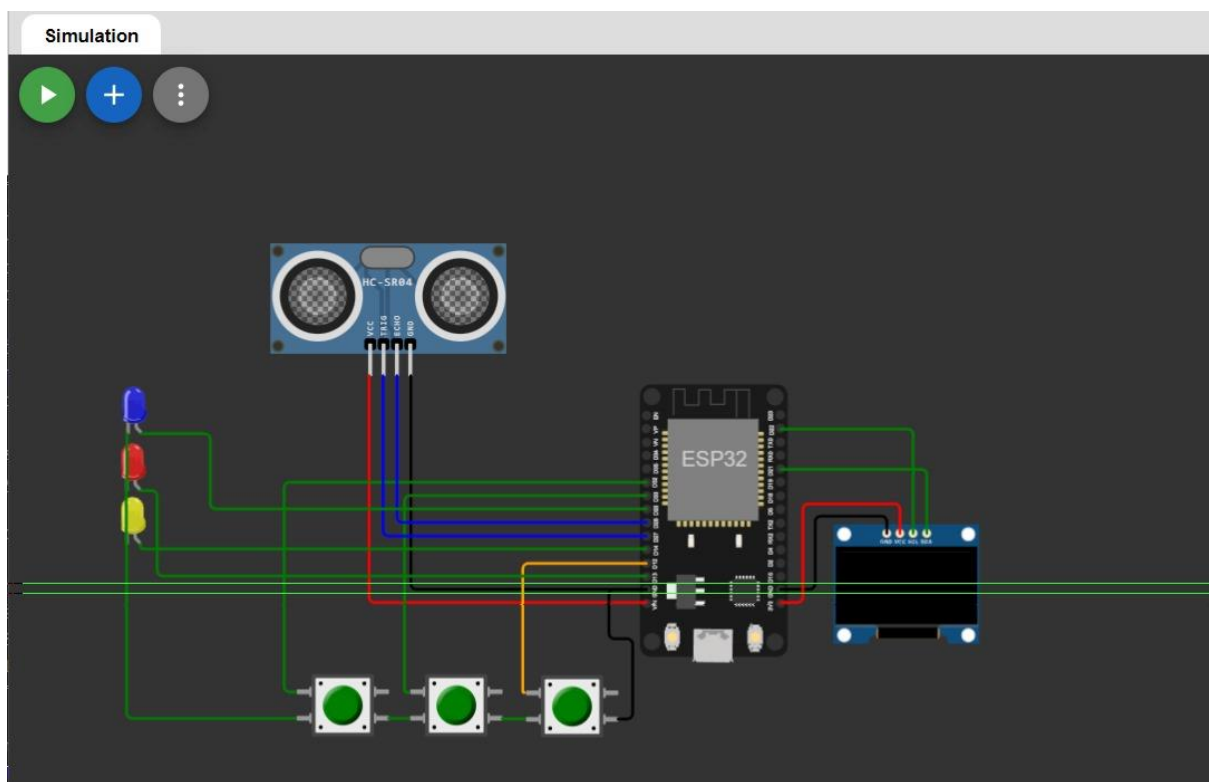
```

```

[ "led2:A", "esp:D13", "green", [ "h12.22", "v61.32" ] ],
[ "led3:A", "esp:D25", "green", [ "h49.73", "v53.95" ] ],
[ "led1:C", "btn3:2.1", "green", [ "v0" ] ]
],
"dependencies": {}
}

```

CIRCUIT DIAGRAM:



WEB DEDVELPOMENT PLATFORM:

HTML:

```

<!DOCTYPE html>
<html lang="en">

<head>

```

```
<meta charset="UTF-8">
<meta name="viewport" content="width=device-width, initial-scale=1.0">
<title>Water Monitor</title>
<link rel="stylesheet" href="styles.css">
</head>

<body>
  <div class="container">
    <h1>Water Monitor</h1>
    <div class="status">
      <h2>Water Level: <span id="waterLevel">0%</span></h2>
      <h2>Status: <span id="status">Offline</span></h2>
    </div>
    <div class="controls">
      <button id="toggleMode">Toggle Mode</button>
      <button id="toggleRelay">Toggle Relay</button>
      <button id="toggleBuzzer">Toggle Buzzer</button>
    </div>
  </div>
  <script src="script.js"></script>
</body>
</html>
```

CSS:

```
body {
  font-family: Arial, sans-serif;
}
```

```
.container {
  text-align: center;
  margin-top: 50px;
```

```
}
```

```
.status {  
    margin-bottom: 20px;  
}
```

```
.controls {  
    display: flex;  
    justify-content: center;  
}
```

```
button {  
    margin: 10px;  
    padding: 10px 20px;  
    font-size: 16px;  
}
```

JAVASCRIPT:

```
document.addEventListener("DOMContentLoaded", function () {  
    var waterLevelSpan = document.getElementById("waterLevel");  
    var statusSpan = document.getElementById("status");  
    var toggleModeBtn = document.getElementById("toggleMode");  
    var toggleRelayBtn = document.getElementById("toggleRelay");  
    var toggleBuzzerBtn = document.getElementById("toggleBuzzer");
```

```
    // Example WebSocket connection to the server (replace 'localhost' with your server  
    address)
```

```
    var socket = new WebSocket("ws://localhost:3000");
```

```
    socket.onopen = function () {  
        statusSpan.textContent = "Online";
```



```
    statusSpan.style.color = "green";  
};
```

```
socket.onmessage = function (event) {  
    var data = JSON.parse(event.data);  
    waterLevelSpan.textContent = data.waterLevel + "%";  
};
```

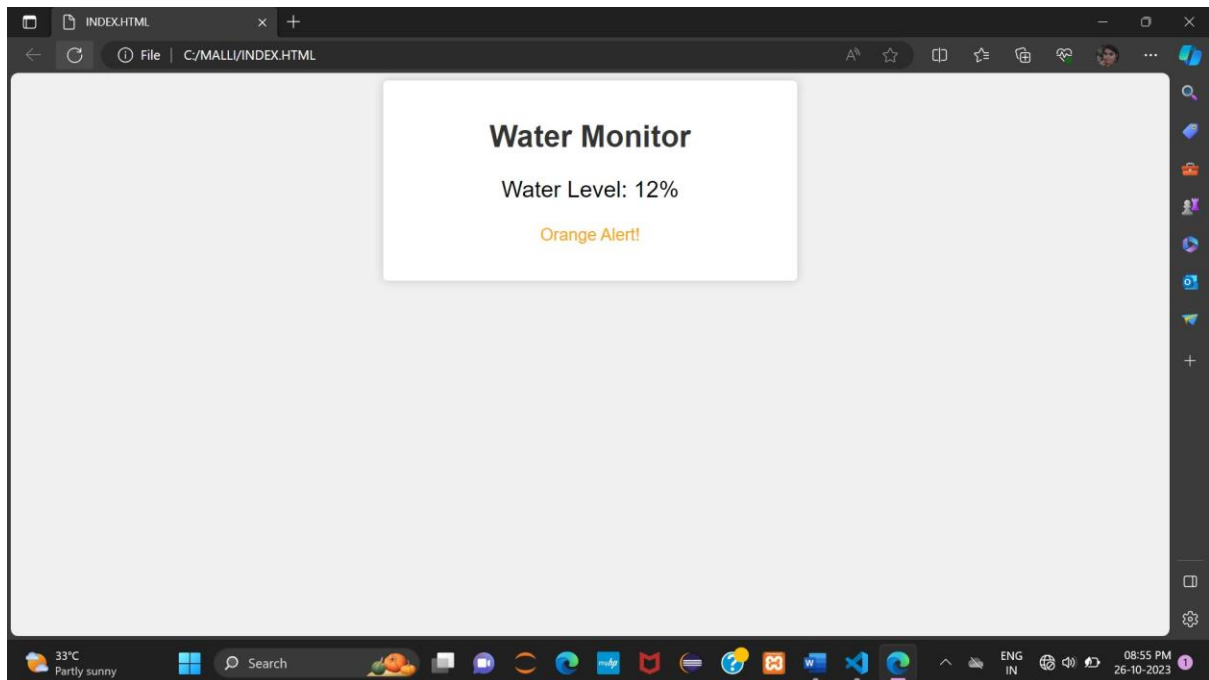
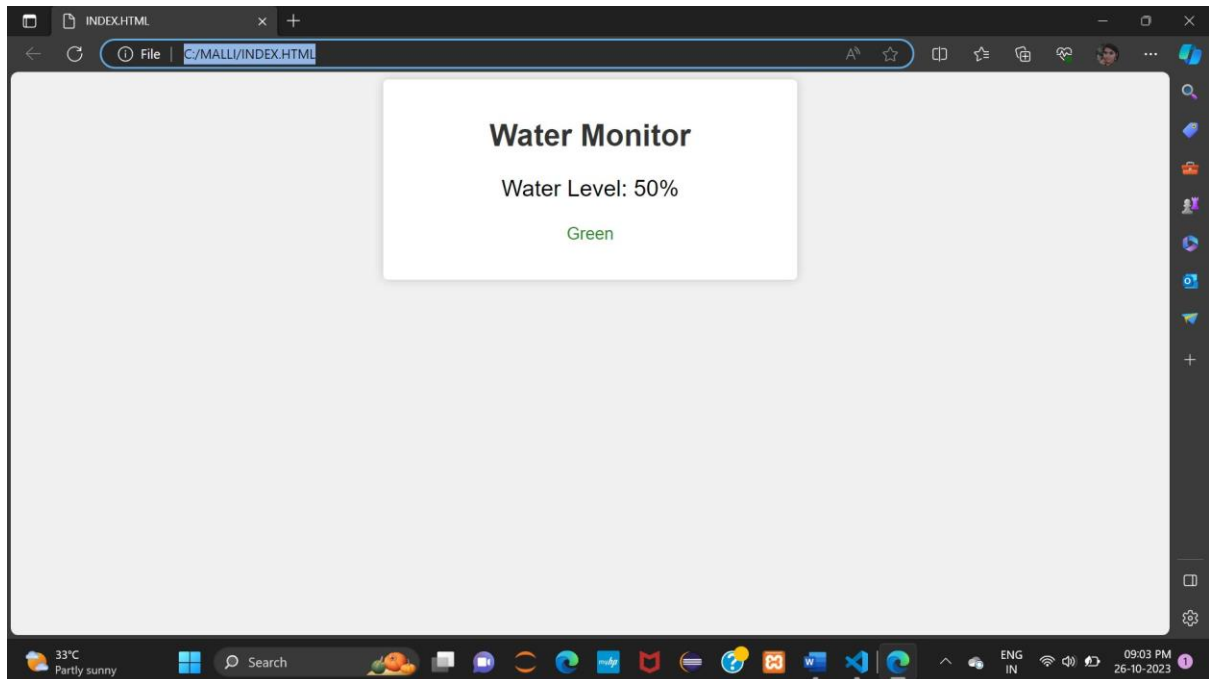
```
socket.onclose = function () {  
    statusSpan.textContent = "Offline";  
    statusSpan.style.color = "red";  
};
```

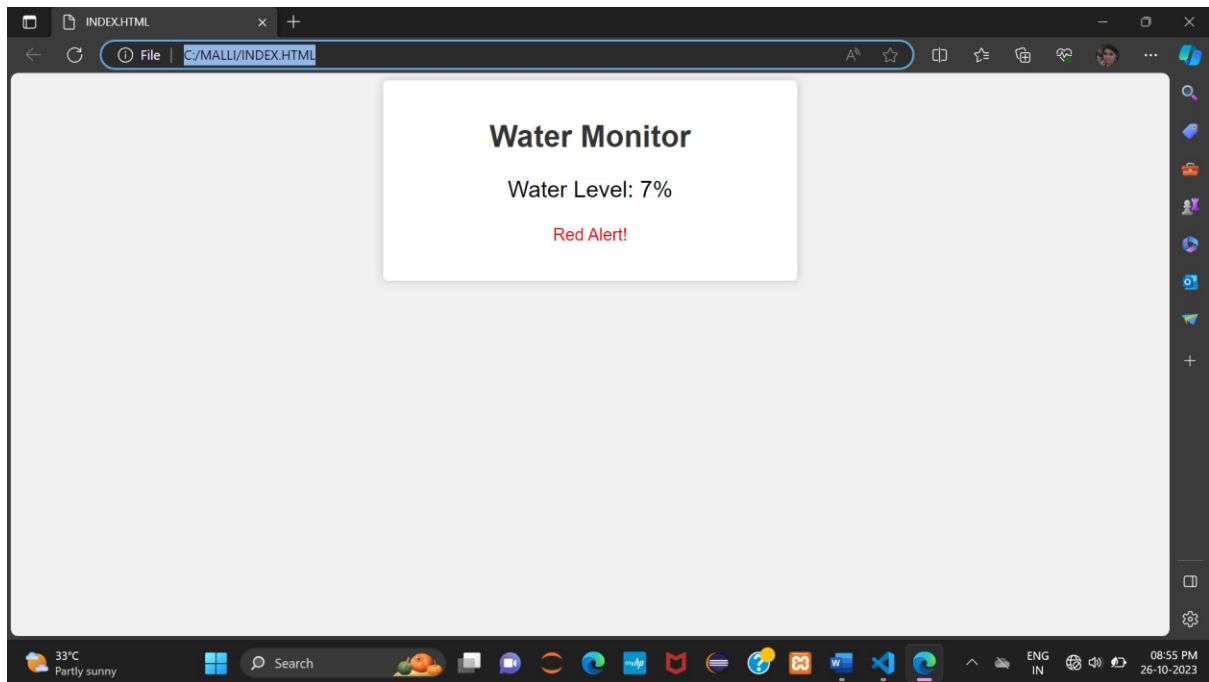
```
toggleModeBtn.addEventListener("click", function () {  
    // Send a message to the server to toggle the mode  
    socket.send("toggleMode");  
});
```

```
toggleRelayBtn.addEventListener("click", function () {  
    // Send a message to the server to toggle the relay  
    socket.send("toggleRelay");  
});
```

```
toggleBuzzerBtn.addEventListener("click", function () {  
    // Send a message to the server to toggle the buzzer  
    socket.send("toggleBuzzer");  
});  
});
```

OUTPUT:





CONCLUSION:

The source code for Smart Water Management using C and for simulation diagram Json has been successfully created. By using web development technologies like HTML, CSS, JAVASCRIPT to create a platform that displays real-time water level status. We have designed the platform to receive and display real-time water level data.