Linear Transformation: Level 3- Tutorial Questions

- 1. Let $T: \mathbb{R}^2 \to \mathbb{R}^3$ be a linear map such that T(-1,2) = (1,-1,1) and T(2,-1) = (-1,1,-1). Then T(2,1) =
- 2. Let $T: M_2(R) \to M_2(R)$ be given by T(A) = AB BA, where $B = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}$. The dim $(Ker\ T)$ is
 - (1) 0
 - (2) 1
 - (3) 2
 - $(4) \ 3$
- 3. If $T: \mathbb{R}^3 \to \mathbb{R}^3$ is a linear map given by T(x,y,z) = (x-y,y+3z,x+2y), then T^{-1} is

 - $\begin{array}{l} (1) \ \frac{1}{3}(2x+z,-x+z,\frac{x}{3}+y-\frac{z}{3}) \\ (2) \ \frac{1}{3}(2x+y,-x+y,\frac{x}{3}-\frac{y}{3}+z) \\ (3) \ \frac{1}{3}(x+2y,x-y,-\frac{x}{3}+\frac{y}{3}-z) \\ (4) \ \frac{1}{3}(x-2y,x+y,\frac{x}{3}-\frac{y}{3}-z) \end{array}$
- 4. Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be given by T(x,y) = (x+y,x).
 - (1) 1-1 but not onto
 - (2) not 1-1 but onto
 - (3) both 1-1 and onto
 - (4) neither 1-1 nor onto
- 5. Consider the vector space C over R. Let T be a linear operator on C defined by $T(z) = \overline{z}$. Then
 - (1) T is 1-1, but not onto
 - (2) T is onto, but not 1-1
 - (3) T is both 1-1 and onto
 - (4) T is neither 1-1 nor onto
- 6. Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be a linear maps on \mathbb{R}^3 defined by T(x,y,z) = (x,y,0). Then the null space of T is generated by which one of the following vector?
 - (1) (0,1,0)
 - (2) (0,0,1)
 - (3) (1,0,0)
 - (4) none of these
- 7. Let T and S be two linear maps on \mathbb{R}^3 defined by T(x,y,z)=(0,y,x) and S(x,y,z)=(x,0,0). Then
 - (1) T is idempotent, but S is not
 - (2) S is idempotent, but T is not
 - (3) both T and S are idempotent
 - (4) neither T nor S is idempotent
- 8. Let $T: M_2(R) \to M_2(R)$ be given by T(A) = AB BA, where $B = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}$. The dim $(Ker\ T)$ is
 - (1) 0

- (2) 1
- (3) 2
- $(4) \ 3$
- 9. Let $T: \mathbb{R}^n \to \mathbb{R}^n, m > n$ be a linear map. Consider the following statements about T
 - (i) T can be 1-1 (ii) T can be onto (iii) $\dim(T(\mathbb{R}^n)) \geq n$
 - (1) only (i) is true
 - (2) only (ii) is false
 - (3) only (ii) is true
 - (4) only (iii) is true
- 10. Let $T: P_2(t) \to P_2(t)$ be given by $T(a_0 + a_1t + a_2t^2) = a_1 + 2a_2t$. The matrix of T relative to the standard basis is
 - $\begin{array}{ccccc}
 (1) & \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} \\
 (2) & \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix} \\
 (3) & \begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix} \\
 (4) & \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \\
 (4) & \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$
- 11. Let T be the linear operator on R^2 given by $T(x,y) = (f_1(x,y), f_2(x,y)) = (4x 2y, 2x + y)$, then find the matrix of T in the basis $\{f_1(1,1), f_2(1,1)\}$
 - $\begin{array}{c|ccc}
 (1) & \begin{bmatrix} 3 & -2 \\ 1 & 2 \end{bmatrix} \\
 (2) & \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \\
 (3) & \begin{bmatrix} 4 & -2 \\ 2 & 1 \end{bmatrix} \\
 (4) & \begin{bmatrix} 1 & 1 \end{bmatrix}
 \end{array}$
 - $(4) \begin{bmatrix} 1 & 1 \\ -1 & 0 \end{bmatrix}$
- 12. If $T: \mathbb{R}^2 \to \mathbb{R}^3$ is a linear map such that T(1,0) = (2,3,1) and T(1,1) = (3,0,2). Then
 - (1) T(x,y) = (x+y, 2x+y, 3x-3y)
 - (2) T(x,y) = (2x+y, 3x-3y, x+y)
 - (3) T(x,y) = (2x y, 3x + 3y, x y)
 - (4) T(x,y) = (x-y, 2x+y, 3x+3y)
- 13. Let V be the vector space of 2×2 matrices over R and let $M=\begin{bmatrix}1&2\\3&4\end{bmatrix}$. Let T be the linear operator on V defined by T(A)=MA, for all A in V. Then trace of T is
 - (1) 5
 - (2) 10
 - (3) 0
 - (4) none of these

14. A linear transformation E on a vector space is a projection on some subspace	ace of V . Then
(1) $E^2 = 0$	
(2) $E^2 = I$ (3) $E^2 = E$	
(4) none of these	
15. Let T be the linear operator on \mathbb{R}^3 given by $T(x,y,z)=(x+3y+3z,4z,4y+3z,4z,4z,4z,4z,4z,4z,4z,4z,4z,4z,4z,4z,4z$	(5z, 9z). Then
(1) T is diagonalizable, but T^2 is not	

- (2) T^2 is diagonalizable, but T is not
- (3) both T and T^2 are diagonalizable
- (4) neither T nor T^2 is diagonalizable
- 16. Let $T: \mathbb{R}^4 \to \mathbb{R}^4$ be given by T(x, y, z, t) = (y + 2z, x + z, 2x + y + 2t, 2z). Then
 - (1) T has no real eigen values
 - (2) all real eigen values of T are positive
 - (3) all real eigen values of T are negative
 - (4) T has both positive and negative real eigen values
- 17. Let V be a four dimensional vector space with basis $\{v_1, v_2, v_3, v_4\}$. Let $T: V \to V$ be a linear map defined by $T(v_1) = v_2$, $T(v_2) = v_3$, $T(v_3) = v_4$ and $T(v_4) = 5v_1 - 2v_2 - \frac{1}{2}v_3 - v_4$. The minimal polynomial is
 - (1) $x^3 \frac{x^2}{2} + 2x 5$

 - (2) $\frac{x^2}{2} + 2x 5$ (3) $x^4 + x^3 + \frac{x^2}{2} + 2x 5$ (4) 2x 5
- 18. Let T be a linear operator on \mathbb{R}^3 defined by T(x,y,z)=(x,y,0). Then
 - (1) (0,0,4) is in the range space
 - (2) $(2, \frac{1}{\sqrt{2}}, 0)$ is in the zero space
 - (3) (1,1,1) is in the range space
 - (4) (0,0,1) is in the zero space
- 19. Let $T: \mathbb{R}^4 \to \mathbb{R}^3$ be the linear transformation given by T(x,y,z,w) = (x-y+z+w,x+2z-w,x+z)y + 3z - 3w). Then the dimension of the range space of T is:
 - (1) 0

 - $(4) \ 3$
- and $T:V\to V$ be the linear map defined by T(A)=AM, where V be the vector space of all 2×2 real matrices. Then rank and nullity of T, respectively are:
 - (1) 1,3
 - (2) 3,1
 - (3) 2,2
 - (4) 4,0
- 21. Let T_1 and T_2 be linear operators on R^2 defined as $T_1(x,y)=(y,x)$ and $T_2(x,y)=(x,0)$. Then
 - (1) $T_1T_2 \neq T_2T_1$
 - (2) $T_1T_2 = T_2T_1$
 - (3) $T_1T_2(x,y) = (0,x)$

- (4) $T_2T_1(x,y) = (y,0)$
- 22. Given $T: V \to W$ is a linear map
 - (1) T is 1-1 \Rightarrow nullity (T) = 0
 - (2) $T \text{ is } 1\text{-}1 \Rightarrow \text{nullity } (T) \neq 0$
 - (3) nullity $(T) = 0 \Rightarrow T$ is 1-1
 - (4) nullity $(T) = 0 \Leftrightarrow T \text{ is } 1-1$
- 23. Let T be a linear operator on a finite dimensional vector space V. If $m(t) = t^r + a_{r-1}t^{r-1} + a_{r-2}t^{r-2} + a_{r-1}t^{r-1}$ + $a_1t + a_0$, $a_0 \neq 0$ is the minimal polynomial of T, then
 - (1) T is invertible
 - (2) T is not singular
 - (3) 0 is not a root of m(t)
 - (4) 0 is not an eigen value of T
- 24. Let T be a linear operator on R^2 satisfying $T^2 T + 1 = 0$. Then
 - (1) T is 1-1
 - (2) T is not 1-1
 - (3) Trace T is in R
 - (4) In some cases Trace (T) in R and in some cases Trace (T) not in R
- 25. Le tT be a map on F[X]. Then which of the following is/are linear transformation(s?)
 - (1) T(f(x)) = -f(x)
 - (2) T(f(x)) = f(-x)
 - (3) T(f(x)) = f(0)
 - (4) T(f(x)) = f(x) + f(-x)
- 26. Let T and S be two invertible linear operators on a vector space V over a field F. Then
 - (1) $(TS)^{-1} = T^{-1}S^{-1}$
 - $(2) (ST)^{-1} = S^{-1}T^{-1}$
 - (3) ST = TS
 - (4) None of these
- 27. Let T be a linear operator on an n dimensional vector space V over a field F and let T has n distinct eigen values. Then
 - (1) T is diagonalizable
 - (2) T is invertible
 - (3) T is invertible as well as diagonalizable
 - (4) T is not invertible
- 28. Let P be the vector space of all polynomials f(x) with real coefficients defines on [0, 1]. Let D and T be two linear operators on P defined by $Df(x) = \frac{d}{dx}(f(x))$ and T(f(x)) = x.f(x). Then
 - (1) DT = TD
 - (2) $DT \neq TD$
 - (3) $DT(f(x) = f(x) + x \cdot \frac{d}{dx}(f(x))$ (4) $TD(f(x)) = x \cdot \frac{d}{dx}(f(x))$
- 29. Let T be a linear operator on a 3 dimensional vector space V satisfying $T^3 T^2 T + I = 0$. Then
 - (1) T is 1-1
 - (2) T is onto
 - (3) T is invertible

- (4) $T^{-1} = I + T T^2$
- 30. Let V be the vector space of polynomials over R of degree at most n. Define $T: V \to V$ by $T(p(x)) = x \cdot \frac{d}{dx}(p(x))$. Then
 - (1) T is 1-1
 - (2) T is onto
 - (3) T is not invertible
 - (4) Rank of T is n
- 31. The geometrical effect of the linear transformation associated with the matrix $\begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$ is:
 - (1) a rotation by an angle 90°
 - (2) a stretching along X axis
 - (3) a reflexion w.r.t X axis
 - (4) stretching along Y axis and a reflection w.r.t Y axis

