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Tutorial -3
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1) Pseudo code for linear Search
    for (i=u ton)
        if (arr[i] = = key)
print "Element found"
2) Recursive
     void insertion (int arr[], intn)
             if (n <=1)
             return;
              insertion (an, n-1)
              int num = arr[n-1];
              int j=n-2;
              while (j>=0 && arr[j] >num)
               ( arr[j++] = arr[j];
              arrlit 13 = num;
     i terative
        for (1=1 ton)
        { key = A[i]
             J= i-1
             while (js=0 & A [j]>key)
             ( AG+1] = AG]
              7 j=j-1,
             A Git 17 = Ky;
      Insertion sort is online sorting because it doesn't known
      The whole input, more input can be inserted while the
      insertion posting is running.
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3) Complexity of different sorting algorithm	3)	Complexity	of	different	sorting	algorithm.
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Name	Best case	Worst case	Average
Selection Sorting	(n²)	O(n2)	O(n2)
Bubble sorting	O(n)	0(12)	(n2)
Insertion Sorting	0(^)	0 (n²)	0 (n²)
Heap Sorting	O(nlogn)	Oh loga)	O(nlogn)
Quick Sorting	O(aloga)	C(2)	O(n logn)
Merge Sorting.	O (nlogn)	O(nlogn)	O (nlogn)

4) Implace sorting

Bubble Selection Insextion

quick heap

Merge Bubble

Juser Hon

Stable sorting

Online sorting

Insertion.

5) Iterative int b-search (int arr [], int d, int r, int key) 2 while (d = 8) 1 int m= ((1+x)/2);

> if (arr[m] == ky) return m; else if (key carr[m] 8=m-1;

l=m+1;

seturn - 1

Time complexity (n)

```
Reccorsive:
   int b_search (intarres, intl, into, int key)
    d white ( d == x) d
          int m= ((1+x)/2);
           if (Key = = arr[m])
            return m;
           else if (key carren])
           octurn besearch (arr, I, md-1, ky);
             return b_search (arr, mid+1, r, key);
    3 return -1;
              Time lomplexity - O ( dog n )
     T(n) = T(n/2) +1
                              -(1)
6)
      T(n/2) = T(n/4) +1
                              -(2)
      T (n/4) = T(n/8)+1
                              -(3)
      T(n) = T(n/2)+1
             = T(n/4)+2
             = T(n/8) + 3
            = T( = + )+ K
   let gt = n
         R = \log n T(n) = T(\frac{n}{n}) + \log \ln n
     T(n) = T(1) + logn
      T(n) = 0 (luga)
     for (i=0; ien; i+t)
      d for lint j=0; j<n; j++)
           1 if (arr[i] tarr[j] == k)
                   print & ( " 0/6 d 0/6 d ", i, i);
```

- 8) Quick foot is fastest general purpose bost 2n most practical Dihustions quick sort is the method of choice as stability is important & space is available, runge boost might be best.
- 9) Inversions in array:

 A pair (A[i], A[i]) is said to be inversion if A[i] > A[i]

 i'< j

 Total no. of inversions in given array are 31 using merge sost
- 10) Worst case (O(n2)) When the pivot element is an extreme (smallest / largest) element. This happens when input array is sosted or reverse sorted & either first or last element is selected as pivot.

Best case (O(n logn)). The best case occurs when we will

select pivot element as a mean element.

11) Merge Sort
Best case - T(n) = 2T(n/2) + O(n) } O(n logn)

Worst case - T(n) = 2T(n/2) + O(n) }

Quick sort

Best case - $T(n) = 2T(n/2) + O(n) \rightarrow O(n \log n)$ Worst case - $T(n) = T(n-1) + O(n) \rightarrow O(n^2)$

In Quick sort paray of elements are divided into 2 part repeatedly until it is not possible to divide furthere

In merge sost - The elements are split it into 2 subarray (n/2) again & again until only I element is left.

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12) for (int i=0; ix n-1;) tt)

d int ment 1;

for (int j=i+1; ix n; i++)

f if (a Emin] > a[i])

min = j,

int key = a(min];

while (min > i)

d a [min) = a[min-j];

mn--;

3 a C i J = Key;
```

13) A better version of bubble sort, is known as modified bubble sort, includes a flag that is set of a exchange is made after an entire pass over. If no exchange is made then it should be called the array is already order because no. I should be called to be switched.

```
void bubble (int 200 [], int n)

2 for (inti=0; i=n; i++)

2 surphs =0;

2 refars [j] > arr [j+1]

4 int t= arr [j];

arr [j+1] = t;

surpht;

3

break;
```