# Distributed memory parallelization of Lax-Wendroff Flux Reconstruction

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The presentation is consists of following parts:

• Flux Reconstruction

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- 2 Lax-Wendroff Flux Reconstruction

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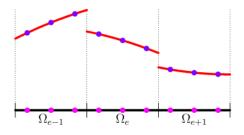
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- 2 Lax-Wendroff Flux Reconstruction
- Parallelization of TrixiLW.jl
- Results
- MPI Remote Memory Access

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$$f_h^{\delta}(\xi, t) = \sum_{j=0}^{N} f(u_j^e(t)) l_j(\xi)$$
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where each  $l_j(\xi)$  is Lagrange polynomial of degree N and u are the solution values (unknowns).

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 $\xi \in [0,1]$  is a point in reference element.

$$x \to \xi = \frac{x - x_{e - \frac{1}{2}}}{\Delta x_e}$$

Continuous flux approximation  $f_h$  with the help of correction function  $g_L$  and  $g_R$ :

$$f_h(\xi, t) = \left[ f_{e-\frac{1}{2}}(t) - f_h^{\delta}(0, t) \right] g_L(\xi) + f_h^{\delta}(\xi, t) + \left[ f_{e+\frac{1}{2}}(t) - f_h^{\delta}(1, t) \right] g_R(\xi)$$
(2)

where  $f_{e-\frac{1}{\alpha}}(t)$  is numerical flux function.

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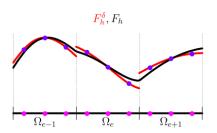


Figure: Discontinuous and continuous flux<sup>[1]</sup>

## Correction function

Correction function should satisfy the following conditions:

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  $g_R(0) = 0$   
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• Correction function should approximate 0 in some sense.

Example of correction functions: Radau and g2.

• Single stage, high-order accurate method.

#### LWFR.

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Taylor's expansion

$$u^{n+1} = u^n + \sum_{m=1}^{N+1} \frac{(\Delta t)^m}{m!} \partial_t^m u^n + O(\Delta t^{N+2})$$

$$= u^n - \sum_{m=1}^{N+1} \frac{(\Delta t)^m}{m!} (\partial_t^{m-1} f)_x + O(\Delta t^{N+2})$$

$$= u^n - \Delta t \frac{\partial F}{\partial r} (u^n) + O(\Delta t^{N+2})$$

$$x \to \xi = \frac{x - x_{e - \frac{1}{2}}}{\Delta x_e}$$

• Update step looks like this:

$$(u_j^e)^{n+1} = (u_j^e)^n - \frac{\Delta t}{\Delta x_e} \frac{dF_h}{d\xi}(\xi_j), \quad 0 \le j \le N$$
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$$F(u^n) = \sum_{m=0}^{N} \frac{\Delta t^m}{(m+1)!} \partial_t^m f(u)$$

is an approximation to time average flux in the interval  $[t^n, t^{n+1}]$ Order of accuracy in both **space** and **time**: N+1

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- Support multi-node parallelization for Tree and P4est mesh

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Data that needs to be communicated:

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At what places MPI communication is needed?: mpi\_interfaces



Red lines: mpi\_interfaces

Grey lines: interfaces

# Example Implementation

```
function rhs!(du, u, t, dt, ...)
    start_mpi_receive!(mpi_cache, ...)
    # Calculate volume integral
    calc_volume_integral!(du, u, t, dt, ...)
    # Prolong solution to MPI interfaces
    prolong2mpiinterfaces!(cache, u, mesh, equations, ...)
    start_mpi_send!(mpi_cache, mesh, equations, ...)
    # Serial computation
    # finish mpi communication
    finish_mpi_receive!(mpi_cache, mesh, equations,...)
    # Calculate MPI interface fluxes
    calc_mpi_interface_flux!(surface_flux_values,...)
    # Finish to send MPI data
    finish_mpi_send!(mpi_cache)
    return nothing
end
```

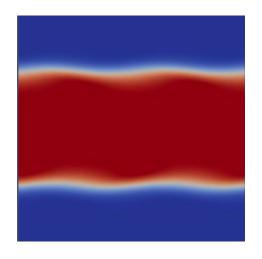
#### Data structures

```
Example struct:
```

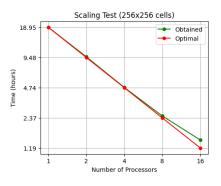
```
mutable struct MPICache{uEltype <: Real}</pre>
    mpi_neighbor_ranks::Vector{Int}
    mpi_neighbor_interfaces::Vector{Vector{Int}}}
    # contains data
    mpi_send_buffers::Vector{Vector{uEltype}}}
    mpi_recv_buffers::Vector{Vector{uEltype}}}
    # non-blocking communication
    mpi_send_requests::Vector{MPI.Request}
    mpi_recv_requests::Vector{MPI.Request}
end
```



# Animation for Kelvin-Helmholtz



# Scaling Results<sup>1</sup>



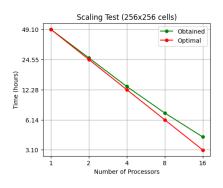


Figure: Isentropic Vortex problem

For isentropic vortex problem:

speed-up: 13.23

efficiency: 82.6 %

Figure: Kelvin Helmholtz problem

For Kelvin-Helmholtz problem:

speed-up: 11.86 efficiency: 74.12%

¹on Dual Intel(R) Xeon(R) Gold 6148 CPU @ 2.40GHz

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- No ordering.

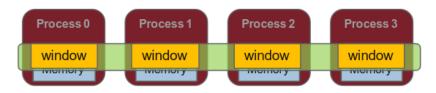


Figure: Memory Window

- MPI WIN ALLOCATE
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- MPI\_WIN\_ALLOCATE\_SHARED
  - We want multiple processes on the same node share a buffer.

# Code Example

```
function collective_win_create(u)
    win = MPI.Win_create(u, comm)
    return win
end

function collective_win_free(win)
    MPI.free(win)
end
```

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#### • MPI\_PUT

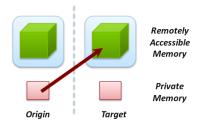


Figure: MPI\_PUT<sup>3</sup>

#### • MPI\_GET



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• MPI\_ACCUMULATE (atomic)



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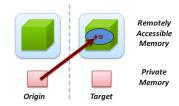


Figure: MPI\_ACCUMULATE<sup>3</sup>

### Atomic operations:

• These operations execute without the interruption of any other process in between their execution phase.

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### MPI\_Win\_fence: Active target synchronization

- Collective synchronization model.
- Between a pair of MPI\_Win\_fence, any number of RMA operations can be performed.
- assert argument can be provided for optimization.

For example: assert = MPI\_MODE\_NOPUT

MPI\_Win\_fence(int assert, MPI\_Win win)

# Code Example

```
MPI.Win_fence(win)
if process_id !== size - 1
    MPI.Put!(u[1], win; rank=1, disp=0)
else
    MPI.Put!(u[N], win; rank=1, disp=0)
end
MPI.Win_fence(win)
```

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- Two types of lock: Shared and Exclusive
- **Shared:** Other process with same lock type can access concurrently.
- Exclusive: No other process can access concurrently.
- MPI\_Win\_unlock does the needed synchronization.

```
MPI_Win_lock(int locktype, int rank, int assert, MPI_Win win)
...
// RMA operations
...
MPI_Win_unlock(int rank, MPI_Win win)
```

Listing: Usage of lock/unlock

## Example Implementation

```
function get_ghost_values!(param, u, win)
    if rank !== size -1
        buf1 = fill(0.0, 1)
        MPI.Win_lock(win; rank=next, type=MPI.LOCK_SHARED)
        MPI.Put!(u[N+1], win; rank=next, disp=0)
        MPI.Get!(buf1, win; rank=next, disp=1)
        MPI.Win_unlock(win, rank=next)
        u[N+2] = buf1[1]
    else
        buf2 = fill(0.0, 1)
        MPI.Win_lock(win; rank=next, type=MPI.LOCK_SHARED)
        MPI.Put!(u[N+1], win; rank=next, disp=0)
        MPI.Get!(buf2, win; rank=next, disp=2)
        MPI.Win_unlock(win; rank=next)
        u[N+2] = buf2[1]
    end
end
```

# FAQs

### What is the difference between RMA and shared memory?



Figure: RMA

Figure: Shared memory

Does RMA work with the CPUs on different node? Yes, it does. With the help of modern hardware such as **Infiniband** which follows (Remote direct memory access) RDMA protocols.

### References

- [1] Babbar, A., Kenettinkara, S., & Chandrashekar, P. (2022). Lax-Wendroff flux reconstruction method for hyperbolic conservation laws. Journal of Computational Physics, 467, 111423.
- [2] Schlottke-Lakemper, M., Gassner, G. J., Ranocha, H., Winters, A. R., & Chan, J. (2024). Trixi.jl (v0.8.3). Zenodo. https://doi.org/10.5281/zenodo.12683615
- [3] Hoefler, T., Balaji, P., Gropp, W., & Thakur, R. (2016, November). Advanced MPI Programming [Tutorial] https://web.cels.anl.gov/thakur/sc16-mpi-tutorial/slides.pdf