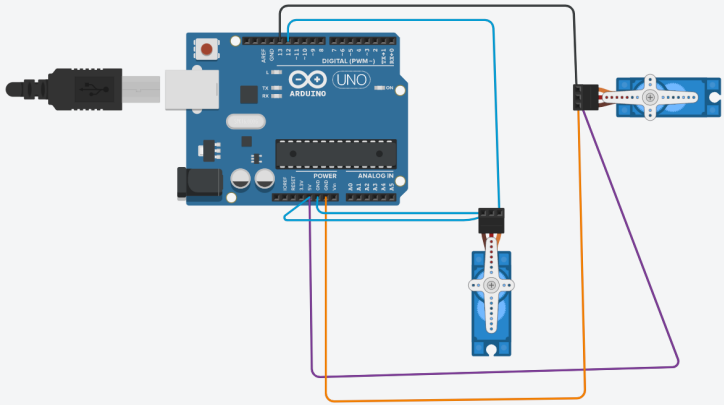


```

1 // C++ code
2 //
3 void setup()
4 {
5   pinMode(13, OUTPUT); //enable 1,2
6   pinMode(11, OUTPUT); //input 1
7   pinMode(9, OUTPUT); //input 2
8   digitalWrite(13,HIGH);
9
10  pinMode(12, OUTPUT); //enable 3,4
11  pinMode(6, OUTPUT);
12  pinMode(5, OUTPUT);
13  digitalWrite(12,HIGH);
14 }
15
16 void loop()
17 {
18   digitalWrite(11, HIGH);
19   digitalWrite(9, LOW);
20   delay(1000); // Wait for 1000 millisecond(s)
21   digitalWrite(11, LOW);
22   digitalWrite(9, HIGH);
23   delay(1000); // Wait for 1000 millisecond(s)
24   digitalWrite(6, HIGH);
25   digitalWrite(5, LOW);
26   delay(1000);
27   digitalWrite(6, LOW);
28   digitalWrite(5, HIGH);
29   delay(1000);
30 }

```



Text

```

1 #include<Servo.h>
2
3 Servo servo1;
4 Servo servo2;
5
6 void setup()
7 {
8   servo1.attach(13);
9   servo2.attach(12);
10 }
11
12 void loop()
13 {
14   servo1.write(0);
15   servo2.write(0);
16   delay(1000);
17   servo1.write(45);
18   servo2.write(45);
19   delay(1000);
20   servo1.write(90);
21   servo2.write(90);
22   delay(1000);
23 }

```