Numerical Methods: Direct and Iterative Solvers in Python

This repository consists of python implementation of Gaussian Elimination, Jacobi, Preconditioned Gradient Descent and Generalised Minimum Residual Solvers.

- All the Solvers' python scripts are made as modular as possible with proper comments.
- 2. The matrix A and RHS vector b are generated using Random Number Generator functions separately for both respectively in each solver's python file inside the corresponding directory.
- 3. Solution time measuring snippet is also included in each solver's python file
- 4. The results (data file) is generated inside the python code (as a separate function). Each linear system of equations (LSE) (10 x 10, 100 x 100, 1000 x 1000 etc) result file is separate for each solver. They are generated in the script and are placed under the *Results* directory with the following name convention:

```
<Solver Name>_LSE_<row>_by_<col>
```

e.g. for Gauss solver LSE 10×10 :

GAUSS_LSE_10_by_10

This file consists of the following details:

- 1. Solution vector
- 2. Residual Norm Error
- 3. Run time
- 4. Iterations (if required)

NOTE:

For all the solvers, my computer could take only up to $1000 \times 1000 \text{ LSE}$ except PCG Solver which could compute for $10000 \times 10000 \text{ LSE}$ as well (Results can be checked in *Results* directory). I could observe for at most 2 hours for $10000 \times 10000 \text{ LSE}$. But the solvers current implementation couldn't complete.

Steps for executing the scripts

Gaussian Elimination Solver

```
cd Gauss
python gauss_elim_prog.py <row> <col>
```

You can see the results data file in Results directory.

Jacobi Solver

```
cd Jacobi
python jacobi_prog.py <M> <N> <No. of iterations>
```

Preconditioned Conjugate Gradient (PCG) Solver

```
cd PCG
python PCG_prog.py <N> <No. of iterations>
```

Generalized Minimal Residual Method (GMRES) Solver

```
cd GMRes
python GMRES_prog.py <M> <N> <No. of iterations>
```