

* Spacetime: A manifold of events endowed by a metric.

A set of pts with well understood connection props

When and where something happens

A notion of distance b/w events on a manifold.

* STR = (GR - gravity) = The theory of relativity on FLAT SPACETIME

* Natural units: $c=1$

$$\Rightarrow [\text{energy}] = [\text{mass}] = [(\text{length})^{-1}] = [(\text{time})^{-1}]$$

* $\Delta \vec{x} \doteq \Delta x^\mu$

Abstract notation Frame dependent component notn

$$\Delta x^\mu \equiv (\Delta t, \Delta x, \Delta y, \Delta z) \equiv (\Delta x^0, \Delta x^1, \Delta x^2, \Delta x^3)$$

* LORENTZ TRANSFORMATION

↳ relates components in 2 frames

More general form for 4-vector transforms:

$$\Delta x^{\mu'} = \Lambda^{\mu'}_{\nu} \Delta x^\nu$$

- flat space convention

$$\Delta x^{\mu'} = \frac{\partial x^{\mu'}}{\partial x^\nu} \Delta x^\nu$$

* Basis Vectors: $\Delta \vec{x} = \Delta x^\mu \hat{e}_\mu = \Delta x^\nu \hat{e}_\nu$

↳ Has meaning indep of chosen coord

$$\Delta x^\mu \hat{e}_\mu = \Lambda^\nu_\mu \Delta x^\mu \hat{e}_\nu \Rightarrow \Lambda^\nu_\mu \hat{e}_\nu = \hat{e}_\mu \Rightarrow \hat{e}_{\nu'} = \Lambda^\mu_{\nu'} \hat{e}_\mu$$

inverse Lorentz matrix

$$\Lambda^\mu_{\alpha'} \Lambda^{\alpha'}_\nu = \delta^\mu_\nu$$

↳ Kronecker

$$\hat{e}_{\nu'} = \frac{\partial x^\mu}{\partial x^\nu} \hat{e}_\mu$$

* Invariant Space-time Interval: $\Delta s^2 \equiv \text{Lorentz Scalar}$

$$\Delta s^2 = -(\Delta x^0)^2 + (\Delta x^1)^2 + (\Delta x^2)^2 + (\Delta x^3)^2 = \Delta x^\mu \eta_{\mu\nu} \Delta x^\nu$$

$$\Delta s^2 = \Delta \vec{x} \cdot \Delta \vec{x} \quad \{ \text{inner prod} \}$$

Δs^2 {
 < 0 , timelike
 > 0 , spacelike
 = 0 , Null

$$\eta = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Infinitesimal
"Distance"

$$ds^2 = dx^\mu \eta_{\mu\nu} dx^\nu = dx^{\mu'} \eta_{\mu'\nu'} dx^{\nu'}$$

MINKOWSKI METRIC

$$\eta^{\mu\nu} \text{ is inverse of } \eta_{\mu\nu} \Rightarrow \eta^{\alpha\beta} \eta_{\mu\nu} = \delta^\alpha_\mu$$

* NOTE : when : $d\vec{x} = dx^\mu \hat{e}_\mu$, we say \hat{e}_μ is a coordinate basis
this isn't always true. ex. spherical coord. with $\hat{e}_i = \hat{r}, \hat{\theta}, \hat{\phi}$

* Important 4-vecs: $\vec{u} = \frac{d\vec{x}}{d\tau}$
 4-VELOCITY \downarrow Time elapsed in rest frame of
 obj whose velo is measured
 \downarrow Proper time

$$\boxed{\vec{u} \doteq (\gamma, \gamma \underline{v})}$$

Here $\gamma = \frac{1}{\sqrt{1-v^2}}$ and $\underline{v} = \frac{dx}{dt}$ is the "usual" 3-velo

$$\left\{ \begin{array}{l} \vec{v} = 4\text{-vector} \\ \underline{v} = 3\text{-vector} \end{array} \right.$$

$$\vec{u} \stackrel{\text{Rest frame}}{\doteq} (1, \underline{0}) ; \quad \vec{u} \cdot \vec{u} = u^\mu \eta_{\mu\nu} u^\nu = -1$$

4-MOMENTUM: $\vec{p} = m \vec{u}$ is Lorentz invariant

$$= (\gamma m, \gamma m \underline{v}) = (E, \underline{p}) \quad \begin{array}{l} \text{Relativistic 3-momentum} \\ \downarrow \text{Energy} \end{array}$$

$$\vec{p} \cdot \vec{p} = -m^2 \vec{u} \cdot \vec{u} = -m^2 = -E^2 + |\underline{p}|^2 \Rightarrow \boxed{E^2 = m^2 + |\underline{p}|^2}$$

* Consider an obs Q and another obs A.

Let \vec{p} be the 4-mom of A and \vec{u} the 4-velo of Q.
What does Q measure the energy of A to be?

$$\vec{p} \doteq (E_A, \underline{p}_A)$$

$$\vec{u} \doteq (1, \underline{0}) \quad \begin{array}{l} \text{Q's 4-velo in} \\ \text{his own ref} \end{array}$$

Observe: $\vec{p} \cdot \vec{u} = -E_Q$

$$\text{Lorentz invariant} \Rightarrow \boxed{\vec{p} \cdot \vec{u} = -E} \quad \text{Holds no matter in which frame you are.}$$

* 4-acceleration: $\vec{a} = \frac{d\vec{u}}{d\tau} = \frac{d^2\vec{x}}{d\tau^2}$

$$\text{Note: } \frac{d}{d\tau} (\vec{u} \cdot \vec{u}) = \frac{d}{d\tau} (1) = 0 = 2 \vec{a} \cdot \vec{u} \Rightarrow \boxed{\vec{a} \cdot \vec{u} = 0}$$

* Tensors more generally: a $\binom{0}{N}$ Tensor would be a Mapping from N 4-vectors to a Lorentz invariant scalar.

$$\tilde{\eta}(\vec{A}, \vec{B}) = \vec{A} \cdot \vec{B} = A^\alpha \eta_{\alpha\beta} B^\beta = a^{\text{scalar}}$$

The metric $\eta_{\alpha\beta}$ is a $\binom{0}{2}$ tensor

$$\text{Linearity: } \tilde{\eta}(\lambda \vec{A}, \vec{B}) = \lambda \tilde{\eta}(\vec{A}, \vec{B})$$

$$\tilde{\eta}(\vec{A}, \vec{B}) = \vec{A} \cdot \vec{B} = A^\alpha \eta_{\alpha\beta} B^\beta = \tilde{a}$$

Linearity: $\tilde{\eta}(\lambda \vec{A}, \vec{B}) = \lambda \tilde{\eta}(\vec{A}, \vec{B})$

$$\eta_{\alpha'\beta'} = \Lambda^{\mu}_{\alpha'} \Lambda^{\nu}_{\beta'} \eta_{\mu\nu} = \frac{\partial x^{\mu}}{\partial x^{\alpha'}} \cdot \frac{\partial x^{\nu}}{\partial x^{\beta'}} \eta_{\mu\nu}$$

* One form: $(0, 1)$ Tensor a.k.a. dual vectors

$$\tilde{\eta}(\vec{e}_\alpha, \vec{e}_\beta) = \eta_{\alpha\beta} \rightarrow \text{similarly for a 1-form } \tilde{p}: \tilde{p}(\vec{e}_\alpha) = p_\alpha$$

$$\tilde{p} = p_\alpha \tilde{\omega}^\alpha \quad \text{dual basis} \quad \underbrace{p_\alpha A^\alpha = \tilde{p}(\vec{A})}_{\text{A Scalar}} \quad \text{and} \quad \tilde{\omega}^\beta \vec{e}_\beta = \delta^\beta_\alpha$$

* Contraction, raising & lowering indices.

$$p^\mu \eta_{\mu\nu} A^\nu = p_\nu A^\nu = p^\mu A_\mu = \vec{p} \cdot \vec{A} = \tilde{p}(\vec{A}) = \tilde{A}(\vec{p})$$

* 3D space: $\frac{d\phi}{dt} = \frac{dx}{dt} \cdot \frac{\partial \phi}{\partial x} + \frac{dy}{dt} \cdot \frac{\partial \phi}{\partial y} + \frac{dz}{dt} \cdot \frac{\partial \phi}{\partial z} = \underline{u} \cdot \underline{\nabla} \phi$ "usual" 3D gradient

4D spacetime: $\frac{d\phi}{d\tau} = \frac{dt}{d\tau} \cdot \frac{\partial \phi}{\partial t} + \frac{dx}{d\tau} \cdot \frac{\partial \phi}{\partial x} + \frac{dy}{d\tau} \cdot \frac{\partial \phi}{\partial y} + \frac{dz}{d\tau} \cdot \frac{\partial \phi}{\partial z} = \underline{u}^\alpha \frac{\partial \phi}{\partial x^\alpha}$
 4-velo \downarrow Gradient 1-form.

one-form
 $\tilde{\partial}\phi \equiv \{\partial_\alpha \phi\}$, NOTATION: $\boxed{\frac{d\phi}{d\tau} = u^\alpha \partial_\alpha \phi = \nabla_u \phi}$

* ABSTRACT NOTATION OF THE BASIS:

$$\partial_\beta x^\alpha = \frac{\partial x^\alpha}{\partial x^\beta} = \delta^\alpha_\beta \quad ; \quad \tilde{\omega}^\alpha(\vec{e}_\beta) = \delta^\alpha_\beta$$

$$dx^\alpha = \tilde{\omega}^\alpha \quad \text{and} \quad \vec{e}_\beta = \vec{\partial}_\beta$$

$$\boxed{dx^\mu(\vec{\partial}_\nu) = \frac{\partial x^\mu}{\partial x^\nu} = \delta^\mu_\nu}$$

* Tensor of type (M, N) is a multilinear map from M-1 forms & N-vectors to a Lorentz scalar.

* Raising & Lowering indices: $\eta_{\alpha\beta} T^\beta{}_{rs} = T_{rs}$ and $\eta^{\alpha\beta} T_{\beta rs} = T^{\alpha}{}_{rs}$

* Basis of Tensors:

$$\boxed{\tilde{T} = T^\gamma{}_{\alpha\beta} \vec{e}_\gamma \otimes \tilde{\omega}^\alpha \otimes \tilde{\omega}^\beta}$$

outer product — order matters!

* Electromagnetism: Field strength tensor $\rightarrow F_{\mu\nu} = \begin{bmatrix} 0 & -E_1 & -E_2 & -E_3 \\ E_1 & 0 & B_1 & -B_2 \\ E_2 & -B_1 & 0 & B_3 \\ E_3 & B_2 & -B_3 & 0 \end{bmatrix} = -F_{\nu\mu}$

* 4-vector potential $\vec{A} = (\phi, \vec{A})$ for $c=1$

$$\begin{bmatrix} 0 & -E_1 & -E_2 & -E_3 \\ E_1 & 0 & B_1 & -B_2 \\ E_2 & -B_1 & 0 & B_3 \\ E_3 & B_2 & -B_3 & 0 \end{bmatrix}$$

- 4-vector potential $\vec{A} = (\phi, \underline{A})$ for $c=1$
- 4-vector current $\vec{J} = (\rho, \underline{J})$

$$F^{0i} = E^i \quad \text{and} \quad F^{ij} = -\epsilon^{ijk} B_k$$

$$\partial_j F^{ij} - \partial_0 F^{0i} = J^i$$

$$\partial_i F^{0i} = J^0$$

\rightarrow Maxwell's Eqns

$$T^{00} = \begin{bmatrix} E_0 & 0 & B_1 & -B_2 \\ E_1 & -B_1 & 0 & B_3 \\ E_2 & B_2 & -B_3 & 0 \end{bmatrix} \quad T^{00}$$

ϵ^{ijk} = Levi-Civita Symbol
(Tensor densities soon)

Tensorial form:

$$\partial_\mu F^{\nu\mu} = J^\nu$$

and

$$[\partial_{[\mu} F_{\nu]\lambda}] = \partial_\mu F_{\nu\lambda} + \partial_\nu F_{\lambda\mu} + \partial_\lambda F_{\mu\nu} = 0$$

★ ENERGY & MOMENTUM:

Definition of T^{00} -(Energy Momentum Tensor) is the flux of 4-Momentum p^μ across a surface of constant x^0 .

$T^{00} \equiv$ flux of p^0 (energy) in the x^0 (time) direction \Rightarrow ENERGY DENSITY ρ

$T^{0i} = T^{i0} \equiv$ Momentum flux

$T^{ij} \equiv$ stress terms - forces b/wn infinitesimal elements of the fluid - Viscosity

$T^{ii} \equiv$ i^{th} component of force being exerted (per unit Ar.) \equiv Pressure P_i

MIP

DUST: non-interacting matter.

$$N^\mu = n U^\mu$$

$$\rho = mn$$

No.-flux - 4-vector

No. density in rest frame

\hookrightarrow rest frame en-density

Rest frame of dust: $N^\mu = (n, 0, 0, 0)$ & $p^\mu = (m, 0, 0, 0) \Rightarrow T^{00} = \rho$, rest all 0.

$$\text{Guess} \Rightarrow [T_{\text{dust}}^{00} = \rho^0 N^0 = \rho U^0 U^0]$$

$$\text{PERFECT FLUID: } T^{00} = \begin{bmatrix} \rho & 0 & 0 & 0 \\ 0 & P & 0 & 0 \\ 0 & 0 & P & 0 \\ 0 & 0 & 0 & P \end{bmatrix} \Rightarrow [T^{00} = (\rho + P) U^0 U^0 + P \eta^{00}]$$

Equation of state $P = P(\rho)$

- for dust : $P = 0$

- for isotropic gas of photons : $P = \frac{1}{3} \rho$

- for vacuum energy : $T^{00} = -(\rho_{vac}) \eta^{00}$

- Eqs in G.R.

$$\text{Conservation of } T^{00}: [\partial_\mu T^{00} = 0] \quad (\text{flat space})$$

$$\star \text{Projection Tensor: } [P^\sigma_\nu = \delta^\sigma_\nu + U^\sigma U_\nu] \rightarrow \text{projects a vector, say } V^\mu \text{ orthogonal to } U^\kappa$$