

Z20K11xM OneshuntFoc Release Notes

Supports all Z20K11xM devices

1 Overview

The One Shunt FOC control demo utilizes Z20K11x's rich peripheral resources, realize the pmsm sensorless control based on the FOC algorithm. The rotor angle and speed are estimated from Flux observer. Current sample method is one shunt sample way. All the arithmetical operations are based on fixed point number format(Q15).

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2 FOC Demo Introduce

Docs folder contains:

- Z20K11XM_OnehuntFoc_Demo_ReleaseNotes.pdf

Focus on the files:

App > **pmsm.c**: source code and header files for the motor application;

App > **user_coeff.h**: head file related motor control coefficients ;

App > **user_pmsm.h**: head file related motor parameters;

Hal> **hal_cfg.c**: source code file related HW configuration;

Hal> **hal_cfg.c**: head file related HW configuration;

IARProject folder contains:

Z20K11XM_OnehuntFoc series IAR Project.

Application:

Debug can be operated with below variables:

Live Watch	
Expression	Value
ctrlObj.state	CTRL_State_Idle
ctrlObj.startMotor	0
estObj.ElecFreq	0
ctrlObj.freqRef	0

ctrlObj.state: Motor control status.

ctrlObj.startMotor: 0 stop; 1 run (run order can be set only in Idle status).

estObj.ElecFreq: observer feedback frequency value.

ctrlObj.freqRef: setup frequency value.

3 New in this release

Main features:

- Fixed point operations
- Foc sensorless control
- Speed and current loop
- Flux observers
- One shunt sensor
- SVPWM type
- PWM phase shift
- PWM duty cycle limit
- Calculation optimization

Z20K11XM Onehunt Foc Release Notes, Demo, Mar, 2023

4 List of Changes

4.1 Changes

This is the new release files.

Features	Issue
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	•
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5 Version Tracking

Data	Version	Comments
2023/03/08	Demo	Only Demo for one shunt foc.

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