

University of Waterloo Department of Electrical and Computer Engineering Spring 2014 – ECE457A Cooperative and Adaptive Algorithms



# 10. Solving Job Shop Scheduling Problem using Metaheuristics Algorithms

## Job Shop Scheduling

The job shop scheduling problem (JSSP) is an optimization problem which can be applied in real workshops. The main target is to assign a certain number of jobs (n) to a certain number of machines (m) so that to achieve the minimum makespan. Usually the number of jobs is larger than the number of machines and different jobs may have different processing time, so different assignment strategies will lead to different makespan. There are  $m^n$  assignment options in total, so it is not viable to illustrate all possible assignment options for large m and n. In this case, how to use algorithms to achieve optimum objectives or acceptable sub-optimum objectives in a certain amount of time is a challenging problem and it is highly related to real life.

## Problem Statement & Modeling

The variables in this project are defined as follows:

- . n, number of Jobs
- . m, number of identical Machine
- . J, an array of each Jobs' weight (processing time)
- . S, an array of each Jobs' Schedule

Constraints:

n > m > 1,  $n, m \in Z^+$  $\forall s \in S$ ,  $s \in Z^+ \& 1 \le s \le m$ 

Cost function:

 $f(x) = max_i f(i), \qquad i = 1, 2, \dots, m$ 

Where f(i) is the makespan on i-th machine

Our objective is to minimize the cost function subject to these constraints.

For example:

J=(2,3,4,6,2,2)

S=(1,2,2,3,1,1) is an optimal solution

The optimal cost is 7

#### Metaheuristics Tabu Search In order the find the neighbour with the lowest cost, the algorithm will loop The initial solution is randomly generated. through every valid neighbour and evaluate its cost. The neighbour with the Neighbours of each schedule lowest cost will be selected as the best neighbour. Each schedule will have (m-1)\*n neighbours, where m is the number of machines and n is the number of jobs. neighbours will only have one job scheduled on a The list length of the tabu list is user-defined. The tabu list acts like a queue (first different machine. in first out) in which the oldest move will be deleted when a new move is appended. A new move is appended every time after finding a best neighbour. Simulated Annealing **Initial solution** Set the initial temperature $T_0=30$ , and using the geometric cooling schedule to update the Randomly generate an initial solution temperate at every two iterations **Generating new solution** $T_{new} = \partial \times T_{old}$ Using swap to generate new solutions (inserting & deleting is not necessary in this problem) Update strategy Set the final temperature to be 0.01 If the new solution is better than best so far solution, accept Otherwise, calculate the difference between these two objective values $\Delta f$ Calculating $p = e^{-\Delta f/T}$ , and generate a random number r If p>r then accept, otherwise decline **Genetic Algorithm** -The crossover will exchange chromosome information at a specified crossover site, This part uses Genetic Algorithm to find the optimal solution for the job scheduling problem. The process was inspired by the evolution of organisms in -After each crossover, evolve will be called, and the fittest of the older population, or natural. It employs random crossover, mutation and evolution to achieve the goal its offspring will survive. of finding the optimal scheduling for a set of given jobs. - The evolve function will maximize the model function, 1/(1+cost), which is the same - The population size is set to 100 - Chromosome length depends on the range of the possible output -The old and the new population will be compared, and the fitter of the two will get - Crossover Probability was set to 95% passed to the next generation - Mutation probability was set to 5% - There will be 2 sites of mutation, when the mutation event occurs - A given number mutation sites were generated, and the binary bits at the generated -Evolve function will be called, and the older generation and the newer generation will **PSO** be compared, the fittest of the two will get passed on to the next generation - Speed is calculated based on each particle's personal best solution and the best This part uses the Ring Topology or lbest Particle Swarm Algorithm to find solution of its neighbour. c1 = 1.4944, c2 = 1.4944, w = 0.9optimal solution for job scheduling problem. Each particle communicates with - The new solution is calculated by adding its previous location and its new speed, four adjacent neighbour. Each particle calculates its speed based on the best When the new cost of the new location is smaller than a particle's local best, it updates solution in its neighbour and its personal best. its local best and update its neighbour's neighbour best when applicable. Asynchronous update method is used to reduce run time load requirement, neighbour - All particles starts with 0 speed at all n directions. best is updated when all particle finishes its calculation for its current round. - All particles starts at location randomly assigned between 1~m in all dimensions, Local best solution is the same as particle's location The algorithm is terminated when set number of particles completes set number of **ACO** Local search criteria Local search depends on the number of pheromone, and the cost to move the next level. The This part uses Ant Colony System to find the optimal solution for the job cost is calculate by the extra number of time required for including the next job in certain scheduling problem. The process is similar to find a shortest path between two machine. The cost can be zero. Experience VS Explore the new scheduling is used. A nodes on a weighted tree graph. random value is generate to compare with r0. If the rand value is smaller than r0, the local search will select the route with max amount of pheromone. All ants starts at layer 0 of the tree, which means no job has been scheduled. Otherwise, it will do a roulette wheel selection based on $\frac{pheromone}{route cost+1}$ All nodes have initial pheromone of 1.

### **Experimental Results**

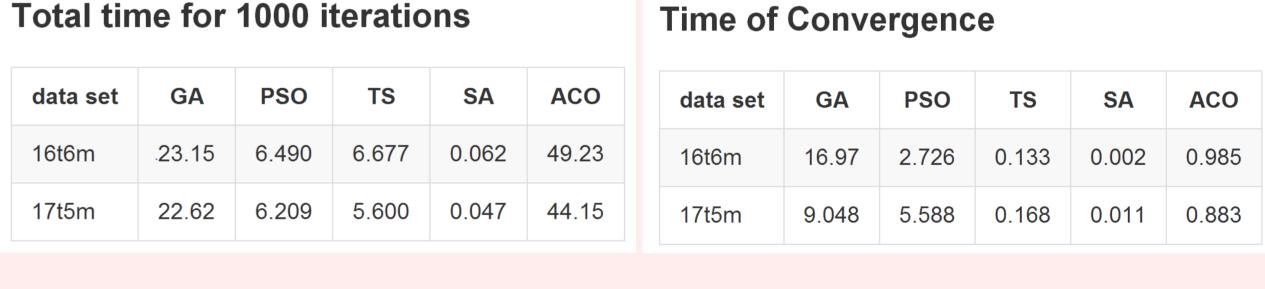
**Experiment Setup** 

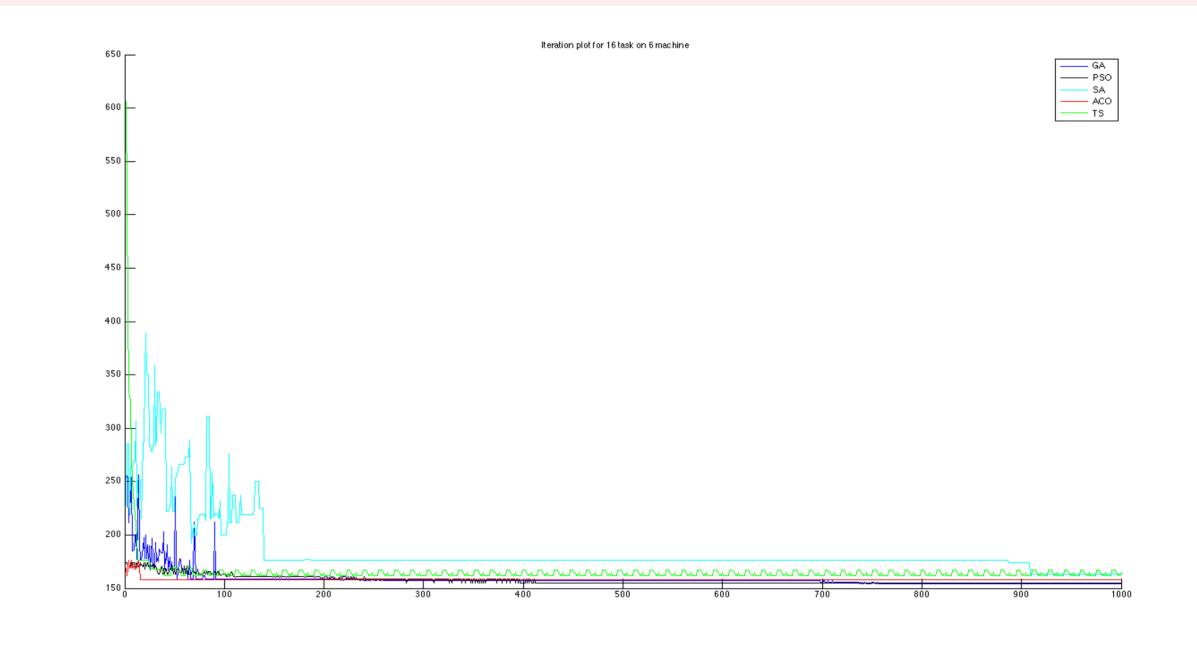
Two dataset generated by brute force algorithm, and all metaheuristics algorithm tested against the two dataset. Each metaheuristics algorithm runs 1000 iterations for each dataset.

#### **Evaluation Metrics**

- 1. Result (40%)
- 2. Total CPU time for 1000 iterations (20%)
- 3. Convergence CPU time for each algorithm (40%)

#### **Comparative Study**





#### Conclusion

Based on our experiment of 5 different metaheuristics algorithm for two different test points of our simplified job shop scheduling problem, it is concluded that in the same number of iterations GA finds the most optimal solution, and SA takes the minimum CPU time to converge. In the same number of iterations, TS finds the least optimal solution, while consuming a moderate amount of CPU time to converge, therefore it is considered the worst solution however it takes only a fraction of CPU time comparing to other algorithms, therefor SA is still a good solution for this problem when computation resources are limited and only a sub-optimal solution however it consumed large amount of CPU time to converge, therefore it's not considered a desired solution. PSO finds the second best solution and also takes second most CPU time to converge. Therefore depending on the amount of CPU power and the how good the solution needs to be, PSO and GA are both good solution for this problem.

Only the global best ants can deposit pheromone on their path. The number of pheromone deposited equals to  $\Delta \tau = \frac{1}{\text{heat cost}}$ .

Pheromone will decrease 40% after each round.