CS 488 Final Project

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Eva

A WebGPU Real-time Ray Tracer Written in Rust

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1. Overview

Eva is a real-time ray tracer built in Rust using WebGPU, with an integrated scripting API.

2.1. Texture Mapping

Any material can be assigned a texture. Textures are sourced from: ./eva/assets/textures.

```
# Load a texture.
texture_handle = Eva.add_texture("texture.png")

# Add the texture to a material.
textured_material = Material(
    1.0,
    0.0,
    (1.0, 1.0, 1.0),
    texture=texture_handle
)

# Add the material to some geometry.
box = Box()
box.set_material(textured_material)
```

2.2. Skyboxes

Scenes can optionally set a skybox. Skyboxes are sourced from: ./eva/assets/skybox. Skyboxes are defined by six images, listed in the order: ["x", "-x", "y", "-y", "z", "-z"], defining the six faces of a cube.

```
Eva.add_skybox([
    "clouds/x.png",
    "clouds/-x.png",
    "clouds/y.png",
    "clouds/-y.png",
    "clouds/z.png",
    "clouds/-z.png",
])
```

2.3. Phong Shading

Eva can render .obj meshes with triangular faces. If the mesh has vertex normals, Phong Shading is applied.



Figure 1: Suzanne Phong Shading

2.4. Real-time Ray Tracing

Eva supports two render modes RenderStatic and RenderDynamic. Implementing RenderDynamic makes your application real-time, and provides update and handle_input methods.

```
class Realtime(RenderDynamic):
    def __init__(self):
        super().__init__()

    self.cube = Box()
    self.add_geometry(cube)

def update(self):
    self.cube.rotate_x(1)

def handle_input(self, key, state):
    # Move the camera left and right in response to input.
    if state == "Pressed" and key == "A":
        self.camera.translate(-1, 0, 0)
    if state == "Pressed" and key == "D":
        self.camera.translate(1, 0, 0)
```

2.5. Reflections

2.6. Python Scripting

Eva is divided into two core components: /eva and /eva-py. /eva-py defines a scripting API for the /eva renderer. Scripts are sourced from /scripts.

Scripts can be run using the utilities run.sh and debug.sh. debug.sh will display build logs.

To run a script, my-scene.py execute:

```
./debug.sh my-scene
```

2.7. TODO: Photon mapping

2.8. PBR Materials

A material is defined by a roughness, metallicness, color, an optional texture, and an optional emissiveness.

```
ruby = Material(0.1, 1.0, (1, 0.1, 0.1))
blue_light = Material(0, 0, (0, 0, 1), light=(0.0, 0.0, 1.0))
earth_handle = Eva.add_texture("earth.jpeg")
earth = Material(0, 0, (1, 1, 1), texture=earth_handle)
```



Figure 2: A grid of spheres with metallic (left to right) and roughness (top to bottom) values ranging from [0,1].

3. Technical Overview

3.1. Project Structure

- /eva: Core renderer.
- /eva-macros: Marcos for the core renderer.
- /eva-py: Python3 scripting API.
- /eva-py/python/eva_py: Pure Python3 wrapper on the Rust bindings.
- /eva-py-macros: Macros for the Python3 scripting API.
- /scripts: Python3 scripts.

Note: In Rust macros must be put into a separate crate.

3.2. Ray Tracer

The ray tracer lives in /eva. It's written in 100% safe Rust and WGSL (WebGPU Shading Language).

- /eva/src
 - /shader: Types that can be loaded into the WGSL shaders.
 - /scene: Scene definition.
 - /renderer: The machinery that creates the WebGPU primitives, loads GPU data, and runs the shaders.

- /eva/assets/shaders
 - display.wgsl: Fragment and vertex shader.
 - ray_tracer.wgsl: Ray tracer compute shader.

Eva uses <u>winit</u> as the windowing API. It's cross-platform and the defacto API in the Rust ecosystem. After creating a winit::Window, to use the ray tracer, you first create a StaticRenderContext which contains information about your scene that will not change. This includes the loaded textures, materials, and some parameters for the ray tracer. Using the StaticRenderContext and the Window you can build a Renderer using the RendererBuilder.

```
let window: winit::Window = todo!("create a window");
let static_context: StaticRenderContext = todo!("create a static context");
let mut renderer = RendererBuilder::new(window, static_context).build();
```

Eva uses wgpu to access WebGPU. The RendererBuilder will create the WebGPU buffers, bind group layouts, bind groups (where possible), pipelines, textures, shader modules, and create all of the required WebGPU core API components including the Device, Queue, Surface, and Adapter. build() then loads this state into a Renderer.

The Renderer has one function, render, which takes in a DynamicRenderContext. The DynamicRenderContext contains things that *will change*. This includes the positions of objects in your Scene, and the position and orientation of your Camera.

```
let mut renderer: Renderer = RendererBuilder::new(window, static_context).build();
let mut dynamic: DynamicRenderContext = todo!();
loop {
  renderer.render(dynamic);
  update(dynamic);
}
```

On render, all of the data is loaded into the shaders and the render commands are encoded using a WebGPU CommandEncoder. There are two* render passes, a ComputePass and a RenderPass. The ComputerPass, which uses ray_tracer.wgsl, will run ray_tracer.wgsl once for each pixel in the screen using "working groups" (a collection of runs of a compute shader). Each run will compute the color of the pixel and store it in a texture. The RenderPass uses display.wgsl which is a simple shader that is used to compute the UVs for sampling from the texture written to by the ComputePass. The screen buffers are then swapped and the new frame is displayed.

The Renderer *does not* have any notion of a render loop. Updates can be handled in whatever way you want so long as you can provide the Renderer with a DynamicRenderContext. This made it significantly easier to enable runtime update()s from Python.

3.3. Scripting Bindings

The scripting bindings live in /eva-py. Eva uses <u>pyo3</u> to generate bindings and <u>maturin</u> to create the Python3 package eva_py. The raw pyo3 bindings are not very easy to work with directly due to Rust's ownership rules (e.g. once I "give" an object to Rust it can no longer be updated from Python), and type restrictions (e.g. cannot build a robust class hierarchy). For those reasons, a pure Python layer - /eva-py/python/eva_py - was added to make the scripting API easier to work with. (HINDSIGHT).

The eva_py package can be built as follows:

```
cd eva-py
# create a virtual environment
```

^{*}There's a third render pass to take screenshots.

```
python3 -m venv .env
source .env/bin/activate
# install maturin
pip install maturin
# start maturin
maturin develop
python3 "script-that-uses-eva.py"
```

3.4. Scripting API

Not comprehensive overview of the scripting API.

```
# import the module
from eva_py import *
# create a skybox (from /eva/assets/skybox)
Eva.add skybox(["x", "-x", "y", "-y", "z", "-z"])
# load a texture (from /eva/assets/textures)
wood_handle = Eva.add_texture("wood.png")
rock_material = Material(
  0.9, # roughness
  0.3, # metalicness
  (1, 0, 0), # rgb colour
  # texture=wood handle (optional) texture handle
  # light=(1, 1, 1) (optional) light emissiveness
rock_handle = Eva.add_material(rock_material)
# create a mesh (from /eva-py/assets/meshes)
suzanne = Mesh("suzanne.obj").translate(1, 0, 0) \
                             .set_material(rock_handle)
```

For a more comprehensive look at how it can be used, check out the /scripts/flappy-bird for a dynamic example and /scripts/nonhier for a static example.

4. Development Process

4.1. Lighting

4.2. Web

5. Games and Images

6. Post Mortem

The biggest trump card for this project is that I didn't know what I wanted to do until I started building it. I looked at my output images and considered what would make them better and I let that, more than my core objectives, drive my development process. Perhaps a little more research at the proposal phase could have helped to avoid some of this, but I could *see* what my project would look like at that point so it was hard to look forward and know what I'd want to add.

That said, two things were harder than I thought they would have been:

6.1. Porting Eva to the Web

Yes, wgpu compiles to WASM but the work extends far beyond that.

- i) Getting the Python scripting to work in the web was very tricky and something I ultimately sided against doing. To make real-time updates work, my renderer requires exclusive access to the Python3 Global Interpreter Lock (GIL) to run the Python code and fetch the updated values. On the web, this is hard because WASM is single-threaded. So, although I could have gotten the scripts to compile to WASM, I couldn't have run them in my browser without significantly modifying how I handle the updates and added a lot of #[cfg(target = "wasm")] annotations for conditional rendering.
- ii) Assets. Loading assets on the web requires making requests. This is fine, but it requires an asynchronous runtime, like NodeJS, to poll the Futures (promises in JavaScript) to see if the asset is ready. Threads cannot block. Eva and Eva-py fetch texture assets, mesh assets, and create screenshots. To make these asynchronous, I needed to either move all asset loading into Rust and add an async runtime for Rust that was WASM compatible, or add an async runtime for both Rust and Python. And for Python runtimes, I needed it to be compatible with pyodide so it could run in the browser.

For those reasons, I decided to not port the application to the web.

6.2. GPU Compatibility

Not all GPUs have the same features. The WebGPU Adapter is used to ask for a Device and Queue supporting a certain set of features, if they're available. The WebGPU Instance, a wrapper on your native GPU, allows you to create a Surface (a fancy texture) given a winit::Window and can tell you what the capabilities of that Surface are. Because I work at home on my local machine, I found out rather late into this assignment that the features and capabilities of the Device and Surface of my local machine (an M1 Max Macbook Pro) are different than what are available on the school Linux machines. My project would not run. Fixing this required changing texture formats, storage types for texture, and some other shader-specific logic. This was a non-trivial diff I was not expecting.

7. Resources

7.1. Dependencies

- $\underline{\mathsf{wgpu}}$: Rust implementation of the WebGPU specification.
- pyo3: Rust to Python3 bindings.
- maturin: Python3 package builder for pyo3 generated bindings.
- nalgebra: Rust linear algebra.
- winit: Rust cross-platform windowing.
- pollster: Rust crate for statically resolving Futures.
- <u>bytemuck</u>: Rust crate for converting data types into bytes.
- <u>image</u>: Rust crate for encoding and decoding images.
- encase: Rust crate for byte-aligning structures for use in WebGPU shaders.
- obj: Rust crate for loading .obj meshes.
- half: Rust crate for handling 16-bit floating float numbers.

7.2. Learning Resources