

# Timothy Devon Morris

PERCEPTION ENGINEER · APPLIED MATHEMATICIAN

735 Independence Blvd NW, Christiansburg, Virginia 24073

☎ (434)-221-4992 | ✉ devonmorris1992@gmail.com | 📱 DevonMorris | 📍 DevonMorris | 💻 devonmorris1992 | 🌐 http://devonmorris.dev

## Summary

Hungry for opportunities to tackle hard problems, such as large-scale SLAM, geometric perception, and L5 autonomy. Strong desire to produce systems that deliver business value and an exceptional user experience. Software craftsman & self-proclaimed vim master.

## Skills & Technologies

### Programming Languages

- C++17
- Python
- CMake
- Bash
- Lua

### Technologies

- GTest & GMock
- Git
- Docker
- Linux
- OpenCV
- ROS
- Vim

### Concepts

- Bayesian State Estimation & Tracking
- Graph-Based Probabilistic Modeling
- Multi-modal Sensor Calibration
- SLAM
- UAS Detect & Avoid
- SOLID Design Principles
- Software Design Patterns

## Work Experience

### Torc Robotics

TECH LEAD & PRODUCT OWNER - SENSORS & CALIBRATION SOFTWARE

- Designed and implemented factor-graph based Sensor to IMU calibration tool in C++17
- Decomposed work for 3 year plan to meet business MVP deliverables
- Coordinated with other teams to discover requirements and identify dependencies
- Hired, mentored and onboarded 3 engineers

*Blacksburg, Virginia*

*October 2021 - Present*

### Torc Robotics

PERCEPTION ENGINEER

- Lead team in designing, implementing and delivering multi-modal calibration tool in C++
- Delivered calibration toolset saving Torc \$2.5 million in operating costs annually
- Served as scrum master for team of 7 engineers

*Blacksburg, Virginia*

*October 2020 - Sept 2021*

### Aurora Flight Sciences

AUTONOMY ENGINEER

- Implemented distributed C++ services to perform conflict detection and resolution for detect & avoid applications
- Deployed detect & avoid system to software-in-the-loop and processor-in-the-loop simulations

*Cambridge, Massachusetts*

*May 2019 - Present*

### Magicc Lab

RESEARCH ASSISTANT

- Implemented a fast complementary filter for fixed-wing attitude estimation
- Designed and Implemented a Monte Carlo Tree Search algorithm for multi-agent path planning

*Provo, Utah*

*April 2017 - April 2019*

## Education

### Georgia Institute of Technology

M.S. IN COMPUTER SCIENCE

- 4.0 GPA

*Remote*

*Aug 2020 - Aug 2023*

### Brigham Young University

M.S. IN ELECTRICAL ENGINEERING

- 4.0 GPA

*Provo, Utah*

*April 2017 - August 2019*

### Brigham Young University

B.S. IN APPLIED AND COMPUTATIONAL MATHEMATICS

- Graduated with Cum Laude honors and 3.94 GPA
- Emphasis in Electrical Engineering: Signals and Systems

*Provo, Utah*

*Sept 2011 - April 2017*