

FIRMWARE RELEASE NOTES

Versions V3.0.17 to v3.0.23

Model VLP-16

LiDAR Sensor



Velodyne

For all new features and changes, refer to the documentation that accompanies the new firmware release for details on usage.

V3.0.23 (30-Mar-2015)

- ADDED: Data packet tagging
 - Every data packet now identifies the type of sensor and return type the packet is formatted for. Future version of HDL-32E firmware will support this as well.
 - The following chart explains what the bytes mean:

Return Type	Field (37) Address: 4DEh	Field (21) address: 4DFh
HDL32 Strongest	37	21
HDL32 Last	38	21
HDL32 Dual	39	21
VLP16 Strongest	37	22
VLP16 Last	38	22
VLP16 Dual	39	22

- ADDED: Added additional factory functions to detect encoder errors.
- CHANGED: Updated field of view setting to use whole degree increments
 - FOV configuration was made to match HDL-32E by incrementing in whole degree increments. Range is now 0-359 instead of 0-35999.
 - NOTE: Any previous setting will be reset to default after firmware update. Downgrading to an older version will not update the setting to the old range.
- CHANGED: Updated web interface graphics
- FIXED: Issue with zero crossing
 - Sensor would occasionally drop a small amount of data when crossing the point of zero degrees rotation.
- FIXED: Snapshot filename
 - By default, the snapshot filename would be saved as all zeros, this has been corrected.
- FIXED: Error in NMEA sentence processing
 - Fixes incompatibility with certain GPS units that support non-zero fractional second fields in the NMEA \$GPRMC sentence. This could cause the Top of Hour Counter to be off as much as 1 second.
- FIXED: Bug in encoder logic
 - This bug prevented phase lock from operating correctly.

V3.0.17

- Initial commercial release. Please see documentation for included features.



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