EXPERIMENT-10

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Course: CSA1789 Artificial Intelligence

Q) Write the python program to solve 8-Puzzle problem

Program:

```
import copy

from heapq import heappush, heappop

n = 3

rows = [ 1, 0, -1, 0 ]
cols = [ 0, -1, 0, 1 ]

class priorityQueue:

    def __init__(self):
        self.heap = []


    def push(self, key):
        heappush(self.heap, key)


    def pop(self):
        return heappop(self.heap)


    def empty(self):
        if not self.heap:
            return True
        else:
            return False

class nodes:

    def __init__(self, parent, mats, empty_tile_posi,
                 costs, levels):


        self.parent = parent


        self.mats = mats

        self.empty_tile_posi = empty_tile_posi
```

```
        self.costs = costs

        self.levels = levels

    def __lt__(self, nxt):
        return self.costs < nxt.costs

def calculateCosts(mats, final) -> int:

    count = 0
    for i in range(n):
        for j in range(n):
            if ((mats[i][j]) and
                (mats[i][j] != final[i][j])):
                count += 1

    return count

def newNodes(mats, empty_tile_posi, new_empty_tile_posi,
             levels, parent, final) -> nodes:


    new_mats = copy.deepcopy(mats)


    x1 = empty_tile_posi[0]
    y1 = empty_tile_posi[1]
    x2 = new_empty_tile_posi[0]
    y2 = new_empty_tile_posi[1]
    new_mats[x1][y1], new_mats[x2][y2] = new_mats[x2][y2], new_mats[x1][y1]


    costs = calculateCosts(new_mats, final)

    new_nodes = nodes(parent, new_mats, new_empty_tile_posi,
                      costs, levels)
    return new_nodes


def printMatsrix(mats):

    for i in range(n):
        for j in range(n):
            print("%d " % (mats[i][j]), end = " ")

        print()


def isSafe(x, y):

    return x >= 0 and x < n and y >= 0 and y < n
```

```
def printPath(root):

   if root == None:
      return

   printPath(root.parent)
   printMatsrix(root.mats)
   print()


def solve(initial, empty_tile_posi, final):


   pq = priorityQueue()


   costs = calculateCosts(initial, final)
   root = nodes(None, initial,
            empty_tile_posi, costs, 0)

   pq.push(root)


   while not pq.empty():

      minimum = pq.pop()
      if minimum.costs == 0:

         printPath(minimum)
         return

      for i in range(n):
         new_tile_posi = [
            minimum.empty_tile_posi[0] + rows[i],
            minimum.empty_tile_posi[1] + cols[i], ]

         if isSafe(new_tile_posi[0], new_tile_posi[1]):


            child = newNodes(minimum.mats,
                     minimum.empty_tile_posi,
                     new_tile_posi,
                     minimum.levels + 1,
                     minimum, final,)


            pq.push(child)

initial = [ [ 1, 2, 3 ],
         [ 5, 6, 0 ],
         [ 7, 8, 4 ] ]

final = [ [ 1, 2, 3 ],
      [ 5, 8, 6 ],
```

[0, 7, 4]]

empty_tile_posi = [1, 2]

solve(initial, empty_tile_posi, final)

Output: