HW8 of ME5701. Sun Zhanhong. A9225292J

[**Optional**.] Work out the differential operators, Gradient, Divergence and Laplacian in Cylindrical and Spherical coordinates

Assume $X = (X_1, X_2, X_3)^T$ in courtesian coordinate, and $X = (M_1, U_2, U_3)^T$ in other approximate.

Therefore, by chain rule, (full differential)

$$\eta \chi = \frac{2n'}{2x} \eta n' + \frac{2n'}{4x} \eta n'' + \frac{2n'}{3x} \eta n''$$

Let
$$h_i = \left| \frac{\partial x}{\partial w_i} \right|$$
 for $i = 1, 2, 3$.

Hen
$$e_i = \frac{\partial x}{\partial u_i}$$
,

and dx = hieidni + hzezduz+ hzezduz

Therefore,
$$\nabla X = \frac{1}{h_1} \frac{\partial X}{\partial u_1} e_1 + \frac{1}{h_2} \frac{\partial X}{\partial u_2} e_2 + \frac{1}{h_3} \frac{\partial X}{\partial u_3} e_3$$

$$\nabla \cdot X = \frac{1}{h_1 h_2 h_3} \left(\frac{\partial X_1 h_2 h_3}{\partial u_1} + \frac{\partial (X_2 h_3 h_1)}{\partial u_2} + \frac{\partial (X_3 h_1 h_2)}{\partial u_3} \right)$$

For cylindrical coordinate.

$$h_1 = 1$$
, $h_2 = r$. $h_3 = 1$

For spherical coordinate

Therefore, for cylindrical coordinate,

$$\frac{\partial}{\partial x_{1}} = \frac{\partial}{\partial r}; \frac{\partial}{\partial x_{2}} = \frac{\partial}{\partial y}; \frac{\partial}{\partial x_{3}} = \frac{\partial}{\partial z}$$

$$\nabla f = \frac{\partial}{\partial r} e_{r} + \frac{\partial}{r} \frac{\partial}{\partial y} e_{p} + \frac{\partial}{\partial z} e_{z}$$

$$\nabla f = \frac{\partial}{\partial r} (r \frac{\partial}{\partial r}) + \frac{\partial}{r} \frac{\partial}{\partial z} + \frac{\partial}{\partial z}$$

$$\nabla f = \frac{\partial}{r} (r \frac{\partial}{\partial r}) + \frac{\partial}{r} \frac{\partial}{\partial z} + \frac{\partial}{\partial z}$$

$$\nabla f = \frac{\partial}{\partial x_{1}} (r \frac{\partial}{\partial r}) + \frac{\partial}{r} \frac{\partial}{\partial z} + \frac{\partial}{r} \frac{\partial}{\partial z}$$

$$\nabla f = \frac{\partial}{\partial x_{1}} (r \frac{\partial}{\partial r}) + \frac{\partial}{r} \frac{\partial}{\partial z} + \frac{\partial}{r} \frac{\partial}{\partial z}$$

$$\nabla f = \frac{\partial}{\partial r} (r^{2} \frac{\partial}{\partial r}) + \frac{\partial}{r} \frac{\partial}{\partial z} + \frac{\partial}{r} \frac{\partial}{\partial z} + \frac{\partial}{r} \frac{\partial}{\partial z}$$

$$\nabla^{2} f = \frac{\partial}{r^{2}} \frac{\partial}{\partial r} (r^{2} \frac{\partial}{\partial r}) + \frac{\partial}{r^{2}} \frac{\partial}{\partial z} + \frac{\partial}{r} \frac{\partial}{\partial z} + \frac{\partial}{r} \frac{\partial}{\partial z} (sind \frac{\partial}{\partial z})$$

Use Taylor expansion to obtain the coefficients α , β and γ for the forward and backward difference formulae

Portial difference here is only with respect to X. By Taylor expansion, So we can write $f(a+\Delta x) = f(a) + \Delta x f'(a) + \frac{\Delta x}{2} f''(a) + \frac{\partial^2}{\partial a} f''(a)$ it as a function

 $= \frac{f(a+ax)-f(a)}{ax} = f'(a)+ax f''(a) + \frac{0^3(ax)}{ax}$

 $\Rightarrow f'(a) = \frac{f(a+b\lambda) - f(a)}{b\lambda} - b\lambda f''(a) + O(b\lambda)$

the first error term is proportional to ax

That means the fun difference is first-order aumanted in ax.

 $\Rightarrow f(\alpha) = \frac{f(\alpha + \delta x) - f(\alpha)}{x^{2}} + O(\delta x)$

By Taylor expansion,

$$f(a-ax) = f(a) - ax f'(a) + ax^2 f''(a) + 0 (ax)$$

=> $\frac{f(a-\Delta x)-f(a)}{-\Delta x}=f'(a)-\frac{\Delta x}{2}f''(a)+o'(\Delta x)$

=> $f'(\alpha) = \frac{f(\alpha) - f(\alpha - \delta X)}{\delta X} + \frac{\delta X}{3} f''(\alpha) + \theta^{2}(\delta X)$

fian-fia-ox) + 0 (6x)

$$\Rightarrow \begin{cases} d=0 \\ q=1 \end{cases}$$