Linear Models for Regression

Master's Degree in Bioinformatics and Computational Biology - Machine Learning

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Contents

Introduction

2 1-Dimensional Linear Regression

3 Multiple Linear Regression

4 Summary



Exercise

Questionnaire

Please, fill in the questionnaire regarding your prior knowledge about this topic.



Introduction



Supervised Learning: Regression (I)



Definition (Supervised Learning)

Supervised learning is the Machine Learning (ML) task of learning a function that maps an input to an output based on example input–output pairs.

Definition (Regression Problem)

A regression problem is a supervised learning problem where the outputs are continuous.



Examples (Regression Problems)

- ▶ Predicting the wind energy production at a certain hour using Numerical Weather Predictions.
- ▶ Predicting the weight of a person based on the height, age, gender, etc.
- Predicting the future price of a stock based on its current value, the value of related stocks, the current trends, etc.



Supervised Learning: Regression (II)



Elements of a Supervised Learning Problem

Data Set of input–output pairs, $\mathcal{D} = \{(\mathbf{x}_i, y_i)\}_{i=1}^N$.

Features Vector of attributes (independent/input variables, covariates...), $\mathbf{x}_i \in \mathcal{X}$.

Target Label (dependent variable, outcome...), $y_i \in \mathcal{Y}$.

Model Mapping from the input to the output space, $f_{\theta}: \mathcal{X} \to \mathcal{Y}$, with θ the model parameters.

Learning Algorithm Procedure to obtain a model based on the data, $\mathcal{A}: \mathcal{D} \to f_{\theta}(\cdot)$.



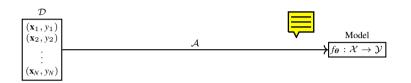
- In a regression setting usually $\mathcal{Y} = \mathbb{R}$.
- In many situations, specially after preprocessing the data, $\mathcal{X} = \mathbb{R}^d$.

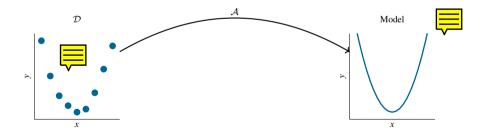




Illustration









3/26

Linear Models for Regression



"Simplest" approaches to regression:



- Ignore the input: constant model.
- Define the output as a linear combination of the inputs: **linear model**.

Advantages

- ► Simple.
- ► Robust (small variance).
- Interpretable.
- Easy to train.
- Easy to predict.

Disadvantages

- Limited flexibility.
- ▶ Under-fitting (large bias).



1-Dimensional Linear Regression



1-D Linear Model



- In the simplest case, d = 1 and $\mathcal{X} = \mathbb{R}$.
- ▶ The data becomes $\mathcal{D} = \{(x_i, y_i)\}_{i=1}^N$, with $x_i \in \mathbb{R}$ and $y_i \in \mathbb{R}$.
- ▶ The corresponding linear model is simply a line, with parameters $\theta = \{b, w\}$.
 - $b \in \mathbb{R}$ is the intercept or bias term.
 - $w \in \mathbb{R}$ is the slope of the line.
 - The model is defined as:

$$f_{\boldsymbol{\theta}}(x) = \boldsymbol{b} + \boldsymbol{w}x.$$

The learning algorithm will determine b and w using \mathcal{D} .



1-D Linear Model - Exercise



Given a 1-dimensional linear model with parameters $\theta = \{b, w\}$, with b = 1 and w = 2.

- \blacksquare Compute the output of the model for x = 2.
- ② Compute the output of the model for x = -1.



Notebook

1-Dimensional Linear Regression: First Example





Quality of the Model



▶ A procedure is needed to determine the bias b and the slope w, optimizing the quality of the model.



- ► The quality of the model has to be defined. Usually from two points of view:
 - Error An error term $\mathcal{E}_{\mathcal{D}}(\theta)$ measures how well the model fits the training data. Complexity A regularization term $\mathcal{R}(\theta)$ penalizes the complexity of the model.

Error Term for a 1-Dimensional Linear Model



Residual For the *i*-th pattern,
$$r_i = y_i - f_{\theta}(x_i) = y_i - (b + wx_i)$$
.

Mean Squared Error (MSE) MSE
$$(b, w) = \mathbb{E}[R^2] \approx \frac{1}{N} \sum_{i=1}^{N} r_i^2 = \frac{1}{N} \sum_{i=1}^{N} (y_i - (b + wx_i))^2$$
.

Mean Absolute Error (MAE) MAE
$$(b, w) = \mathbb{E}[|R|] \approx \frac{1}{N} \sum_{i=1}^{N} |r_i| = \frac{1}{N} \sum_{i=1}^{N} |y_i - (b + wx_i)|.$$





Quality of the 1-Dimensional Model - Exercise



Exercis

> Questionnaire

Given a 1-dimensional linear model with parameters $\theta = \{b, w\}$, with b = 1 and w = 2, and for the following data:

4
1

- Compute the MAE.
- Ompute the MSE.



Notebook

1-Dimensional Linear Regression: Quality of the Model





Optimization



Definition (Optimization)

- ▶ Optimize (from Latin *optimus*, best) is to "make the best or most effective use of (a situation or resource)".
- ► Optimization is ubiquitous.
 - In nature.
 - In daily tasks.
 - As a strategy to design procedures.

Formalization

An optimization problem consists in finding the best element θ^* of a certain space S with respect to some criteria given by an objective function F:

$$\boldsymbol{\theta}^{\star} = \underset{\boldsymbol{\theta} \in \mathcal{S}}{\operatorname{arg \, min}} \ \{\mathcal{F}(\boldsymbol{\theta})\}.$$



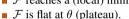


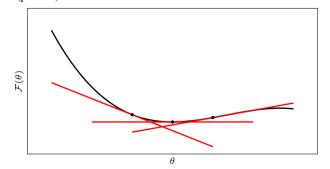
Gradient-Based Optimization: 1-Dimensional Problems



- Given a 1-dimensional function $\mathcal{F}(\theta)$, its derivative $\mathcal{F}'(\theta)$ corresponds to the slope of the line which is tangent to the graph of \mathcal{F} at θ .
 - If it is negative, \mathcal{F} and its tangent go down.
 - If it is positive, \mathcal{F} and its tangent go up.
 - If it is 0, the tangent is horizontal, hence there are two options:









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Training a 1-D Linear Model



▶ The most common choice for the error function is the MSE.



- It is differentiable.
- It corresponds to the distance between the vector of predictions and the vector of targets.
- It is a natural choice when the observation noise is assumed to be **Gaussian**.

More detail in the appendix Bayesian Perspective.

▶ The learning algorithm for training the linear model consists in solving the problem:

$$\min_{b,w \in \mathbb{R}} \{ MSE(b,w) \} = \min_{b,w \in \mathbb{R}} \left\{ \frac{1}{N} \sum_{i=1}^{N} (y_i - (b + wx_i))^2 \right\}.$$

► How is this problem solved?



- It is **differentiable**: the optima are characterized by the zeros of the derivatives.
- It is **convex**: there are no local minima.



Training a 1-D Linear Model: Optimization (I)





$$\min_{b,w \in \mathbb{R}} \{ MSE(b,w) \} = \min_{b,w \in \mathbb{R}} \left\{ \frac{1}{N} \sum_{i=1}^{N} (y_i - (b + wx_i))^2 \right\}.$$



$$\frac{\partial}{\partial b} \operatorname{MSE}(b, w) \bigg|_{\substack{b=b^* \\ w=w^*}} = 0 \implies -\frac{2}{N} \sum_{i=1}^{N} (y_i - (b^* + w^* x_i)) = 0$$

$$\implies -\frac{2}{N} \sum_{i=1}^{N} y_i + \frac{2}{N} \sum_{i=1}^{N} b^* + \frac{2}{N} \sum_{i=1}^{N} w^* x_i = 0$$

$$\implies -\frac{1}{N} \sum_{i=1}^{N} y_i + b^* + w^* \underbrace{\frac{1}{N} \sum_{i=1}^{N} x_i}_{\overline{z}} = 0 \implies b^* = \overline{y} - w^* \overline{x}.$$



Training a 1-D Linear Model: Optimization (II)



$$\min_{b,w \in \mathbb{R}} \{ MSE(b,w) \} = \min_{b,w \in \mathbb{R}} \left\{ \frac{1}{N} \sum_{i=1}^{N} (y_i - (b + wx_i))^2 \right\}.$$

$$\frac{\partial}{\partial w} \operatorname{MSE}(b, w) \Big|_{\substack{b=b^{\star} \\ w=w^{\star}}} = 0 \implies -\frac{2}{N} \sum_{i=1}^{N} x_{i} (y_{i} - (b^{\star} + w^{\star} x_{i})) = 0$$

$$\Rightarrow -\frac{2}{N} \sum_{i=1}^{N} x_{i} y_{i} + \frac{2}{N} \sum_{i=1}^{N} x_{i} b^{\star} + \frac{2}{N} \sum_{i=1}^{N} w^{\star} x_{i}^{2} = 0$$

$$\stackrel{b^{\star} = \overline{y} - w^{\star} \overline{x}}{\Rightarrow} -\frac{2}{N} \sum_{i=1}^{N} x_{i} y_{i} + \frac{2}{N} \sum_{i=1}^{N} x_{i} \overline{y} - \frac{2}{N} \sum_{i=1}^{N} x_{i} w^{\star} \overline{x} + \frac{2}{N} \sum_{i=1}^{N} w^{\star} x_{i}^{2} = 0$$

$$\Rightarrow -\sum_{i=1}^{N} x_{i} \underbrace{(y_{i} - \overline{y})}_{i} + w^{\star} \sum_{i=1}^{N} x_{i} \underbrace{(x_{i} - \overline{x})}_{i} \implies w^{\star} = \frac{\sum_{i=1}^{N} x_{i} \hat{y}_{i}}{\sum_{i=1}^{N} x_{i} \hat{x}_{i}} = \frac{\sum_{i=1}^{N} \hat{x}_{i} \hat{y}_{i}}{\sum_{i=1}^{N} \hat{x}_{i} \hat{x}_{i}}$$



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Training a 1-D Linear Model: Optimization (III)



In summary, the Least Squares Regression Line is the solution of the following problem:

$$\min_{b,w \in \mathbb{R}} \left\{ \frac{1}{N} \sum_{i=1}^{N} (y_i - (b + wx_i))^2 \right\}.$$

These auxiliary elements are defined:

$$\bar{y} = \frac{1}{N} \sum_{i=1}^{N} y_i$$
 (Mean Target),

 $\hat{\mathbf{v}}_i = \mathbf{v}_i - \bar{\mathbf{v}}$ (Centred Target).



$$\bar{x} = \frac{1}{N} \sum_{i=1}^{N} x_i$$
 (Mean Feature),

$$\hat{x}_i = x_i - \bar{x}$$
 (Centred Feature).

Least Squares Regression Line



$$w^* = \frac{\sum_{i=1}^{N} \hat{x}_i \hat{y}_i}{\sum_{i=1}^{N} \hat{x}_i \hat{x}_i}; \ b^* = \bar{y} - w^* \bar{x}.$$

Example in the appendix Perfect 1-Dimensional Linear Model

Training a 1-Dimensional Linear Model - Exercise



Given the following data: Compute the value of \bar{x} and \bar{y} . Compute the value of \hat{x}_i and \hat{y}_i . Compute the value of w^* and b^* . Compute the corresponding MSE value.



Notebook

1-Dimensional Linear Regression: Optimization





Multiple Linear Regression



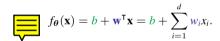
Linear Model





- For simplicity, $\mathcal{X} = \mathbb{R}^d$.
- ▶ The data becomes $\mathcal{D} = \{(\mathbf{x}_i, y_i)\}_{i=1}^N$, with $\mathbf{x}_i = (x_{i,1}, x_{i,2}, \dots, x_{i,d}) \in \mathbb{R}^d$ and $y_i \in \mathbb{R}$.
- ▶ The corresponding linear model is a hyperplane, with parameters $\theta = \{b, \mathbf{w}\}$.
 - $b \in \mathbb{R}$ is the intercept or bias term.
 - $\mathbf{w} = (w_1, w_2, \dots, w_d) \in \mathbb{R}^d$ is the normal vector of the hyperplane.
 - The model is defined as:





▶ The **learning algorithm** will determine b and w using \mathcal{D} .



Linear Model - Exercise



Exercise

Questionnaire

Given a 2-dimensional linear model with parameters $\theta = \{b, \mathbf{w}\}$, with b = 1 and $\mathbf{w} = (1, 2)^{\mathsf{T}}$.

- **①** Compute the output of the model for $\mathbf{x} = (1, 1)^{\mathsf{T}}$.
- ② Compute the output of the model for $\mathbf{x} = (-1, 0)^{\mathsf{T}}$.



Notebook

Multiple Linear Regression: First Example





Linear Equations (I)



- A procedure is needed to determine the bias b and the vector w.
- A first approach is to try to match all input–output pairs $(\mathbf{x}_i, y_i), i = 1, \dots, N$. Specifically:

$$\begin{cases} b + \mathbf{w}^{\mathsf{T}} \mathbf{x}_{1} = y_{1} \\ b + \mathbf{w}^{\mathsf{T}} \mathbf{x}_{2} = y_{2} \\ \dots \\ b + \mathbf{w}^{\mathsf{T}} \mathbf{x}_{N} = y_{N} \end{cases} \equiv \begin{cases} b + w_{1} x_{1,1} + w_{2} x_{1,2} + \dots + w_{d} x_{1,d} = y_{1} \\ b + w_{1} x_{2,1} + w_{2} x_{2,2} + \dots + w_{d} x_{2,d} = y_{2} \\ \dots \\ b + w_{1} x_{N,1} + w_{2} x_{N,2} + \dots + w_{d} x_{N,d} = y_{N} \end{cases}.$$

The following matrix notation can simplify the equations:

$$\mathbf{X} = \begin{pmatrix} x_{1,1} & x_{1,2} & \dots & x_{1,d} \\ x_{2,1} & x_{2,2} & \dots & x_{2,d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{N,1} & x_{N,2} & \dots & x_{N,d} \end{pmatrix}; \quad \tilde{\mathbf{X}} = \begin{pmatrix} 1 & x_{1,1} & \dots & x_{1,d} \\ 1 & x_{2,1} & \dots & x_{2,d} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{N,1} & \dots & x_{N,d} \end{pmatrix}; \quad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix}; \quad \tilde{\mathbf{w}} = \begin{pmatrix} b \\ w_1 \\ \vdots \\ w_d \end{pmatrix},$$

where $\mathbf{X} \in \mathbb{R}^{N \times d}$ is the data matrix, $\tilde{\mathbf{X}} \in \mathbb{R}^{N \times (d+1)}$ is the data matrix with a constant term, $\mathbf{y} \in \mathbb{R}^N$ is the vector of targets and $\tilde{\mathbf{w}} \in \mathbb{R}^{d+1}$ is the weight vector including the intercept.

Linear Equations (II)



The system of equations becomes:



$$\tilde{\mathbf{X}}\tilde{\mathbf{w}}=\mathbf{y}.$$

- Since $\tilde{\mathbf{X}} \in \mathbb{R}^{N \times (d+1)}$, $\tilde{\mathbf{w}} \in \mathbb{R}^{d+1}$ and $\mathbf{v} \in \mathbb{R}^{N}$:
 - N equations.
 - d+1 unknowns.
- ▶ Usually, $N \gg d + 1$ and the system is **overdetermined**.
- The inverse of $\tilde{\mathbf{X}}$ is not defined.
- The Moore-Penrose pseudo-inverse can be used instead, $\tilde{\mathbf{X}}^\dagger = (\tilde{\mathbf{X}}^\intercal \tilde{\mathbf{X}})^{-1} \tilde{\mathbf{X}}^\intercal$.



A different approach also justifies this method.



Quality of the Model



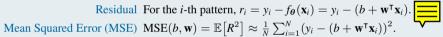
- An alternative procedure is needed to determine the bias b and the vector w.
 - The solution is to optimize the quality of the model, probably not fitting exactly the training data.
- The quality of the model has to be defined. Usually from two points of view:

Error An error term $\mathcal{E}_{\mathcal{D}}(\boldsymbol{\theta})$ measures how well the model fits the training data.

Complexity A regularization term $\mathcal{R}(\theta)$ penalizes the complexity of the model.

Error Term for a Linear Model

Residual For the *i*-th pattern,
$$r_i = y_i - f_{\theta}(\mathbf{x}_i) = y_i - (b + \mathbf{w}^{\mathsf{T}}\mathbf{x}_i)$$
.



Mean Absolute Error (MAE) MAE
$$(b, \mathbf{w}) = \mathbb{E}[|R|] \approx \frac{1}{N} \sum_{i=1}^{N} |y_i - (b + \mathbf{w} \mathbf{x}_i)|$$
.



Quality of the Model - Exercise



Exercis

□ Questionnaire

Given a 2-dimensional linear model with parameters $\theta = \{b, \mathbf{w}\}$, with b = 1 and $\mathbf{w} = (1, 2)^{\mathsf{T}}$, and for the following data:

$x_{i,1}$		
1	1	4
-1	0	2

- Compute the MAE.
- Ompute the MSE.



Gradient-Based Optimization: Multdimensional Problems

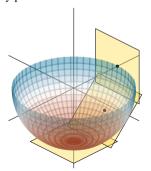




▶ In several dimensions, the derivative is generalized to the gradient (the vector of partial derivatives):

$$abla_{m{ heta}} \mathcal{F} = egin{pmatrix} rac{\partial}{\partial heta_1} \mathcal{F} & rac{\partial}{\partial heta_2} \mathcal{F} & \dots & rac{\partial}{\partial heta_d} \mathcal{F} \end{pmatrix}^{\intercal}.$$

- The gradient defines the tangent hyperplane.
- It points in the direction of greatest increase of \mathcal{F} .
- If it is $\mathbf{0}$ at $\boldsymbol{\theta}$, then $\boldsymbol{\theta}$ is a stationary point.





Training a Linear Model



▶ The most common choice for the error function is the MSE.



- It is differentiable.
- It corresponds to the **distance** between the vector of predictions and the vector of targets.
- It is a natural choice when the observation noise is assumed to be Gaussian.

More detail in the appendix Bayesian Perspective.

▶ The learning algorithm for training the linear model consists in solving the problem:



$$\min_{\substack{b \in \mathbb{R} \\ \mathbf{w} \in \mathbb{R}^d}} \left\{ MSE(b, \mathbf{w}) \right\} = \min_{\substack{b \in \mathbb{R} \\ \mathbf{w} \in \mathbb{R}^d}} \left\{ \frac{1}{N} \sum_{i=1}^{N} (y_i - (b + \mathbf{w}^\mathsf{T} \mathbf{x}_i))^2 \right\}.$$

- ► How is this problem solved?
 - It is **differentiable**: the optima are characterized by the zeros of the gradient.
 - It is **convex**: there are no local minima.



Training a Linear Model: Optimization (I)



$$\begin{array}{l}
\text{nin} \\
\in \mathbb{R} \\
\in \mathbb{R}^d
\end{array}$$

$$\{\mathsf{MSE}(b,\mathbf{w})\} = \min_{\substack{b \in \\ \mathbf{w} \in \mathbb{R}}} (b,\mathbf{w})$$

$$\min_{\substack{b \in \mathbb{R} \\ \mathbf{w} \in \mathbb{R}^d}} \left\{ MSE(b, \mathbf{w}) \right\} = \min_{\substack{b \in \mathbb{R} \\ \mathbf{w} \in \mathbb{R}^d}} \left\{ \frac{1}{N} \sum_{i=1}^N (y_i - (b + \mathbf{w} \mathbf{x}_i))^2 \right\} \equiv \min_{\tilde{\mathbf{w}} \in \mathbb{R}^{d+1}} \left\{ \left(\mathbf{y} - \tilde{\mathbf{X}} \tilde{\mathbf{w}} \right)^{\mathsf{T}} \left(\mathbf{y} - \tilde{\mathbf{X}} \tilde{\mathbf{w}} \right) \right\}.$$

$$\left.
abla_{\tilde{\mathbf{w}}} \operatorname{MSE}(\tilde{\mathbf{w}}) \right|_{\tilde{\mathbf{w}} = \tilde{\mathbf{w}}^{\star}} = \mathbf{0} \implies 2\tilde{\mathbf{X}}^{\intercal} \left(\mathbf{y} - \tilde{\mathbf{X}} \tilde{\mathbf{w}}^{\star} \right) = \mathbf{0}$$

$$\implies \tilde{X}^\intercal y - \tilde{X}^\intercal \tilde{X} \tilde{w}^\star = 0$$

$$\implies \tilde{X}^\intercal \tilde{X} \tilde{w}^\star = \tilde{X}^\intercal y$$

$$\Longrightarrow \boxed{\tilde{\mathbf{w}}^\star = \left(\tilde{\mathbf{X}}^\intercal \tilde{\mathbf{X}}\right)^{-1} \tilde{\mathbf{X}}^\intercal \mathbf{y} = \tilde{\mathbf{X}}^\dagger \mathbf{y}}\,.$$



Training a Linear Model: Optimization (II)



▶ In summary, the Least Squares Linear Model is the solution of the following problem:

$$\min_{\substack{b \in \mathbb{R} \\ \mathbf{w} \in \mathbb{R}^d}} \left\{ \frac{1}{N} \sum_{i=1}^{N} (y_i - (b + \mathbf{w}^{\mathsf{T}} \mathbf{x}_i))^2 \right\}.$$

Least Squares Linear Model



$$egin{pmatrix} b^\star \ \mathbf{w}^\star \end{pmatrix} = \tilde{\mathbf{w}}^\star = \tilde{\mathbf{X}}^\dagger \mathbf{y} = egin{bmatrix} \mathbf{1} & \mathbf{X} \end{bmatrix}^\dagger \mathbf{y}.$$

Example in the appendix **Perfect Linear Model**.



Notebook

Multiple Linear Regression: Optimization





Summary



Linear Models for Regression: Summary



- A regression problem is a supervised problem with continuous targets.
- A simple yet useful regression model is the **linear model**.
 - The prediction is a linear combination of the features.
- ► In order to train the linear model, an **optimization problem** is usually solved.
- ► The MSE is often used to measure the quality of the model.
 - It is a natural choice.
 - The resultant problem can be solved in closed-form using the pseudo-inverse of the data matrix.



Linear Models for Regression

Carlos María Alaíz Gudín

Introduction

Supervised Learning: Regression

Linear Models

1-Dimensional Linear Regression

1-Dimensional Linear Model Quality of the Model Learning Algorithm

Multiple Linear Regression

Linear Model Linear Equations Quality of the Model Learning Algorithm

Summary



Additional Material

Additional Material

Perfect 1-Dimensional Linear Model Perfect Linear Model Bayesian Perspective



Training a 1-Dimensional Linear Model - Example



Example (Perfect Case)

- ▶ In the perfectly linear case, $y_i = wx_i + b$.
- ► This implies:

$$\bar{y} = \frac{1}{N} \sum_{i=1}^{N} y_i = \frac{1}{N} \sum_{i=1}^{N} (wx_i + b) = w\bar{x} + b,$$

$$\hat{y}_i = y_i - \bar{y} = wx_i + b - w\bar{x} - b = w(x_i - \bar{x}) = w\hat{x}_i.$$

► Therefore, the regression lines becomes:

$$w^* = \frac{\sum_{i=1}^{N} \hat{x}_i \hat{y}_i}{\sum_{i=1}^{N} \hat{x}_i \hat{x}_i} = \frac{w \sum_{i=1}^{N} \hat{x}_i^2}{\sum_{i=1}^{N} \hat{x}_i^2} = w;$$

$$b^* = \bar{y} - w^* \bar{x} = w \bar{x} + b - w \bar{x} = b.$$



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Training a Linear Model - Example



Example (Perfect Case)

- In the perfectly linear case, $y_i = \mathbf{w}^\mathsf{T} \mathbf{x}_i + b$.
- In matrix notation, $\mathbf{v} = \tilde{\mathbf{X}}\tilde{\mathbf{w}}$.
- Therefore, the linear model becomes:

$$\begin{split} \tilde{\mathbf{w}}^{\star} &= \tilde{\mathbf{X}}^{\dagger} \mathbf{y} \\ &= \left(\tilde{\mathbf{X}}^{\intercal} \tilde{\mathbf{X}} \right)^{-1} \tilde{\mathbf{X}}^{\intercal} \mathbf{y} \\ &= \left(\tilde{\mathbf{X}}^{\intercal} \tilde{\mathbf{X}} \right)^{-1} \tilde{\mathbf{X}}^{\intercal} \left(\tilde{\mathbf{X}} \tilde{\mathbf{w}} \right) \\ &= \left(\tilde{\mathbf{X}}^{\intercal} \tilde{\mathbf{X}} \right)^{-1} \left(\tilde{\mathbf{X}}^{\intercal} \tilde{\mathbf{X}} \right) \tilde{\mathbf{w}} \\ &= \tilde{\mathbf{w}}. \end{split}$$



Training a Linear Model: Bayesian Perspective (I)



- ▶ There is an additional justification for using the MSE in a linear model.
- ► The output is assumed to be a linear transformation of the input corrupted with Gaussian noise:

$$y_i = \mathbf{w}^\mathsf{T} \mathbf{x}_i + \epsilon_i,$$

where $\epsilon_i \sim \mathcal{N}(0, \sigma)$.

► The likelihood of the data becomes:

$$p(\mathcal{D}|\mathbf{w}) \propto \prod_{i=1}^{N} \exp\left(-\frac{\epsilon_i^2}{2\sigma^2}\right) = \prod_{i=1}^{N} \exp\left(-\frac{(y_i - \mathbf{w}^{\mathsf{T}} \mathbf{x}_i)^2}{2\sigma^2}\right).$$

 $\mathbf{w}^{\star} \in \mathbb{R}^d$ is selected as the maximizer of the likelihood:

$$\max_{\mathbf{w} \in \mathbb{R}^d} \left\{ \prod_{i=1}^N p(\mathcal{D}|\mathbf{w}) \right\} = \max_{\mathbf{w} \in \mathbb{R}^d} \left\{ \prod_{i=1}^N \exp\left(-\frac{(y_i - \mathbf{w}^\mathsf{T} \mathbf{x}_i)^2}{2\sigma^2}\right) \right\}.$$



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Training a Linear Model: Bayesian Perspective (II)



▶ Equivalently, instead of maximizing the likelihood, the minus log-likelihood is minimized:

$$\min_{\mathbf{w} \in \mathbb{R}^d} \left\{ \sum_{i=1}^N (y_i - \mathbf{w}^\mathsf{T} \mathbf{x}_i)^2 \right\},\,$$

which coincides with the least squares problem for a linear model.

- Bayesian Linear Regression is more than this.
- The prior can be used to impose structure, use prior knowledge, etc.

