

# Assignment 07 | Advance Algorithms

## CE-092

Assignment submission for Advance Algorithms subject week 7.

[nevilparmar24@gmail.com](mailto:nevilparmar24@gmail.com)

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### Task 1:

Write a program to find the Convex Hull for a given set of points in 2-D using Graham's Scan Method.

Code:

```
/*
 * @Author: nevil
 * @Date: 2020-09-04 16:11:58
 * @Last Modified by: nevil
 * @Last Modified time: 2020-09-04 16:18:05
 */
#include<bits/stdc++.h>
using namespace std;

struct Point
{
    int x, y;
};

Point p0;

// A utility function to find next to top in a stack
Point nextToTop(stack<Point> &S)
{
```

```

    Point p = S.top();
    S.pop();
    Point res = S.top();
    S.push(p);
    return res;
}

// A utility function to swap two points
int swap(Point &p1, Point &p2)
{
    Point temp = p1;
    p1 = p2;
    p2 = temp;
}

// A utility function to return square of distance
int distSq(Point p1, Point p2)
{
    return (p1.x - p2.x) * (p1.x - p2.x) +
           (p1.y - p2.y) * (p1.y - p2.y);
}

int orientation(Point p, Point q, Point r)
{
    int val = (q.y - p.y) * (r.x - q.x) -
              (q.x - p.x) * (r.y - q.y);

    if (val == 0) return 0; // colinear
    return (val > 0) ? 1 : 2; // clock or counterclock
wise
}

```

```

int compare(const void *vp1, const void *vp2)
{
    Point *p1 = (Point *)vp1;
    Point *p2 = (Point *)vp2;

    int o = orientation(p0, *p1, *p2);
    if (o == 0)
        return (distSq(p0, *p2) >= distSq(p0, *p1)) ?
-1 : 1;

    return (o == 2) ? -1 : 1;
}

void convexHull(Point points[], int n)
{
    int ymin = points[0].y, min = 0;
    for (int i = 1; i < n; i++)
    {
        int y = points[i].y;

        if ((y < ymin) || (ymin == y &&
            points[i].x <
points[min].x))
            ymin = points[i].y, min = i;
    }

    swap(points[0], points[min]);

    p0 = points[0];
    qsort(&points[1], n - 1, sizeof(Point), compare);

    int m = 1; // Initialize size of modified array

```

```

    for (int i = 1; i < n; i++)
    {
        while (i < n - 1 && orientation(p0, points[i],
                                         points[i + 1])
== 0)

            i++;

        points[m] = points[i];
        m++; // Update size of modified array
    }

    if (m < 3) return;

    stack<Point> S;
    S.push(points[0]);
    S.push(points[1]);
    S.push(points[2]);

    for (int i = 3; i < m; i++)
    {
        while (orientation(nextToTop(S), S.top(),
points[i]) != 2)
            S.pop();
        S.push(points[i]);
    }

    while (!S.empty())
    {
        Point p = S.top();
        cout << "(" << p.x << ", " << p.y << ")" <<
endl;

```

```
        S.pop();
    }
}

// Driver program to test above functions
int main()
{
    cout << "Enter the number of points : ";
    int n;
    cin >> n;
    Point points[n];
    cout << "Enter the points (x , y) : " ;
    for(auto i = 0 ; i < n; i++)
        cin >> points[i].x >> points[i].y;

    convexHull(points, n);
    return 0;
}
```

Output:

```

TERMINAL  PROBLEMS  OUTPUT  DEBUG CONSOLE
PS N:\Third Year\AA\LABS\L7> g++ .\grahamScan.cpp
PS N:\Third Year\AA\LABS\L7> .\a.exe
Enter the number of points : 7
Enter the points (x , y) : 0 3
2 3
1 1
2 1
3 0
0 0
3 3

HULL
(0, 3)
(3, 3)
(3, 0)
(0, 0)
PS N:\Third Year\AA\LABS\L7> █
```

## Complexity :

Let  $n$  be the number of input points.

The algorithm takes  $O(n \log n)$  time if we use a  $O(n \log n)$  sorting algorithm.

The first step (finding the bottom-most point) takes  $O(n)$  time. The second step (sorting points) takes  $O(n \log n)$  time. The third step takes  $O(n)$  time. In the third step, every element is pushed and popped at most one time. So the sixth step to process points one by one takes  $O(n)$  time, assuming that the stack operations take  $O(1)$  time. Overall complexity is  $O(n) + O(n \log n) + O(n) + O(n)$  which is  $O(n \log n)$

Nevil Parmar  
CE-092

<https://nevilparmar.me>