

3. When run camera code, some error will display, as shown below.

```
RuntimeError                                Traceback (most recent call last)
/usr/local/lib/python3.6/dist-packages/jetbot-0.3.0-py3.6.egg/jetbot/camera.py in __init__(self, *
    29         if not re:
--> 30             raise RuntimeError('Could not read image from camera.')
    31

RuntimeError: Could not read image from camera.

During handling of the above exception, another exception occurred:

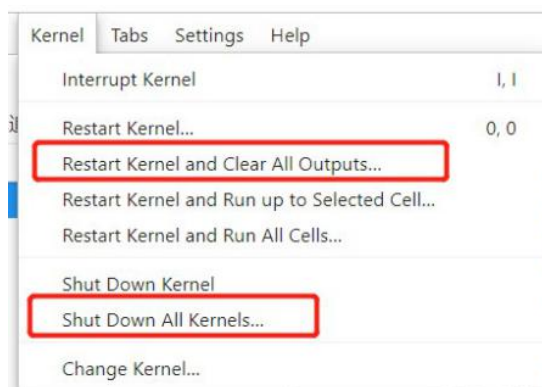
RuntimeError                                Traceback (most recent call last)
<ipython-input-1-611c7c1d6a18> in <module>
      2 from jetbot import bgr8_to_jpeg
      3 import PID
--> 4 camera = Camera.instance(width=720, height=720)

/usr/local/lib/python3.6/dist-packages/traitlets/config/configurable.py in instance(cls, *args, *
    508         # Create and save the instance
    509         if cls._instance is None:
--> 510             inst = cls(*args, **kwargs)
    511             # Now make sure that the instance will also be returned by
    512             # parent classes' _instance attribute.

/usr/local/lib/python3.6/dist-packages/jetbot-0.3.0-py3.6.egg/jetbot/camera.py in __init__(self, *
    35         self.stop()
    36         raise RuntimeError(
--> 37             'Could not initialize camera. Please see error trace.')
    38
    39         atexit.register(self.stop)

RuntimeError: Could not initialize camera. Please see error trace.
```

- 1) Please check if the camera is plugged in correctly.
- 2) Go to the command terminal and enter `ls /dev` to see if the video 0 device can be checked.
- 3) Click **[kernel]** on the jupyterLab interface, click **[Shut down all kernels]**, and wait for 30s.
- 4) Click **[Restart kernel and clear all outputs]**... After waiting for 30s to clear, re-run the code.



If the error is display all the time, please restart the car.