

## Differential PCM:

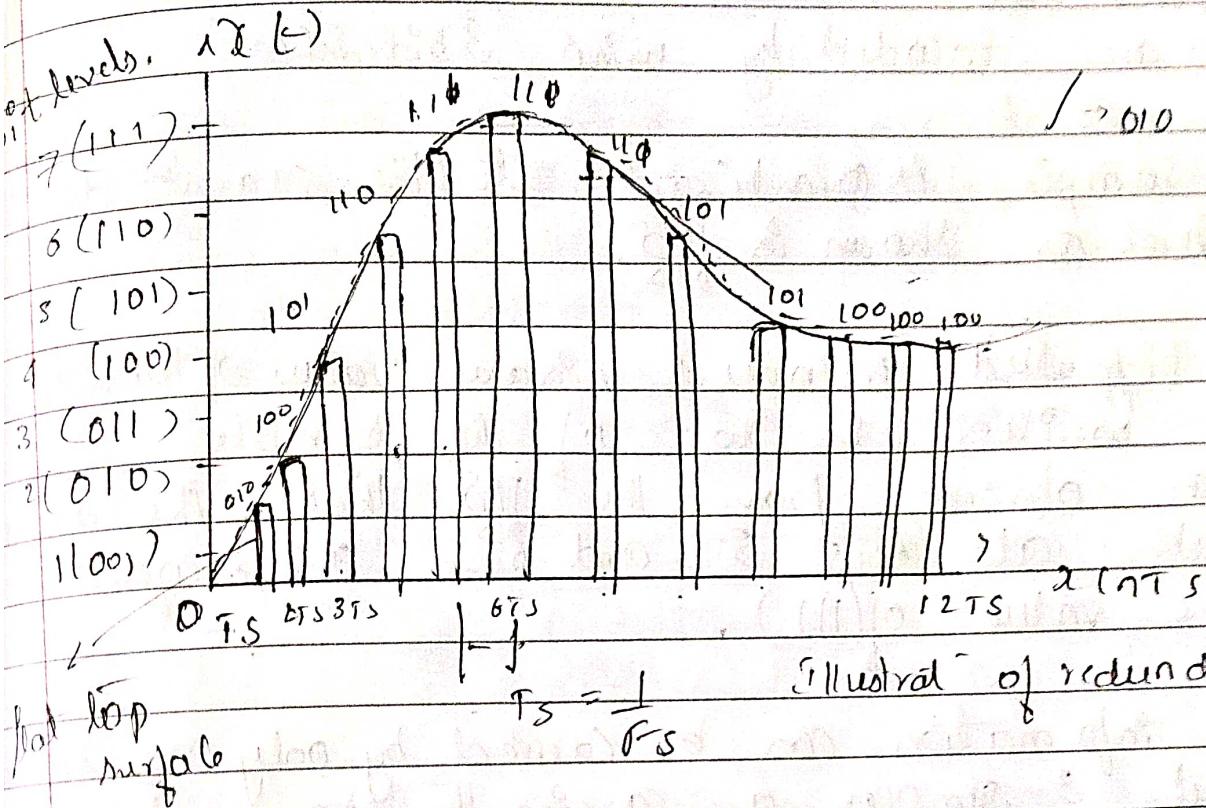


Illustration of redundant info in PCM

(i) It may be observed that the samples of a signal are highly correlated with each other, this is due to the fact that any signal does not change fast. This means that value from present to next sample does not differ by large amount.

(ii) The adjacent samples of signal carry the same info with a little difference. When these samples are encoded by a standard PCM system the resulting encoded signal contains some redundant info. Fig illustrates this redundant information.

(iii) Shows a continuous time signal  $x(t)$  by dotted line. This signal is sampled by flat top sampling @ intervals  $T_S, 2T_S, \dots$ . The

The sampling frequency selected to be higher than request rate samples are encoded by using 3bit DPCM

- ① The sample is quantized to the nearest digital level as shown in fig.

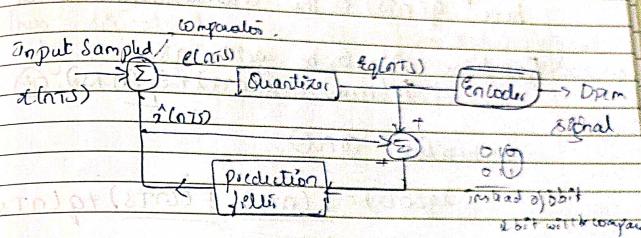
The (quantized) encoded binary value of each sample is written in top of the sample we can observe from the fig that the sample taken at 4TS, 5TS and 6TS are encoded to same value of (111).

- ② This information can be carried by only one sample but 3 samples are carrying the same information means that it is the redundant.

- ③ Consider another example of samples taken at 10TS and 11TS. The difference b/w these samples only due to last bit (1001101) and just 1 bit is redundant.

- ④ If this redundancy is reduced then overall bit rate will ↓ and no of bits required to transmit one sample will also be reduced this type of DPCM scheme is known as differential pulse code modulation

② In fact the DPCM works on the principle of prediction. The value of present sample is predicted from the past samples so b/w the predictor may not be exact but it is very close to the actual sample value.



- ⑤ Fig shows the transmission of DPCM system the quantized signal is denoted by  $y(nTs)$  and predicted signal is denoted by  $\hat{x}(nTs)$ . The comparator finds out the difference b/w actual sample value and predicted sample value. This is known as prediction error and is denoted by  $e(nTs) = y(nTs) - \hat{x}(nTs)$ .

thus Error is diff b/w unquantized i/p signal  $x(nTs)$  and prediction of  $\hat{x}(nTs)$ .

The predicted value is produced by using predictor. The Quantizer o/p signal  $y(nTs)$  and previous prediction is added and given as input to prediction signal  $\hat{x}(nTs)$ . This makes the signal more and more close to the actual signal. and it can be encoded by

using small no. of bits. Thus no. of bpts/s sample are reduced in DPCM.

- ① The Quantizer O/p can be written as  
 $e_q(nTs) = \hat{x}(nTs) + q(nTs)$  (1)  
 here  $q(nTs)$  is the Quantization Error

Quantizer O/p can be written as  
 $\hat{x}(nTs) = x(nTs) + e_q(nTs)$  (2)

Substitute (1) in (2)

$$x_q(nTs) = \hat{x}(nTs) + e_q(nTs) + q(nTs)$$

$$\Rightarrow e(nTs) = x(nTs) - \hat{x}(nTs)$$

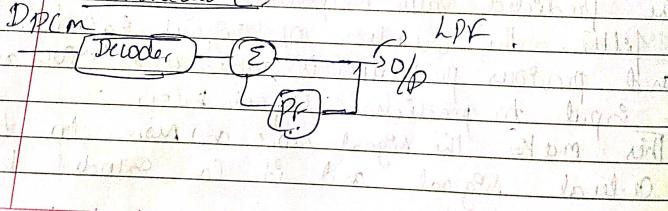
$$e(nTs) = x(nTs) - \hat{x}(nTs)$$

$$x(nTs) = e(nTs) + \hat{x}(nTs)$$

$$\text{Now } x_q(nTs) = x(nTs) + q(nTs)$$

Quantize  $x_q(nTs)$  is sum of original value and Quantized Error  $q(nTs)$ .

Block Diagram :-



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Decoder first reconstruct the Quantized Error signal from incoming of Binary Signal. The predict's output and Quantized error signals are summed up to give the Quantized version of the original signal.

- ② Thus signal at receiver differ from actual signal by Quantize Error  $q(nTs)$  which is introduced primarily in the reconstructed signal.

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## UNIT 03: DIGITAL MODULATION TECHNIQUE

Using carrier we have

ASK  $\rightarrow$  1-mm 0-  
PSK  $\rightarrow$  1-m 0-> m  
FSK  $\rightarrow$  each have assigned freq for 1 and 0.

Design specific (characteristic of any mod technique)

- 01 Data rate (Mbps)
- 02 Maximum probability of symbol error.
- 03 Minimum transmitter power.
- 04 Maximum channel band width (MHz)
- 05 Max immune to noise.
- 06 Minimum circuit complexity.

### Type of Digital Modulation:

- (1) Coherent (2) Noncoherent
- (1) Coherent DM:-

Bas. Digital modul' can be classified into coherent and non coherent techniques. Depending on which, the receiver is equipped with a phase recovery circuit or

The phase recovery circ ensures that the oscillator supplying locally generated carrier wave receiver is synchronized to the oscillator supplying the carrier wave used to originally modulate the incoming data stream in the transmitter.

- a) Coherent DMT are: which employ coherent detection, in coherent detection the local carrier generated at the receiver is phase locked with carrier at the transmitter.  
Thus the detection is done by comparing received noise signal and locally generated carrier it is also called as synchronous detection.
- b) Non coherent :- in which the detection process doesn't need receiver carrier to be phase locked with transmitted carrier

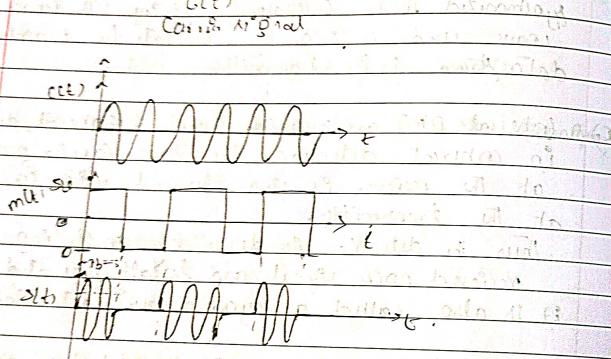
Advantage of such type of system.

- (1) The system become simple but the drawback of such a system is that error probability increases.

### Coherent Binary Modulation Technique:

@. Coherent Binary ASK (On-off key)

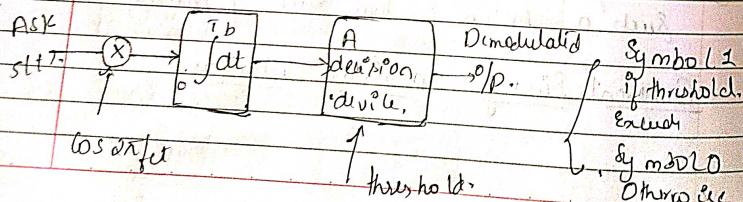
Binary wave  
 in. unipolar.      product modulator       $\rightarrow$  Binary ASK signal  
 form.                   $s(t)$



$$s(t) = \sqrt{2} p_s \cdot \cos(\omega_n)(t) \leftarrow (t_{\text{begin}} - t_1) \cdot$$

$$S(t) = 0 \quad - (D)$$

(b). Coherent Demodulation:



## Cohesive Binary Phase shift key

- in a BPSK, Binary symbols 1 and 0 modulate the phase of the carrier. Let us assume that  $C_0$  is a signal given as  $s(t) = A \cos(\omega_0 t + \phi)$ . Here  $A$  is peak of the sinusoidal carrier.

For the Standard.  $P = A^2$   $A = \sqrt{P}$

now, when the symbol is changed then the phase of the current will also be change by an amount  $180^\circ$  or  $\pi$  radian.

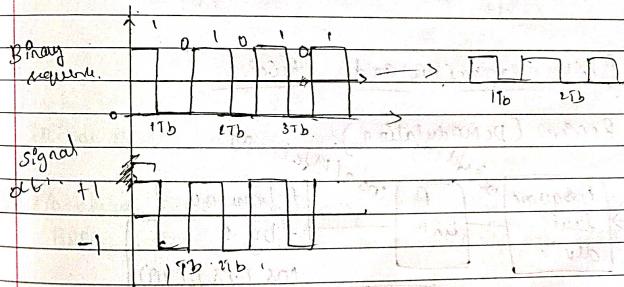
- ⑤ Let us consider for symbol 1.  $s_1(t) = \sqrt{2}p(\cos 2\pi f_1 t)$ .  
 If symbol 0 is, we have  $s_2(t) = \sqrt{2}p(\cos 2\pi f_2 t + \pi)$   
 $s_2(t) = -\sqrt{2}p(\cos 2\pi f_2 t)$ .

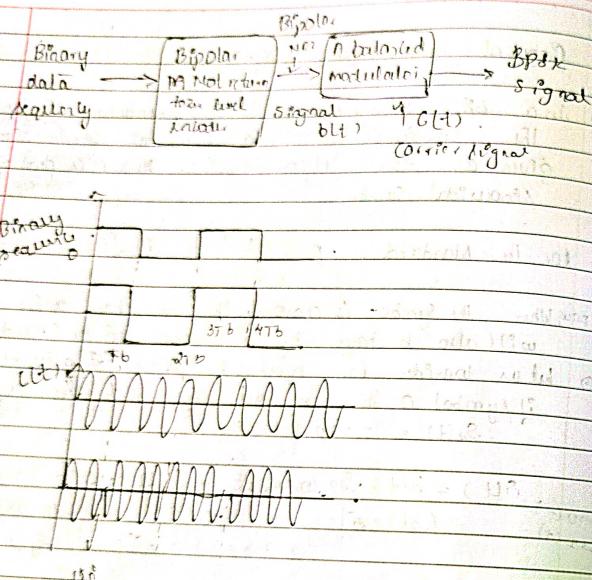
$$S(t) = b(t) \sqrt{a_p} (\cos \omega t + (b(t) = 1))$$

$$(b(t) = 0) \rightarrow b(t) = 0 \Leftrightarrow -\sqrt{2}p \cos 2\pi f t \quad (1)$$

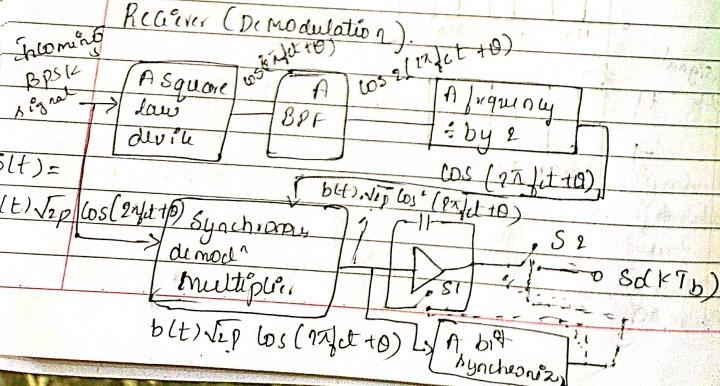
$$b(t) = 1 \rightarrow \sqrt{2}p \cos 2\pi f t$$

$$b(t) = 1 \rightarrow \sqrt{a_p} \cos 2\pi f t$$





### BPSK Transmitter and Receiver.



equations to separate carrier from  $r(t)$

Mathematical Exp.:

$$s(t) = b(t) \sqrt{P} \cos(2\pi f_c t + \theta) \quad \text{---(1)}$$

$$\rightarrow \cos^2(2\pi f_c t + \theta) \leftarrow \text{square law dev.} \quad \text{---(2)}$$

$$\frac{1 + \cos 2(2\pi f_c t + \theta)}{2}$$

$$= \frac{1}{2} + \frac{1}{2} \cos 2(2\pi f_c t + \theta) \leftarrow \text{square law dev.} \quad \text{---(3)}$$

$$(1) \rightarrow \cos 2(2\pi f_c t + \theta) \rightarrow 2\pi f_c \text{ o/p BPF}$$

$$\text{BPF} = \cos(2\pi f_c t + \theta) \quad \text{---(4)}$$

$$= b(t) \sqrt{P} \cos(2\pi f_c t + \theta) \times \cos(2\pi f_c t + \theta) \rightarrow \text{o/p o/p BPF}$$

$$= b(t) \sqrt{P} \cos^2(2\pi f_c t + \theta)$$

$$= b(t) \sqrt{P} \left( \frac{1 + \cos 2(2\pi f_c t + \theta)}{2} \right)$$

$$= b(t) \sqrt{P} \left( \frac{1 + \cos 2(2\pi f_c t + \theta)}{2} \right), \quad \text{---(5)}$$

$S_2 \rightarrow$  decision making dev.

- (a) Fig. shows Block diagram of BPSK receiver. The transmitted BPSK signal is given as  $b(t) \sqrt{P} \cos(2\pi f_c t + \theta)$ .

- (b) This signal undergoes a phase change depending upon time delay from transmitter end to a receiver end.

- Q This received signal, carrier is separated because this is coherent detection.
- Received signal is allowed to pass through a square law device. Output of square law device is given as Eq(1)
- Q Here  $y_c$  represents a DC level, this signal is then allowed to pass through a BPF whose pass band is centered around  $\omega_{fc}$ . BPF removes the DC level of  $y_c$  and at the o/p we obtain eq(2)
- Q This signal is having frequency  $\omega_{fc}$ , hence it is passed through a freq. divider by 2 thus @ the o/p of freq. divider we get a carrier signal whose freq is  $\omega_c$  as given in Eq(3)
- Q The synchronous /coherent DM multiplies the I/P signal and the received carrier hence at the o/p of multiplier we get eq(4).
- Q This signal is then applied to the bit synchronizer and integrator. The integrator integrates the signal over 1bit period. The bit synchronizer takes care of starting and ending time of a bpt.
- Q At end of bpt dur of 1B bit synchronizer closes switch S1 temporarily. This connects the O/p of S to the decision logic. The synchronizer then opens switch S2 and switch

- 1 → Integrator, o/p  
0 → 0
- S1 is closed temporarily.
- Q The integrator then integrates the next bit. Let us assume that one bit period is  $T_b$  contains integral  $\frac{1}{2}$  cycles of the carrier. This means that one bit phase change occurs of the carrier only at zero crossings. This is shown in Fig(1).
- 
- Frequency Shift Key :-
- FSK is a type of Digital Modulation technique in which the frequency of signal is varied to represent the p/p digital data. However Amplitude and phase of modulated carrier signal remains constant.
- Q The FSK signal may be viewed as a sum of 2 unmodulated ASK signals but with const amplitude and with carrier freq  $\omega_{fc1}$  for transmitting '0' and other with another carrier freq  $\omega_{fc2}$  by transmitting '1'.
- FSK signal can be expressed as

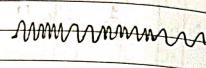
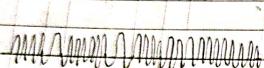
$$FSK(t) = \begin{cases} \sin \omega_1 t & \text{for binary '0'} \\ \sin \omega_2 t & \text{for binary '1'} \end{cases}$$

$$\omega_1 = \omega_0 + \Delta\omega, \quad \omega_2 = \omega_0 - \Delta\omega$$

1 0 1 1 0 1 0 1 1 1

Data waveform 1 0 1 1 0 1 0 1 1 1

UP-NRZ



Interpretation

- ① When the i/p binary data changes from 1 to 0 and vice versa, the BFSK signal freq shifts from  $f_1$  to  $f_2$ , and vice versa.
- ② It can be seen that when the i/p data changes from a logic 1 to 0 or vice versa, there is an abrupt phase discontinuity in the analog binary FSK signal.
- ③ Continuous phase frequency shift key is a binary FSK, where  $f_1$  and  $f_2$  are generated from the centre frequency  $f_c$  by an 'Exalt' multiple of  $\Delta$ . On half of the bit rate  $F_b$ , this ensures a smooth phase transition in the BFSK signal when it changes from  $f_1$  to  $f_2$ .

Polar +ve un. -ve

The time duration of one bit is same as the symbol time duration of 0 of the binary FSK signal. Hence the bit rate  $F_b$  equals the baud rate.

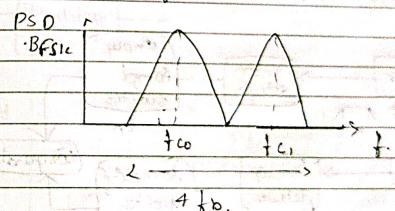
④ The minimum BW for BFSK signal is given as

$$B_{BFSK} = |(f_{c1} + f_{c2}) - (f_{c1} - f_{c2})|$$

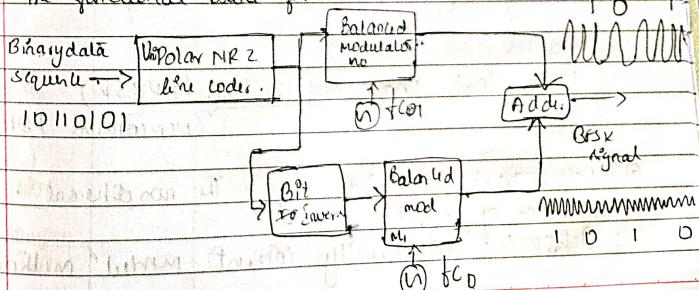
$$= |(f_{c1} - f_{c2})| + 2f_b$$

⑤ The difference  $f_{c1}$  and  $f_{c2}$  ( $f_{c1} - f_{c2}$ ) is chosen to be equal to  $2f_b$  then BW of BFSK is  $\frac{2}{3}f_b$ .

$$B_{BFSK} = \frac{2}{3}f_b$$

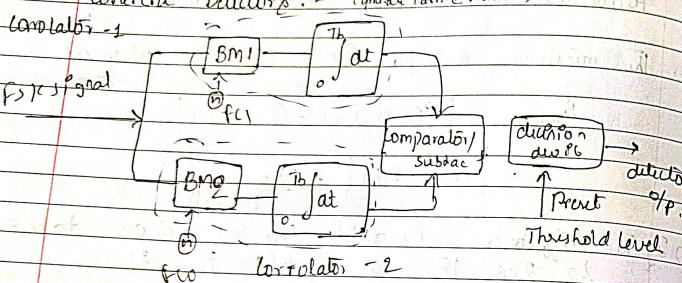


The functional Block of FSK :-

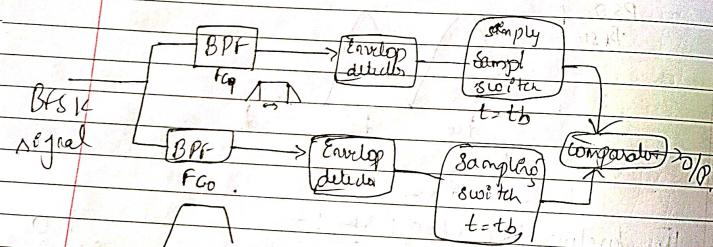


Detectors :-

Coherent Detectors :- (same as receiver)



NON-Coherent BFSK



Differential phase key shifting (DPSK)  
(Noncoherent DPSK)

① Differential phase shift keying is the noncoherent version of BPSK.  
DPSK is a differentially coherent modulated method.

$$\begin{array}{l|l} 0 \wedge 0 \rightarrow x \\ x \wedge 0 \rightarrow 0 \\ x \wedge 1 \rightarrow x \end{array}$$

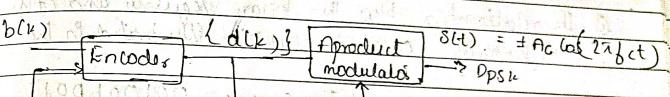
$$1 \wedge 1 = 1 = 0 \wedge 0$$

DPSK does not need a synchronous carrier at the demodulator.

The i/p sequence of binary bits is modified such that next bit depends upon the previous bit.

Therefore in the receiver the previous received bits are used to detect the present bit.

Generation of DPSK



$$S(t) = \pm A_c \cos(2\pi f_ct)$$

$$A_c \cos(2\pi f_ct)$$

Binary data.	0	0	1	0	0	1	0	0	1
Differential binary data (x no)	1	*	0	1	1	0	0	1	0

Phase of DPSK	0	π	0	π	0	π	0	π	0
shifted diff. (mod. dat.)	1	0	0	1	0	1	0	0	0

Phase of DPSK	0	π	0	0	π	0	0	π	0
shifted (dat.)	1	0	0	1	0	0	1	0	0

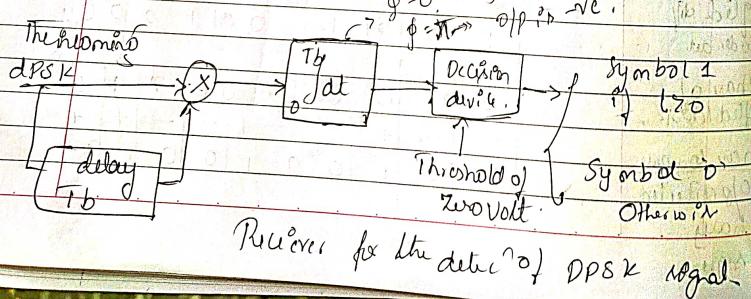
Phase (original)	-	-	+	-	+	-	+	-	+
binary	0	0	1	0	0	1	0	0	1

Phase (original)	0	π	0	0	π	0	0	π	0
binary	0	0	1	0	0	1	0	0	1

A schematic arrangement for generating DPSK signal is shown in fig

- ① Data stream  $B(x)$  is applied to the I/P of the encoder. The O/P of encoder is applied to one I/P of product modulator. Other I/P of this product modulator is sinusoidal carrier of fixed amplitude and frequency applied.
- ② The relationship b/w the binary sequence and P+1 differentially encoded version illustrated in the table
- ③ For a assumed data sequence 0010010011 in this illustration, it has been assumed that encoding has been done in such a way that transition in the binary sequence w.r.t previously encoded bit is represented by a symbol '0' and no transition from symbol 1.
- ④ It may be noted that extra bit symbol ± is arbitrarily added as an initial bit. This is essential to determine the encoded sequence.

Detection of DPSK :-



Rules for the detection of DPSK signal

The detection of DPSK as shown in the fig. The received DPSK is applied I/P of multiplier other I/P of multiplier, a delayed version of received DPSK signal.

The delayed version of received DPSK signal is seen shown in the 4<sup>th</sup> row of the table.

- ⑤ The I/P of diff. is proportional to  $\cos \phi$  here  $\phi$  is the difference b/w the carrier phase angle of the received DPSK signal & its delayed version, measured in the last bit interval.
- ⑥ The phase of the DPSK signal and its delayed version have been known in 3<sup>rd</sup> and 5<sup>th</sup> row respectively. The phase diff b/w 2 sequences in each bit interval is used to determine the sign of the phase. Comparative opp.
- ⑦ When  $\phi$  is 0 the Integrator opp is true, when  $\phi \neq 0$  the Int. opp is -ve. By comparing the Integrator output to the decision level of 0V, the decision device can reconstruct a binary sequence by assuming a symbol 0 for +ve opp and a symbol 1 for -ve opp.

The reconstructed Binary data is shown in last row of the table. It is true seen that in absence of noise the receiver can construct the binary data exactly.

DPSK may be known as non coherent version of PSK

It may also be noted that 'reconstructed' is invariant with the value of initial bit in encoded data.

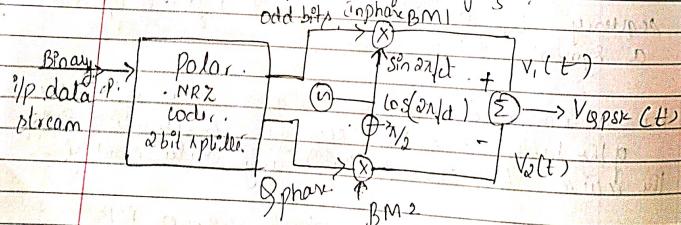
#### Advantages :-

- DPSK doesn't need carrier at the receiver end. This means that circuit complexity is reduced.
- The BW requirement of DPSK is reduced compared to BPSK.

#### Disadvantages :-

- Noise interference in DPSK is more.
- Because DPSK uses 2 successive bits for its reception, error in the 1st bit creates errors in the 2nd bit. Therefore error propagation in DPSK is more.

#### Quadrature phase shift keying:-



$$V_{QPSK}(t) = \sqrt{2} [ I(t) \sin \omega_0 t - Q(t) \cos \omega_0 t + I(t) \sin 2\pi f_c t + Q(t) \cos 2\pi f_c t ]$$

$$V_{QPSK}(t) = \sqrt{2} [ I(t) \sin \omega_0 t - Q(t) \cos \omega_0 t ]$$

(135°), 3π/4

10

-sin 2πf<sub>c</sub>t

00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

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3π/4 (-135)

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01

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3π/4 (-135)

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01

π/4 (+45)

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11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

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00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

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00

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π/4 (+45)

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00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

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11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

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00

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01

π/4 (+45)

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-sin 2πf<sub>c</sub>t

11 (90)

π/4 (+45)

+cos 2πf<sub>c</sub>t

-sin 2πf<sub>c</sub>t

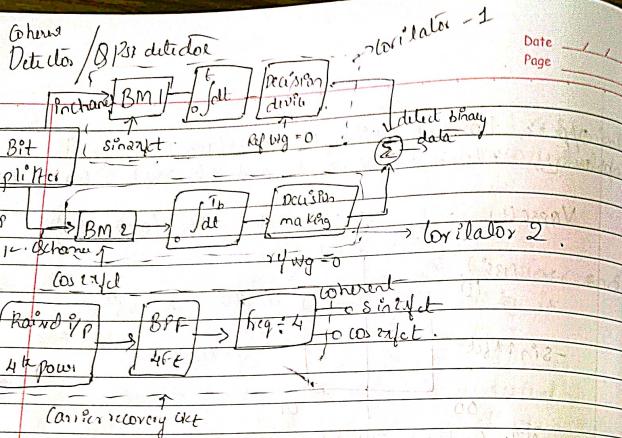
00

3π/4 (-135)

-cos 2πf<sub>c</sub>t (90)

01

π/4 (+45



- QPSK -> Home delay of  $T_b$  before BMS  
↳ received  $\pm 180^\circ$  of transmitted (amplitude).
- ① Consider a QPSK system having bit rate of 9600 bps/sec. Determine the BW required by QPSK signal using raised cosine filter with roll-off factor of 0.35 and 0.3 ( $\alpha$ ).

> Rule:  $BW = 2B_{PSK}$  and  $\alpha$ .

$$\text{Signal BW} = \frac{1}{2} \times \text{Symbol rate} \times (1 + \text{roll-off factor})$$

$$B_{PSK} = \frac{1}{2} \times 9600 \times (1 + 0.35)$$

$$= 6480 \text{ Hz}$$

$$= 4800 \times 1.5$$

$$= 7200 \text{ Hz}$$

### ② M-ary PAM / M-ary D.M techniques

-> In Binary PSK we transmit each data bit individually where i/p bit rate  $F_b = 1/T_b$ .

In multi level M-array one of the  $M$  possible signals transmitted during each bit interval of  $T_b$  second.

③ QPSK is one of the two efficient DM techniques that makes use of Quadrature multiplexing. Just like BPSK, in QPSK too the info is carried in the phase of transmitted carrier signal but in QPSK we combine 2 successive bits in a bit stream to form a symbol.

④ With 2 bits there are 4 possible combinations depending on which of the 4 2-bit symbols develops in i/p bit data stream.

We transmit one or more of 4 linearly spaced  $T_b$  bits differing in phase by  $90^\circ$  or  $180^\circ$  with another. Then in a QPSK modulator each bit generates 4 possible phases ( $+45^\circ, +135^\circ, -45^\circ, -135^\circ$ ) hence the name Quadrature (4 phases).

⑤ Mathematically Signal for 1 symbol duration consisting of 2 bits each can be expressed as:

$$S_{QPSK}(t) = \begin{cases} \sin 2\pi f_c t - \frac{\pi}{4} & 00 \\ \sin 2\pi f_c t - \frac{\pi}{4} & 01 \\ \sin 2\pi f_c t + \frac{\pi}{4} & 10 \\ \sin 2\pi f_c t + \frac{\pi}{4} & 11 \end{cases}$$

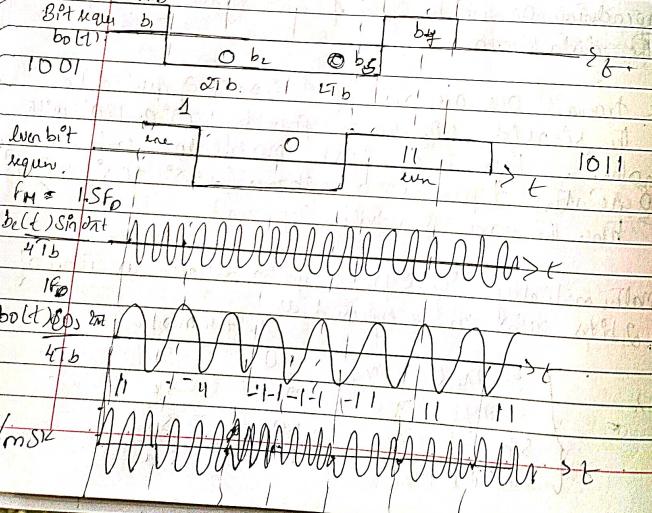


### Minimum Shift Keying: - (MSK)

- ① The bandwidth requirement of QPSK is high but they have other side effects. for ex:- filling all, the amplitude of the waveform.
- ② MSK overcomes these problems. In MSK the QPSK waveform is continuous in phase and hence there are no abrupt changes in amplitude.
- ③ The side lobes of MSK are very small hence BPF is not required.

To avoid inter-channel interference. (BPF is not req in other)

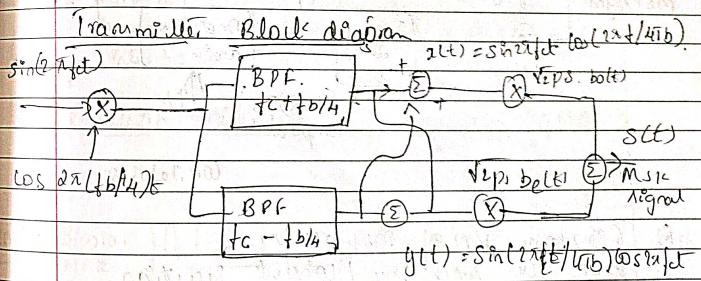
Bit sequence	odd even	0, 0, 0, 0, 1, 1, 1, 1, 0	$\rightarrow 2T_b$
Bit map	$b_1$	$b_2$	$b_3$
$b_0(t)$	0	$b_2$	by



### Corresponding MSK

- Fig shows the waveform of MSK. The binary bit sequence is  $b(t)$ .
- Two waveform are generated for odd and even bits.  $b_0(t)$  represent odd bits and  $b_1(t)$  represent even bits.
- ④ The duration of each bit in  $b_0(t)$  and  $b_1(t)$  is  $2T_b$ .  $T_s = 2T_b$ .
  - ⑤ The waveform  $b_0(t)$ ,  $b_1(t)$  have an offset of  $T_b$ . This offset is crucial in MSK.
  - ⑥  $b_0(t)$  is multiplied by  $\sin(2\pi t/4T_b)$  and odd.  $b_1(t)$  is multiplied by  $\cos(2\pi t/4T_b)$ .

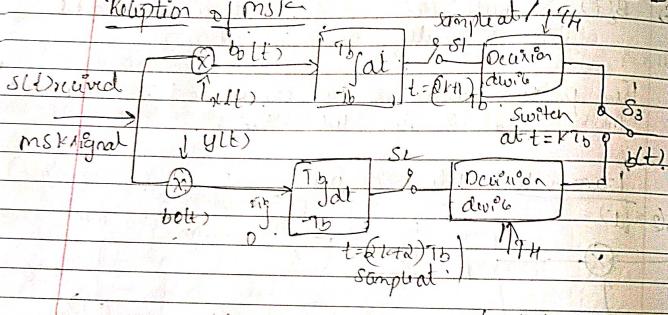
Then product waveform are known and the transmitted MSK signal is represented in  $V_{MSK}$ .



### MSK Demodulation

- Fig shown - BDP msk.
- ① 2 sine signal sin(2πf<sub>c</sub>t) and cos(2πf<sub>c</sub>t) are mixed. The BPF at this point only passes sum and difference frequencies. The o/p of BPF are the added and subtracted such that signals x(t) and y(t) are generated.
  - ② Signal x(t) is multiplied by V<sub>pp</sub> × b(t) and y(t) is multiplied by V<sub>pp</sub>. The o/p of multiplication is then added to give final MSK signal.

Reception of msk



- ③ FRS shown. BDP msk receiver.
- MSK uses synchronous coherent decapsulation. The signal x(t) and y(t) are multiplied with the received MSK signal.

here x(t) and y(t) have same value as shown in

Transmitter block diagram:

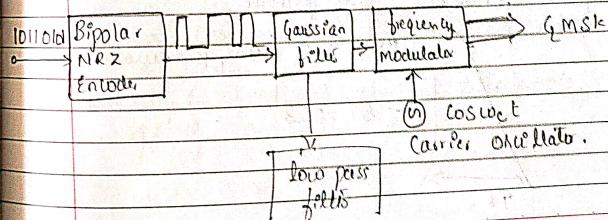
- ① The o/p of multipliers are bold and belt. The f integrates over the period of  $2T_b$ , for the upper code states. The sampling occurs in  $(K+2)T_b$ . Then the decision device decides between  $V \pm 1$ .

- ② similarly in lower oscillator, o/p is belt. The o/p of e decision device are toggled by  $T_b$ . The word has s operator @  $T = K T_b$  and simply multiplies the 2 (bold, belt) oscillator o/p.

Advantages :-

- ① The bandwidth is moderate than QPSK.
- ② MSK does not have amplitude varia.
- ③ Power spectral density wider mainlobe. Interchannel interference is reduced.

Gaussian Minimum Shift Keying:- (GMSK).



- Q. MSK is a continuous phase mod scheme where the modulated carrier contains no phase discontinuity and frequency change occur at twice carrier bit rate.

MSK is unique due to the relationship between frequency and symbol rate.

The difference between a logic one and zero is always equal to half the data rate. In other words,  $B_f(m_1) = 0.5$  for MSK.

Complications with MSK: The fundamental problem with MSK is, the spectrum is not compact enough to realize data rate approaching the RF channel B.W.

A plot of the spectrum for MSK reveals sidelobes extending well above the data rate.

For wireless data transmission system, which require more efficient use of RF channel Band width, is necessary to reduce the energy of the MSK sidelobes. Because R is not adequate for multi user wireless com application.

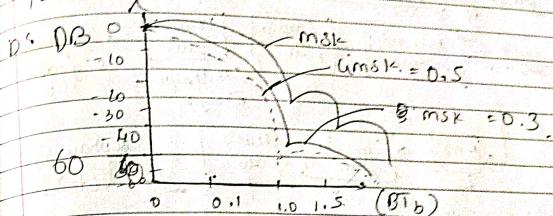
It requires very stringent specification with regard to adjacent channel interference.



$$B_f = 0.5 \text{ (BW, } BT = 0.5\text{)}$$

$\therefore BT = 0.3$ .

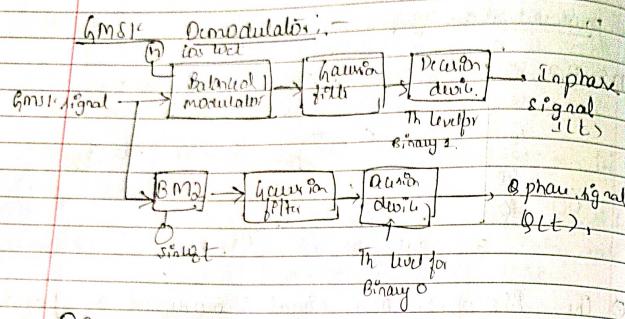
#### power spectral density for MSK



- Q. The PSD of an MSK signal is modified by passing the modulated data stream through a dispersive LPF such as Gaussian filter before carrier modulation.
- Q. The Gaussian filter has narrow BW with sharp cutoff characteristics and negligible over. in its impulse response.
- Q. Such a modified MSK using Gaussian filter is called GMSK, or modulation.

#### Advantages of Gaussian filter

- Q1. Reduct in the transmitted BW of the signal.
- Q2. Uniform envelope.
- Q3. Spectral containment i.e. Reduct of side lobe level of the power spectral.
- Q4. Reduct in adjacent channel interference.
- Q5. Suppression of out-of-band noise.



QAM:-

- ① Here in multilevel M-array DM technique one of the  $M$  possible signal elements are transmitted during each interval to send  $n$  bits.
- ② The no. of possible signal levels is given by  $2^m$  where  $m$  is an integer, which represents the no. of bits in each symbol.
- ③ The signal elements are distinguished by different pulse amplitude level. In "bandpass m-array digital mod"  $M$ -signal element can differ in their amplitude level as in the case of marray ASK or in the frequency as in the case of marray FSK or in the phases and the phase of marray PSK.
- ④ In M-array DM, m-signal elements can differ in their amplitude levels as well as in their phases.

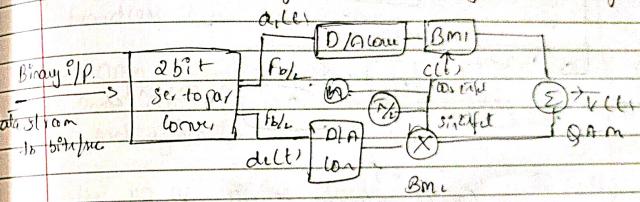
resulting Marray Quadrature Amplitude Modem (QAM)

The QAM signal can be expressed as,  $s(QAM)$

$$s_{QAM}(t) = d_1(t) \cos(2\pi f_c t + d_2(t) \sin(2\pi f_c t))$$

$$d_1(t) = 0 \text{ if } d_1(t) = 1 \rightarrow \text{data 1 (Binary data 0 and 1)}$$

- ⑤ For an  $q$  of QAM system let consider to transmit a  $2^q$  symbol for every  $1$  bit. Here we have  $2^q = 16$  different possible symbols which are to be able to generate 16 distinguishable signals.



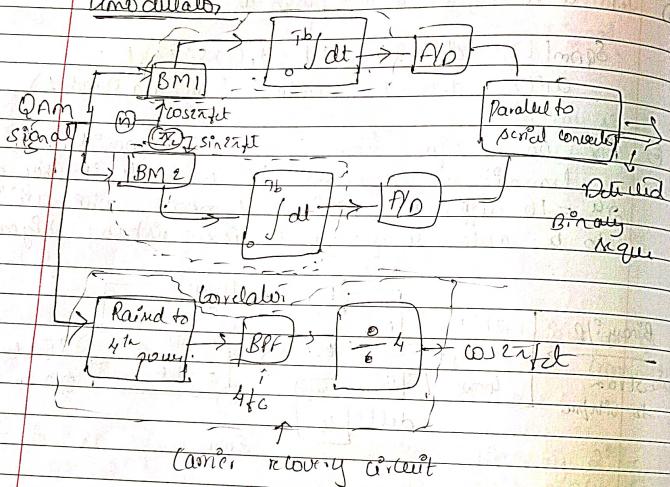
- ⑥ The Ifp is a data stream of binary digits. @ a rate of  $f_b$  bits/sec.

- ⑦ The data stream is converted into 2 separate data streams of  $f_b/2$  bits each, by taking alternate bits for the 2 data streams.

- ⑧ ASK / PSK data is ASK modulated with carrier cos effect. Other data stream is PSK modulated by the same carrier signal shifted by  $90^\circ$ . The Q modulated signals are then added.

and transmitted.

### Demodulator



- ① Fig shows the block schematic of QAM de-coherent demodulator. It is similar to the QPSK coherent demodulator.

A local set of quadrature carrier signal is recovered for synchronous detection by raising the received signal to the 4<sup>th</sup> power.

- ② The component/freq comp @ 4fc is extracted using a BPF tuned @ 4fc and then divides the frequency by 4. The available quadrature comp. Signals are

applied to 2 correlators each comprising of a Bm and an integrator.

- ③ The original 6 bits are then recovered by using a local converter and parallel to serial converter.

QAM is an efficient way to achieve high data rate with a narrow band channel by increasing the no of bits / symbol. And uses a combination of amplitude and phase modulation. Higher level QAM  $\rightarrow$  64 QAM or more. BW efficient and are used for high data rate transmission applied in terrestrial microwave digital radio, Digital video broadcast (cable and modem).

- ④ A QAM modulator uses 4 diff amplitude and 16 diff phase angles. How many bits does it transfer per each symbol?

$\Rightarrow$  The no of possible levels / symbol is the multiplication of the no of different amplitude level and no of diff phases per QAM.

For 64m 4 diff amplitude and 16 diff phases, the no of possible states / symbol.

$$M = 4 \times 16 = 64$$

$$\text{no of bits / symbol. } M = 2^n = 64 \Rightarrow n = 6$$

Hence all 6 bits will be transmitted / symbol.

- (3). Compute and tabulate the results for BW efficiency of marray FSK signal for / and m-array PSK signal for  $M = 2, 4, 8, 16, 32, 64$ .  
 : Need to find BW efficiency.

$B_{FSK}$  for QAM

$B_{PSK}$  for QAM

$\log_2 M$   $\log_2 M$

$M = 2, 4, 8, 16, 32, 64$

$M = 2 \quad 1 \text{ bit/sec/Hz} \quad 0.5 \text{ sec} \quad 1 \text{ bit/sec/Hz}$

$M = 4 \quad 2 \text{ bits/sec/Hz} \quad 0.25 \text{ sec} \quad 2 \text{ bits/sec/Hz}$

$M = 8 \quad 3 \text{ bits/sec/Hz} \quad 0.15 \text{ sec} \quad 3 \text{ bits/sec/Hz}$

$M = 16 \quad 4 \text{ bits/sec/Hz} \quad 0.075 \text{ sec} \quad 4 \text{ bits/sec/Hz}$

$M = 32 \quad 5 \text{ bits/sec/Hz} \quad 0.0375 \text{ sec} \quad 5 \text{ bits/sec/Hz}$

$M = 64 \quad 6 \text{ bits/sec/Hz} \quad 0.01875 \text{ sec} \quad 6 \text{ bits/sec/Hz}$

Error performance of 8PSK

- ① for an 8PSK system operating @ 20mgs bits/sec

with a carrier to noise power ratio of 11dB. Determine

the minimum SNR required to achieve a probability of

error of  $10^{-6}$ . The corresponding minimum

EB ratio for an 8PSK system is a 19dB

$$f_b = 20M \text{ bits/sec} \quad \text{Carrier to noise ratio} = 11\text{dB}$$

$$\text{SNR} = ?$$

Energy per bit to noise power ratio

It is used to compare 2 or more Digital mod' system that uses different marray mod's technique.  
 (FSK, PSK, QAM) operating @ different transm rate  
 ( $B \text{ bits/sec}$ ) it is a simple and accurate comparison  
 of their error performance

$$E_b(\text{dB}) = \frac{C(\text{dB})}{N} + B(\text{dB})$$

$$B = \frac{E_b(\text{dB}) - C(\text{dB})}{f_b}$$

$$= 19 - 11$$

$$\frac{B}{f_b} = 3 \text{ dB} = \text{antilog}(\frac{3}{10}) \approx 2$$

$$B = 20 \text{ mbit}$$

$$B = 40 \text{ MHz}$$

Digital Modulation & Application

FSK ② Addressing, Paging Service.

BPSK ② Telemetry

QPSK ② GPRS, Bluetooth, Satellite com, Digital video broadcasting

8PSK ② Satellite comm.

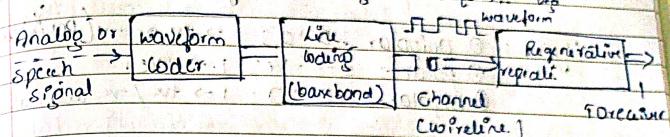
16/32 PSK ② Microwave digital radio links, Digital video broadcasting

64 PSK ② Digital VB, Set-top box, Modem

MSK/GMSK ② Mobile, cellular com (GSM/CDMA)

#### UNIT 04

Base Band Transmission  
(Line Coding techniques)



#### Desirable properties of line coders:-

WKT: How to convert an Analog signal to a digital data sequence of 0's & 1's (D). Either by using wave form encoders such as PCM, AMODUL etc.

The Digital o/p comprising of a long sequence of binary symbols 1's and 0's. It is neither uniform nor suitable for direct transmission over the common channel.

Hence Binary symbols are required to be converted into electrical pulses or waveform having finite voltage levels so as to make it compatible for transmission over the common channel.

Line coding is a process by which Digital symbols are transformed into waveforms that are compatible with the characteristics of the Base band channel.

QAM is also used in satellite TV and telephone transmission.

Unipolar :- If 1 of tv includes the mark to

### Properties of line code

#### D) Transmission power efficiency

- Types :-  
① Unipolar :  $0 \rightarrow 0$ ;  $1 \rightarrow +v$  or  $-v$  (unipolar)  
② Polar :  $0 \rightarrow -ve$ ;  $1 \rightarrow +ve$  (polar)  
③ Bipolar ;  $0 \rightarrow 0$ ;  $1 \rightarrow +ve/-ve$  (alternately)

a. UP :- Represented by only 1 level  $+ve \rightarrow v$   
An UP can be  $(UP-RZ)$  or  $(UP-NRZ)$

b. Polar :- Represented by 2 distinct non zero  
symmetrical but opposite voltage levels ( $+v, -v$ )

c. Bipolar :- Also known as Pseudoternary (3V<sub>TG</sub> level)  
( $+v, -v, 0v$ ) or alternate mark inversion

D) TPE Efficiency :-  $TPE = \frac{\text{Power polar}}{\text{Power unipolar}}$

E) TDO :- TV<sub>TG</sub> level can be categorized as either unipolar  
or polar. The TPE can be ↑ by using  
polar V<sub>TG</sub> levels.

D2. Duty cycle :- Ratio of bit duration for which the binary pulse  
is high to total transmission voltage into the entire  
bit duration. It is measured at the transmitter  
end & it is same as receiver end.

In non return to zero the duty cycle is 100%  
thus the binary pulse is maintained high for

the entire bit duration so binary pulse is maintained  
low for binary data '0' for entire bit dur.

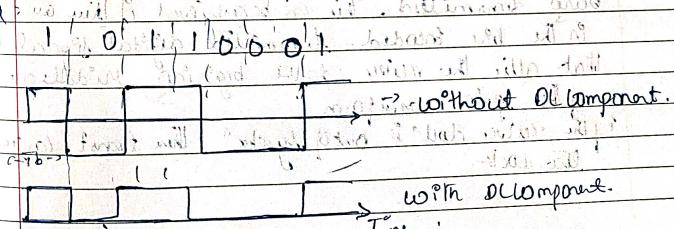
D) In return to zero line coding format the binary  
pulse is maintained high for binary data 1  
for 50% of the entire bit dur only.

When the binary pulse is maintained low for binary data  
0 for the entire bit duration, so the duty cycle  
is less than 100% of specified bit duration

#### D3. DC Component

Some common system like telephone system a telephone  
line cannot pass frequencies below 300 Hz and a  
long distance link using transformer cannot allow  
transmission of frequency along 0 is called DC component.

This effect is clear when the V<sub>TG</sub> level is constant for  
whole the frequency spectrum shows very low freq  
component therefore we need a line coding technique  
with no dc component.



DL Wandering → change in Amplitude over time

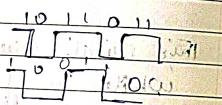
③ In "Digital Iam" a long sequence of either '1's or '0's produced a word in which a receiver may loose the Amplitude reference. This reference is needed for clear cut discrimination of received '1's and '0's in the receiver.

Similar word may also arise when there is significant fluctuation in the '1' and '0's transmitted. This word causes a drift in the baseline, called baseline wandering. This makes difficult for the receiver to decode received data correctly.

#### ④ Bandwidth requirement.

It is desirable that BW of a line code should be as small as possible. This allows more information to be transmitted / unit channel bandwidth.

#### ⑤ Self synchronization



A self digital signal includes timing information in the data being transmitted. This can be achieved if the data transmitted is encoded. Transmitted digital signal that allow the receiver to lock beginning, middle or end of the pulse waveform. If the receiver clock is out of sync then transmit correct line deck.

Explain the working of digital self synchronization.

#### ⑥ Immunity to noise and interference.

The line coding format should be capable to have minimize the effect of noise and interference. This will enable to have minimum errors introduced in transmitted data due to external noise and interference.

#### ⑦ Error detection capability.

It is desirable that line code should have built-in error detection capability which should enable to detect the errors and correct them that occur during transmission.