

V.S.B ENGINEERING COLLEGE,KARUR-639111

ASSIGNMENT-4

Name: ABIRAMI R

Project Title: Smart Farmer- IoT Enabled Smart Farming Application

Project Domain: Internet of Things

1. Write Code and connections in wok Wi for ultrasonic sensor. whatever distance is less than 100 CMS send "Alert" to IBM cloud and display in device recent events.

Solution:

```
//Pins

const int TRIG_PIN = 7 ;
const int ECHO_PIN = 8;

//Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;

void setup() {

// The Trigger pin will tell the sensor to range find
  Pin Mode(TRIG_PIN, OUTPUT);
  digital Write(TRIG_PIN, LOW);

//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
  pinMode(ECHO_PIN, INPUT ) ;

// We'll use the serial monitor to view the sensor output
```

```

Serial.begin(9600)
}

void loop()
{ unsigned long
t1;

unsigned long t2;
unsigned long pulse_width;
float cm;
float inches;

// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);

// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN )==0 );

// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after ~70 min
t1= micros ();
while (digitalRead(ECHO_PIN) == 1);
t2= micros ();
pulse_width = t2-t1;

// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (~ 340m/s)
cm=pulse_Width / 58 ;

```

```

inches = pulse_width/148.0;

// Print out results
if (pulse_width > MAX _
DIST ){Serial.println("Out of
range");
} else
{ Serial.println("*****");
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);

if( cm < 100 ){
    //while(true){
        Serial.println("Alert!!");
    //}
}
Serial.print("*****");
}

//wait at least 1000ms before next measurement
Delay(1000);
}

```

Output:

1.If the distance is less than 100 CMS ,it alert

WOKWI

SAVE

SHARE

Docs

hc-sr04.ino

diagram.json

Library Manager

```

1 // Pins
2 const int TRIG_PIN = 7;
3 const int ECHO_PIN = 8;
4
5 // Anything over 400 cm (23200 us pulse) is "out of range"
6 const unsigned int MAX_DIST = 23200;
7
8 void setup() {
9
10 // The Trigger pin will tell the sensor to range find
11 pinMode(TRIG_PIN, OUTPUT);
12 digitalWrite(TRIG_PIN, LOW);
13
14 //Set Echo pin as input to measure the duration of
15 //pulses coming back from the distance sensor
16 pinMode(ECHO_PIN, INPUT);
17
18 // We'll use the serial monitor to view the sensor output
19 Serial.begin(9600);
20 }
21
22 void loop() {
23
24 unsigned long t1;
25 unsigned long t2;
26 unsigned long pulse_width;
27 float cm;
28 float inches;
29

```

Simulation

00:00.599 62%

The Measured Distance in cm : 227.10

Activate Windows

Go to Settings to activate Windows.

2.Simulation and code execution:

WOKWI

SAVE

SHARE

Docs

Simulation

Code

Simulation

Code

```

1 // Pins
2 const int TRIG_PIN = 7;
3 const int ECHO_PIN = 8;
4
5 // Anything over 400 cm (23200 us pulse) is "out of range"
6 const unsigned int MAX_DIST = 23200;
7
8 void setup() {
9
10 // The Trigger pin will tell the sensor to range find
11 pinMode(TRIG_PIN, OUTPUT);
12 digitalWrite(TRIG_PIN, LOW);
13
14 //Set Echo pin as input to measure the duration of
15 //pulses coming back from the distance sensor
16 pinMode(ECHO_PIN, INPUT);
17
18 // We'll use the serial monitor to view the sensor output
19 Serial.begin(9600);
20 }
21
22 void loop() {
23
24 unsigned long t1;
25 unsigned long t2;
26 unsigned long pulse_width;
27 float cm;
28 float inches;
29
30 // Hold the trigger pin high for at least 10 us
31 digitalWrite(TRIG_PIN, HIGH);
32 delayMicroseconds(10);
33 digitalWrite(TRIG_PIN, LOW);
34
35 // Wait for pulse on echo pin
36 while (digitalRead(ECHO_PIN) == 0) {}
37
38 // Measure how long the echo pin was held high (pulse width)
39 // Note: the maximum timeout will overflow after ~18 ms
40 t1 = micros();
41 while (digitalRead(ECHO_PIN) == HIGH) {}
42 t2 = micros();
43 pulse_width = t2 - t1;
44
45 // Calculate distance in centimeters and inches. The unitary
46 // for time is us at the speed of sound (340 m/s)
47 cm = pulse_width / 58.8;
48 inches = pulse_width / 148.0;
49
50 // Print out results
51 if (pulse_width < MAX_DIST) {
52 Serial.println("Out of range");
53 } else {
54 Serial.println("The Measured Distance in cm : ");
55 Serial.println(cm);
56
57 // Print out results
58 Serial.println("The Measured Distance in inches : ");
59 Serial.println(inches);
60 }
61
62 // Wait at least 100ms before next measurement
63 delay(100);
64 }
65

```

