TABLE TENNIS USING HAND GESTURE-PONGER

**DESIGN PROJECT– 1 REPORT**

***Submitted by***

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***in partial fulfillment for the award of the degree of***

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****

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**BONAFIDE CERTIFICATE**

Certified that this project report **Table Tennis Using Hand Gesture** is the bonafide work of **DANI N (21113004) & DHARSHAN R E (21113049)** who carried out the project work under my supervision during the academic year 2**022-2023**.

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**ABSTRACT**

Hand motion detection technology is a cutting-edge computer vision application that could revolutionize table tennis. Unlike the traditional inputs such as keyboard & mouse and controller, this technology captures live footage of players, tracks their hand movements and landmarks, and uses a deep learning algorithm to identify specific gestures associated with various game functions. By in real-time by providing them a constant efficiency, this recognition technology is attracted players and improves their techniques and their overall gaming experience. In addition, it can make table tennis more accessible to people with mobility places, allowing them to participate in the game using hand movements instead of physical movements. The potential benefits of this technology are not limited to table tennis. However, it is important to note that this technology and game have some limitations such as precise control, the possibility of error detection, and the cost of implementation. But this hand gesture technology can interact with normal people and they can easily understand and can play the game.

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# LIST OF ABBREVIATIONS

|  |  |
| --- | --- |
| CNN  RT | Convolutional Neural Network  Regression Tree |
| FGPA | Field Programmable Gate Array |
| VHDL | Very High-Speed Integrated Circuit |
|  |  |
|  |  |

**CHAPTER 1 INTRODUCTION**

## Overview

Hand Gesture Table Tennis is a game that tracks and recognizes the hand movements of players in a table tennis game. The webcam records video players during gameplay and processes the footage with computer vision technology that recognizes hand movements related to various game functions, e.g. such as hitting the ball and returning the ball. The game offers players a real-time experience of their performance. This technology can be used for more than table tennis and is also accessible to the disabled. Overall, the game of table tennis makes the game more interesting and enjoyable for all skill levels.

## The Motivation of the Project

The motivation for creating a table tennis game using hand gestures could provide a deep and interactive gaming experience that does not require physical paddles. By using hand gestures, players can have a more natural and easy way of interacting with the game, and it can also promote physical activity and exercise as players move their hands and arms to play this game. This type of game could be a fun and engaging way to challenge players’ hand-and-eye coordination and reflexes for hitting the ball.

## Problem Definition and Scenarios

In the problem definition, the main point is the lack of a natural and easy way of interacting with the game. Difficulty in executing the shots in our direction and creating a game where players can control a virtual table tennis game using hand gestures easily, instead of physical paddles. Therefore, the problem is to create a robust system that can accurately track hand gestures and translate them into precise racket movements to provide the best and most engaging table tennis experience.

## Organization of the Report

The report consists of 10 chapters. This report begins with a preface to the motives and the project being undertaken. Following that in the second chapter, exemplifications and literature reviews are bandied. We discuss the objects of the proposed affiliated work system and its advantages over the subsisting systems in the third chapter of the report. The system design and flowchart are shown in the report's fourth chapter. The project requirements, which include the hardware and software needed to run this system, are discussed in the fifth chapter of the report. A thorough explanation of the modules utilized in the system can be found in Chapter 6. The perpetration and results deduced from executing the inferred system are covered in Chapters 7 and 8 We have discussed the result's conclusion in Chapter 9. The report consists of the contribution of the team in chapter 10 followed by the references section and appendix.

## Summary

The project's primary motivation is to provide an engaging and enjoyable gaming experience that promotes physical activity. The use of hand gestures adds an extra level of immersion to the gameplay, Additionally, the project aims to encourage physical activity by incorporating it into the gameplay.

# CHAPTER 2 LITERATURE REVIEW

## Introduction

## The purpose of this chapter is to review the research papers that were taken for this project. The algorithms used for the project will be examined in this chapter. Research papers extracted from reputed journals

* 1. **Machine Vision-Based Ping Pong Ball Rotation Trajectory**

A machine vision-based system can track the rotation trajectory of a ping pong ball. It consists of a high-speed camera, an image processing module, and a computer vision algorithm. The camera captures the movement of the ball, and the image processing module processes the images.

The algorithm used here is CNN. This algorithm uses edge detection and image segmentation techniques to identify the ball in each frame of the video. It then tracks the motion of the ball by calculating its position, velocity, and acceleration over time. By analyzing the rotation of the ball, spin rate, and direction of the ball, which is used to give its trajectory.

Overall, this machine vision-based system can be used in a variety of applications, including sports training, analysis, and review systems in various sports

* 1. **Machine Learning With The Pong Game**

The Pong game uses a CNN to train an AI agent to play against human players. The game is implemented using Python and the Pygame library for graphics and user interface. The CNN is trained using a dataset of pre-recorded gameplay, similar to the project using a neural network. The game screen pixels are pre-processed to extract features, such as the position of the ball and paddles. The CNN is trained using reinforcement learning with a variant of Q-learning called deep Q-learning. The algorithm learns to predict the Q-value of each action in a given state, and the action with the optimal Q-value is chosen.

* 1. **Pong Game using AI**

Pong game is a simple game. It uses AI on both sides to control Paddles. Model reaction time, which waits some period before making decisions, Two-Part strategy: model accuracy, in which the computer knows where the ball will land and adds a random error factor to pretend that the computer is fallible. In this paper, try to balance the game by making the computer skills better if it starts losing. The algorithm used in this paper is Q-learning reinforcement where the agent tries to make its own decision

* 1. **Design of Pong Game Using VHDL**

The Pong game is designed using VHDL to create the necessary hardware components, including the game screen, paddles, and ball. The game logic is implemented using a finite-state machine algorithm that controls the game components based on the user input and the current state of the game. The VHDL design is then synthesized and implemented in a network processing unit. an NPU is specifically designed for accelerating neural network computations and is a more general-purpose programmable chip.

The Pong game implemented in the network processing unit is connected to the computer keyboard. The network processing unit generates the game screen, receives user input, and plays the game based on the user input and the current state of the game.

* 1. **FPGA Implementation of Pong Game**

First, you need to define the rules of the game, such as how the ball and paddles move, how the score is kept, and when the game ends. Next, you create the graphical interface, which is what the player sees on the screen. This includes creating the ball, paddles, and score displays. Then, you use a hardware description language (HDL) such as Verilog or VHDL to create the necessary hardware components for the game logic and graphical interface. After you've written the HDL code, you use a simulator to test and debug any issues. Finally, you use a synthesis tool to convert the HDL code into a configuration file that can be loaded onto the FPGA, which is what implements the Pong game.

In summary, implementing a Pong game in FPGA involves designing the game logic and graphical interface, creating the necessary hardware components in HDL, testing and debugging using a simulator, and then synthesizing the HDL code into a configuration file that can be loaded onto the FPGA.

## Summary

## Researching several research papers that are related to this work led to the conclusion stated here. Detailed summaries of each research paper have been provided, along with a description of the advantages and disadvantages of each proposed system.

# CHAPTER 3 PROJECT DESCRIPTION

1. **Overview**

In this chapter, the objectives and benefits of the project will be discussed. In addition, the existing system will be evaluated and its drawbacks discussed.

1. **Objective of the Project Work**

Controls the bats on the screen using hand gestures in multiplayer. Hit the ball back using a computer-controlled AI bat on one side. Compete against computer AI to achieve the highest score. Aim to score points by strategically hitting the ball past the computer’s bat and onto the other side of the screen. The direction of the ball depends on our hand movement

**3.3 Existing System**

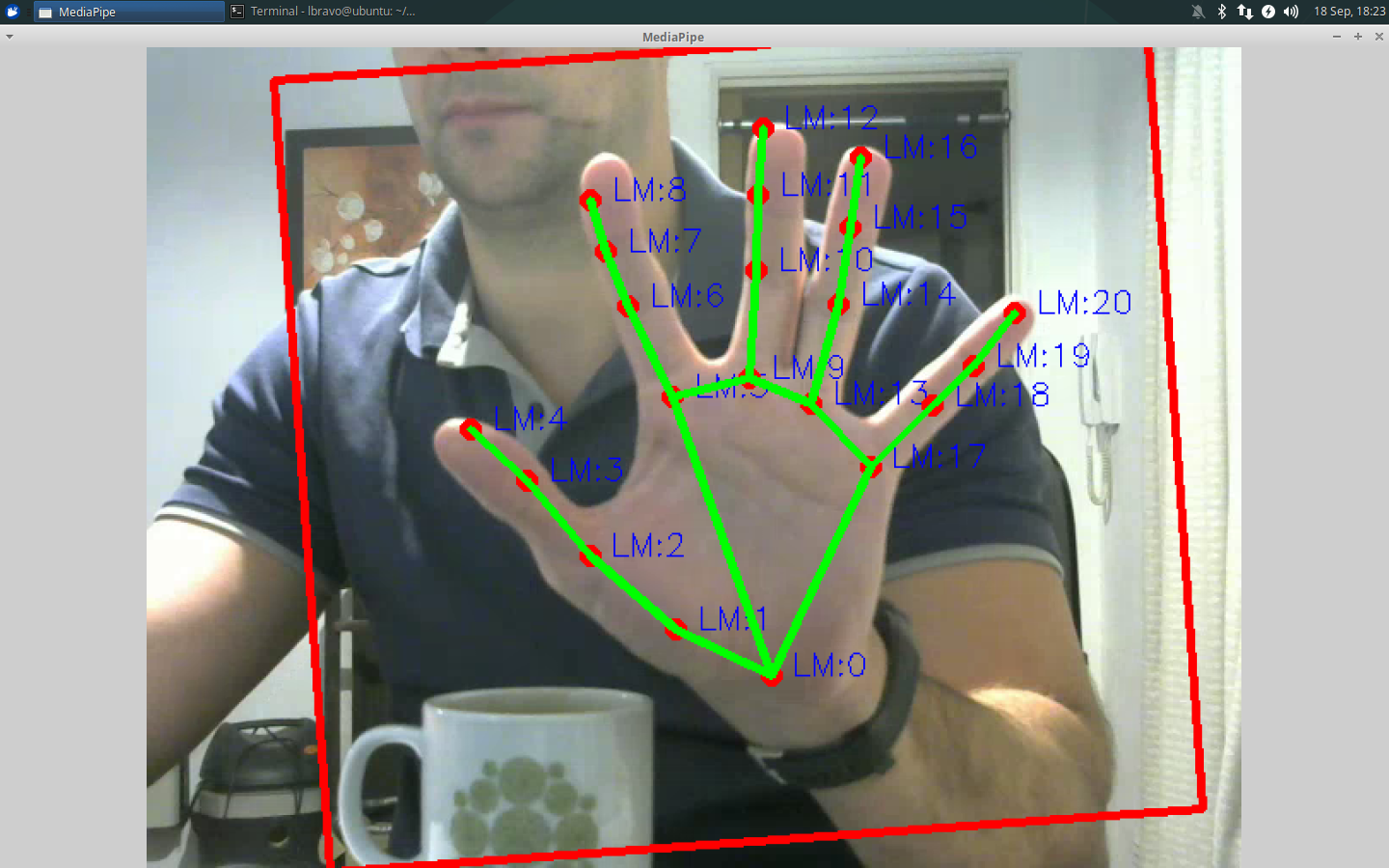
There are several existing systems for table tennis game are electronic scoreboards, robot training systems, virtual reality ping pong, ping pong ball machines, and ping pong tables with built-in sensors. These systems have different skills, budgets, and preferences and these systems are used for gaming, training, coaching, etc. Scoreboards are used for showing the scores of both sides, virtual reality ping pong is used for training the players or for gaming, ping pong robots are tools to improve player training efficiency, ping pong table with build sensor is used for training the players to improve strategy and techniques.

**3.4 Shortcomings of Existing System**

Existing systems include high costs, maintenance requirements and limited availability. These shortcomings will affect the players to fully utilize or access these systems.

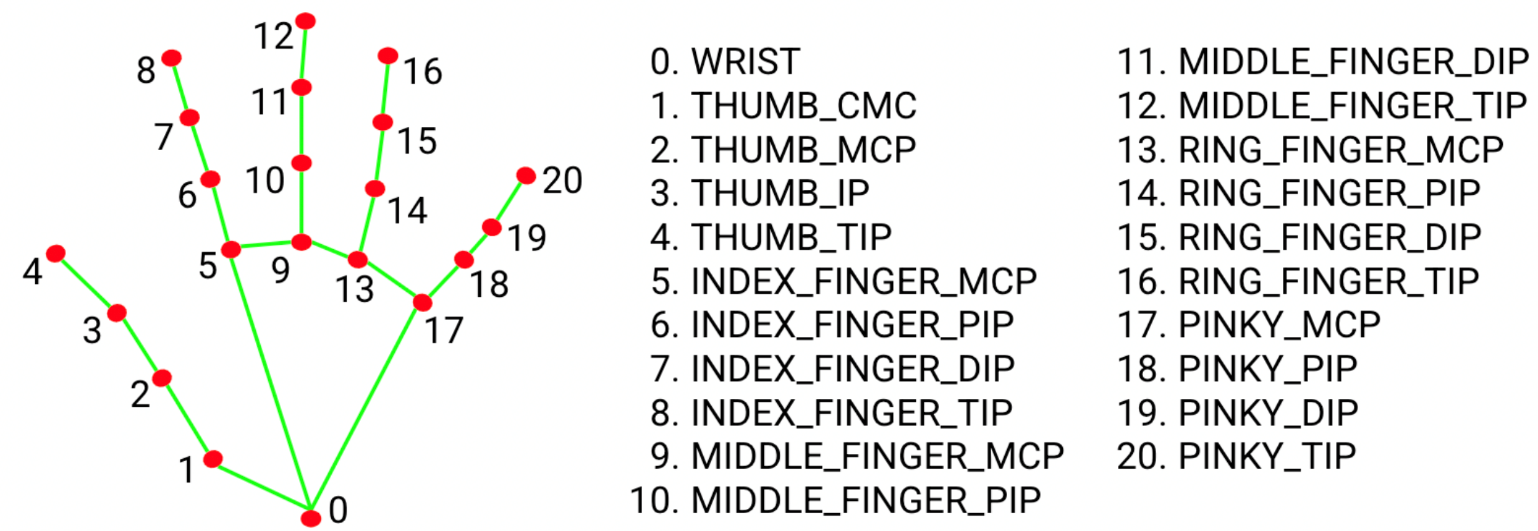
**3.5 Proposed System**

In this project, we have created a table tennis game using our hands. we have set up a webcam and accessed it using computer vision technology. using the webcam and importing Mediapipe module(which is from Google) is used to detect hands type and its landmarks



**Figure 3.1 Detecting Hand Landmarks**

The mediapipe model is a machine learning model which is trained using CNN. From Figure 3.1 we are detecting the hand landmarks(LM:0, LM:1,…., LM:20). In this game, we have set two modes single player and multiplayer which becomes a fun game for alone players as well as multiplayer. the Game has a total of 11 rounds and displays the score of both players at last



**Figure 3.2 Hand Landmarks detection guide**

Continuously monitor hand gestures and update the game accordingly. Figure 3.2 shows that the landmarks number has each identity. Display the updated game state on the screen. The system would involve machine learning techniques to recognize different hand gestures and map them to specific commands for the game. The system would also require a robust camera or sensor to accurately track hand movements in real time.

**3.6 Benefits of the Proposed System**

The proposed system can provide the most natural experience using hand gestures to control the paddles and can feel easier and more natural than using traditional inputs like a keyboard or joystick. Players must use their arms and hands to move the racquet, which can provide a mild workout. Third, is Accessibility this game can be more accessible for players with disabilities that make traditional inputs difficult to use

**3.7 Summary**

We have summarized this chapter about the Existing system, proposed system, and objective. By evaluating the current system, the chapter justifies the need for this project and sets the stage for the proposed system.

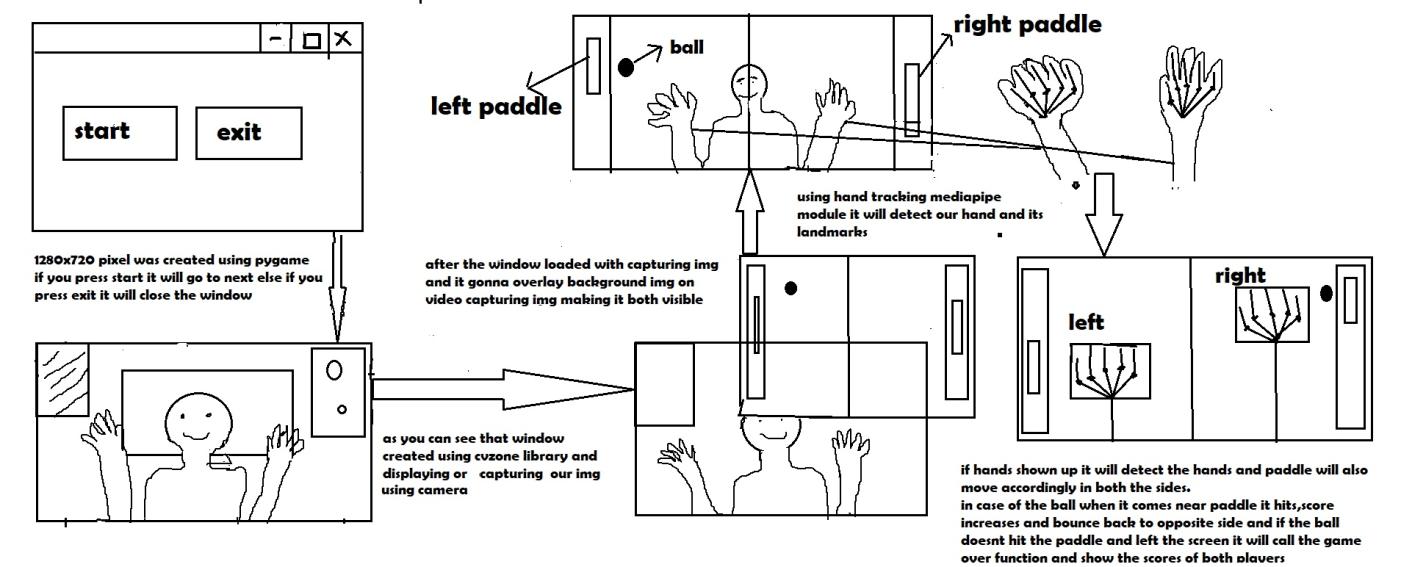
# CHAPTER 4

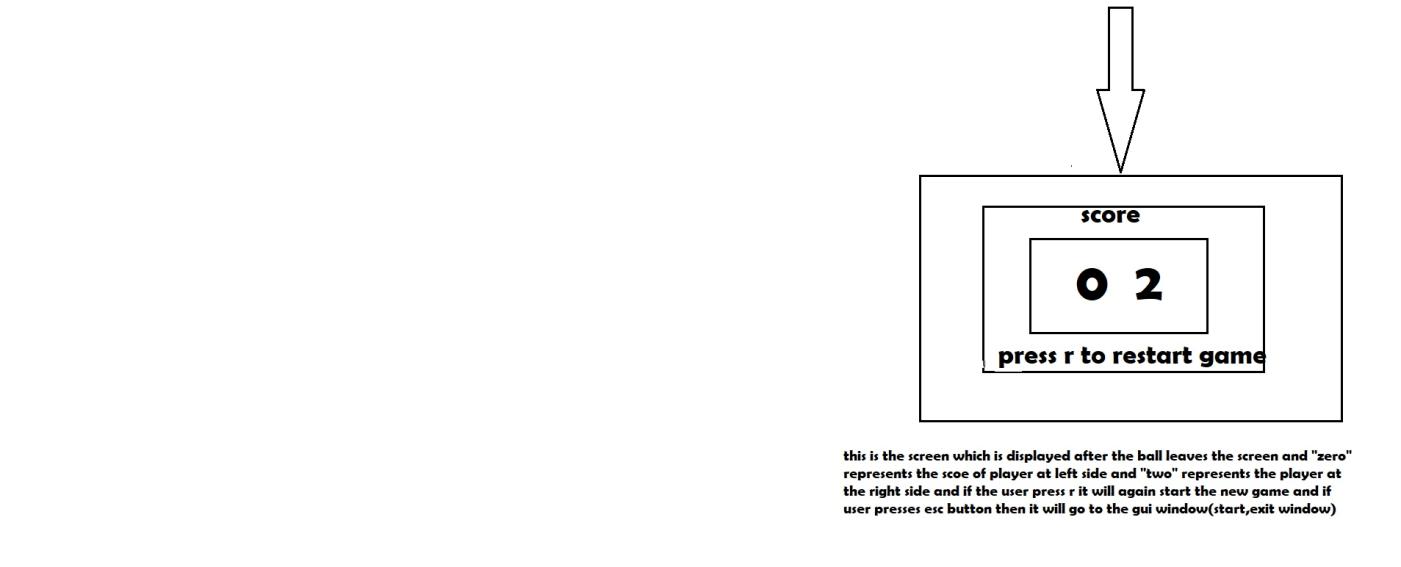
# SYSTEM DESIGN

**4.1 Overview**

In this chapter, we will provide a clear explanation of the architecture diagram for the proposed system.

**4.2 Architecture Diagram**



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**Figure 4.1 Architecture Diagram**

The architecture Diagram in Figure 4.1 explains how and flow of the game, using the pygame module will create an interface window with 1280x720 resolution window has been created, in the user interface has two buttons start and an exit button if the player presses the exit button it will close all window or else if the player presses the start button it will call the game where the game first call camera to access the live footage in 720p resolution, after capturing the background texture will overlay to make a new interface using OpenCV image processing module. Using the hand-tracking media pipe module we will detect hands and landmarks, using handmarks player can control the rackets. The ball has its collision to move according to physics, if the player hits the ball they will have the +one score. If the user misses the ball it will go to the restart screen menu by pressing ‘r’ in the restart menu player can play the game again. The player presses the ‘ESC’ key on the keyboard it will go to the user interface.

**4.3 Summary**

The architecture diagram for the proposed system was discussed and the idea of this project was known by this architecture

**CHAPTER 5**

**PROJECT REQUIREMENTS**

**5.1 Overview**

The hardware and software used in this project will be discussed in this chapter along with its specifications. A brief description of the technology is as follows

* 1. **Software Specifications**

**Framework & Libraries**

* Open cv
* Pygame
* Numpy
* Python 3.10
  1. **Technology Used**
* **Computer Vision**

Used for Image Processing and accessing the webcam.

* **Machine Learning**

Machine learning is a branch of AI and computer science. Which focuses on the use of data and algorithms to imitate the way that human learns.

* **Deep Learning**

It is a method in AI that teaches computers to process the data in the way that human learns

* 1. **Summary**

In this chapter, the hardware and software, and technologies used were mentioned.

**CHAPTER 6**

**MODULE DESCRIPTION**

**6.1 Overview**

The objective of this section is to provide a comprehensive overview of all various modules implemented in this project

**6.2 Modules**

The following modules is used for the implementation of this project

* GUI
* GUI Imports
* Pygame programs
* Image Processing
* Hand Tracking

**6.2.1 GUI**

GUI in simple terms it is a interface for creating video games, Handles graphics, sound, user input, and networking, API, and easy to learn

* + 1. **GUI Imports**

GUI imports is used for importing the images, audio files and it processed to make the interface more colourful.

**6.2.3 Pygame Programs**

It providies constants and events, including key and mouse events, video modes, and color values.

**6.2.4 Image Processing**

This is a computer vision library that provides tools for image and video processing and it is used to capture video from the camera and overlay images onto the video feed.

**6.2.5 Hand Tracking**

The handtracking module is a third-party library built on top of OpenCV and Mediapipe that provides tools for hand detection and tracking in real-time video feeds.

**6.3 Summary**

This section described the description of every module which were used in our code.

**CHAPTER 7**

**IMPLEMENTATION**

**7.1 Overview**

This chapter provides an in-depth description of the implementation process. Additionally, the chapter describes the Pygame interface.

**7.2 Implementation**

Implementation of table tennis using hand gesture is done using pygame(gui),pygame locals,cv2,mediapipe modules.First, pyagme has been used for interface in our game.Second, pygame.locals has beed used for importing audio files and images.Thirs, cv2 has been used for accesing the webcam to get a video of a player and processing images for ball,racket,background images using resize from imutils to resize the imag and change the colour using cvtcolor.Fourth,mediapipe has been used for tracking hands and identifying the hands which helps to move racket based on movement of hands.

**7.4 Summary**

The purpose of this chapter is to provide a detailed description of the proposed system and its implementation. In addition to using Pygame for game interfaces.

**CHAPTER 8**

**RESULT ANALYSIS**

**8.1 Overview**

Implementation of the whole project is well explained in this chapter and the effectiveness of the proposed system is discussed.

**8.2 Result Analysis**

**Table 8.1 Performance Evaluation in Terms of Accuracy**

|  |  |  |  |
| --- | --- | --- | --- |
| Research Papers | AI Bot | Multiplayer | Hand Tracking |
| Yilie Wang et al [1] | - | 40.6% | - |
| Doina et al [2] | 44.6% | - | - |
| Akash et al [3] | 64.7% | 70.34% | - |
| Sudhanshu et al [4] | - | 50.4% | - |
| Shith et al [5] | - | 50.2% | - |
| Proposed System- Ponger | 75.43% | 80.76% | 86.83% |

From the Table 8.1 Performance evaluation is done in terms of accuracy.

For AI Bot Doina et al [2] got 44.6%, Akash et al [3] got 64.7% comparing this existing system(AI Bot) accuracy we have got 75.43%.

For Multiplayer Yilie Wang et al [1] got 40.6%, Akash et al [3] got 60.34%, Sudhansu et al [4] got 50.4%, Shit et al [5] got 50.2% comparing this existing system(Multiplayer) accuracy we have got 80.76%.

For Hand Tracking none of the Authors used Hand Tracking, we got 86.83% in accuracy.

**8.3 Summary**

Thus the implementation of the whole project is well explained in this chapter 8 and the proposed system has also shown how effective it is.

**CHAPTER 9**

**CONCLUSION AND FUTURE WORK**

**9.1 Overview**

The overview of this chapter is to discuss the result of this project, and this discussion is followed by the conclusion and future work of this project's possibilities

**9.2 Conclusion**

The project provides a personalized gameplay experience by allowing players to control the game using intuitive hand gestures and adapting to individual player styles.

It uses deep learning, machine learning for AI bots, and CNN.

Overall, the project contributes to the advancement of interactive technologies and inspires future research and development in this area

**9.3 Future work**

We will continue to future work on this project by implementing this game as one of the online website games, and apps for the Microsoft Store, play store, and app store

Making more efficient and implementing many modes, difficulties, artworks, skill-based bats

**9.4 Summary**

The conclusion and Future work of this chapter are discussed well, detecting the hand landmarks controlling the bats is successful.

**CHAPTER 10**

**INDIVIDUAL TEAM MEMBER’s REPORT**

**10.1 Individual Objective**

**Dani N:**

Researching the different modes for the game, and journal to fit our idea of this project, exploring the algorithms, and comparing them between these algorithms to which one gives more accuracy

**Dharshan R E:**

Exploring the different interfaces, various research papers, and modules for hand tracking and comparing which module library will give more accuracy, paperwork, designing the game interface, and code for efficiency.

**10.2 Role of the Team Members**

**Dani N:**

Reviewing some research papers and collected algorithms, preparing the PPT, and Some parts of “def codes”.

**Dharshan R E:**

Reviewing some research papers and modules to track hands, making efficient interface and some parts “def codes” like AI bot, game over part.

* 1. **Contribution of Team Members**

**Dani N(21113004)**

* Gathering Information such as Research papers, Images, and Youtube videos for reference
* Learning Python Opencv, pygame integration
* Making ppt slides such as Intro, Objective, Architecture Diagram, System requirements, Future work and conclusion, Literature Survey such as Machine Vision Based Ping Pong, Machine Learning with Pong Game, conclusion, and Future work
* Making the pygame Interface and testing it
* Accessing Camera module

**Dharshan R E(21113049)**

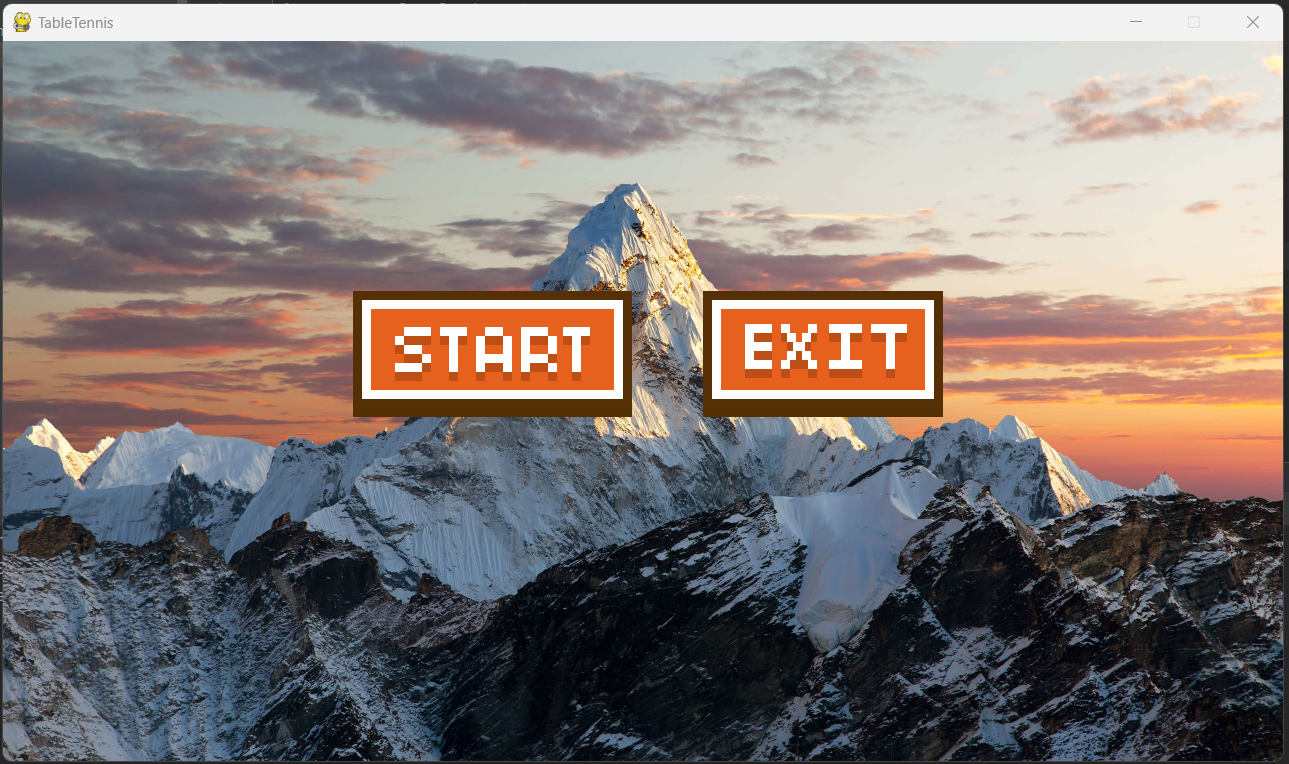
* Gathering Information such as Research papers, Camera access, and Youtube videos for reference
* Learning Python Mediapipe, pygame button module integration with Wav
* Making ppt slides such as Abstract, Goals and Motivation, Module and Modular description, Problem definition, Literature Survey such as Pong game using Ai, VHDL, FGPA, Proposed System/Work, Result and discussion
* Making The pygame button modules and testing it
* Detecting the Hands and its landmarks

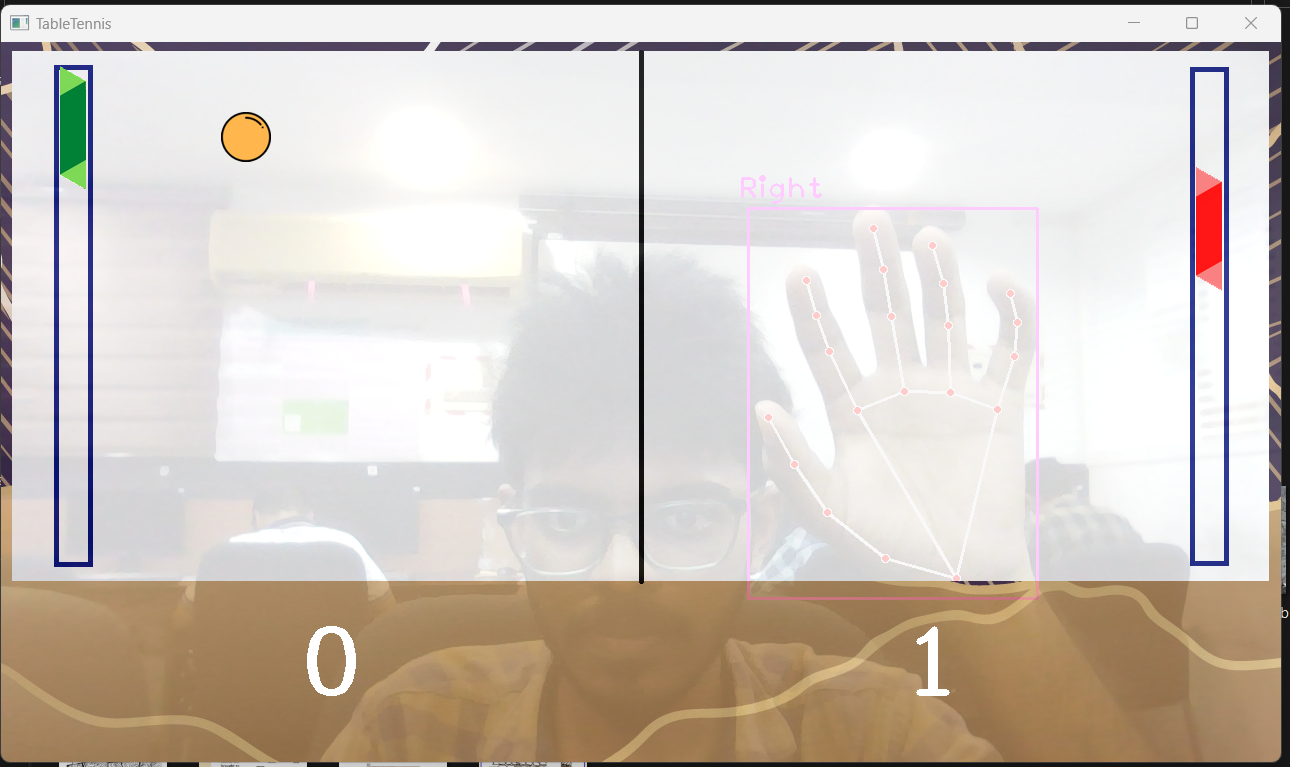
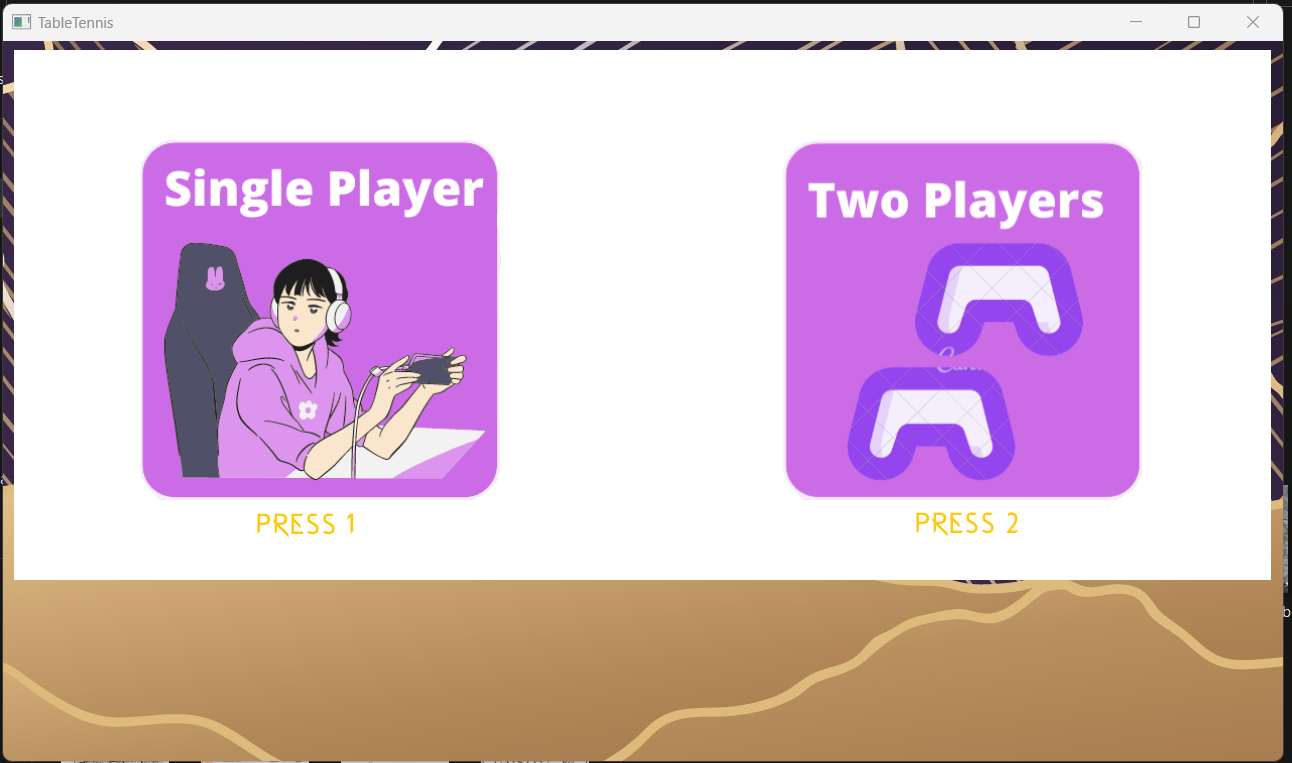
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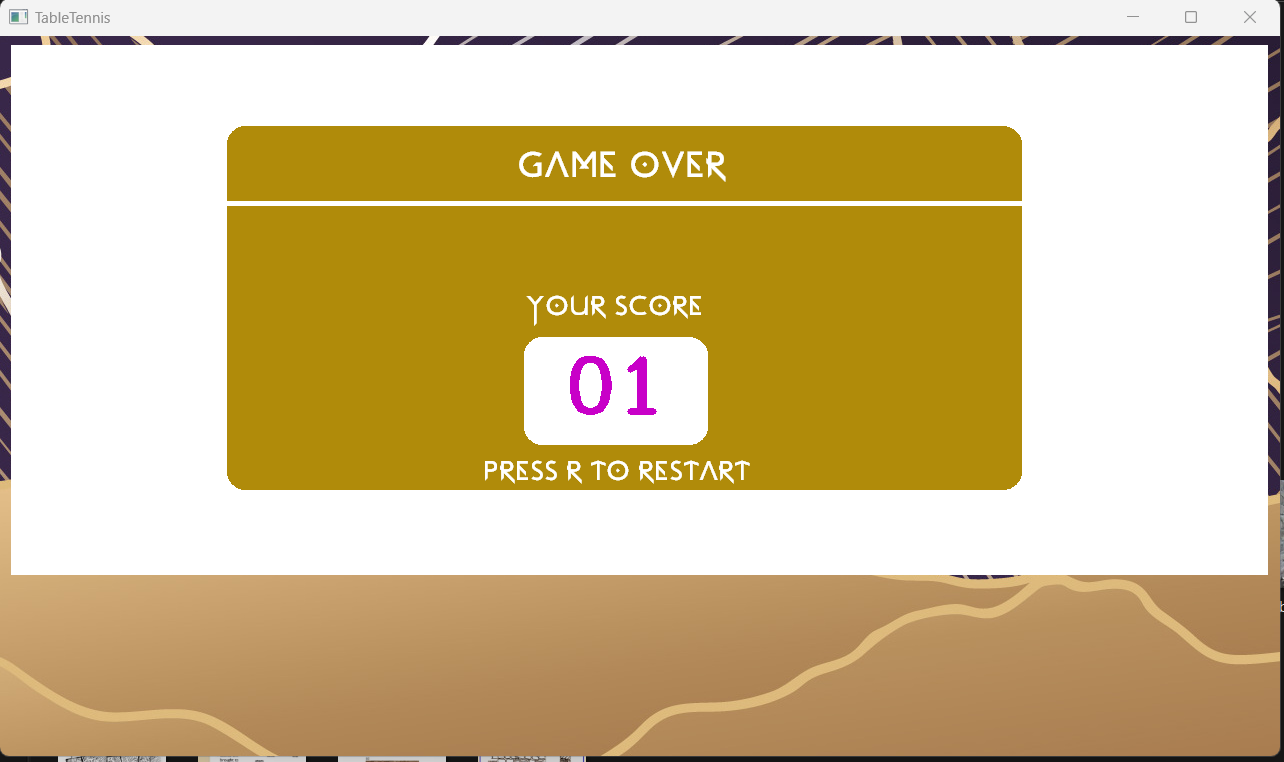
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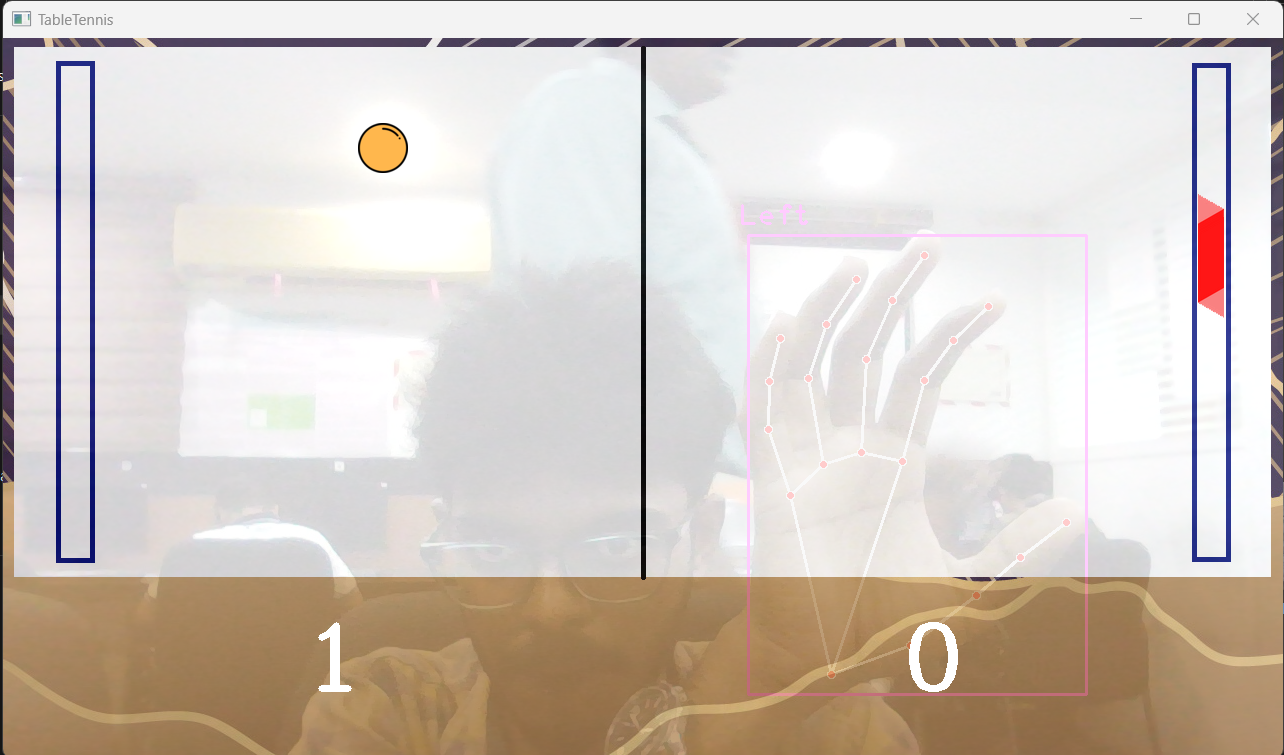
**APPENDIX A**

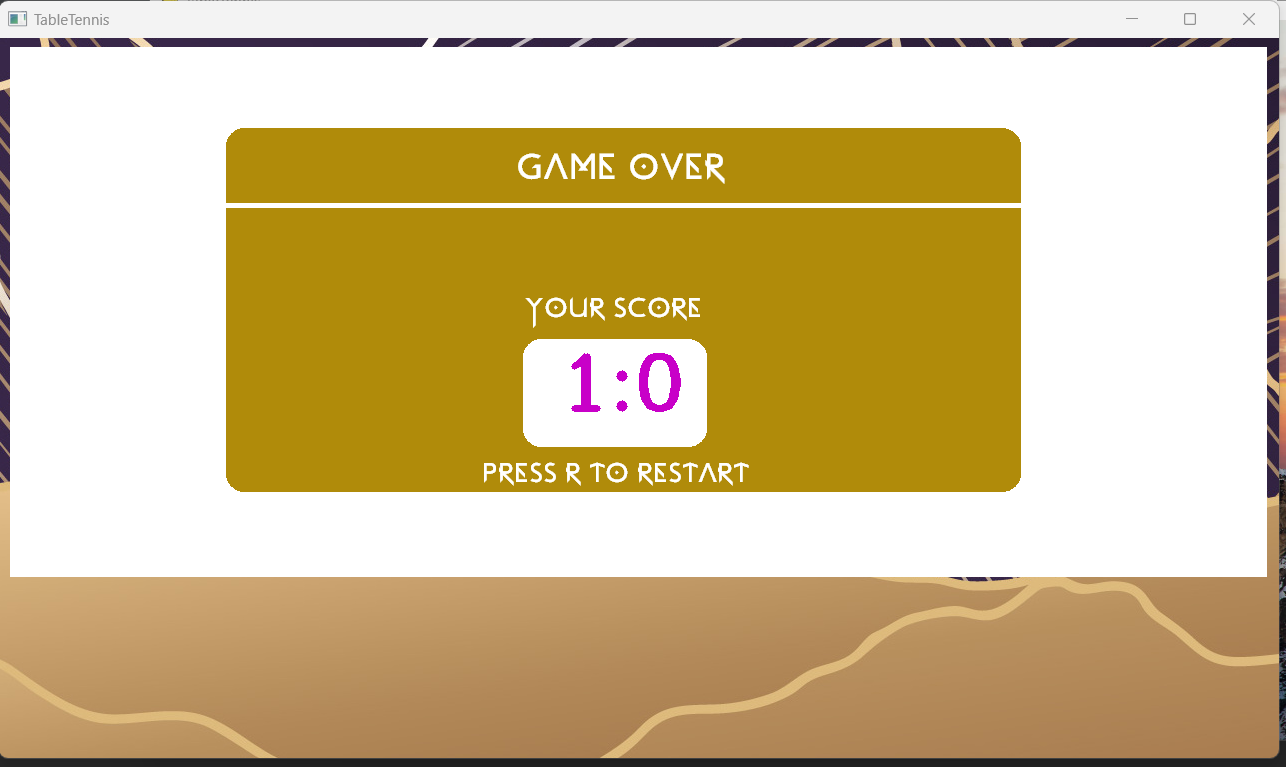
**SAMPLE SCREEN**

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**APPENDIX B**

**SAMPLE CODE**

import pygame

from pygame.locals import \*

import cvzone

import cv2

from cvzone.HandTrackingModule import HandDetector

import numpy as np

import pygame

pygame.mixer.init()

pygame.init()

# Load button images

play\_again\_img = pygame.image.load("start\_btn.png")

play\_again\_img\_hover = pygame.image.load("start\_hover\_btn.png")

play\_again\_img\_clicked = pygame.image.load("start\_clicked\_btn.png")

quit\_img = pygame.image.load("exit\_btn.png")

quit\_img\_hover = pygame.image.load("exit\_hover\_btn.png")

quit\_img\_clicked = pygame.image.load("exit\_clicked\_btn.png")

# Load background image and resize it to screen size

bg\_img = pygame.image.load("background.jpg")

bg\_img = pygame.transform.scale(bg\_img, (1280, 720))

# Load background music

pygame.mixer.music.load("bg\_music.wav")

startSound = pygame.mixer.Sound("sfx.wav")

exit\_sound = pygame.mixer.Sound("click.wav")

screen\_width = 1280

screen\_height = 720

screen = pygame.display.set\_mode((screen\_width, screen\_height))

pygame.display.set\_caption('TableTennis')

#define global variable

clicked = False

counter = 0

class button():

def \_\_init\_\_(self, x, y, normal\_img, hover\_img, clicked\_img):

self.x = x

self.y = y

self.normal\_img = normal\_img

self.hover\_img = hover\_img

self.clicked\_img = clicked\_img

def draw\_button(self):

global clicked

action = False

#get mouse position

pos = pygame.mouse.get\_pos()

#create pygame Rect object for the button

button\_rect = self.normal\_img.get\_rect(topleft = (self.x, self.y))

#check mouseover and clicked conditions

if button\_rect.collidepoint(pos):

if pygame.mouse.get\_pressed()[0] == 1:

clicked = True

screen.blit(self.clicked\_img, button\_rect)

elif pygame.mouse.get\_pressed()[0] == 0 and clicked == True:

clicked = False

action = True

else:

screen.blit(self.hover\_img, button\_rect)

else:

screen.blit(self.normal\_img, button\_rect)

return action

play\_again = button(350, 250, play\_again\_img, play\_again\_img\_hover, play\_again\_img\_clicked)

quit = button(700, 250, quit\_img, quit\_img\_hover, quit\_img\_clicked)

pygame.mixer.music.play(-1)

def table\_tennis\_game():

cap = cv2.VideoCapture(0)

cap.set(3, 1280)

cap.set(4, 720)

# Importing all images

imgBackground = cv2.imread('2DIMAGES/Background.png')

imgGameOver = cv2.imread('2DIMAGES/gameOver.png')

imgGameStart = cv2.imread('2DIMAGES/gameStart.png')

imgBall = cv2.imread('2DIMAGES/ball.png', cv2.IMREAD\_UNCHANGED)

imgBat1 = cv2.imread('2DIMAGES/racket1.png', cv2.IMREAD\_UNCHANGED)

imgBat2 = cv2.imread('2DIMAGES/racket2.png', cv2.IMREAD\_UNCHANGED)

bounce\_sound = pygame.mixer.Sound("2DIMAGES/bounce\_sound.wav")

end\_sound = pygame.mixer.Sound("click.wav")

restart\_sound = pygame.mixer.Sound("restart.wav")

# Hand Detector

detector = HandDetector(detectionCon=0.8, maxHands=2)

# Variables

ballPos = [100, 100]

speedX = 15

speedY = 15

gameOver = False

score = [0, 0]

gameStart = True

solo = True

while True:

\_, img = cap.read()

img = cv2.flip(img, 1)

# Find the hand and its landmarks

hands, img = detector.findHands(img, flipType=False) # with draw

# Overlaying the background image

img = cv2.addWeighted(img, 0.2, imgBackground, 0.8, 0)

# Check for hands

if hands:

for hand in hands:

x, y, w, h = hand["bbox"]

h1, w1, \_ = imgBat1.shape

y1 = y - h1 / 2

y1 = np.clip(y1, 20, 395)

if solo:

# Bot controlling the left bat

bot\_y = ballPos[1] - imgBat1.shape[0] // 2

bot\_y = np.clip(bot\_y, 20, 415)

img = cvzone.overlayPNG(img, imgBat1, (59, int(bot\_y)))

if 59 < ballPos[0] < 59 + imgBat1.shape[1] and bot\_y < ballPos[1] < bot\_y + imgBat1.shape[0]:

speedX = -speedX

ballPos[0] += 30

score[0] += 1

bounce\_sound.play()

if hand['type'] == "Right":

img = cvzone.overlayPNG(img, imgBat2, (1195, int(y1)))

if 1195 - 50 < ballPos[0] < 1195 and y1 < ballPos[1] < y1 + h1:

speedX = -speedX

ballPos[0] -= 30

score[1] += 1

bounce\_sound.play()

else:

if hand['type'] == "Right":

img = cvzone.overlayPNG(img, imgBat1, (59, int(y1)))

if 59 < ballPos[0] < 59 + w1 and y1 < ballPos[1] < y1 + h1:

speedX = -speedX

ballPos[0] += 30

bounce\_sound.play()

if hand['type'] == "Left":

img = cvzone.overlayPNG(img, imgBat2, (1195, int(y1)))

if 1195 - 50 < ballPos[0] < 1195 and y1 < ballPos[1] < y1 + h1:

speedX = -speedX

ballPos[0] -= 30

bounce\_sound.play()

# Game Over

if solo:

if ballPos[0] < 40 or ballPos[0] > 1200:

gameOver = True

else:

if ballPos[0] < 40:

score[1] += 1

elif ballPos[0] > 1200:

score[0] += 1

if ballPos[0] < 40 or ballPos[0] > 1200:

ballPos = [100, 100]

speedX = 15

speedY = 15

if max(score) == 1:

gameOver = True

if gameOver and solo:

img = imgGameOver

cv2.putText(img, str(score[0] + score[1]).zfill(2), (565, 375), cv2.FONT\_HERSHEY\_COMPLEX,

2.5, (200, 0, 200), 5)

elif gameOver:

img = imgGameOver

cv2.putText(img, str(score[0]) + ":" + str(score[1]), (560, 370), cv2.FONT\_HERSHEY\_COMPLEX,

2.5, (200, 0, 200), 5)

elif gameStart:

img = imgGameStart

# if game not over move the ball

else:

# Move the Ball

if ballPos[1] >= 500 or ballPos[1] <= 10:

speedY = -speedY

ballPos[0] += speedX

ballPos[1] += speedY

# Draw the ball

img = cvzone.overlayPNG(img, imgBall, ballPos)

cv2.putText(img, str(score[0]), (300, 650), cv2.FONT\_HERSHEY\_COMPLEX, 3, (255, 255, 255), 5)

cv2.putText(img, str(score[1]), (900, 650), cv2.FONT\_HERSHEY\_COMPLEX, 3, (255, 255, 255), 5)

cv2.imshow("TableTennis", img)

key = cv2.waitKey(1)

if key == ord('r') or key == ord('R'):

restart\_sound.play()

ballPos = [100, 100]

speedX = 15

speedY = 15

gameOver = False

score = [0, 0]

imgGameOver = cv2.imread('2DIMAGES/gameOver.png')

gameStart = True

elif key == ord('1') and gameStart:

solo = True

gameStart = False

elif key == ord('2') and gameStart:

solo = False

gameStart = False

elif key == 27:

cv2.destroyAllWindows()

end\_sound.play()

break

run = True

while run:

screen.blit(bg\_img, (0, 0)) # adding background image

if play\_again.draw\_button():

startSound.play()

table\_tennis\_game()

counter = 0

if quit.draw\_button():

run = False

for event in pygame.event.get():

if event.type == pygame.QUIT:

run = False

pygame.display.update()

pygame.quit()

**APPENDIX D**

**TEAM DETAILS**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| S.NO | ROLL NUMBER | TEAM MEMBERS | EMAIL ID | CONTACT NUMBER |
| 1 | 21113004 | Dani N | 21113004@student.hindustanuniv.ac.in | 9791197021 |
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