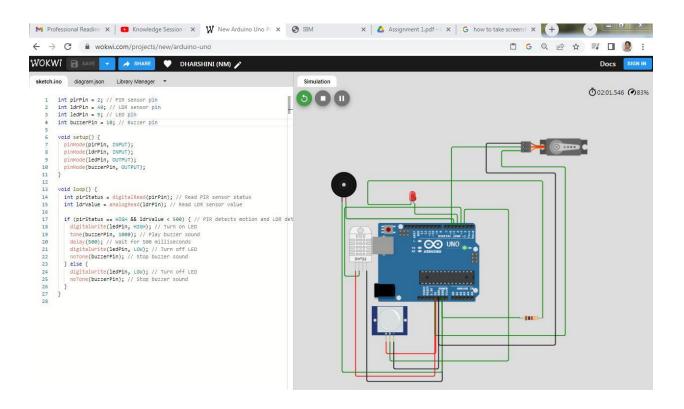
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WOKWI ASSIGNMENT LINK: https://wokwi.com/projects/363966378149904385

SCREEN SHOT OF THE ASSIGNMENT:



sketch.ino:

```
int pirPin = 2; // PIR sensor pin
int ldrPin = A0; // LDR sensor pin
int ledPin = 9; // LED pin
int buzzerPin = 10; // Buzzer pin

void setup() {
   pinMode(pirPin, INPUT);
```

```
pinMode(ldrPin, INPUT);
 pinMode(ledPin, OUTPUT);
 pinMode(buzzerPin, OUTPUT);
}
void loop() {
  int pirStatus = digitalRead(pirPin); // Read PIR sensor status
  int ldrValue = analogRead(ldrPin); // Read LDR sensor value
  if (pirStatus == HIGH && ldrValue < 500) { // PIR detects motion and LDR</pre>
detects low light level
    digitalWrite(ledPin, HIGH); // Turn on LED
    tone(buzzerPin, 1000); // Play buzzer sound
    delay(500); // Wait for 500 milliseconds
    digitalWrite(ledPin, LOW); // Turn off LED
    noTone(buzzerPin); // Stop buzzer sound
  } else {
   digitalWrite(ledPin, LOW); // Turn off LED
   noTone(buzzerPin); // Stop buzzer sound
 }
}
```