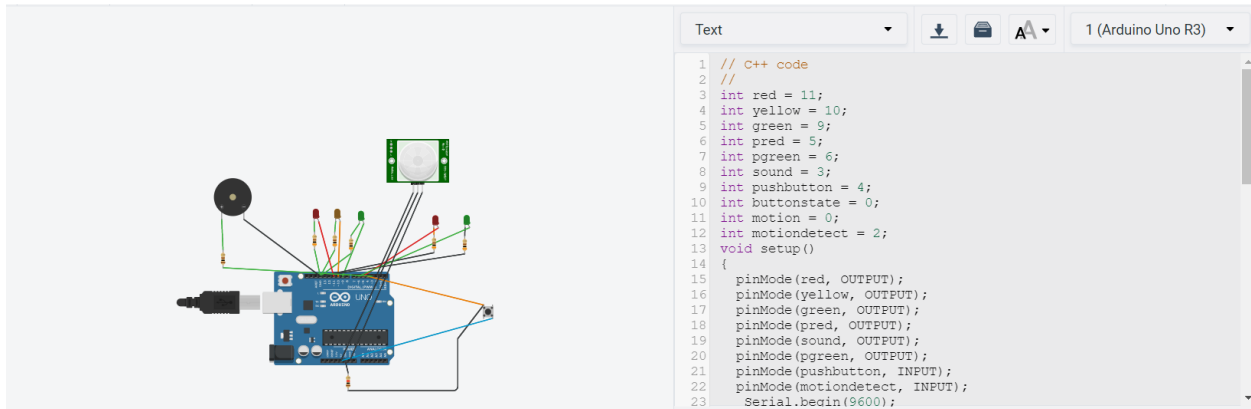


## Question 1



// C++ code

//

int red = 11;

int yellow = 10;

int green = 9;

int pred = 5;

int pgreen = 6;

int sound = 3;

int pushbutton = 4;

int buttonstate = 0;

int motion = 0;

int motiondetect = 2;

void setup()

{

pinMode(red, OUTPUT);

pinMode(yellow, OUTPUT);

pinMode(green, OUTPUT);

pinMode(pred, OUTPUT);

pinMode(sound, OUTPUT);

pinMode(pgreen, OUTPUT);

```
pinMode(pushbutton, INPUT);  
pinMode(motiondetect, INPUT);  
Serial.begin(9600);  
}
```

```
void loop() {  
  trafficLights();
```

```
}
```

```
void trafficLights(){  
  buttonstate = digitalRead(4);  
  motion = digitalRead(2);  
  Serial.println(motion);  
  digitalWrite(green, HIGH);  
  digitalWrite(pred, LOW);
```

```
  if(buttonstate || motion){  
    delay(2000);  
    digitalWrite(green, LOW);  
    digitalWrite(yellow, HIGH);
```

```
    delay(3000);  
    digitalWrite(yellow, LOW);  
    digitalWrite(red, HIGH);  
    digitalWrite(pgreen, HIGH);
```

```
    delay(5000);
```

```
digitalWrite(red, LOW);  
digitalWrite(pgreen, LOW);  
digitalWrite(pred, HIGH);  
    delay(5000);  
delay(10000);
```

```
}
```

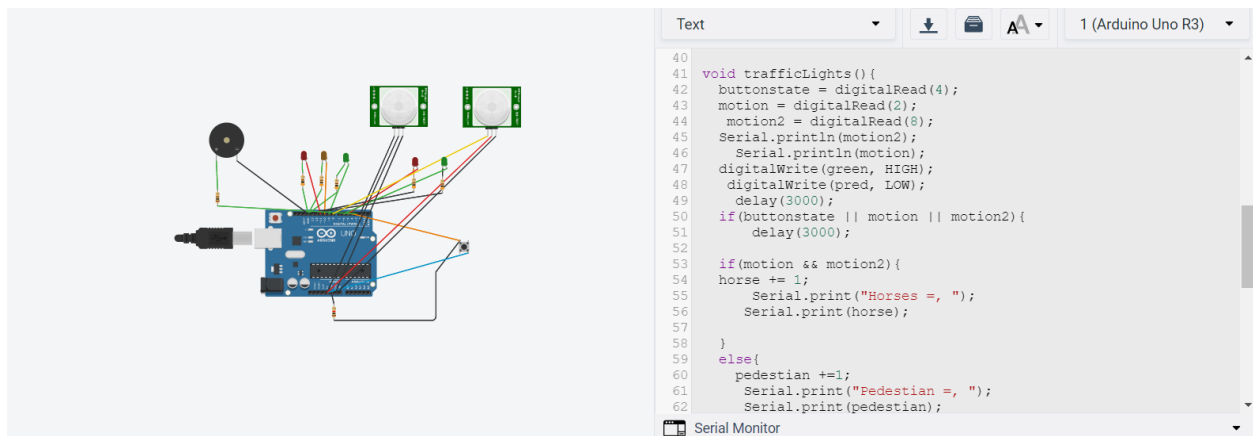
```
}
```

## Question 2

We can use two motion detectors.

If both the motion detectors detect '1' we can confirm that it is a horse or if only one motion detector is detected then it is a pedestrian.

## Question 3



// C++ code

//

int red = 11;

int yellow = 10;

int green = 9;

int pred = 5;

int pgreen = 6;

int sound = 3;

int pushbutton = 4;

int buttonstate = 0;

int motion = 0;

int motion2 = 0;

int motiondetect = 2;

int distance = 0;

```
int pedestrian = 0;
```

```
int horse = 0;
```

```
void setup()
```

```
{
```

```
  pinMode(red, OUTPUT);
```

```
  pinMode(yellow, OUTPUT);
```

```
  pinMode(green, OUTPUT);
```

```
  pinMode(pred, OUTPUT);
```

```
  pinMode(sound, OUTPUT);
```

```
  pinMode(pgreen, OUTPUT);
```

```
  pinMode(pushbutton, INPUT);
```

```
  pinMode(motiondetect, INPUT);
```

```
  pinMode(7, INPUT);
```

```
  pinMode(8, INPUT);
```

```
  Serial.begin(9600);
```

```
}
```

```
void loop() {
```

```
  trafficLights();
```

```
}
```

```
void trafficLights(){
```

```
  buttonstate = digitalRead(4);
```

```
  motion = digitalRead(2);
```

```
motion2 = digitalRead(8);
Serial.println(motion2);
    Serial.println(motion);
digitalWrite(green, HIGH);
digitalWrite(pred, LOW);
    delay(3000);
if(buttonstate || motion || motion2){
    delay(3000);

    if(motion && motion2){
        horse += 1;
        Serial.print("Horses =, ");
        Serial.print(horse);

    }
    else{
        pedestrian +=1;
        Serial.print("Pedestian =, ");
        Serial.print(pedestian);
    }
    delay(100); // Wait for 100 millisecond(s)
    delay(2000);
    digitalWrite(green, LOW);
    digitalWrite(yellow, HIGH);

    delay(3000);
    digitalWrite(yellow, LOW);
    digitalWrite(red, HIGH);
    digitalWrite(pgreen, HIGH);
```

```
tone(sound,988,5000);  
/*for (long i=500; i<10000; i++)  
{  
tone(sound, i, 5000);  
}*/  
delay(5000);  
  
digitalWrite(red, LOW);  
digitalWrite(pgreen, LOW);  
digitalWrite(pred, HIGH);  
    delay(5000);  
delay(10000);  
  
}  
  
}
```