## Design and Analysis of Algorithm

Lecture-28: Approximation Algorithm

#### **Contents**



1 Travelling Salesman Problem

#### Introduction

In the traveling-salesman problem we are given a complete undirected graph G(V, E) that has a nonnegative integer cost c(u, v) associated with each edge  $(u, v) \in E$ , and we must find a a tour of G with minimum cost.

let c(A) denote the total cost of the edges in the subset  $A \subseteq E$ 

$$c(A) = \sum_{(u,v)\in A} c(u,v)$$

#### **Triangle inequality**

In many practical situations,

the least costly way to go from a place u to a place w is to go directly, with no intermediate steps.

We formalize this notion by saying that the cost function c satisfies the triangle inequality if, for all vertices u, v,  $w \in V$ ,

$$c(u, w) \le c(u, v) + c(v, w)$$

# The traveling-salesman problem with the triangle inequality

When the cost function satisfies the triangle inequality, we may design an approximate algorithm for the Travelling Salesman Problem that returns a tour whose cost is never more than twice the cost of an optimal tour.

The idea is to use Minimum Spanning Tree (MST).

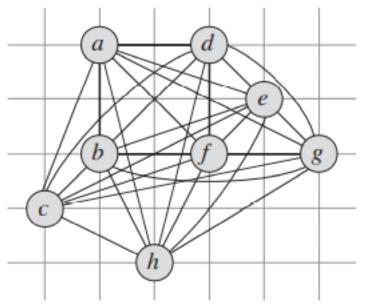
#### **Algorithm**

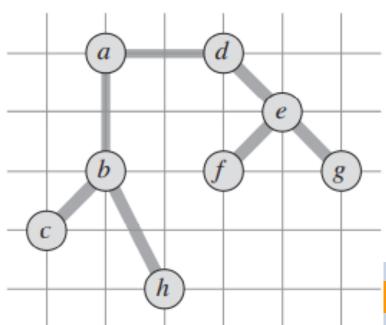
#### APPROX-TSP-TOUR (G, c)

- 1. select a vertex  $r \in G.V$  to be a "root" vertex
- 2. compute a minimum spanning tree T for G from root r using MST-PRIM. (G c r)
- 3. let H be a list of vertices, ordered according to when they are first visited in a preorder tree walk of T
- 4. return the path.

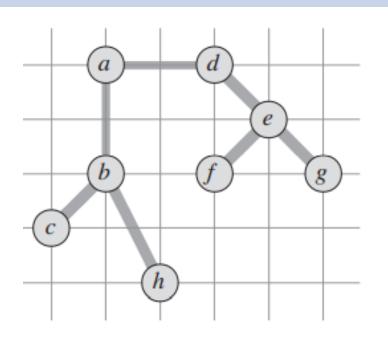
#### **Constructing The Minimum Spanning Tree**

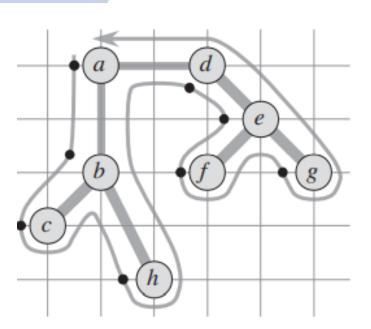
We will be using Prim's Algorithm to construct a minimum spanning tree from the given graph as an adjacency matrix.



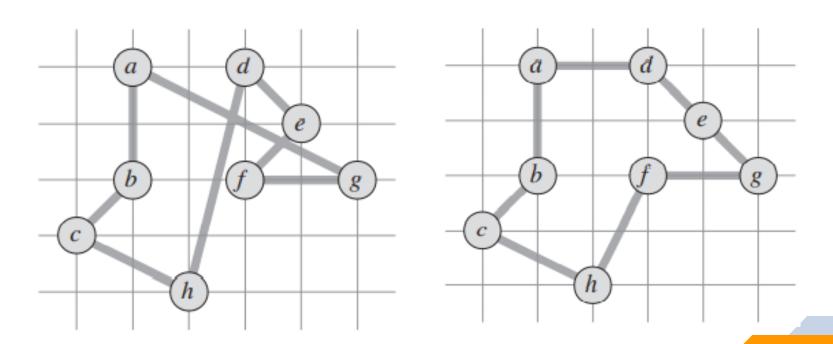


#### Getting the preorder walk/ Depth first search walk

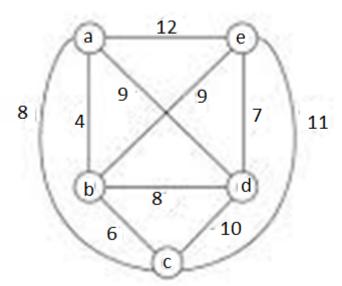




#### The final Path



## Example



#### The set-covering problem

In the set covering problem, two sets are given:

A set U of elements and

A set S of subsets of the set U.

$$U = \bigcup_{x \in S} x$$

Each subset in S is associated with a predetermined cost, and the union of all the subsets covers the set U

#### A greedy approximation algorithm

The greedy method works by picking, at each stage, the set S that covers the greatest number of remaining elements that are uncovered.

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GREEDY-SET-COVER (X, \mathcal{F})

1 U = X

2 \mathcal{C} = \emptyset

3 while U \neq \emptyset

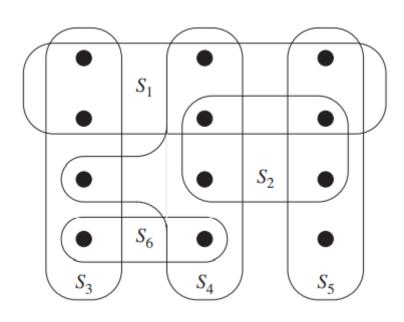
4 select an S \in \mathcal{F} that maximizes |S \cap U|

5 U = U - S

6 \mathcal{C} = \mathcal{C} \cup \{S\}

7 return \mathcal{C}
```

#### **Example**



X consists of the 12 black points and  $S = \{S_1, S_2, S_3, S_4, S_5, S_6\}$ 

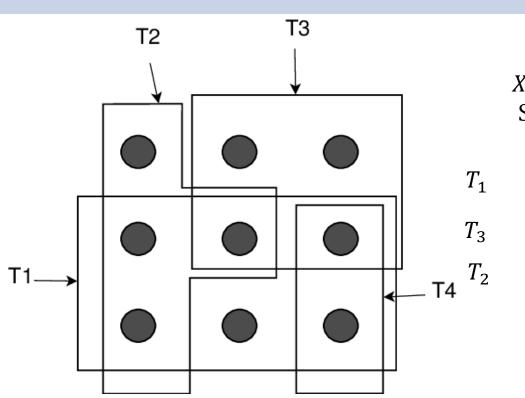
 $S_1$ 

 $S_{4}$ 

 $S_5$ 

 $S_3$ 

### **Example**



X consists of the 9 black points and  $S = \{T_1, T_2, T_3, T_4\}$