Design and Analysis of Algorithm

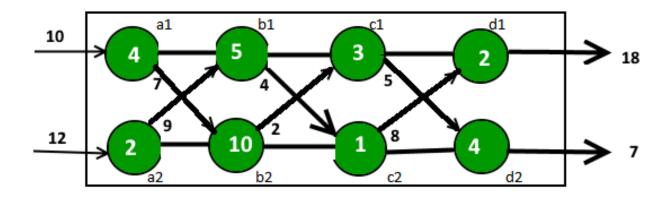
Lecture-15:
Dynamic Programming

Contents



- 1 Multistage graph
- 2 All Pair Shortest Path

Find the shortest path for the assembly line given in the figure



What is the time complexity of Assembly line scheduling?

Consider the following assembly line problem:

```
time_to_reach[2][3] = {{17, 2, 7}, {19, 4, 9}}

time_spent[2][4] = {{6, 5, 15, 7}, {5, 10, 11, 4}}

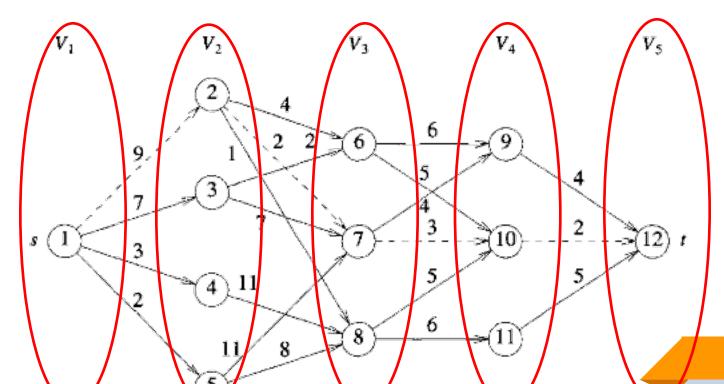
entry_time[2] = {8, 10}

exit_time[2] = {10, 7}

num_of_stations = 4
```

What is the minimum time required to build the car chassis?

A multi stage graph G = (V, E) is a directed graph in which the vertices are partitioned into k > 2 disjoint sets V_i , $1 \le i < k$. In addition, if $\{u, v\}$ is an edge in E, then $u \in V_i$ and $v \in V_{i+1}$ for some $i, 1 \le i < k$.

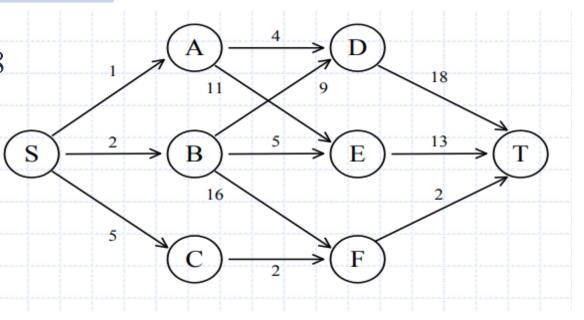


Solution as per greedy is:

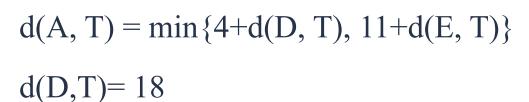
 $S A D T \Rightarrow 1+4+18$

Minimum cost is:

 $S C F T \Rightarrow 5+2+2$

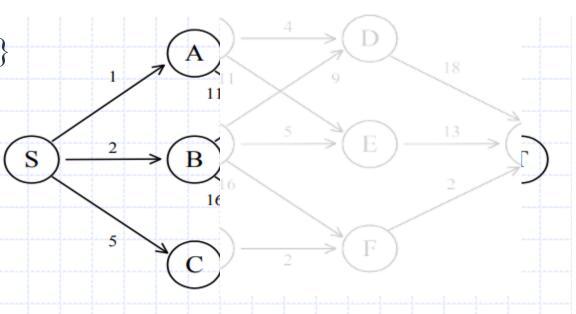


$$d(S, T) = min\{1+d(A, T), 2+d(B, T), 5+d(C, T)\}$$



$$d(E,T) = 13$$

$$d(A,T) = \min(4+18), 11+13) = 22$$

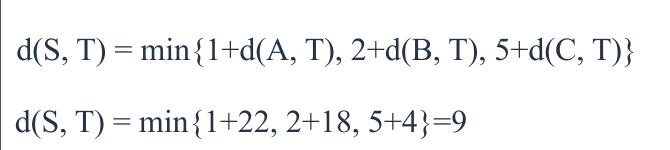


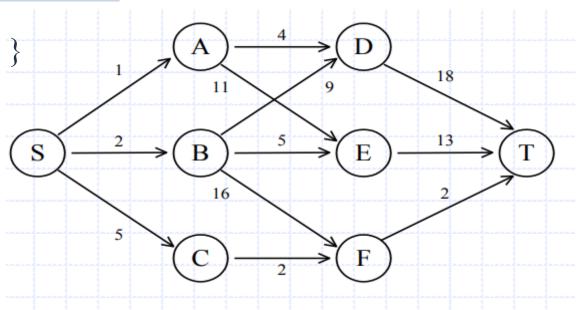
$$d(B, T) = min\{(9+d(D, T), 5+d(E, T), 16+d(F,T))\}$$

 $d(B, T) = min(9 + 18), 5 + 13, 16 + 2) = 18$

$$d(C, T) = 2+d(F,T)$$

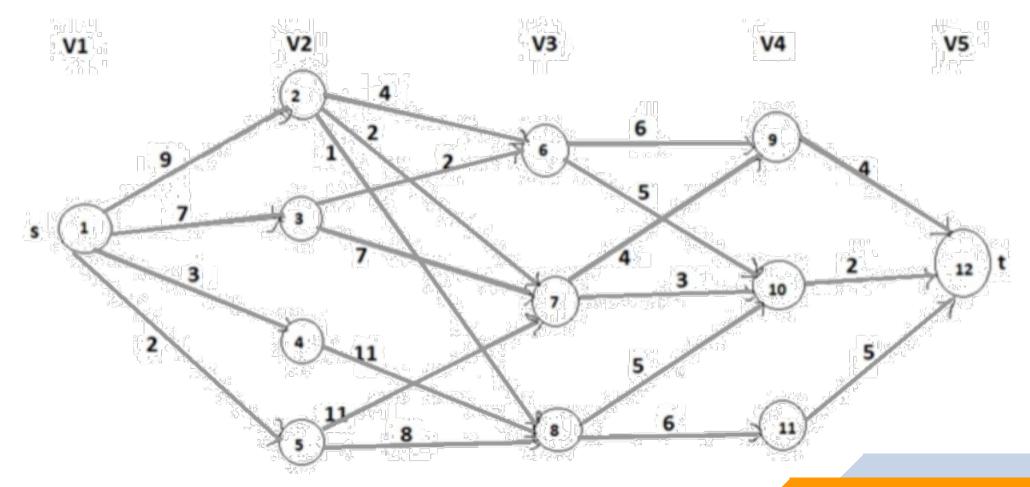
 $d(C, T) = 2 + 2 = 4$





- Backword Reasoning
- Forward Approach

What is the shortest path from source s to destination t.



1-2-7-10-12

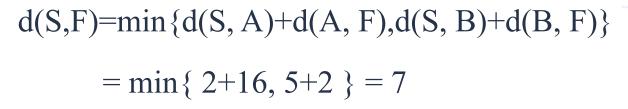
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Forward Reasoning (Backward Approach)

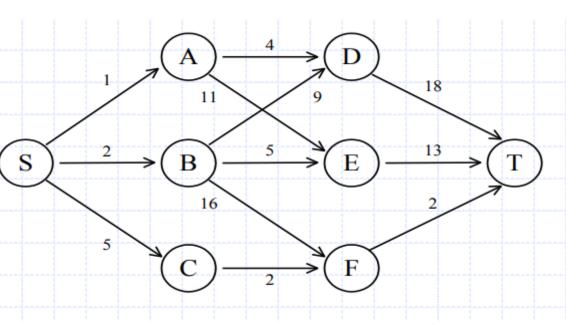
$$d(S, A) = 1 d(S, B) = 2 d(S, C) = 5$$

$$d(S,D)=min\{d(S,A)+d(A,D),d(S,B)+d(B,D)\}$$
$$=min\{1+4,2+9\}=5$$

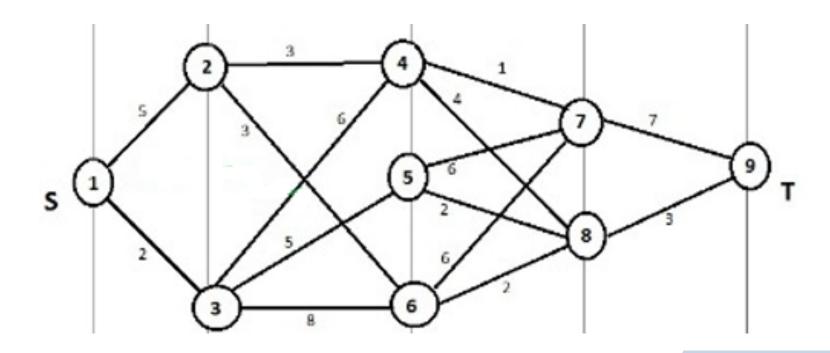
$$d(S,E)=\min\{d(S,A)+d(A,E),d(S,B)+d(B,E)\}$$
$$=\min\{1+11,2+5\}=7$$



$$d(S,T) = \min\{d(S,D)+d(D,T),d(S,E)+d(E,T),d(S,F)+d(F,T)\}$$
$$= \min\{5+18,7+13,7+2\} = 9$$



What is the shortest path from source s to destination t.



All Pair Shortest Path

Problem

Given a directed graph G=(V, E), and a weight function $w: E \to \mathbb{R}$, for each pair of vertices u, v, compute the shortest path weight $\delta(u, v)$, and a shortest path if exists.

Goal: create an $n \times n$ matrix $D = (d_{ij})$ of shortest path distances

i.e., $d_{ij} = \delta(v_i, v_j)$

Possible solution:

Run a SSSP algorithm *n* times, one for each vertex as the source.

Adjacency Matrix Representation of Graphs

 $ightharpoonup n \times n \text{ matrix } \mathbf{W} = (\omega_{ij}) \text{ of edge weights :}$

$$\omega_{ij} = \begin{cases} \omega(v_i, v_j) & \text{if } (v_i, v_j) \in E \\ \infty & \text{if } (v_i, v_j) \notin E \end{cases}$$

- ► assume $\omega_{ii} = 0$ for all $v_i \in V$, because
 - no negative weight cycle
 - ⇒ shortest path to itself has no edge,

i.e.,
$$\delta (v_i, v_i) = 0$$

Floyd Warshall Algorithm

We examine a shortest path i to j in G. This path originates at vertex i and goes through some intermediate vertices (possibly none) and terminates at vertex j.

If k is an intermediate vertex on this shortest path, then the sub paths from i to k and from k to j must be shortest paths from i to k and k to j, respectively. Otherwise, the i to j path is not of minimum length

$$A(i,j) = \min \left\{ \min_{1 \le k \le n} \{ A^{k-1}(i,k) + A^{k-1}(k,j) \}, cost(i,j) \right\}$$

Steps to find all pair shortest path

Remove all the self loops and parallel edges (keeping the lowest weight edge) from the graph.

Write the initial distance matrix.

For diagonal elements (representing self-loops), distance value = 0

For vertices having a direct edge between them, distance value = weight of that edge.

For vertices having no direct edge between them, distance value = ∞ .

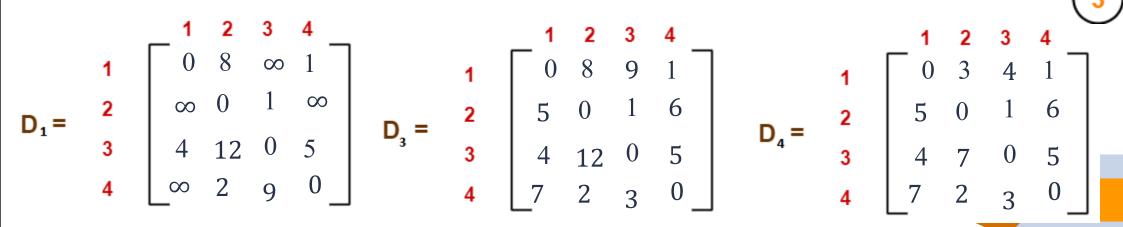
Example

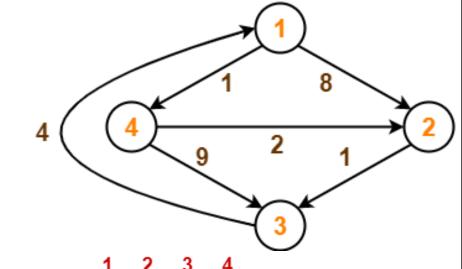
Initial distance matrix

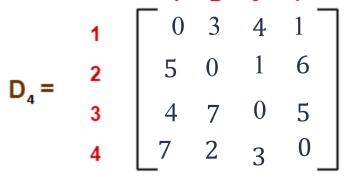
$$A^k(i,j) = \min \{A^{k-1}(i,j), A^{k-1}(i,k) + A^{k-1}(k,j)\}, k \ge 1$$

$$D_0 = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 8 & \infty & 1 \\ 2 & \infty & 0 & 1 & \infty \\ 4 & \infty & 0 & \infty \\ 4 & \infty & 2 & 9 & 0 \end{bmatrix} \quad D_2 = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 8 & 9 & 1 \\ \infty & 0 & 1 & \infty \\ 4 & 12 & 0 & 5 \\ \infty & 2 & 3 & 0 \end{bmatrix}$$

$$D_{2} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 8 & 9 & 1 \\ \infty & 0 & 1 & \infty \\ 4 & 12 & 0 & 5 \\ \infty & 2 & 3 & 0 \end{bmatrix}$$







Example

$$A^{0} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 3 & \infty & 5 \end{bmatrix}$$

$$2 & 2 & 0 & \infty & 4 \\ \infty & 1 & 0 & \infty \\ 4 & \infty & \infty & 2 & 0 \end{bmatrix}$$

$$A^{1} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 3 & \infty & 5 \end{bmatrix}$$

$$2 & 2 & 0 & 9 & 4 \\ \infty & 1 & 0 & 8 \\ \infty & \infty & 2 & 0 \end{bmatrix}$$

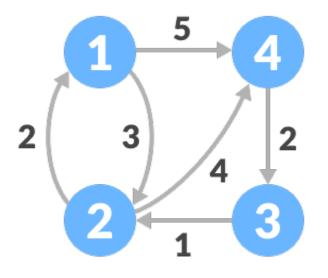
$$A^{2} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 3 & 9 & 5 \\ 2 & 0 & 9 & 4 \\ 3 & 1 & 0 & 5 \\ \infty & \infty & 2 & 0 \end{bmatrix}$$

$$A^{3} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 3 & 9 & 5 \end{bmatrix}$$

$$2 & 2 & 0 & 9 & 4 \\ 3 & 3 & 1 & 0 & 5 \\ 4 & 5 & 3 & 2 & 0 \end{bmatrix}$$

$$A^{4} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 3 & 7 & 5 \end{bmatrix}$$

$$2 & 2 & 0 & 6 & 4 \\ 3 & 3 & 1 & 0 & 5 \\ 4 & 5 & 3 & 2 & 0 \end{bmatrix}$$



Floyd Warshall Algorithm

$$A^{k}(i,j) = \min \{A^{k-1}(i,j), A^{k-1}(i,k) + A^{k-1}(k,j)\}, k \ge 1$$

```
Algorithm AllPaths(cost,A,n)
// cost[1:n,1:n] is the cost adjacency matrix of a graph with
// n vertices; A[i,j] is the cost of a shortest path from vertex
// i to vertex j. cost[i,i] = 0.0, for 1 \le i \le n.

{
	for i := 1 to n do
		for j := 1 to n do
		for k := 1 to n do
		for k := 1 to n do
		for k := 1 to k := 1 to
```

Complexity of Floyd Warshall algorithm is O(n³).