

ee24btech11015 - Dhawal

- 27) The function $f(x) = 2x - x^3 + 3$ has
- a maxima at $x = 1$ and a minima at $x = 5$
 - a maxima at $x = 1$ and a minima at $x = -5$
 - only a maxima at $x = 1$
 - only a minima at $x = 1$
- 28) A lossy capacitor C_x , rated for operation at $5kV, 50Hz$ is represented by an equivalent circuit with an ideal capacitor C_P in parallel with a resistor R_P . The value of C_P is found to be $0.102\mu F$ and the value of $R_P = 1.25M\Omega$. Then the power loss and $\tan \delta$ of the lossy capacitor operating at the rated voltage, respectively, are
- $10W$ and 0.0002
 - $10W$ and 0.0025
 - $20W$ and 0.025
 - $20W$ and 0.04

- 29) Let the Laplace transform of a function $f(t)$ which exists for $t > 0$ be $F_1(s)$ and the Laplace transform of its delayed version $f(t - \tau)$ be $F_2(s)$. Let $F_1^*(s)$ be the complex conjugate of $F_1(s)$ with the Laplace variable set as $s = \sigma + j\omega$. If

$$G(s) = \frac{F_2(s) F_1^*(s)}{|F_1(s)|^2},$$

then the inverse Laplace transform of $G(s)$ is

- an ideal impulse $\delta(t)$
 - an ideal delayed impulse $\delta(t - \tau)$
 - an ideal step function $u(t)$
 - an ideal delayed step function $u(t - \tau)$
- 30) A zero mean random signal is uniformly distributed between limits $-a$ and $+a$ and its mean square value is equal to its variance. Then the r.m.s value of the signal is
- $\frac{a}{\sqrt{3}}$
 - $\frac{a}{\sqrt{2}}$
 - $a\sqrt{2}$
 - $a\sqrt{3}$
- 31) A $220V$, DC shunt motor is operating at a speed of $1440rpm$. The armature resistance is 1.0Ω and armature current is $10A$. If the excitation of the machine is reduced by 10% , the extra resistance to be put in the armature circuit to maintain the same speed and torque will be
- 1.79Ω
 - 2.1Ω
 - 3.1Ω
 - 18.9Ω

- 32) A load center of $120MW$ derives power from two power stations connected by $220kV$ transmission lines of $25km$ and $75km$ as shown in the figure below. The

three generators $G1, G2$ and $G3$ are of $100MW$ capacity each and have identical fuel cost characteristics. The minimum loss generation schedule for supplying the $120MW$ load is



- | | |
|--------------------------------|--------------------------------|
| a) $P1 = 80MW + \text{losses}$ | c) $P1 = 40MW$ |
| $P2 = 20MW$ | $P2 = 40MW$ |
| $P3 = 20MW$ | $P3 = 40MW + \text{losses}$ |
| b) $P1 = 60MW$ | d) $P1 = 30MW + \text{losses}$ |
| $P2 = 30MW + \text{losses}$ | $P2 = 45MW$ |
| $P3 = 30MW$ | $P3 = 45MW$ |

33) The open loop transfer function $G(s)$ of a unity feedback control system is given as,

$$G(s) = \frac{k(s + \frac{2}{3})}{s^2(s + 2)}$$

From the root locus, it can be inferred that when k tends to positive infinity,

- three roots with nearly equal real parts exist on the left half of the s -plane
 - one real root is found on the right half of the s -plane
 - the root loci cross the $j\omega$ axis for a finite value of $k; k \neq 0$
 - three real roots are found on the right half of the s -plane
- 34) A portion of the main program to call a subroutine SUB in an 8085 environment is given below.

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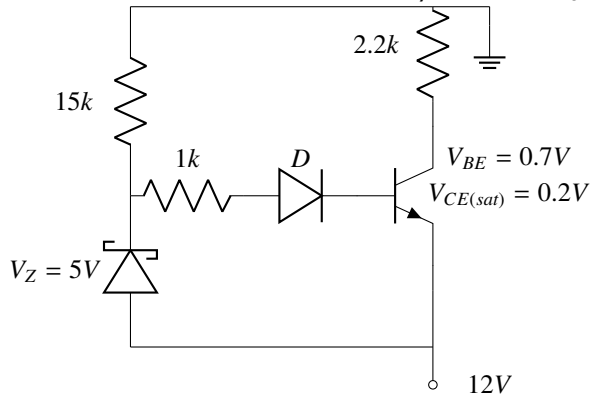
      .
      .
      .
LP:   LXI   D, DISP
      CALL SUB
      .
      .
      .

```

It is desired that control be returned to $LP + DISP + 3$ when the RET instruction is executed in the subroutine. The set of instructions that precede the RET instruction in the subroutine are

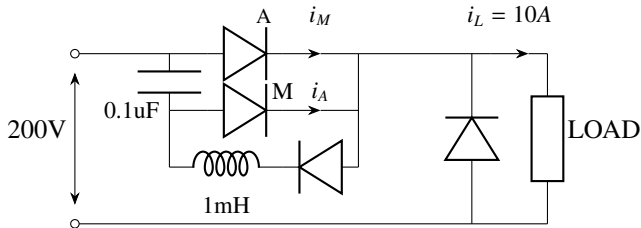
- | | | | | | | | |
|--------|---|--------|---|--------|---|---------|---|
| a) POP | D | b) POP | H | c) POP | H | d) XTHL | |
| DAD | H | DAD | D | DAD | D | INX | D |
| PUSH | D | INX | H | PUSH | H | INX | D |
| | | INX | H | | | INX | D |
| | | INX | H | | | XTHL | |
| | | PUSH | H | | | | |

- 35) The transistor used in the circuit shown below has a β of 30 and I_{CBO} is negligible.



If the forward voltage drop of the diode is $0.7V$, then the current through the collector will be:

- a) $168mA$ b) $108mA$ c) $20.54mA$ d) $5.36mA$
- 36) A voltage commutated chopper circuit, operated at $500Hz$, is shown below.



If the maximum value of load current is $10A$, then the maximum current through the main (M) and auxiliary (A) thyristors will be:

- a) $i_{Mmax} = 12A$ and $i_{Amax} = 10A$ c) $i_{Mmax} = 10A$ and $i_{Amax} = 12A$
b) $i_{Mmax} = 12A$ and $i_{Amax} = 2A$ d) $i_{Mmax} = 10A$ and $i_{Amax} = 8A$
- 37) The matrix $[A] = \begin{pmatrix} 2 & 1 \\ 4 & -1 \end{pmatrix}$ is decomposed into a product of a lower triangular matrix $[L]$ and an upper triangular matrix $[U]$. The properly decomposed $[L]$ and $[U]$ matrices respectively are

- a) $\begin{pmatrix} 1 & 0 \\ 4 & -1 \end{pmatrix}$ and $\begin{pmatrix} 1 & 1 \\ 0 & -2 \end{pmatrix}$ c) $\begin{pmatrix} 1 & 0 \\ 4 & 1 \end{pmatrix}$ and $\begin{pmatrix} 2 & 1 \\ 0 & -1 \end{pmatrix}$
b) $\begin{pmatrix} 2 & 0 \\ 4 & -1 \end{pmatrix}$ and $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ d) $\begin{pmatrix} 2 & 0 \\ 4 & -3 \end{pmatrix}$ and $\begin{pmatrix} 1 & 0.5 \\ 0 & 1 \end{pmatrix}$

- 38) The two vectors $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ a \\ a^2 \end{pmatrix}$, where $a = \left(\frac{1}{2} + j\frac{\sqrt{3}}{2}\right)$, are

- a) orthonormal b) orthonormal c) parallel d) collinear

39) A three-phase 440V, 6 pole, 50Hz, squirrel cage induction motor is running at a slip of 5%. The speed of stator magnetic field with respect to rotor magnetic field and speed of rotor with respect to stator magnetic field are

- a) 0, $-5rpm$ c) $1000rpm$, $-5rpm$
b) 0, $955rpm$ d) $1000rpm$, $955rpm$