

## Objective

This example demonstrates UART communication and blinks an LED using a TCPWM resource on PSoC® 6 MCU, using ModusToolbox™ IDE.

## Requirements

**Tool:** [ModusToolbox™ 1.1](#)

**Programming Language:** C

**Associated Parts:** All [PSoC 6 MCU](#) parts

**Related Hardware:** [PSoC 6 WiFi-BT Pioneer Kit](#), [PSoC 6 BLE Pioneer Kit](#), [PSoC 6 WiFi-BT Prototyping Kit](#)

## Overview

This example uses the Arm® Cortex-M4 (CM4) CPU of PSoC 6 MCU to execute two tasks: UART communication and LED control. At device reset, the default Cortex-M0+ (CM0+) application enables the CM4 CPU and configures CM0+ CPU to go to sleep. The CM4 CPU uses a UART resource to print a “Hello World” message in a UART terminal emulator. When the user presses the Enter key, the LED on the kit starts blinking.

## Hardware Setup

This example uses the PSoC 6 WiFi-BT Pioneer Kit's default configuration. Refer to the kit guide to ensure that the kit is configured correctly. You can also use other PSoC 6 kits by importing the application for that kit.

**Note:** The PSoC 6 BLE Pioneer kit and the PSoC 6 WiFi-BT Pioneer kit ship with KitProg2. ModusToolbox only works with KitProg3. Before using this code example, make sure that the kit is upgraded to KitProg3. See [ModusToolbox Help > ModusToolbox IDE Documentation > User Guide](#); section PSoC 6 MCU KitProg Firmware Loader. If you do not upgrade, you will see an error like “unable to find CMSIS-DAP device” or “KitProg firmware is out of date”.

## Software Setup

This example uses a terminal emulator program. Install one on your PC if you don't have one. The instructions use [Tera Term](#).

## Operation

1. Connect the Pioneer board to your PC using the provided USB cable through the USB connector.
2. Open a terminal program and select the KitProg3 COM port. Set the serial port parameters to 8N1 and 115,200 baud.
3. Import the application into a new workspace. If you are unsure how to import an application, see [KBA225201](#).
4. Program the PSoC 6 MCU device. Select the 'mainapp' project. In the **Quick Panel**, scroll down, and click **Program (Kitprog3)**.
5. After programming, the application starts automatically. Confirm that “Hello World!” is displayed on the UART terminal.
6. Press the **Enter** key. Confirm that the kit LED blinks at an approximate 1-Hz rate.

## Debugging

You can debug the example to step through the code. Use **Debug (KitProg3)** configuration in the **Quick Panel**. If you are unfamiliar with how to start a debug session with ModusToolbox IDE, see [KBA224621](#) in the Cypress community.

## Design and Implementation

This example configures a TCPWM resource in Timer mode to blink the LED, and a serial communication block (SCB) resource to send a message and read serial input.

The TCPWM resource is connected to a clock operating at 2 kHz, with a compare value of 1000. It generates an interrupt on overflow/terminal count and this interrupt is used to toggle the state of the user LED on the kit. The interrupt configuration is done in the firmware.

The Serial Communication Block resource is configured as a UART at 115200 baud, 8N1. It is connected to a clock operating at 923 kHz to generate the correct baud rate. The RX is on pin P5[0] and TX is on P5[1], to match the pin usage on the kit.

The resources are configured and application code runs on the CM4 CPU.

To see all the settings, review the *design.modus* file in the application.

## Resources and Settings

Table 1 lists the resources used in this example, and how they are used in the design.

Table 1. ModusToolbox Resources

Resource	Alias	Purpose	Non-default Settings
Timer Counter (TCPWM)	Timer	Drives the user LED using an interrupt.	See <a href="#">Figure 1</a>
SCB	KIT_UART	Prints a message to a terminal window.	See <a href="#">Figure 2</a>
Digital Output Pin	KIT_LED2	Provides visual feedback.	See <a href="#">Figure 3</a>
	KIT_UART_TX	Used for UART transmit (Tx).	See <a href="#">Figure 4</a>
Digital Input Pin	KIT_UART_RX	Used for UART receive (Rx).	See <a href="#">Figure 5</a>

Figure 1 to Figure 5 show non-default configuration settings for the resources.

Figure 1. Timer Configuration

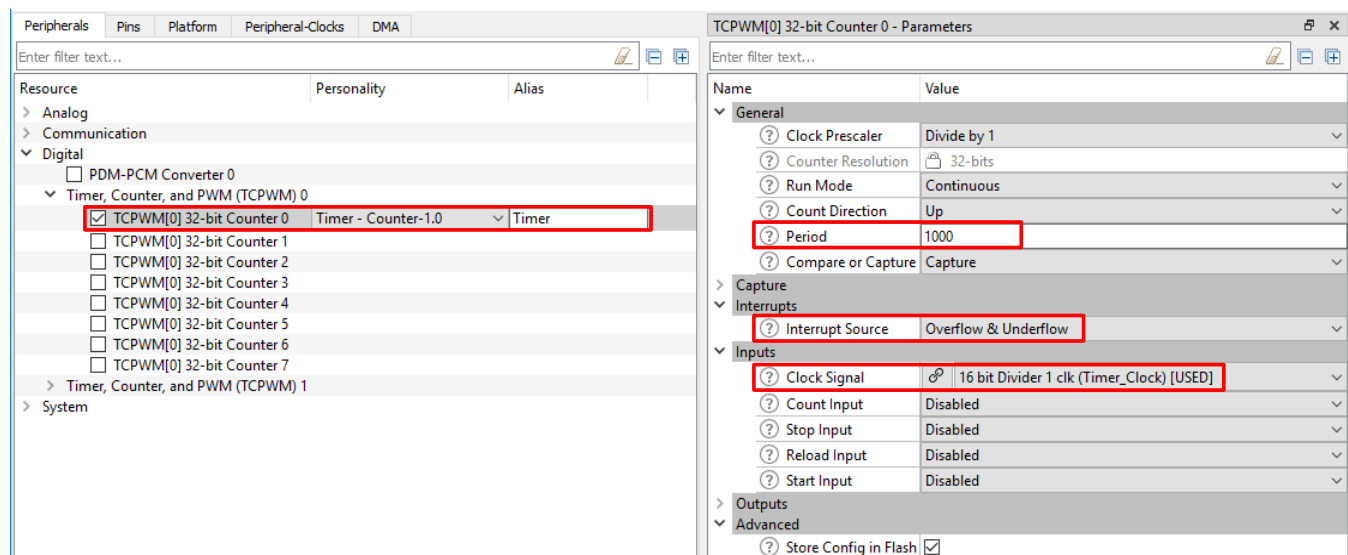
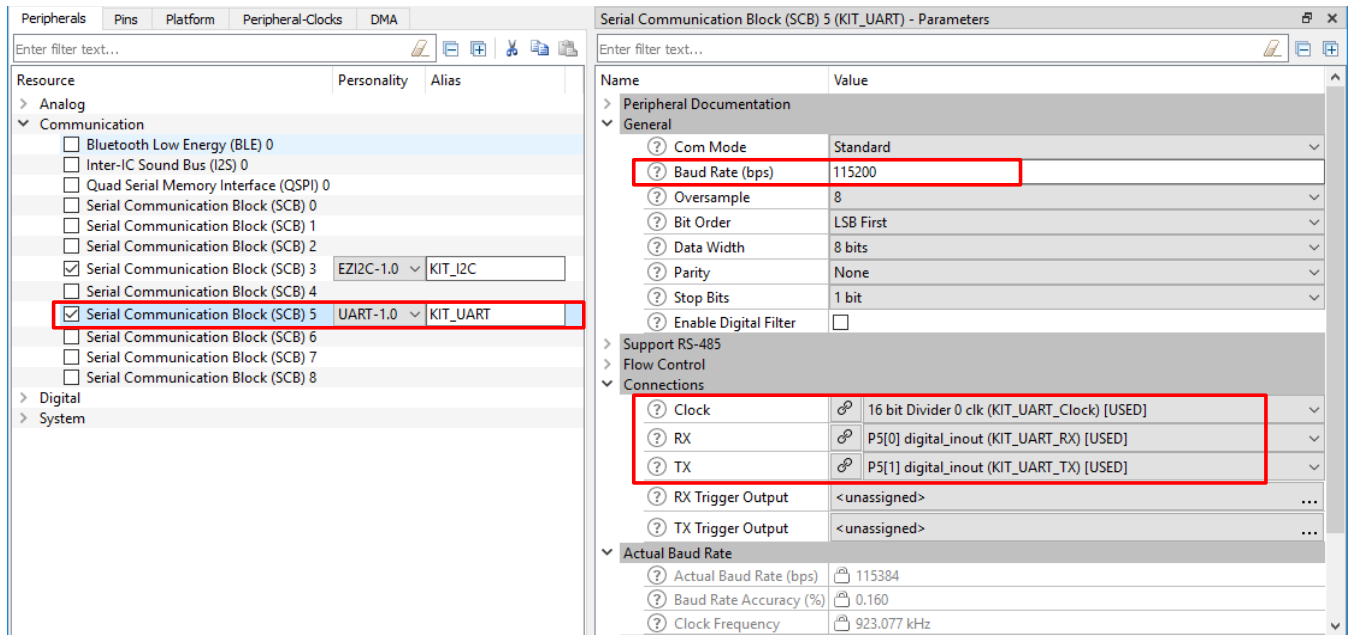


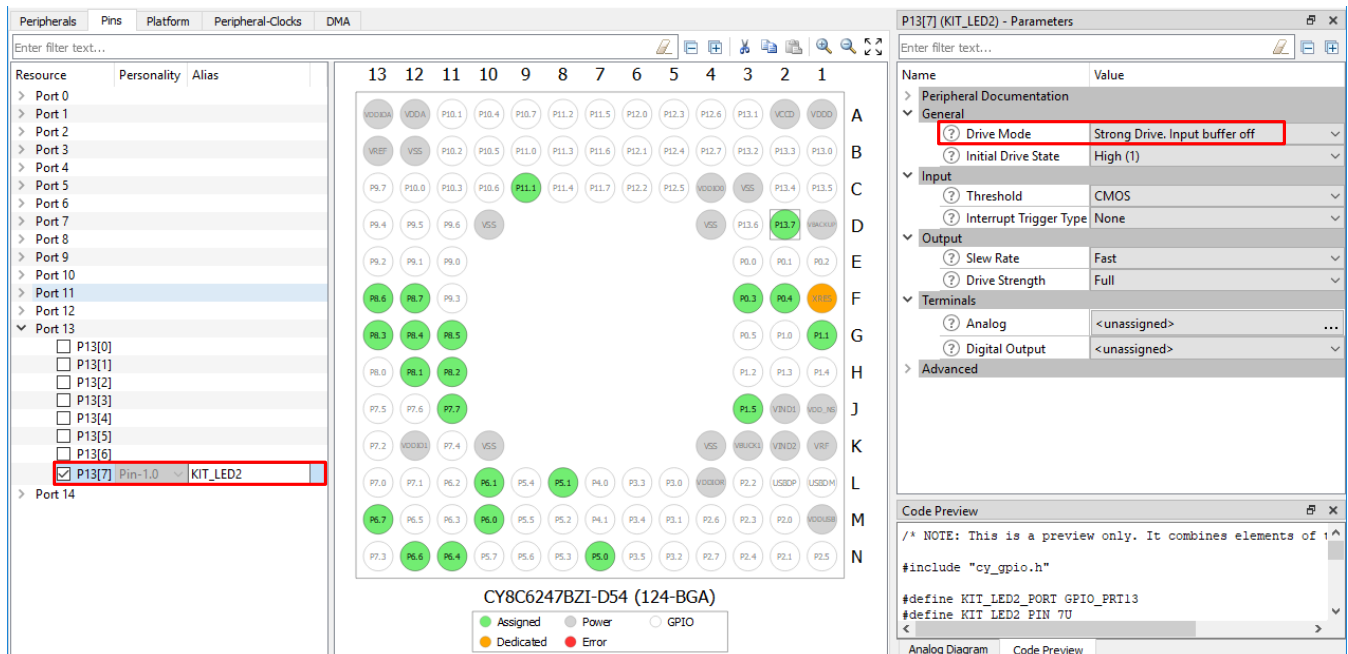
Figure 2. UART Configuration



**Serial Communication Block (SCB) 5 (KIT\_UART) - Parameters**

Name	Value
Com Mode	Standard
Baud Rate (bps)	115200
Oversample	8
Bit Order	LSB First
Data Width	8 bits
Parity	None
Stop Bits	1 bit
Enable Digital Filter	<input type="checkbox"/>
Clock	16 bit Divider 0 clk (KIT_UART_Clock) [USED]
RX	P5[0] digital_inout (KIT_UART_RX) [USED]
TX	P5[1] digital_inout (KIT_UART_TX) [USED]
RX Trigger Output	<unassigned>
TX Trigger Output	<unassigned>
Actual Baud Rate (bps)	115384
Baud Rate Accuracy (%)	0.160
Clock Frequency	923.077 kHz

Figure 3. GPIO Pin configuration for LED



**P13[7] (KIT\_LED2) - Parameters**

Name	Value
Drive Mode	Strong Drive, Input buffer off
Initial Drive State	High (1)
Threshold	CMOS
Interrupt Trigger Type	None
Slew Rate	Fast
Drive Strength	Full
Analog	<unassigned>
Digital Output	<unassigned>

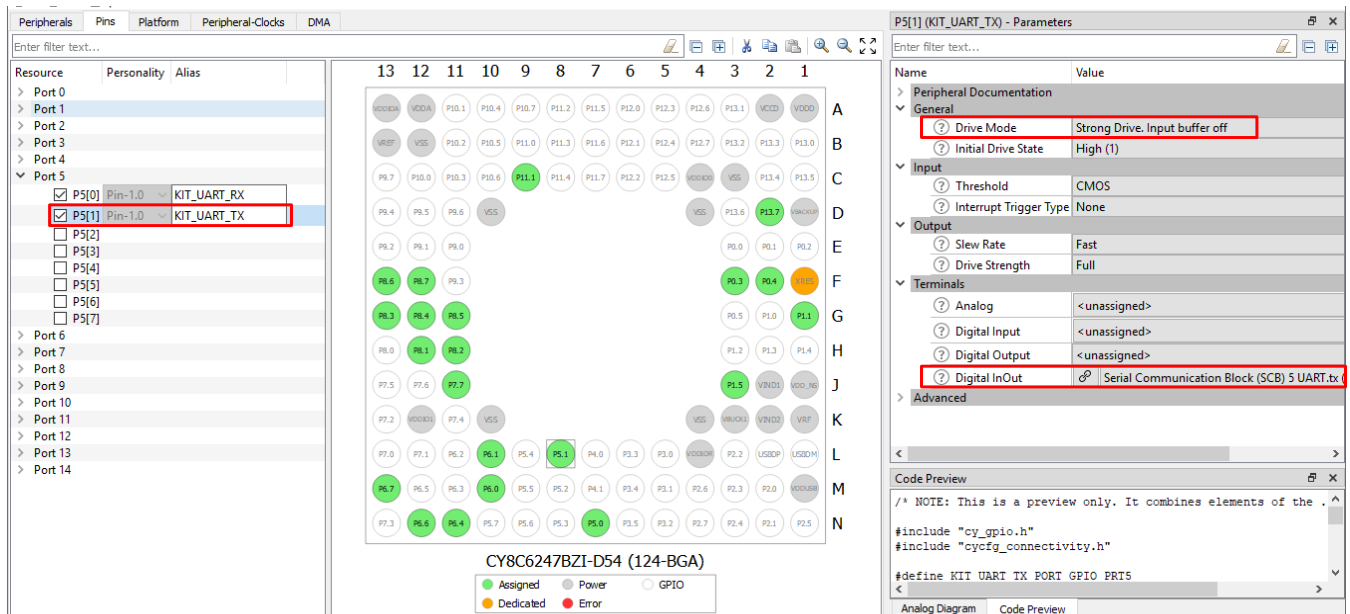
**Code Preview**

```

/* NOTE: This is a preview only. It combines elements of
#include "cy_gpio.h"

#define KIT_LED2_PORT GPIO_PRT13
#define KIT_LED2_PIN 7U
  
```

Figure 4. GPIO Pin Configuration for UART Tx



The screenshot shows the PSoC Creator interface for configuring the GPIO pins of the P5[1] (KIT\_UART\_TX) peripheral. The pin P5[1] is assigned to the KIT\_UART\_TX peripheral. The parameters for this peripheral are shown on the right.

Name	Value
Peripheral Documentation	
General	
Drive Mode	Strong Drive, Input buffer off
Initial Drive State	High (1)
Input	
Threshold	CMOS
Interrupt Trigger Type	None
Output	
Slew Rate	Fast
Drive Strength	Full
Terminals	
Analog	<unassigned>
Digital Input	<unassigned>
Digital Output	<unassigned>
Digital InOut	Serial Communication Block (SCB) 5 UART.tx
Advanced	

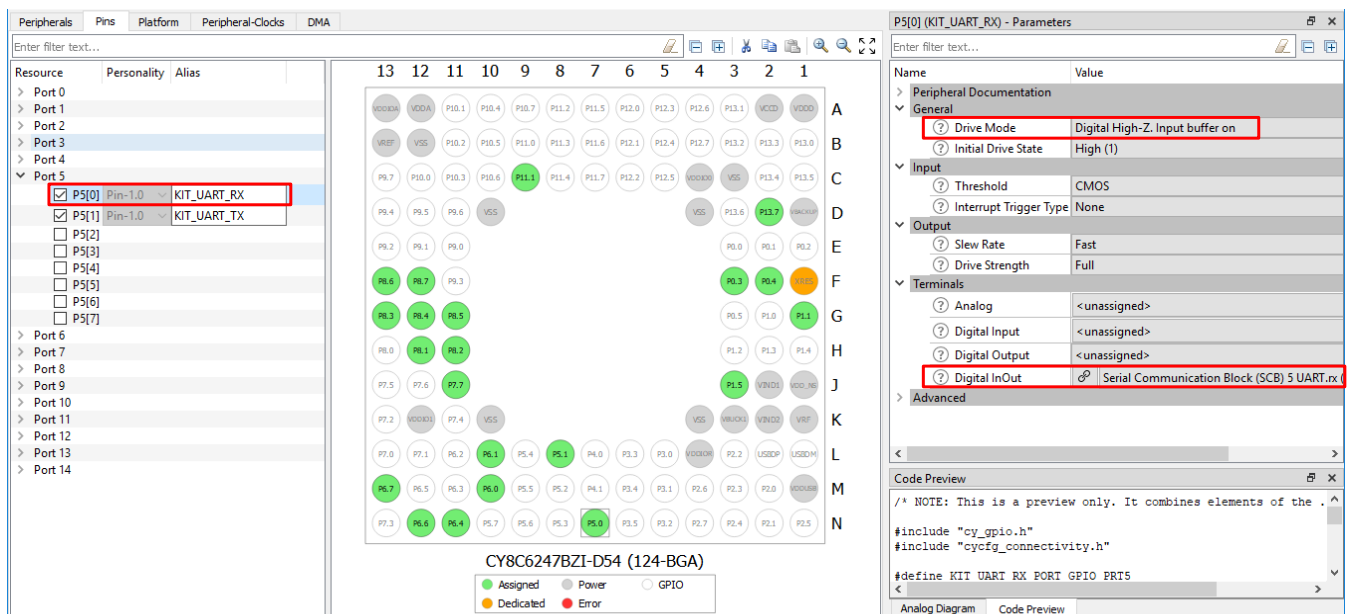
Code Preview:

```

/* NOTE: This is a preview only. It combines elements of the .
#include "cy_gpio.h"
#include "cycfg_connectivity.h"

#define KIT_UART_TX PORT GPIO PRT5
  
```

Figure 5. GPIO Pin Configuration for UART Rx



The screenshot shows the PSoC Creator interface for configuring the GPIO pins of the P5[0] (KIT\_UART\_RX) peripheral. The pin P5[0] is assigned to the KIT\_UART\_RX peripheral. The parameters for this peripheral are shown on the right.

Name	Value
Peripheral Documentation	
General	
Drive Mode	Digital High-Z, Input buffer on
Initial Drive State	High (1)
Input	
Threshold	CMOS
Interrupt Trigger Type	None
Output	
Slew Rate	Fast
Drive Strength	Full
Terminals	
Analog	<unassigned>
Digital Input	<unassigned>
Digital Output	<unassigned>
Digital InOut	Serial Communication Block (SCB) 5 UART.rx
Advanced	

Code Preview:

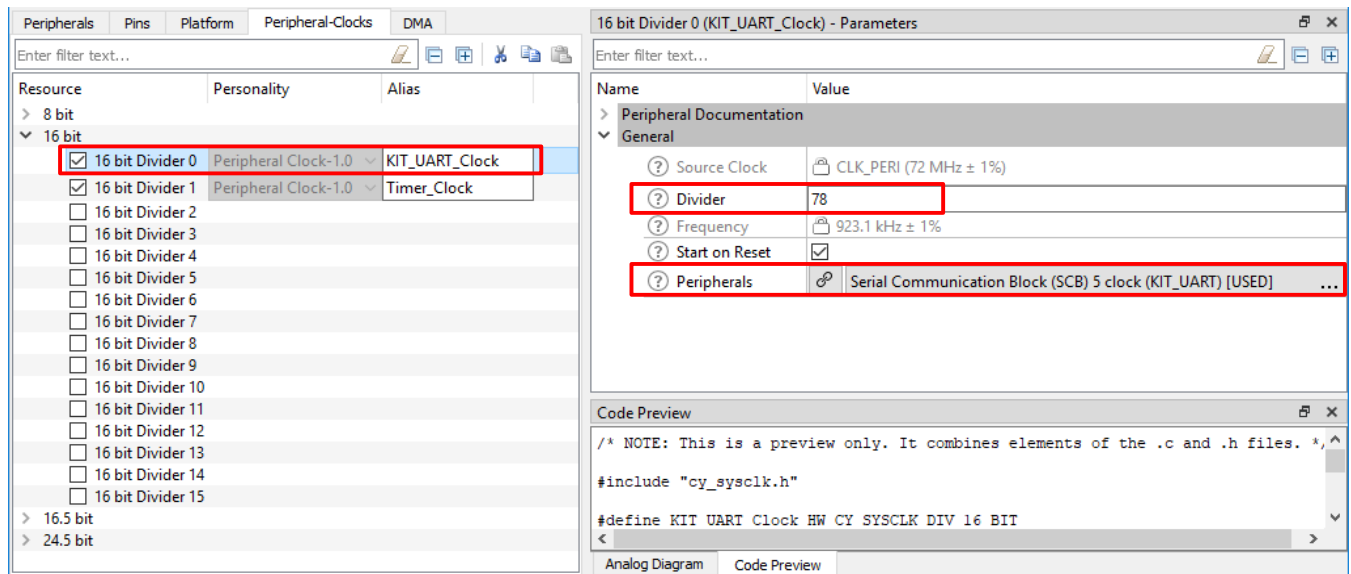
```

/* NOTE: This is a preview only. It combines elements of the .
#include "cy_gpio.h"
#include "cycfg_connectivity.h"

#define KIT_UART_RX PORT GPIO PRT5
  
```

Figure 6 and Figure 7 show the Peripheral-Clock configuration for UART and TCPWM resources respectively.

Figure 6. Peripheral-Clock Configuration for UART



16 bit Divider 0 (KIT\_UART\_Clock) - Parameters

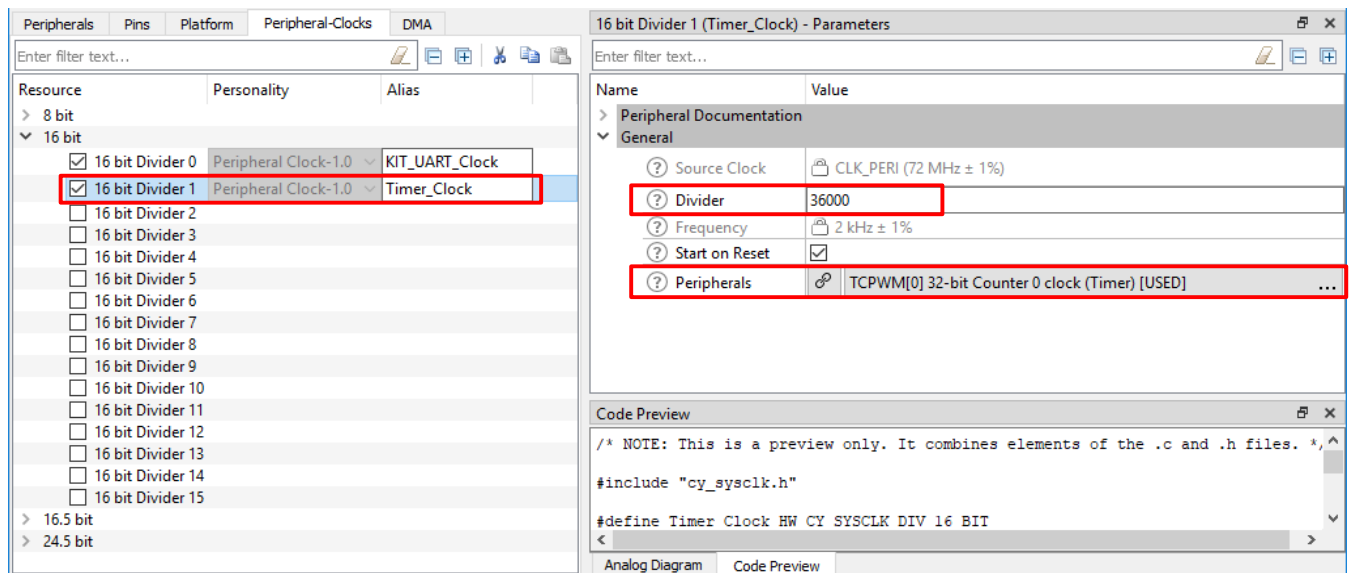
Name	Value
Source Clock	CLK_PERI (72 MHz ± 1%)
Divider	78
Frequency	923.1 kHz ± 1%
Start on Reset	<input checked="" type="checkbox"/>
Peripherals	Serial Communication Block (SCB) 5 clock (KIT_UART) [USED]

```

/* NOTE: This is a preview only. It combines elements of the .c and .h files. */
#include "cy_sysclk.h"

#define KIT_UART_Clock_HW_CY_SYSClk_DIV_16_BIT
  
```

Figure 7. Peripheral-Clock Configuration for Timer



16 bit Divider 1 (Timer\_Clock) - Parameters

Name	Value
Source Clock	CLK_PERI (72 MHz ± 1%)
Divider	36000
Frequency	2 kHz ± 1%
Start on Reset	<input checked="" type="checkbox"/>
Peripherals	TCPWM[0] 32-bit Counter 0 clock (Timer) [USED]

```

/* NOTE: This is a preview only. It combines elements of the .c and .h files. */
#include "cy_sysclk.h"

#define Timer_Clock_HW_CY_SYSClk_DIV_16_BIT
  
```

Table 2 shows the pin assignment for the application.

Table 2. Pin Assignments

Name	Port
LED	P13[7]
UART_RX	P5[0]
UART_TX	P5[1]

## Reusing This Example

This example is designed for the [CY8CKIT-062-WiFi-BT Pioneer Kit](#). To use the design on a different PSoC 6 MCU kit, import the application for that kit. If you are unsure how to import an application, see [KBA225201](#). If changing to a different hardware, you may need to reassign pins.

Table 3. Device and Pin Mapping Table across PSoC 6 MCU Kits

Kit Name	Device Used	LED	UART_RX	UART_TX
CY8CKIT-062-WiFi-BT	CY8C6247BZI-D54	P13[7]	P5[0]	P5[1]
CY8CKIT-062-BLE	CY8C6347BZI-BLD53	P13[7]	P5[0]	P5[1]
CY8CPROTO-062-4343W	CY8C624ABZI-D44	P13[7]	P5[0]	P5[1]

In some cases, a resource used by a code example (for example, a peripheral) is not supported on another device. In that case, the example will not work. If you build the code targeted at such a device, you will get errors. See the device datasheet for information on what a particular resource the device supports.

## Related Documents

For a comprehensive list of PSoC 6 MCU resources, see [KBA223067](#) in the Cypress community.

Application Notes	
<a href="#">AN210781</a> – Getting Started with PSoC 6 MCU with Bluetooth Low Energy (BLE) Connectivity	Describes PSoC 6 MCU with BLE Connectivity devices and how to build your first PSoC Creator project
<a href="#">AN221774</a> – Getting Started with PSoC 6 MCU	Describes PSoC 6 MCU devices and how to build your first ModusToolbox application and PSoC Creator project
<a href="#">AN215656</a> – PSoC 6 MCU: Dual-CPU System Design	Describes the dual-CPU architecture in PSoC 6 MCU, and shows how to build a simple dual-CPU design
Code Examples	
Visit the <a href="#">Cypress GitHub site</a> for a comprehensive collection of code examples using ModusToolbox IDE	
Device Documentation	
<a href="#">PSoC 6 MCU: PSoC 62 Datasheet</a>	<a href="#">PSoC 6 MCU: PSoC 62 Architecture Technical Reference Manual (TRM)</a>
<a href="#">PSoC 6 MCU: PSoC 63 with BLE Datasheet</a>	<a href="#">PSoC 6 MCU: PSoC 63 with BLE Architecture Technical Reference Manual</a>
Development Kit Documentation	
<a href="#">CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit</a>	
<a href="#">CY8CKIT-062-WiFi-BT PSoC 6 WiFi-BT Pioneer Kit</a>	
<a href="#">CY8CPROTO-062-4343W PSoC 6 Wi-Fi BT Prototyping Kit</a>	
Tool Documentation	
<a href="#">ModusToolbox IDE</a>	The Cypress IDE for IoT designers

## Cypress Resources

Cypress provides a wealth of data at [www.cypress.com](http://www.cypress.com) to help you to select the right device, and quickly and effectively integrate the device into your design.

For the PSoC 6 MCU devices, see [KBA223067](#) in the Cypress community for a comprehensive list of PSoC 6 MCU resources.

## Document History

Document Title: CE221773 – PSoC 6 MCU: Hello World

Document Number: 002-23541

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	6322373	SNVN	11/21/2018	New code example
*A	6344057	SNVN	02/06/2019	Code example updated for ModusToolbox 1.1

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