

Objective

This example demonstrates UART communication and blinks an LED using a TCPWM resource on PSoC® 6 MCU, using ModusToolbox™ IDE.

Requirements

Tool: [ModusToolbox™ 1.0](#)

Programming Language: C

Associated Parts: All [PSoC 6 MCU](#) parts

Related Hardware: [PSoC 6 WiFi-BT Pioneer Kit](#), [PSoC 6 BLE Pioneer Kit](#), [PSoC 6 WiFi-BT Prototyping Kit](#)

Overview

This example uses the Arm® Cortex-M4 (CM4) CPU of PSoC 6 MCU to execute two tasks: UART communication and LED control. At device reset, the Cortex-M0+ (CM0+) CPU enables the CM4 CPU. The CM4 CPU uses a UART resource to print a "Hello World" message in a UART terminal emulator. When the user presses the Enter key, the LED on the kit starts blinking.

Hardware Setup

This example uses the PSoC 6 WiFi-BT Pioneer Kit's default configuration. Refer to the kit guide to ensure that the kit is configured correctly. You can also use PSoC 6 BLE Pioneer Kit or PSoC 6 BLE Prototyping Kit or PSoC 6 WiFi-BT Prototyping Board Kit by modifying the application to use the corresponding device on the board.

Note: The PSoC 6 BLE Pioneer kit and the PSoC 6 WiFi-BT Pioneer kit ship with KitProg2. ModusToolbox only works with KitProg3. Before using this code example, make sure that the kit is upgraded to KitProg3. See [ModusToolbox Help > ModusToolbox IDE Documentation > User Guide](#); section [PSoC 6 MCU KitProg Firmware Loader](#). If you do not upgrade, you will see an error like "unable to find CMSIS-DAP device" or "KitProg firmware is out of date".

Software Setup

This example uses a terminal emulator program. Install one on your PC if you don't have one. The instructions use [Tera Term](#).

Operation

1. Connect the Pioneer board to your PC using the provided USB cable through the USB connector.
2. Open your terminal program and select the KitProg3 COM port. Set the serial port parameters to 8N1 and 115,200 baud.
3. Import the application into a new workspace. If you are unsure how to import an application, see [KBA225201](#).
4. Program the PSoC 6 MCU device. Select the 'mainapp' project. In the **Quick Panel**, scroll down, and click **Program Kitprog3**.
5. After programming, the application starts automatically. Confirm that "Hello World!" is displayed on the UART terminal.
6. Press the **Enter** key. Confirm that the kit LED blinks at an approximate 1-Hz rate.

Debugging

You can debug the example to step through the code. Use a **Program+Debug** configuration in the **Quick Panel**. If you are unfamiliar with how to start a debug session with ModusToolbox IDE, see [KBA224621](#) in the Cypress community.

Design and Implementation

This example configures a TCPWM resource in Timer mode to blink the LED, and a serial communication block (SCB) resource to send a message and read serial input.

The TCPWM resource is connected to a clock operating at 2 kHz, with a compare value of 1000. It generates an interrupt on overflow/terminal count and this interrupt is used to toggle the state of the user LED on the kit. The interrupt configuration is done in the firmware.

The Serial Communication Block resource is configured as a UART at 115200 baud, 8N1. It is connected to a clock operating at 923 kHz to generate the correct baud rate. The RX is on pin P5[0] and TX is on P5[1], to match the pin usage on the kit.

All application code runs on the CM4 CPU. The resource configuration is performed by the CM0+ CPU.

To see all the settings, review the *design.modus* file in the project.

Resources and Settings

Table 1 lists the resources used in this example, and how they are used in the design.

Table 1. ModusToolbox Resources

Resource	Alias	Purpose	Non-default Settings
Timer Counter (TCPWM)	Timer	Drives the user LED using an interrupt.	See Figure 1
SCB	KIT_UART	Prints a message to a terminal window.	See Figure 2
Digital Output Pin	KIT_LED2	Provides visual feedback.	See Figure 3
	KIT_UART_TX	Used for UART transmit (Tx).	See Figure 4
Digital Input Pin	KIT_UART_RX	Used for UART receive (Rx).	See Figure 5

Figure 1 to Figure 5 show non-default configuration settings for the resources.

Figure 1. Timer Configuration

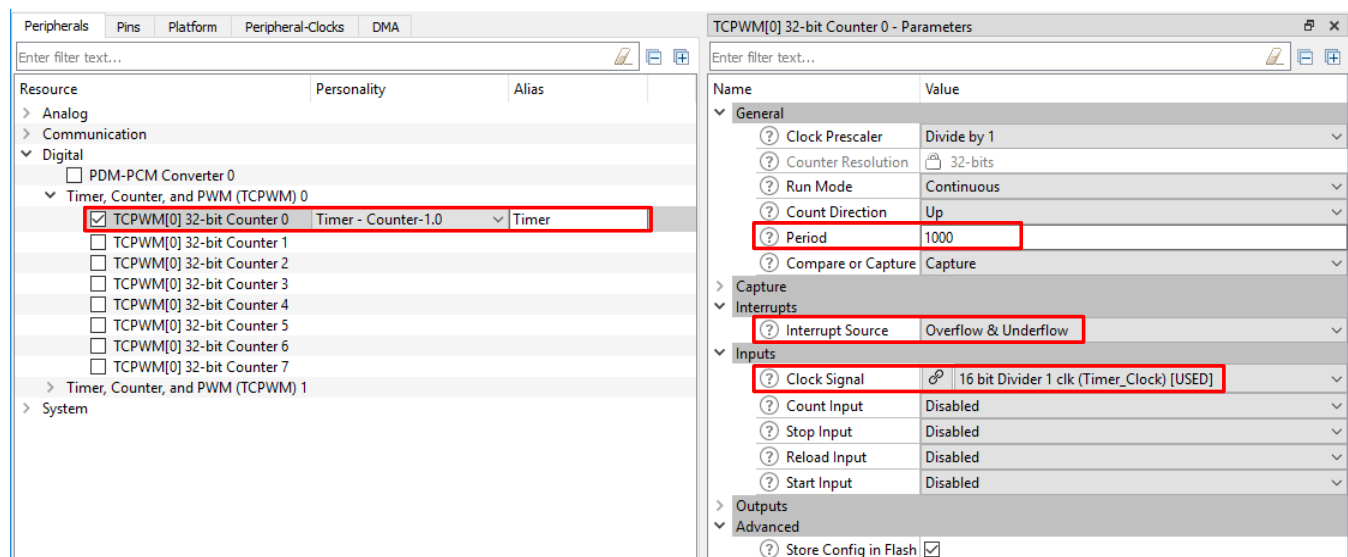
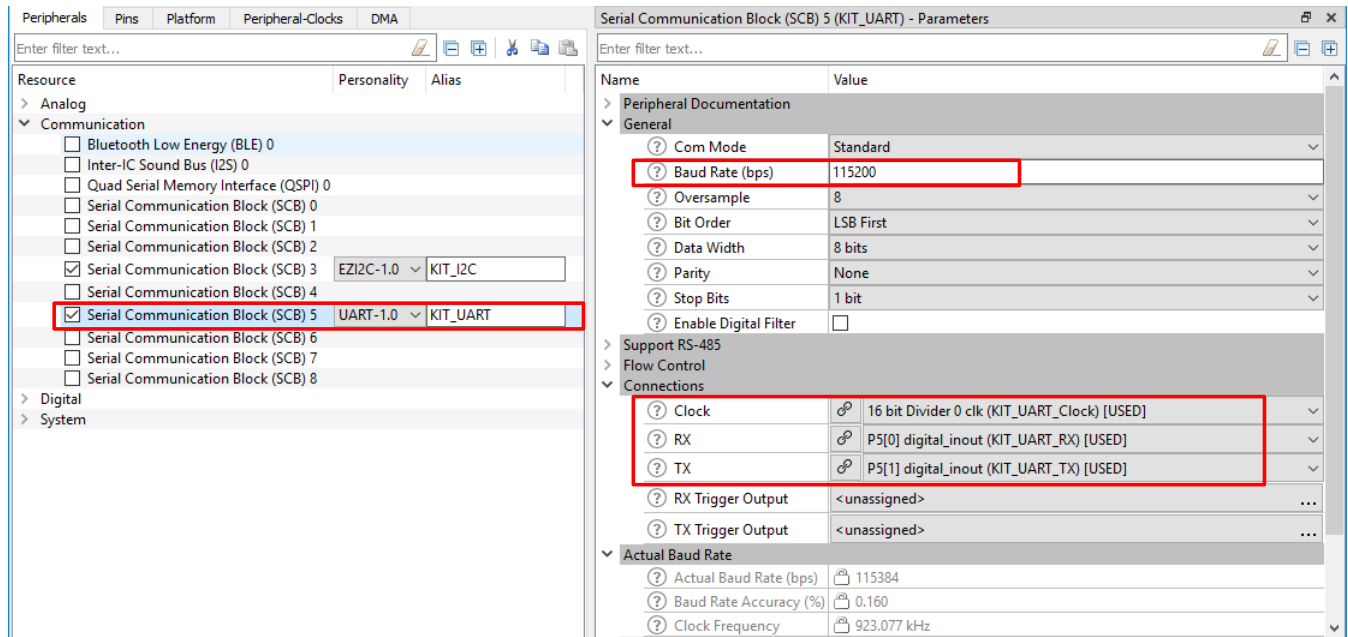


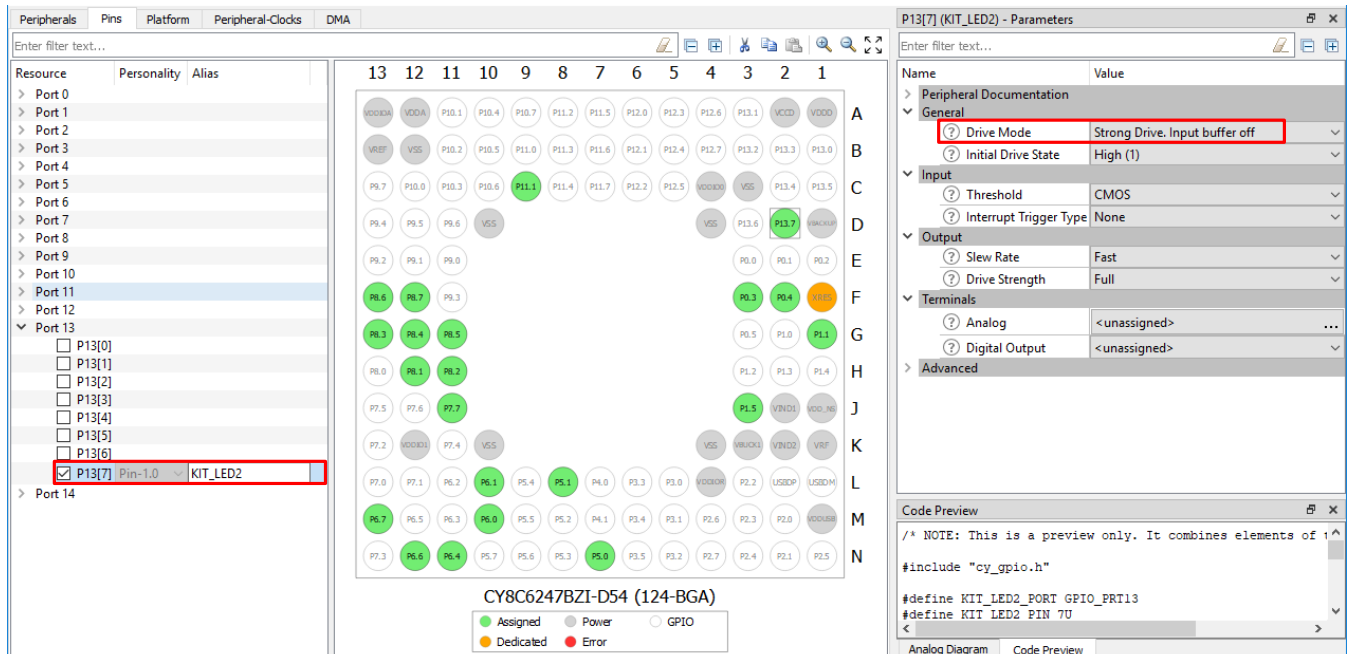
Figure 2. UART Configuration



The screenshot displays the PSoC Creator interface for configuring the UART peripheral. On the left, the 'Resource' pane shows the 'Serial Communication Block (SCB) 5' selected under the 'Communication' category. The right pane, titled 'Serial Communication Block (SCB) 5 (KIT_UART) - Parameters', shows the following settings:

- Com Mode:** Standard
- Baud Rate (bps):** 115200
- Over-sample:** 8
- Bit Order:** LSB First
- Data Width:** 8 bits
- Parity:** None
- Stop Bits:** 1 bit
- Enable Digital Filter:** ☐
- Clock:** 16 bit Divider 0 clk (KIT_UART_Clock) [USED]
- RX:** P5[0] digital_inout (KIT_UART_RX) [USED]
- TX:** P5[1] digital_inout (KIT_UART_TX) [USED]
- Actual Baud Rate:** 115384
- Baud Rate Accuracy (%):** 0.160
- Clock Frequency:** 923.077 kHz

Figure 3. GPIO Pin configuration for LED



The screenshot displays the PSoC Creator interface for configuring the GPIO pin for the LED. On the left, the 'Resource' pane shows 'P13[7] Pin-1.0' selected under the 'Port 13' category. The right pane, titled 'P13[7] (KIT_LED2) - Parameters', shows the following settings:

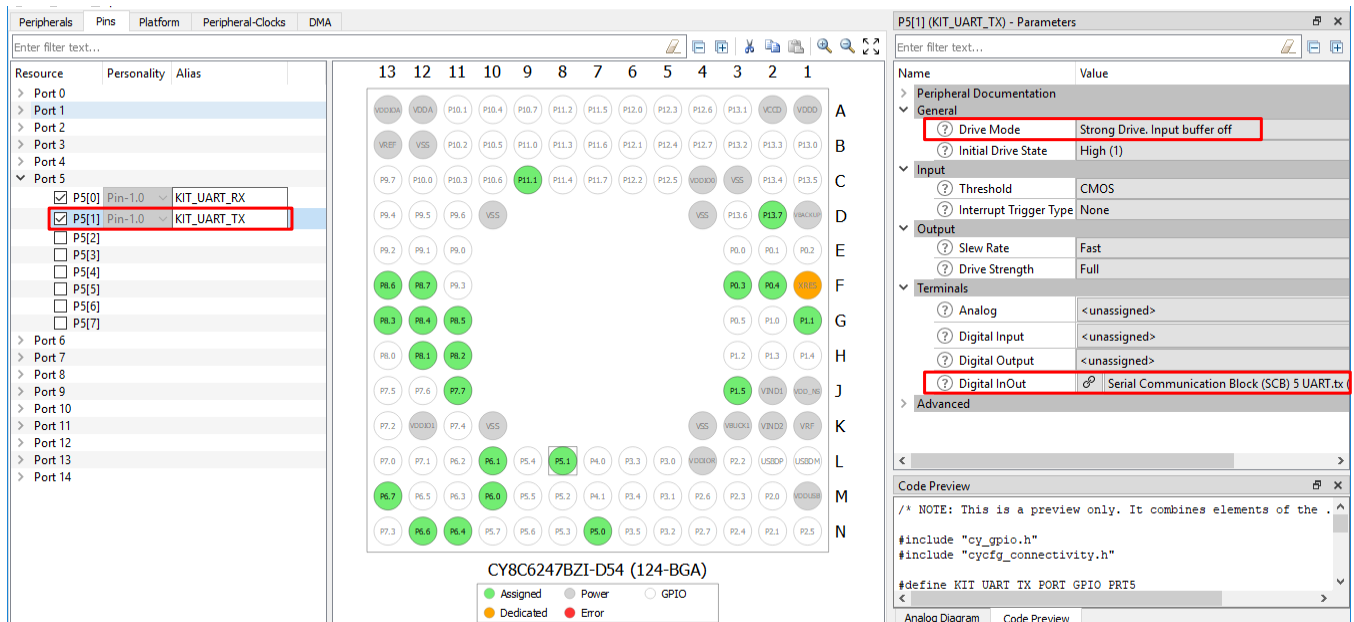
- Drive Mode:** Strong Drive, Input buffer off
- Initial Drive State:** High (1)
- Threshold:** CMOS
- Interrupt Trigger Type:** None
- Slew Rate:** Fast
- Drive Strength:** Full
- Analog:** <unassigned>
- Digital Output:** <unassigned>

The bottom pane shows the code preview for the LED configuration:

```

/* NOTE: This is a preview only. It combines elements of
#include "cy_gpio.h"
#define KIT_LED2_PORT GPIO_PRT13
#define KIT_LED2_PIN 7U
  
```

Figure 4. GPIO Pin Configuration for UART Tx



The screenshot displays the PSoC Creator interface for configuring the GPIO pins of a PSoC 6 MCU. The central pin map shows the CY8C6247BZI-D54 (124-BGA) package with pins 1 through 13. Pin 1 is assigned to P5[1] (KIT_UART_TX). The parameters window for P5[1] (KIT_UART_TX) is open, showing the following configuration:

- General:**
 - Drive Mode: Strong Drive, Input buffer off
 - Initial Drive State: High (1)
- Input:**
 - Threshold: CMOS
 - Interrupt Trigger Type: None
- Output:**
 - Slew Rate: Fast
 - Drive Strength: Full
- Terminals:**
 - Analog: <unassigned>
 - Digital Input: <unassigned>
 - Digital Output: <unassigned>
 - Digital InOut: Serial Communication Block (SCB) 5 UART.tx

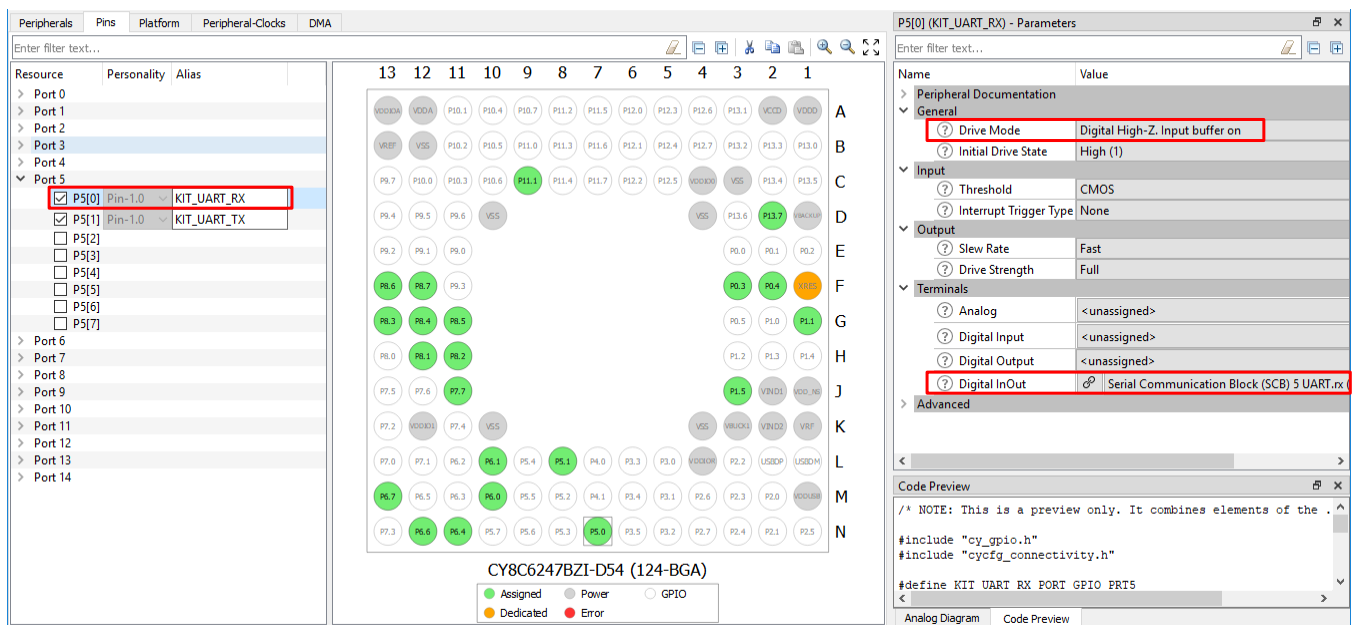
The code preview shows the following configuration:

```

#include "cy_gpio.h"
#include "cycfg_connectivity.h"

#define KIT_UART_TX PORT GPIO PRT5
  
```

Figure 5. GPIO Pin Configuration for UART Rx



The screenshot displays the PSoC Creator interface for configuring the GPIO pins of a PSoC 6 MCU. The central pin map shows the CY8C6247BZI-D54 (124-BGA) package with pins 1 through 13. Pin 0 is assigned to P5[0] (KIT_UART_RX). The parameters window for P5[0] (KIT_UART_RX) is open, showing the following configuration:

- General:**
 - Drive Mode: Digital High-Z, Input buffer on
 - Initial Drive State: High (1)
- Input:**
 - Threshold: CMOS
 - Interrupt Trigger Type: None
- Output:**
 - Slew Rate: Fast
 - Drive Strength: Full
- Terminals:**
 - Analog: <unassigned>
 - Digital Input: <unassigned>
 - Digital Output: <unassigned>
 - Digital InOut: Serial Communication Block (SCB) 5 UART.rx

The code preview shows the following configuration:

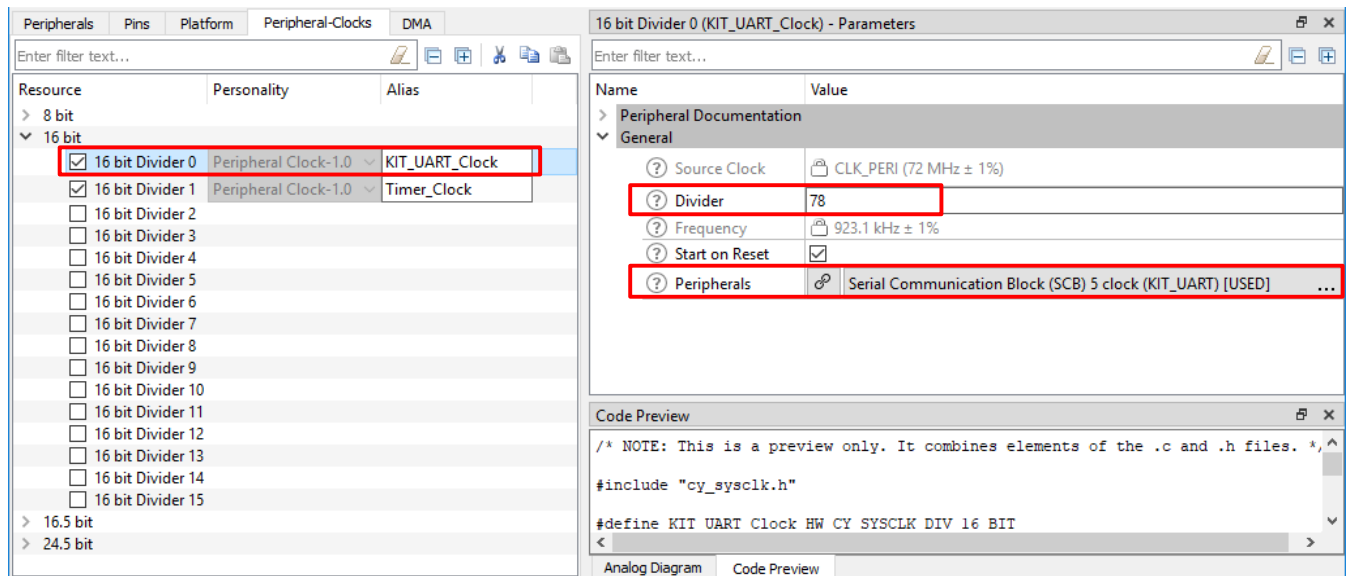
```

#include "cy_gpio.h"
#include "cycfg_connectivity.h"

#define KIT_UART_RX PORT GPIO PRT5
  
```

Figure 6 and Figure 7 show the Peripheral-Clock configuration for UART and TCPWM resources respectively.

Figure 6. Peripheral-Clock Configuration for UART



16 bit Divider 0 (KIT_UART_Clock) - Parameters

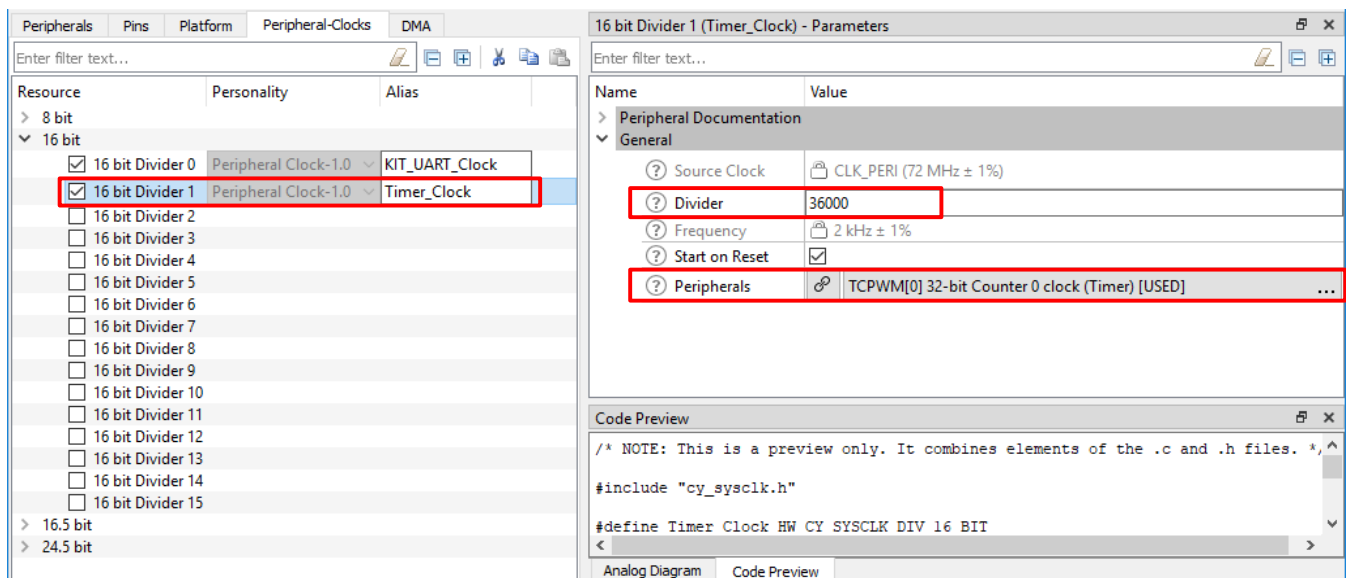
Name	Value
Source Clock	CLK_PERI (72 MHz ± 1%)
Divisor	78
Frequency	923.1 kHz ± 1%
Start on Reset	<input checked="" type="checkbox"/>
Peripherals	Serial Communication Block (SCB) 5 clock (KIT_UART) [USED] ...

```

/* NOTE: This is a preview only. It combines elements of the .c and .h files. */
#include "cy_sysclk.h"

#define KIT_UART_Clock_HW_CY_SYSClk_DIV_16_BIT
  
```

Figure 7. Peripheral-Clock Configuration for Timer



16 bit Divider 1 (Timer_Clock) - Parameters

Name	Value
Source Clock	CLK_PERI (72 MHz ± 1%)
Divisor	36000
Frequency	2 kHz ± 1%
Start on Reset	<input checked="" type="checkbox"/>
Peripherals	TCPWM[0] 32-bit Counter 0 clock (Timer) [USED] ...

```

/* NOTE: This is a preview only. It combines elements of the .c and .h files. */
#include "cy_sysclk.h"

#define Timer_Clock_HW_CY_SYSClk_DIV_16_BIT
  
```

Table 2 shows the pin assignment for the project.

Table 2. Pin Assignments

Name	Port
LED	P13[7]
UART_RX	P5[0]
UART_TX	P5[1]

Reusing This Example

This example is designed for the [CY8CKIT-062-WIFI-BT Pioneer Kit](#). To port the design to a different PSoC 6 MCU device, right-click an application project and choose **Change ModusToolbox Device**. If changing to a different hardware, you may need to reassign pins.

Table 3. Device and Pin Mapping Table across PSoC 6 MCU Kits

Kit Name	Device Used	LED	UART_RX	UART_TX
CY8CKIT-062-WiFi-BT	CY8C6247BZI-D54	P13[7]	P5[0]	P5[1]
CY8CKIT-062-BLE	CY8C6347BZI-BLD53	P13[7]	P5[0]	P5[1]
CY8CPROTO-062-4343W	CY8C624ABZI-D44	P13[7]	P5[0]	P5[1]

In some cases, a resource used by a code example (for example, an IP block) is not supported on another device. In that case, the example will not work. If you build the code targeted at such a device, you will get errors. See the device datasheet for information on what a particular resource the device supports.

Related Documents

For a comprehensive list of PSoC 6 MCU resources, see [KBA223067](#) in the Cypress community.

Application Notes	
AN210781 – Getting Started with PSoC 6 MCU with Bluetooth Low Energy (BLE) Connectivity	Describes PSoC 6 MCU with BLE Connectivity devices and how to build your first PSoC Creator project
AN221774 – Getting Started with PSoC 6 MCU	Describes PSoC 6 MCU devices and how to build your first ModusToolbox application and PSoC Creator project
AN215656 – PSoC 6 MCU: Dual-CPU System Design	Describes the dual-CPU architecture in PSoC 6 MCU, and shows how to build a simple dual-CPU design
Code Examples	
Visit the Cypress GitHub site for a comprehensive collection of code examples using ModusToolbox IDE	
Device Documentation	
PSoC 6 MCU: PSoC 62 Datasheet	PSoC 6 MCU: PSoC 62 Architecture Technical Reference Manual (TRM)
PSoC 6 MCU: PSoC 63 with BLE Datasheet	PSoC 6 MCU: PSoC 63 with BLE Architecture Technical Reference Manual
Development Kit Documentation	
CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit	
CY8CKIT-062-WiFi-BT PSoC 6 WiFi-BT Pioneer Kit	
CY8CPROTO-062-4343W PSoC 6 Wi-Fi BT Prototyping Kit	
Tool Documentation	
ModusToolbox IDE	The Cypress IDE for IoT designers

Cypress Resources

Cypress provides a wealth of data at www.cypress.com to help you to select the right device, and quickly and effectively integrate the device into your design.

For the PSoC 6 MCU devices, see [KBA223067](#) in the Cypress community for a comprehensive list of PSoC 6 MCU resources.

Document History

Document Title: CE221773 – PSoC 6 MCU: Hello World

Document Number: 002-23541

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	6322373	SNVN	11/21/2018	New code example

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