



AUGMENTED STARTUPS

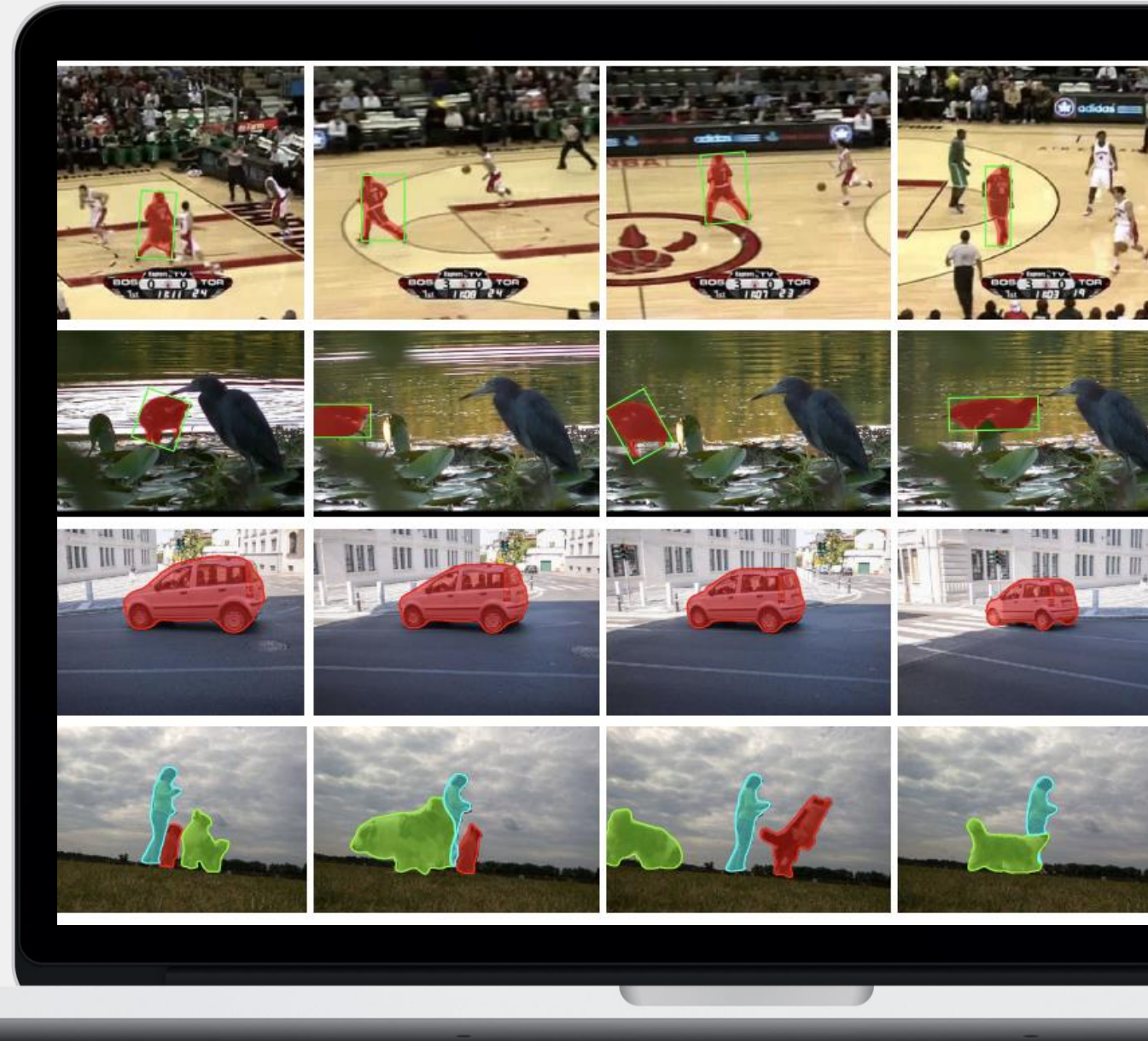
WHERE TECH ENTREPRENEURS COME TO LEARN  
CREATE & INNOVATE

# Video Object Tracking and Segmentation

**SiamMask – A Unifying  
Approach**

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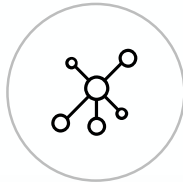
**Paper Review**



# How SiamMask Works?



**SiamFC**

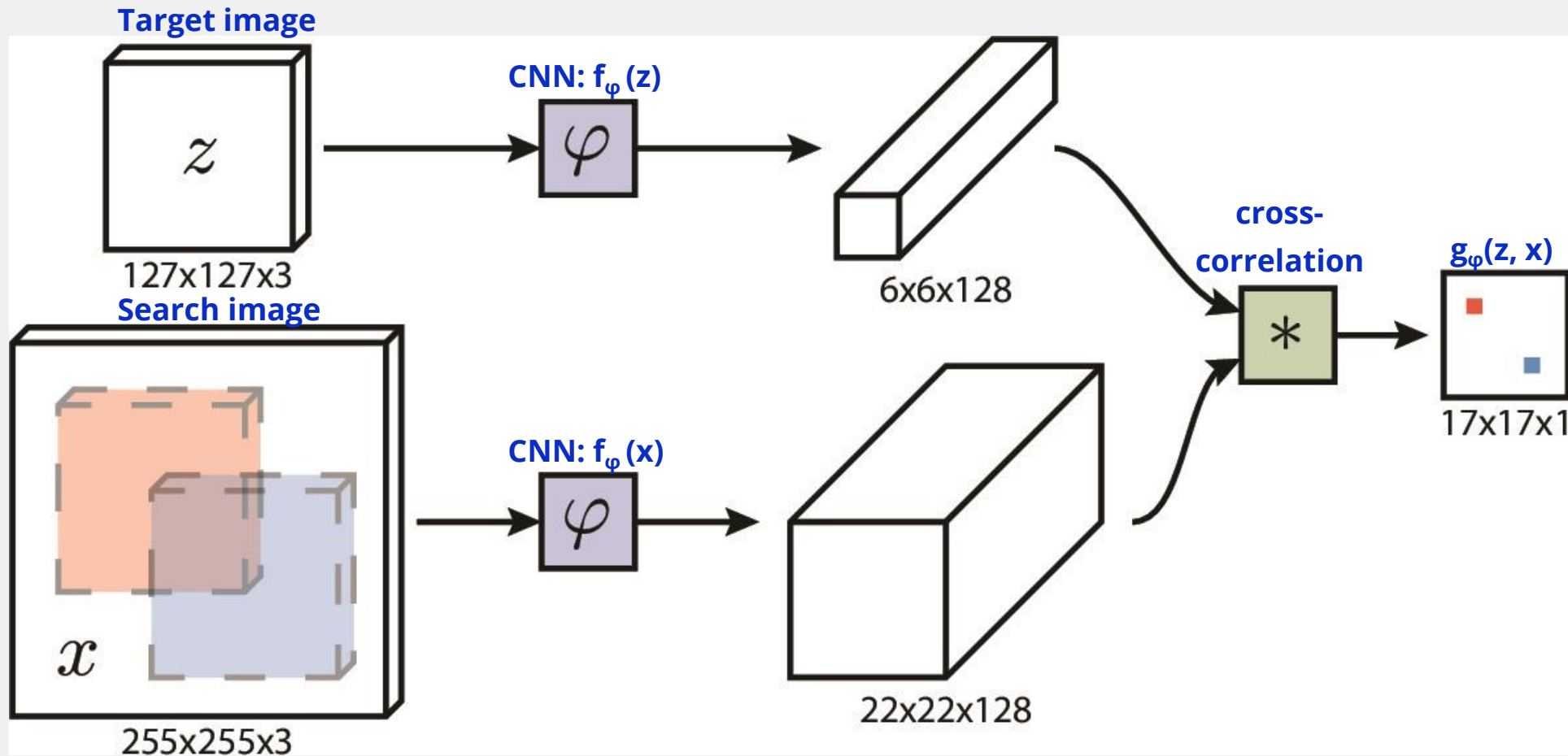


**SiamRPN**

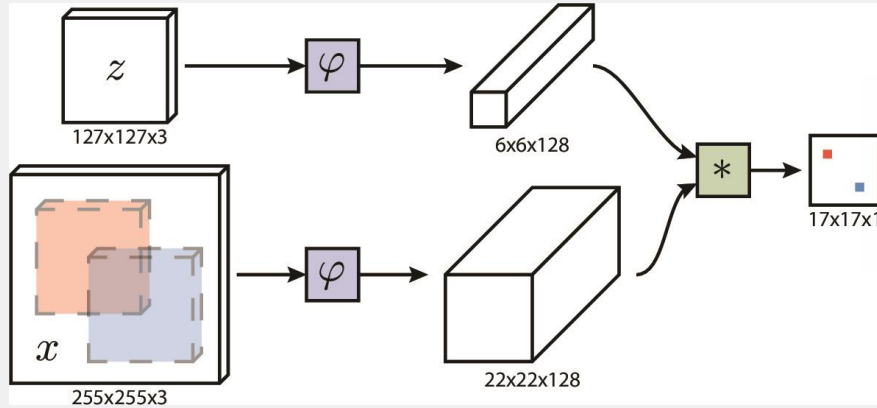


**SiamMask**

# Fully Convolutional Siamese Network



# SiamFC and SiamRPN



$$g_{\varphi}(z, x) = f_{\varphi}(z) * f_{\varphi}(x)$$

(Logistic Loss of SiamFC)

$L_{\text{sim}}$

$L_{\text{box}}$

$L_{\text{score}}$

(Cross-entropy Losses of SiamRPN)



# SiamMask

$$g_{\varphi}(z, x) = f_{\varphi}(z) * f_{\varphi}(x)$$

$L_{\text{sim}}$

$L_{\text{box}}$

$L_{\text{score}}$

Predicted mask corresponding to the n-th RoW

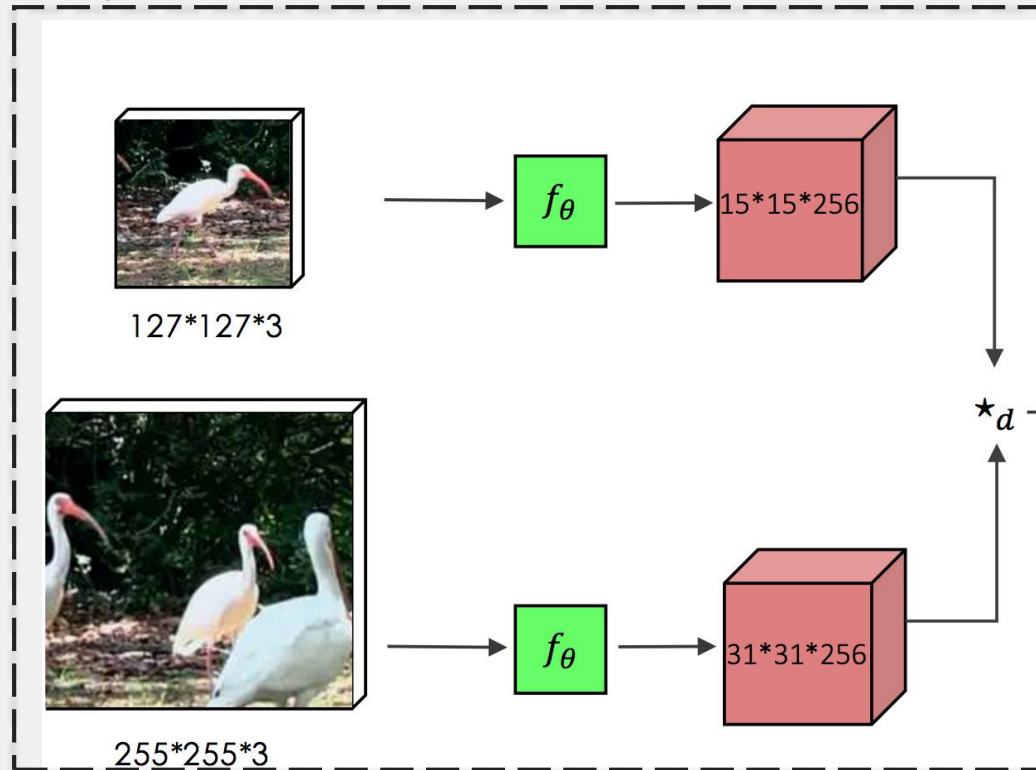
$$m_n = h_{\theta}(g_{\varphi}^n(z, x))$$

$L_{\text{mask}}$

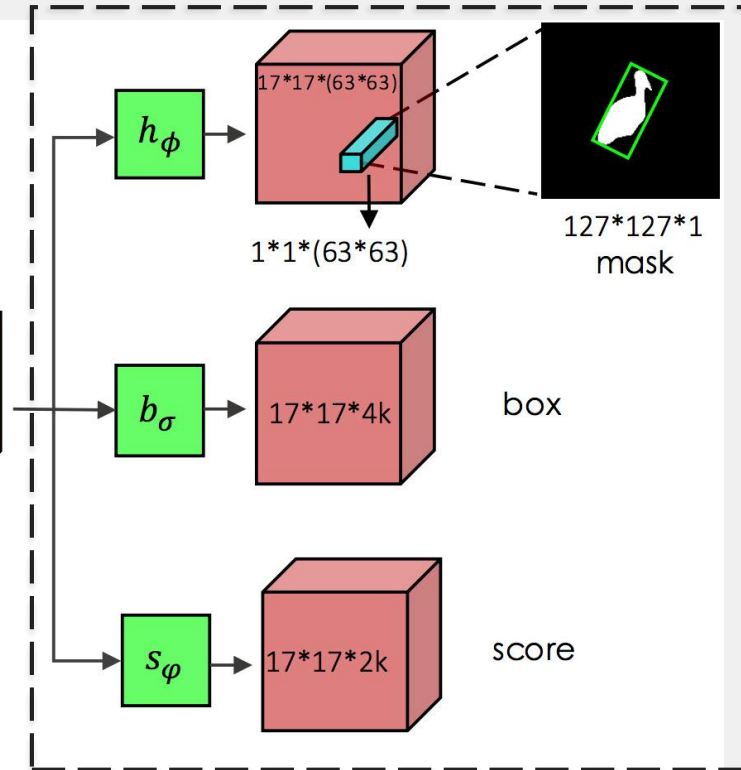
Loss function for the mask prediction task

# SiamMask – variant1

## Fully convolutional network for RoW creation



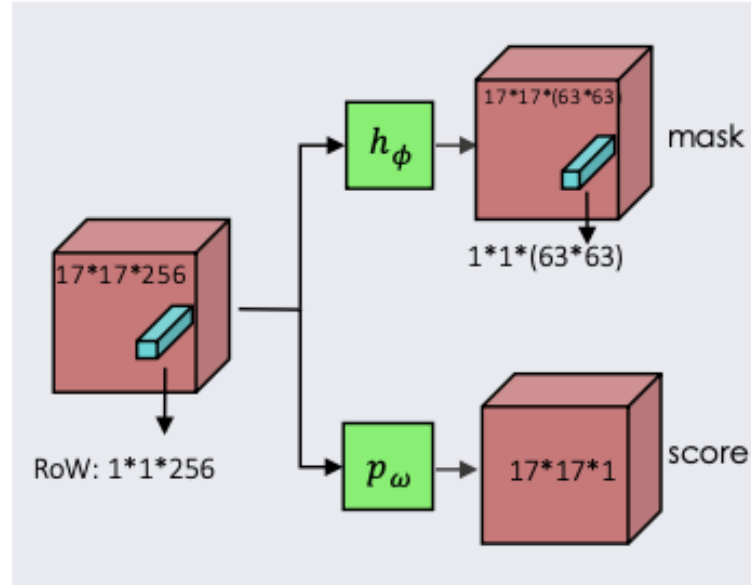
## Neural Network for mask generation



(a) three-branch variant architecture

$$\mathcal{L}_{3B} = \lambda_1 \cdot \mathcal{L}_{mask} + \lambda_2 \cdot \mathcal{L}_{score} + \lambda_3 \cdot \mathcal{L}_{box}$$

# SiamMask – Variant 2

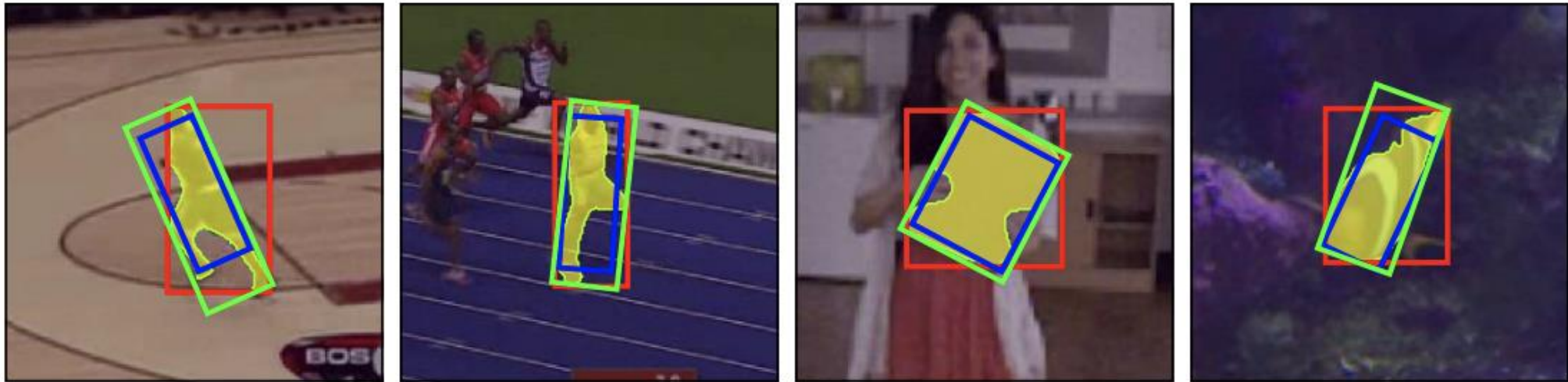


(b) two-branch variant head

$$\mathcal{L}_{2B} = \lambda_1 \cdot \mathcal{L}_{mask} + \lambda_2 \cdot \mathcal{L}_{sim}$$



# SiamMask – Box Generation



**Minmax:** the axis-aligned rectangle containing the object

**MBR:** the minimum bounding rectangle

**Opt:** the rectangle obtained via the optimisation strategy proposed in VOT-2016





# Implementation Details



## Network Architecture

ResNet-50 until the final convolutional layer of the 4-th stage as the backbone



## Training

exemplar and search image patches of  $127 \times 127$  and  $255 \times 255$  pixels respectively



## Inference

evaluated once per frame, without any adaptation

# SiamMask Performance

Init  
(box only)



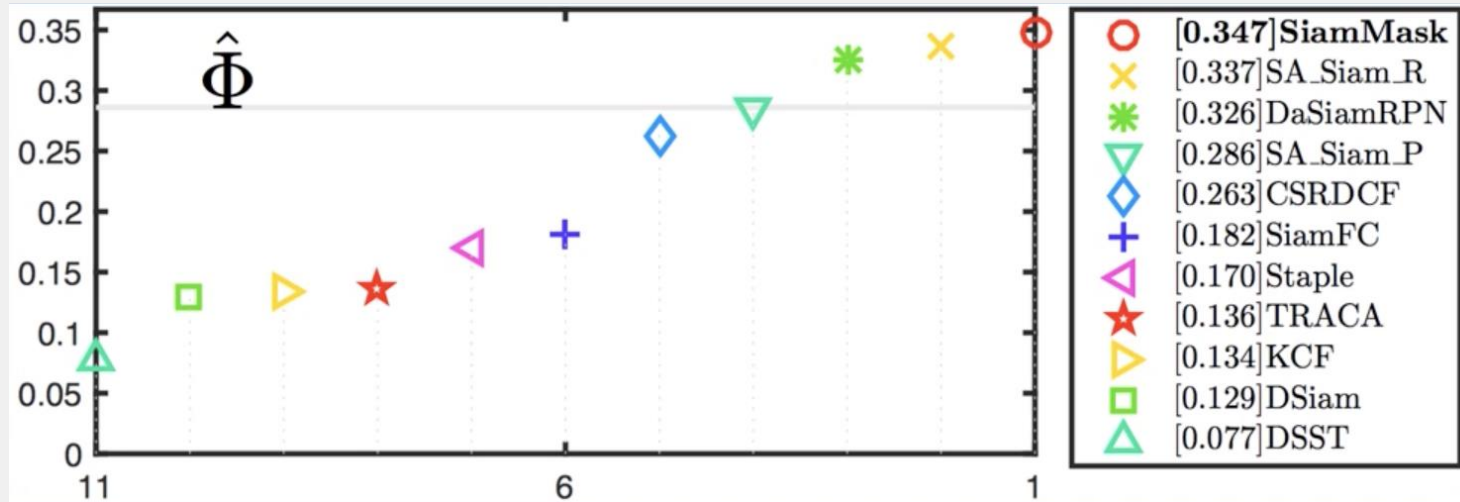
Estimates  
(both box and mask)



...



# SiamMask Performance – VOT2018

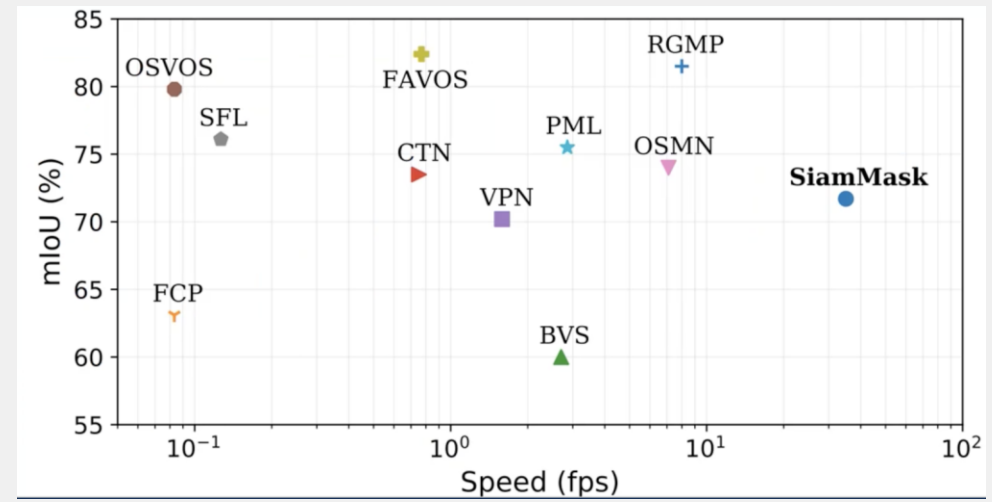


	SiamMask	SiamMask-2B	DaSiamRPN [72]	SiamRPN [31]	SA_Siam_R [17]	CSRDCF [37]	STRCF [32]	LSART [56]	ECO [15]
EAO ↑	<b>0.347</b>	0.334	0.326	0.244	0.337	0.263	0.345	0.323	0.280
Accuracy ↑	<b>0.602</b>	0.575	0.569	0.490	0.566	0.466	0.523	0.495	0.484
Robustness ↓	0.288	0.306	0.337	0.460	0.258	0.318	<b>0.215</b>	0.218	0.276
Speed (fps) ↑	35	40	160	<b>200</b>	32.4	48.9	2.9	1.7	3.7

# SiamMask Performance – DAVIS 2016/2017

	FT	M	$\mathcal{J}_{M\uparrow}$	$\mathcal{J}_{O\uparrow}$	$\mathcal{J}_{D\downarrow}$	$\mathcal{F}_{M\uparrow}$	$\mathcal{F}_{O\uparrow}$	$\mathcal{F}_{D\downarrow}$	Speed
OnAVOS [61]	✓	✓	<b>86.1</b>	<b>96.1</b>	5.2	<b>84.9</b>	<b>89.7</b>	5.8	0.08
MSK [45]	✓	✓	79.7	93.1	8.9	75.4	87.1	9.0	0.1
MSK <sub>b</sub> [45]	✓	✗	69.6	-	-	-	-	-	0.1
SFL [12]	✓	✓	76.1	90.6	12.1	76.0	85.5	10.4	0.1
FAVOS [11]	✗	✓	82.4	96.5	4.5	79.5	89.4	5.5	0.8
RGMP [64]	✗	✓	81.5	91.7	10.9	82.0	90.8	10.1	8
PML [10]	✗	✓	75.5	89.6	8.5	79.3	93.4	7.8	3.6
OSMN [67]	✗	✓	74.0	87.6	9.0	72.9	84.0	10.6	8.0
PLM [71]	✗	✓	70.2	86.3	11.2	62.5	73.2	14.7	6.7
VPN [24]	✗	✓	70.2	82.3	12.4	65.5	69.0	14.4	1.6
<b>SiamMask</b>	✗	✗	71.7	86.8	<b>3.0</b>	67.8	79.8	<b>2.1</b>	<b>35</b>

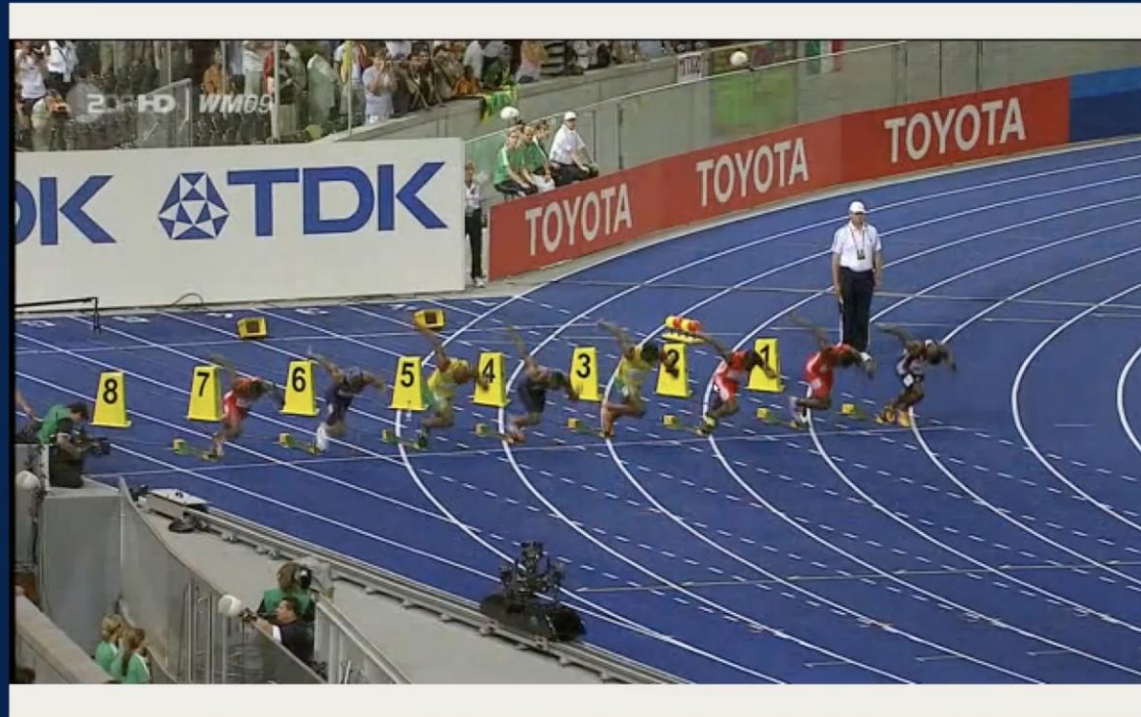
	FT	M	$\mathcal{J}_{M\uparrow}$	$\mathcal{J}_{O\uparrow}$	$\mathcal{J}_{D\downarrow}$	$\mathcal{F}_{M\uparrow}$	$\mathcal{F}_{O\uparrow}$	$\mathcal{F}_{D\downarrow}$	Speed
OnAVOS [61]	✓	✓	<b>61.6</b>	<b>67.4</b>	27.9	<b>69.1</b>	<b>75.4</b>	26.6	0.1
OSVOS [7]	✓	✓	56.6	63.8	26.1	63.9	73.8	27.0	0.1
FAVOS [11]	✗	✓	54.6	61.1	14.1	61.8	72.3	18.0	0.8
OSMN [67]	✗	✓	52.5	60.9	21.5	57.1	66.1	24.3	8.0
<b>SiamMask</b>	✗	✗	51.1	60.5	<b>-1.1</b>	55.0	64.3	<b>1.9</b>	<b>35</b>



# SiamMask Performance – Experimental Results



SiamMask runs at 35 fps (on GPU)  
(video slowed down for better visualization)



VOT sequences

# Important Links



## Blog

<http://www.robots.ox.ac.uk/~qwang/SiamMask/>



## Paper

<https://arxiv.org/pdf/1812.05050.pdf>



## Code

<https://github.com/augmentedstartups/SiamMask>





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