Aim: Write a program to implement Tic-Tac-Toe game problem.

```
Code:
board =
               ["-", "-", "-",
def print_board():
       print(board[0] + " | " + board[1] + " | " + board[2])
       print(board[3] + " | " + board[4] + " | " + board[5])
       print(board[6] + " | " + board[7] + " | " + board[8])
def take_turn(player):
       print(player + "'s turn.")
       position = input("Choose a position from 1-9: ")
       while position not in ["1", "2", "3", "4", "5", "6", "7", "8", "9"]:
               position = input("Invalid input. Choose a position from 1-9: ")
       position = int(position) - 1
       while board[position] != "-":
               position = int(input("Position already taken. Choose a different position: ")) -
1
       board[position] = player
       print_board()
def check_game_over():
       # Check for a win
       if (board[0] == board[1] == board[2] != "-") or \setminus
       (board[3] == board[4] == board[5] != "-") or \
       (board[6] == board[7] == board[8] != "-") or \
       (board[0] == board[3] == board[6] != "-") or \
       (board[1] == board[4] == board[7] != "-") or \
       (board[2] == board[5] == board[8] != "-") or \setminus
       (board[0] == board[4] == board[8] != "-") or \
       (board[2] == board[4] == board[6] != "-"):
               return "win"
       elif "-" not in board:
               return "tie"
       else:
               return "play"
def play_game():
       print_board()
       current player = "X"
       game over = False
       while not game_over:
               take_turn(current_player)
               game_result = check_game_over()
```

play_game()

Output:

Case 1:

Case 2:

Case 3:

Aim: - Write a program to implement BFS (for 8 puzzle problem or Water Jugproblem or any AI search problem).

Code:

```
from collections import deque
initial\_state = [[1, 2, 3], [4, 5, 6], [0, 7, 8]]
goal_state = [[1, 2, 3], [4, 5, 6], [7, 8, 0]]
def print_state(state):
  for row in state:
     print(row)
def possible_moves(state):
  moves = []
  for i in range(3):
     for j in range(3):
       if state[i][j] == 0:
          if i > 0:
             moves.append((i, j, i - 1, j))
          if i < 2:
             moves.append((i, j, i + 1, j))
          if i > 0:
             moves.append((i, j, i, j - 1))
          if j < 2:
             moves.append((i, j, i, j + 1))
  return moves
def bfs(initial_state, goal_state):
  visited = set()
  queue = deque()
  queue.append((initial_state, []))
  while queue:
     current_state, path = queue.popleft()
     visited.add(tuple(map(tuple, current_state)))
     if current_state == goal_state:
        print("Goal state found!")
       print("Path to the goal:")
       for step in path:
          print_state(step)
          print()
       return
     for move in possible_moves(current_state):
```

```
i, j, new_i, new_j = move
    new_state = [list(row) for row in current_state]
    new_state[i][j], new_state[new_i][new_j] = new_state[new_i][new_j],
new_state[i][j]

if tuple(map(tuple, new_state)) not in visited:
    queue.append((new_state, path + [new_state]))

print("Goal state is not reachable.")

bfs(initial_state, goal_state)
```

```
Goal state found!
Path to the goal:
[1, 2, 3]
[4, 5, 6]
[7, 0, 8]
[1, 2, 3]
[4, 5, 6]
[7, 8, 0]
```

Aim: Write a program to implement DFS (for 8 puzzle problem or Water Jug problem or any AI search problem).

Code:

```
def water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1=0, jug2=0,
  visited=set()): if jug1 == target_amount and jug2 == 0:
   return [(jug1,
jug2)
visited.add((jug1,
jug2))
if jug1 < jug1_capacity and (jug1_capacity, jug2) not in visited:
 path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1_capacity,
jug2, visited) if path:
 return [(jug1, jug2)] + path
if jug2 < jug2_capacity and (jug1, jug2_capacity) not in visited:
 path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1,
jug2 capacity, visited) if path:
 return [(jug1, jug2)] +
path if path:
 return [(jug1, jug2)] + path
if jug2 > 0 and (jug1, 0) not in visited:
 path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1, 0,
visited) if path:
  return [(jug1, jug2)] + path
if jug1 > 0 and jug2 < jug2_capacity:
pour_amount = min(jug1, jug2_capacity - jug2)
path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1 - pour_amount,
jug2 + pour_amount, visited)
```

```
if path:
    return [(jug1, jug2)] + path
pour_amount = min(jug2, jug1_capacity - jug1)
path = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount, jug1 + pour_amount, jug2 - pour_amount, visited)
    if path:
        return [(jug1, jug2)] + path return []
    jug1_capacity = 4 jug2_capacity= 3 target_amount = 2
    solution = water_jug_dfs(jug1_capacity, jug2_capacity, target_amount) if solution:
        for step, state
        inenumerate(solution):
        print(f"Step{p+1}: {state}")
else:
        print("No solution found.")
```

```
Step 1: (0, 0)
Step 2: (4, 0)
Step 3: (1, 3)
Step 4: (1, 0)
Step 5: (0, 1)
Step 6: (4, 1)
Step 7: (2, 3)
Step 8: (2, 0)
```

Aim: - Write a program to implement Single Player Game (Using any Heuristic Function)

```
Code: -
import random
def heuristic_guess(low, high):
  return (low + high) // 2
def play_game():
  print("Welcome to the Guessing Game!")
  target_number = random.randint(1, 100)
  low, high = 1, 100
  attempts = 0
  while True:
    guess = heuristic_guess(low, high)
    print(f"I guess {guess}")
    if guess == target_number:
       print(f"Congratulations! I guessed the number {target_number} in {attempts}
attempts.")
       break
    elif guess < target_number:
       print("Too low!")
       low = guess + 1
    else:
       print("Too high!")
       high = guess - 1
    attempts += 1
if___name___== "_main_":
  play_game()
```

```
Welcome to the Guessing Game!
I guess 50
Too low!
I guess 75
Too low!
I guess 88
Too low!
I guess 94
Too low!
I guess 97
Too low!
I guess 97
Too high!
I guess 95
Too low!
I guess 96
Congratulations! I guessed the number 96 in 6 attempts.
```

AIM: Implement A* algorithm.

```
Code:
import heap
class Node:
  def__init_(self, state, parent=None, action=None, cost=0, heuristic=0):
     self.state = state
     self.parent = parent
     self.action = action
     self.cost = cost
     self.heuristic = heuristic
  def lt (self, other):
     return (self.cost + self.heuristic) < (other.cost + other.heuristic)
def astar(start_state, goal_state, get_neighbors, heuristic):
  open list = []
  closed\_set = set()
  start_node = Node(start_state, None, None, 0, heuristic(start_state, goal_state))
  heapq.heappush(open_list, start_node)
  while open_list:
     current_node = heapq.heappop(open_list)
     if current_node.state == goal_state:
       path = []
       while current_node:
          path.append((current_node.state, current_node.action))
          current node = current node.parent
       return list(reversed(path))
     closed_set.add(current_node.state)
     for neighbor_state, action, step_cost in get_neighbors(current_node.state):
       if neighbor state in closed set:
          continue
       g_score = current_node.cost + step_cost
       h_score = heuristic(neighbor_state, goal_state)
       f_score = g_score + h_score
       neighbor_node = Node(neighbor_state, current_node, action, g_score, h_score)
       # Check if the neighbor is already in the open list
       found = False
       for node in open_list:
          if node.state == neighbor state:
            found = True
            if g_score < node.cost:
               open_list.remove(node)
               heapq.heappush(open_list, neighbor_node)
```

```
break
        if not found:
          heapq.heappush(open_list, neighbor_node)
  return None # No path found
def get_neighbors(state):
  x, y = state
  neighbors = []
  for dx, dy in [(1, 0), (-1, 0), (0, 1), (0, -1)]:
     new_x, new_y = x + dx, y + dy
     if 0 \le \text{new}_x < \text{len(grid)} and 0 \le \text{new}_y < \text{len(grid[0])} and \text{grid[new}_x][\text{new}_y] == 0:
        neighbors.append(((new_x, new_y), f"Move to ({new_x}, {new_y})", 1))
  return neighbors
def manhattan_distance(state, goal):
  x1, y1 = state
  x2, y2 = goal
  return abs(x1 - x2) + abs(y1 - y2)
# Example usage
start = (0, 0)
goal = (3, 3)
grid = [[0, 0, 0, 0], [1, 1, 0, 1], [0, 0, 0, 0], [1, 0, 1, 0]]
path = astar(start, goal, get_neighbors, manhattan_distance)
if path:
  for state, action in path:
     print(f"Action: {action}, State: {state}")
else:
  print("No path found.")
```

```
Action: None, State: (0, 0)
Action: Move to (0, 1), State: (0, 1)
Action: Move to (0, 2), State: (0, 2)
Action: Move to (1, 2), State: (1, 2)
Action: Move to (2, 2), State: (2, 2)
Action: Move to (2, 3), State: (2, 3)
Action: Move to (3, 3), State: (3, 3)
```

Aim: Write a program to implement mini-max algorithm for any game development.

```
Code:
import math
def minimax(curDepth, nodeIndex, maxTurn, scores, targetDepth):
  if curDepth == targetDepth:
    return scores[nodeIndex]
  if maxTurn:
    return max(
       minimax(curDepth + 1, nodeIndex * 2, False, scores, targetDepth),
       minimax(curDepth + 1, nodeIndex * 2 + 1, False, scores, targetDepth)
    )
  else:
    return min(
       minimax(curDepth + 1, nodeIndex * 2, True, scores, targetDepth),
       minimax(curDepth + 1, nodeIndex * 2 + 1, True, scores, targetDepth)
    )
# Driver code
scores = [3, 5, 2, 9, 12, 5, 23, 23]
treeDepth = int(math.log2(len(scores))
print("The optimal value is:", minimax(0, 0, True, scores, treeDepth))
```

```
The optimal value is : 12
```

Aim: Assume given a set of facts of the form father (name1, name2) (name1is the father of name2).

```
Code:
female(pam).
female(liz).
female(pat).
female(ann).
male(jim).
male(bob).
male(tom).
male(peter).
parent(pam,bob).
parent(tom,bob).
parent(tom,liz).
parent(bob,ann).
parent(bob,pat).
parent(pat,jim).
parent(bob,peter).
parent(peter,jim).
mother(X,Y):-parent(X,Y),female(X).
father(X,Y):-parent(X,Y),male(X).
sister(X,Y):-parent(Z,X),parent(Z,Y),female(X),X == Y.
brother(X,Y):-parent(Z,X),parent(Z,Y),male(X),X = Y.
grandparent(X,Y):-parent(X,Z),parent(Z,Y).
grandmother(X,Z):-mother(X,Y),parent(Y,Z).
grandfather(X,Z):-father(X,Y),parent(Y,Z).
wife(X,Y):-
parent(X,Z),parent(Y,Z),female(X),male(Y).
uncle(X,Z):-brother(X,Y),parent(Y,Z).
```



```
Aim : Define a predicate brother(X,Y) which holds iff X and Y arebrothers.
Define a predicate cousin(X,Y) which holds iff X and Y are cousins.
Define a predicate grandson(X,Y) which holds iff X is a grandson of Y.
Define a predicate descendent(X,Y) which holds iff X is a descendent of Y.
Consider the following genealogical tree: father(a,b). father(a,c). father(b,d).
father(b,e). father(c,f).
Say which answers, and in which order, are generated by your
definitions for the following queries in Prolog:
?- brother(X,Y).
?-cousin(X,Y).
?- grandson(X,Y).
?- descendent(X,Y).
Code:
father(kevin,milu).
father(kevin, yash).
father(milu, meet).
father(milu,raj).
father(yash,jay).
brother(X,Y):-father(K,X),father(K,Y).
cousin(A,B):-father(K,X),father(K,Y),father(X,A),father(Y,B).
grandson(X,Y):-father(X,K),father(K,Y).
descendent(X,Y):-father(K,X),father(K,Y).
descendent(X,Y):-father(K,X),father(K,Y),father(X,A),father(Y,B).
```



Aim: Write a program to solve Tower of Hanoi problem using Prolog.

Code:

$$\begin{split} & \text{move}(1,\!X,\!Y,\!_) :\text{-write}('\text{Move top disk from '}), \, \text{write}(X), \, \text{write}('\text{ to '}), \text{write}(Y), \, \text{nl.} \\ & \text{move}(N,\!X,\!Y,\!Z) :\text{-} \\ & N > 1, \\ & M \text{ is } N - 1, \, \text{move}(M,\!X,\!Z,\!Y), \\ & \text{move}(1,\!X,\!Y,\!_), \\ & \text{move}(M,\!Z,\!Y,\!X). \end{split}$$



Aim: Write a program to solve N-Queens problem using Prolog.

```
Code:
% render solutions nicely.
:- use_rendering(chess).
%%
      queens(+N, -Queens) is nondet.
%
%
       @param
                      Queens is a list of column numbers for placing the queens.
       @author Richard A. O'Keefe (The Craft of Prolog)
%
queens(N, Queens):-
  length(Queens, N),
       board(Queens, Board, 0, N, _, _),
       queens(Board, 0, Queens).
board([], [], N, N, _, _).
board([_|Queens], [Col-Vars|Board], Col0, N, [_|VR], VC):-
       Col is Col0+1,
       functor(Vars, f, N),
       constraints(N, Vars, VR, VC),
       board(Queens, Board, Col, N, VR, [_|VC]).
constraints(0, _, _, _) :- !.
constraints(N, Row, [R|Rs], [C|Cs]):-
       arg(N, Row, R-C),
       M is N-1.
       constraints(M, Row, Rs, Cs).
queens([], _, []).
queens([C|Cs], Row0, [Col|Solution]):-
       Row is Row0+1,
       select(Col-Vars, [C|Cs], Board),
       arg(Row, Vars, Row-Row),
       queens(Board, Row, Solution).
```



Aim: Write a program to solve 8 puzzle problem using Prolog.

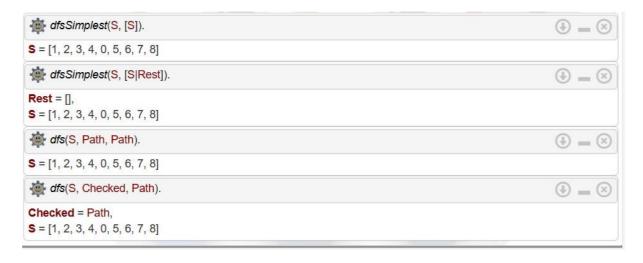
Code:

goal([1,2,3, 4,0,5, 6,7,8]). move([X1,0,X3, X4,X5,X6, X7,X8,X9], [0,X1,X3,X4,X5,X6,X7,X8,X9]). move([X1,X2,0, X4,X5,X6, X7,X8,X9], [X1,0,X2, X4,X5,X6, X7,X8,X9]). move([X1,X2,X3, X4,0,X6,X7,X8,X9], [X1,X2,X3, 0,X4,X6,X7,X8,X9]). move([X1,X2,X3, X4,X5,0,X7,X8,X9], [X1,X2,X3, X4,0,X5,X7,X8,X9]). move([X1,X2,X3, X4,X5,X6, X7,0,X9], [X1,X2,X3, X4,X5,X6, 0,X7,X9]). move([X1,X2,X3, X4,X5,X6, X7,X8,0], [X1,X2,X3, X4,X5,X6, X7,0,X8]). move([0,X2,X3, X4,X5,X6, X7,X8,X9], [X2,0,X3, X4,X5,X6, X7,X8,X9]). move([X1,0,X3, X4,X5,X6, X7,X8,X9], [X1,X3,0, X4,X5,X6, X7,X8,X9]). move([X1,X2,X3, 0,X5,X6, X7,X8,X9], [X1,X2,X3, X5,0,X6, X7,X8,X9]). move([X1,X2,X3, X4,0,X6, X7,X8,X9], [X1,X2,X3, X4,X6,0, X7,X8,X9]). move([X1,X2,X3, X4,X5,X6,0,X8,X9], [X1,X2,X3, X4,X5,X6,X8,0,X9]). move([X1,X2,X3, X4,X5,X6,X7,0,X9], [X1,X2,X3,X4,X5,X6,X7,X9,0]). move([X1,X2,X3, 0,X5,X6, X7,X8,X9], [0,X2,X3,X1,X5,X6,X7,X8,X9]). move([X1,X2,X3, X4,0,X6, X7,X8,X9], [X1,0,X3, X4,X2,X6, X7,X8,X9]). move([X1,X2,X3, X4,X5,0, X7,X8,X9], [X1,X2,0, X4,X5,X3, X7,X8,X9]). move([X1,X2,X3, X4,X5,X6, X7,0,X9], [X1,X2,X3, X4,0,X6, X7,X5,X9]). move([X1,X2,X3, X4,X5,X6, X7,X8,0], [X1,X2,X3, X4,X5,0, X7,X8,X6]). move([X1,X2,X3, X4,X5,X6, 0,X8,X9], [X1,X2,X3, 0,X5,X6, X4,X8,X9]). move([0,X2,X3, X4,X5,X6, X7,X8,X9], [X4,X2,X3, 0,X5,X6, X7,X8,X9]). move([X1,0,X3, X4,X5,X6, X7,X8,X9], [X1,X5,X3, X4,0,X6, X7,X8,X9]).

move([X1,X2,0, X4,X5,X6, X7,X8,X9], [X1,X2,X6, X4,X5,0, X7,X8,X9]). move([X1,X2,X3, 0,X5,X6, X7,X8,X9],

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$$\begin{split} & [X1, X2, X3, X7, X5, X6, 0, X8, X9]). \\ & move([X1, X2, X3, X4, 0, X6, X7, X8, X9], \\ & [X1, X2, X3, X4, X8, X6, X7, 0, X9]). \\ & move([X1, X2, X3, X4, X5, 0, X7, X8, X9], \\ & [X1, X2, X3, X4, X5, X9, X7, X8, 0]). \\ & dfsSimplest(S, [S]) :- goal(S). \\ & dfsSimplest(S, [S|Rest]) :- move(S, S2), dfsSimplest(S2, Rest). \\ & dfs(S, Path, Path) :- goal(S). \\ & dfs(S, Checked, Path) :- move(S, S2), \\ & + member(S2, Checked), dfs(S2, [S2|Checked], Path). \\ \end{split}$$



Aim: Write a program to solve travelling salesman problem using Prolog.

```
Code:
edge(a, b, 3).
edge(a, c, 4).
edge(a, d, 2).
edge(a, e, 1).
edge(b, c, 4).
edge(b, d, 6).
edge(b, e, 3).
edge(c, d, 5).
edge(c, e, 2).
edge(d, e, 6).
edge(b, a, 3).
edge(c, a, 4).
edge(d, a, 2).
edge(e, a, 6).
edge(c, b, 4).
edge(d, b, 5).
edge(e, b, 3).
edge(d, c, 5).
edge(e, c, 2).
edge(e, d, 6).
edge(a, h, 2).
edge(h, d, 1).
len([], 0).
len([H|T], N):-len(T, X), N is X+1.
best_path(Visited, Total):- path(a, a, Visited, Total).
path(Start, Fin, Visited, Total) :- path(Start, Fin, [Start], Visited, 0, Total).
path(Start, Fin, CurrentLoc, Visited, Costn, Total) :- edge(Start, StopLoc, Distance),
NewCostn is Costn + Distance, \+ member(StopLoc,CurrentLoc),
path(StopLoc, Fin, [StopLoc|CurrentLoc], Visited, NewCostn, Total).
path(Start, Fin, CurrentLoc, Visited, Costn, Total) :- edge(Start, Fin, Distance),
reverse([Fin|CurrentLoc], Visited), len(Visited, Q), (Q\=7 -> Total is 100000; Total is Costn
+ Distance).
shortest_path(Path):- setof(Cost-Path, best_path(Path,Cost), Holder),pick(Holder,Path).
best(Cost-Holder,Bcost-_,Cost-Holder):- Cost<Bcost,!.
best(.X.X).
pick([Cost-Holder|R],X):- pick(R,Bcost-Bholder),best(Cost-Holder,Bcost-Bholder,X),!.
pick([X],X).
```

