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# Multi-class Brain Tumor Segmentation using Graph Attention Network

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**Presenters:** 

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### **Presentation Overview**

- Introduction
- Literature review
- Proposed Solution
- Experimental study and results
- Conclusion



### Introduction

#### Background:

- Brain tumors can be fatal, significantly impact the quality of life, and fundamentally change the lives of both the patient and their loved ones.
- Malignant tumors have a limited chance of surviving, so early detection and diagnosis of brain tumors are essential.

#### Motivation:

- Gliomas are one of the most prevalent forms of brain tumors among all others. Most gliomas are classified as Low-grade gliomas (LGG) and High-grade gliomas (HGG).
- A study by the US National Cancer Institute (NCI) found that every year, 18,000 Americans
  are diagnosed with a glioma brain tumor, most of which pass away within 14 months.



### Introduction Cont.

#### Challenges:

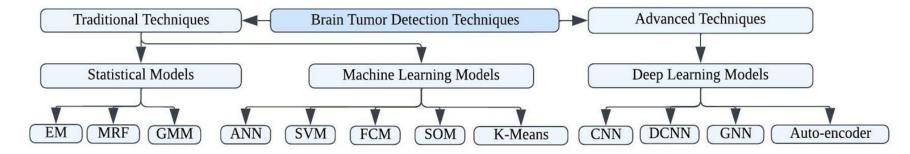
- Processing of the entire brain.
- Applying graph neural network (GNN) on legacy datasets (i.e., non-graphical data).

#### Contributions:

- A computationally efficient and accurate model for brain tumor segmentation as compared to relevant state-of-the-art methods.
- Exhaustive experimental analysis on benchmark datasets and thorough comparative analysis.



### Literature Review



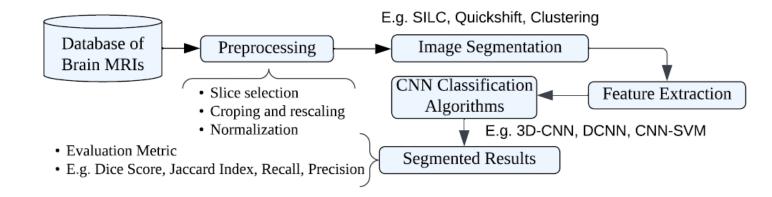
• <u>Methodologies for brain tumor detection</u>: ANN- Artificial Neural Network, SVM- Support Vector Machine, FCM- Fuzzy c-means SOM- Self Organized Map, CNN-Convolution Neural Networks, GNN-Graph Neural Networks, DCNN-Deep Convolution Neural Networks, EM- Expectation Maximization MRF-Markov Random Fields, GMM-Gaussian Mixture Model

#### Traditional Methods:

- SVM concept was studied by Shubhangi et al. [5] who combined knowledge-based approaches with multi-spectral analysis.
- In 2010, Gopal et al. [6] proposed work on MRI brain tumor detection using fuzzy c-means along with intelligent optimization tools.
- Javaid et al. [8] presented a sophisticated fully automated tumor recognition model using kernel-based fuzzy C-means, achieving an accuracy of 98.7%.



### Literature Review Cont.



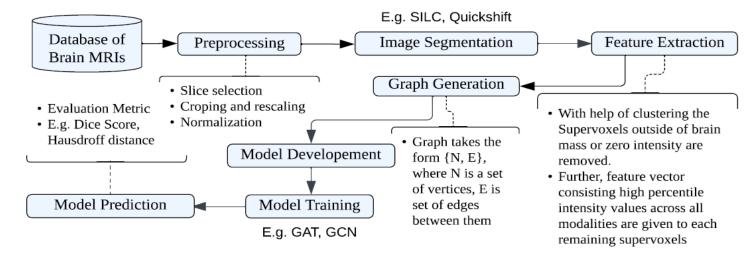
### Advanced methods:

- In recent years, deep convolutional neural networks (DCNNs) have shown excellent results in various medical image segmentation tasks.
  - Longet *et al.* [9], in 2015, developed a fully convolutional network (FCN) for pixel-level classification.
  - Following this idea, several DL-based segmentation models have been developed for various applications, including brain tumor segmentation.

Next: Literature Review – GNN



### Literature Review Cont.



### • Graph Neural Network (GNN):

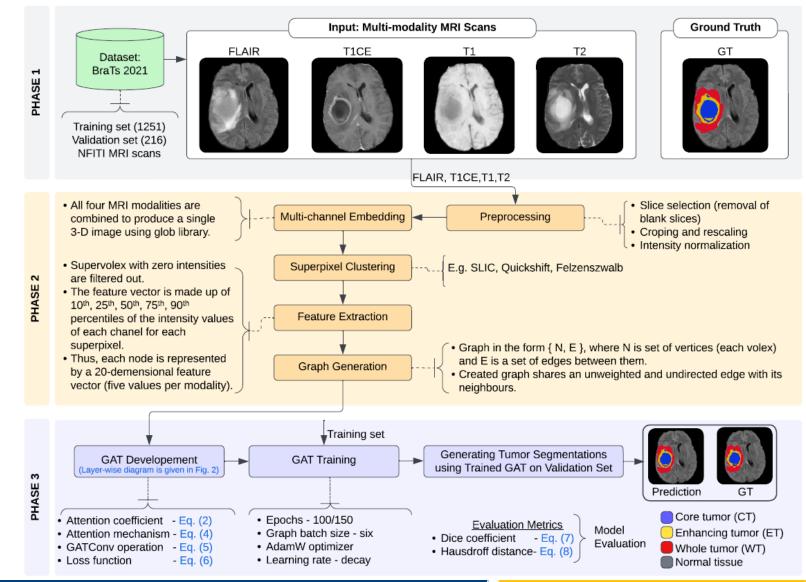
- DL-based graph data processing, known as GNN, was first introduced by Gori et al., in 2005 [15].
- One of the most advanced techniques, in this category, is the graph attention network (GAT), which was introduced by Yoshua Bengio's research team, in 2018.
- Hyeonwoo et al. [16] combined a multi-view representation using multiple simultaneous self-constructing graph (SCG) modules to transform image data into a graph representation and applied graph convolutional network (GCN) to learn segmentation.
- o Similarly, Wei et al. [19] proposed a method to determine isocitrate dehydrogenase mutation status in glioma using structural brain networks and GNNs.



### **Proposed Solution**

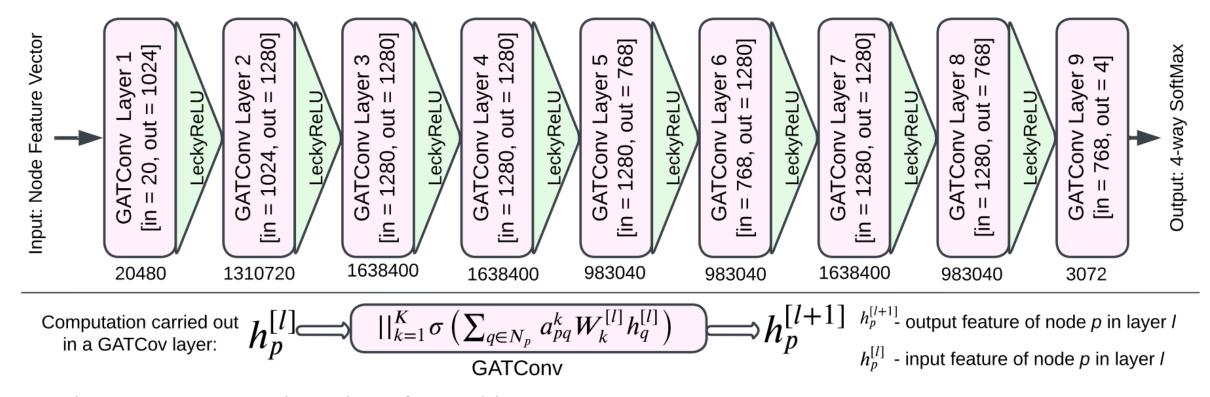
<u>Detailed functional flow</u> <u>diagram</u> of the proposed GATbased MRI brain tumor segmentation framework.

- It consists of three abstract phases:
  - Phase 1: Input
  - Phase 2: Data curation
  - Phase 3: Model building and evaluation.





### Proposed Solution: Layer-wise Schematic of the GAT



- It subsumes ~10 M total number of trainable parameters.
- It stacks eight GATConv layers with LeakyReLu activation, and the top layer is formed by a GATConv layer with Softmax activation.







### Proposed Solution: The Mathematical Formulation of the GAT

- The mathematical formulation of the GATs learning layer:
  - (Eq (5) in the paper)
- Attention coefficient e as:

(Eq (2) in the paper)

Attention mechanism:

(Eq (4) in the paper)

Multi-label cross-entropy loss:

(Eq (6) in the paper)

$$\mathbf{h}_p^{[l+1]} = \left\| \sigma \left( \sum_{q \in N_p} a_{pq}^k W_k^{[l]} h_q^{[l]} \right) \right\|$$

$$e_{pq} = a\left(\vec{Wh_p}, \vec{Wh_q}\right)$$

$$\sigma_{pq} = \frac{\exp\left(LeakyReLU\left(\vec{a^T}\left[\vec{W}\vec{h_p} \parallel \vec{W}\vec{h_q}\right]\right)\right)}{\sum_{k \in N_p} \exp\left(LeakyReLU\left(\vec{a^T}\left[\vec{W}\vec{h_p} \parallel \vec{W}\vec{h_k}\right]\right)\right)}$$

$$Loss = \sum_{c=0}^{C} (1_{c=y}) W_c \log(\widehat{P}_y)$$



### Proposed Solution: Hyperparameter Setting

- The GAT is trained for 300 epochs on mini-batches of 6 graphs.
   Note: The training converges between 100 and 150 epochs in different runs depending on the graph mini-batch size.
- We used the **AdamW optimizer** with a **weight decay of 0.0001** and exponentially decrease learning rate.
- SLIC configuration: k = 15000 and m = 0.5 has the best achievable segmentation accuracy.
- The cross-validation phase's top-performing GAT model comprised 8 layers with 256 neurons each.
- Attention heads and Residuals used for the model training are [4, 5, 5, 5, 3, 5, 5, 3] and [False, False, False, False, False, False], respectively.



### **Experimental Study and Analysis**

#### • Environment:

- System specifications: AMD Ryzen 7 4800HS 2.90 GHz processor, a Tesla K80 GPU with 2496
   CUDA cores, and 35 GB of DDR5 VRAM on Google Colab, the model was trained and tested.
- The per-sample prediction time was 1.7 seconds on the above configurations.

#### Evaluation Metrics:

o Dice score and the 95th percentile of the symmetric Hausdorff distance are two measures used to assess the performance of the models.

$$Dice = \frac{2TP}{2TP + FP + FN}$$

(Eq (7) in the paper)

$$HD95 = 95\% \left( d\left(\widehat{Y}, Y\right) \middle\| d\left(Y, \widehat{Y}\right) \right)$$

(Eq (8) in the paper)



### Experimental Study and Analysis: Quantitative Analysis

Performance of various models on the BRATS2021 validation dataset and their % of improvement compared to the baseline model introduced in [18].

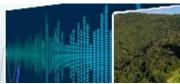
Models	Dice Score (%)				HD95				Avg. % of Improvement	
	WT	CT	ET	Average	WT	CT	ET	Average	Dice Score	HD95
GNN [18]	0.87	0.78	0.74	0.80	6.92	16.67	20.40	14.66	Baseline	
GNN-CNN [18]	0.89	0.81	0.73	0.81	6.79	12.62	28.20	15.87	1.3 ↑	8.3 ↓
3D CMM-Net [27]	0.84	0.81	0.75	0.80	10.16	24.64	35.00	23.26	0	58.7 ↓
3D-UNet [28]	0.87	0.76	0.73	0.79	6.29	14.70	30.50	17.16	1.3 ↓	17.1 ↓
3D ResUNet [29]	0.90	0.85	0.82	0.86	4.3	9.89	17.89	10.69	7.5 ↑	27.1 ↑
DNN [30]	0.90	0.84	0.81	0.85	7.3	22.32	19.58	16.4	6.3 ↑	11.9 ↓
GAT (this work)	0.91	0.86	0.79	0.85	5.91	6.08	9.52	7.17	6.3 ↑	51.1 ↑

Note: Dice coefficient (higher is better), and hd95 (lower is better).

↓ And ↑ stand for '+' and '-' Improvement, respectively. The best performances are inked in blue

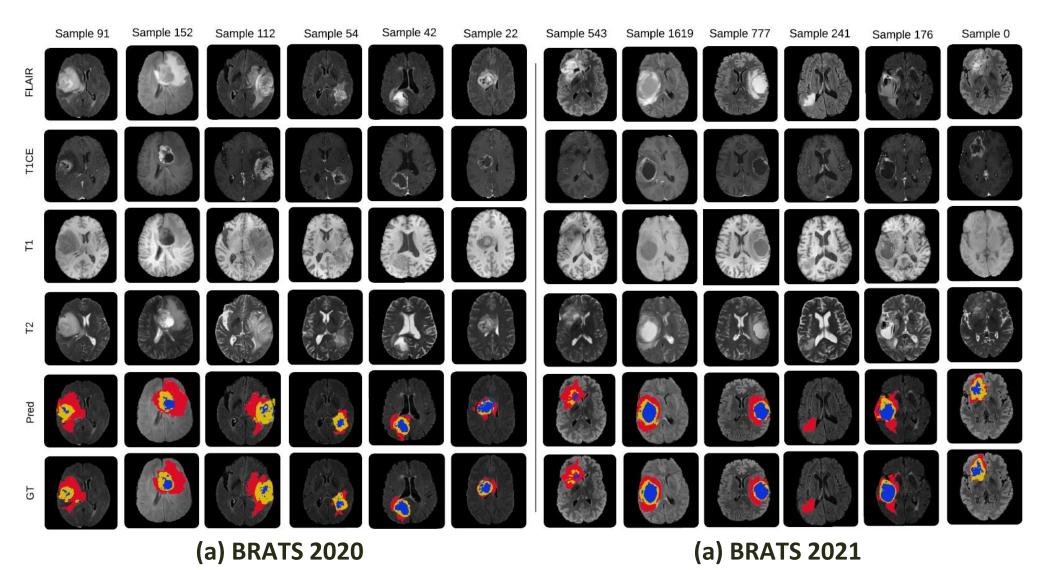


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**Next: Conclusion** 

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### Conclusion

- Exploiting advancement in AI and computer vision for lifesaving medical diagnosis is extremely significant.
- In response to that, this work proposes a **graph attention-based neural network** for effectively segmenting **multi-class tumors** from **multi-modality MRI** scans.
- Exploiting graph attentional layer that is computationally efficient (does not require expensive matrix operations and is parallelizable across all nodes in the graph).
- The exhaustive experimental studies and comparative analysis on the benchmark datasets show that the **proposed model** can **achieve competitive performances**.
- It shows an overall improvement > 6% and > 50%, respectively in dice score and HD95 evaluation metrics compared to an existing GNN-based baseline model.

Next: Acknowledgment 15



### Acknowledgment

This work was inspired in part by the pioneering research conducted by various researchers in graph neural networks and MRI segmentation.

Next: References 16



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Next: Q&A



### End of the Presentation

Thank you for attending and listening

• Q&A: Please let us know if you have any questions

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