

EE2703 : Applied Programming Lab Assignment 3

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1. Introduction

The aim of this assignment is to analyze “Linear Time-invariant Systems” using the `scipy.signal` library in Python. We limit our analysis to systems with rational polynomial transfer functions.

2. Theory

We mainly consider 3 systems: A forced oscillatory system, A coupled system of Differential Equations and an RLC low pass filter. Using functions such as `sp.impulse`, `sp.lti` and `sp.lsim` from the signal toolbox imported from `scipy.signal` as `sp`, and `poly1d` from `numpy`, we attempt to find the transfer function as well as time response of the various above mentioned systems.

3. Assignment Questions

1. Time response of spring system

We first consider the forced oscillatory system (with 0 initial conditions):

$$x + 2.25x = f(t) \tag{1}$$

$$f(t) = \cos(1.5t)\exp(-0.5t)u(t) \tag{2}$$

We solve for $X(s)$ using the following equation, derived from the above equation.

$$X(s) = \frac{s + 0.5}{((s + 0.5)^2 + 2.25)(s^2 + 2.25)} \tag{3}$$

We then use the impulse response of $X(s)$ to get its inverse Laplace transform for $0 < t < 50s$.

2. Spring system with a smaller decay

We now see what happens with a smaller Decay Constant.

$$f(t) = \cos(1.5t)\exp(-0.05t)u(t) \tag{4}$$

We notice that the result is very similar to that of question 1, except with a different amplitude. This is because the system takes longer to reach a steady state.

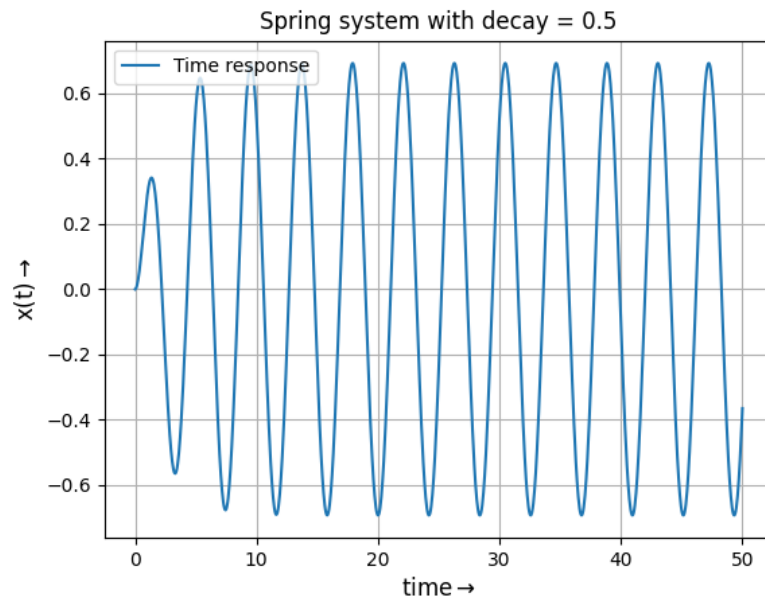


Figure 1: System Response with Decay = 0.5

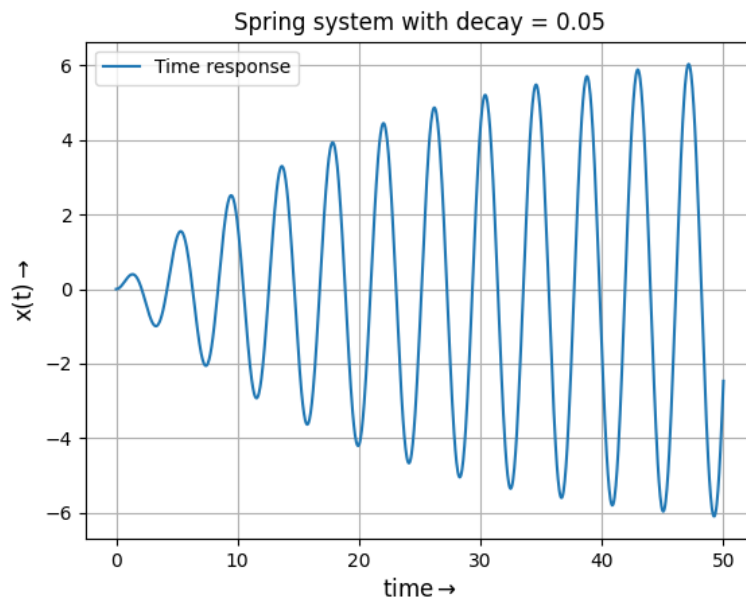


Figure 2: System Response with Decay = 0.05

3. Response over varying frequencies

We now see what happens when we vary the frequency from 1.4 to 1.6 in steps of 0.05. We note that the amplitude of the response is maximum at $\omega = 1.5$, which means it is the natural frequency of the given system.

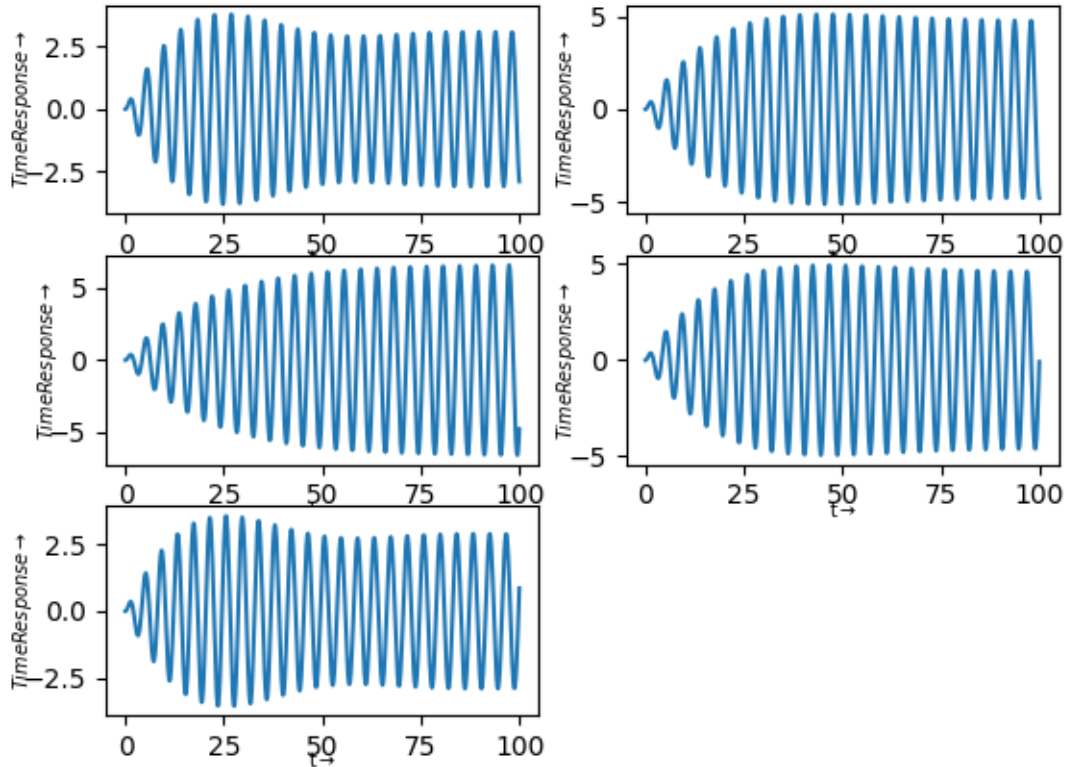


Figure 3: Responses with varying frequency

4. Solving for coupled equations

We now consider a coupled differential equations:

$$\ddot{x} + (x - y) = 0 \quad (5)$$

$$\ddot{y} + 2(y - x) = 0 \quad (6)$$

which results into the 4th order equation:

$$\ddot{\ddot{x}} + 3\ddot{x} = 0 \quad (7)$$

Solving with the initial conditions: $x(0) = 1, \dot{x}(0) = \dot{y}(0) = y(0) = 0$. by taking Laplace Transform and then using *sp.impulse*, we find $x(t)$ and $y(t)$ for $0 < t < 20s$

$$X(s) = \frac{s^2 + 2}{s^3 + 3s} \quad (8)$$

$$Y(s) = \frac{2}{s^3 + 3s} \quad (9)$$

We notice that $x(t)$ and $y(t)$ are sinusoids which are out of phase and have different amplitudes but both oscillate with the same frequency.

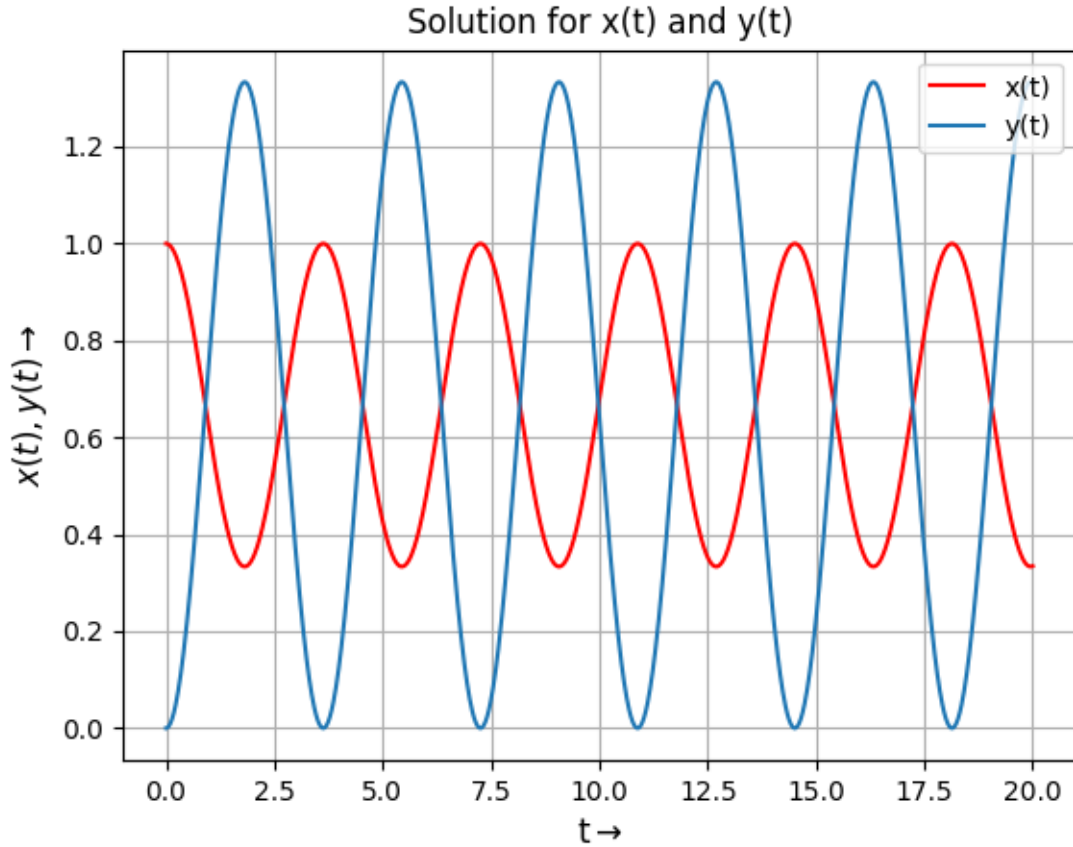


Figure 4: Coupled Oscillations

5. Two-Port Network Transfer Function

The transfer function for the given two-port network is given as:

$$H(s) = \frac{10^{12}}{s^2 + 10^8 s + 10^{12}} \quad (10)$$

The magnitude and phase response are obtained using `signal.bode()` function:

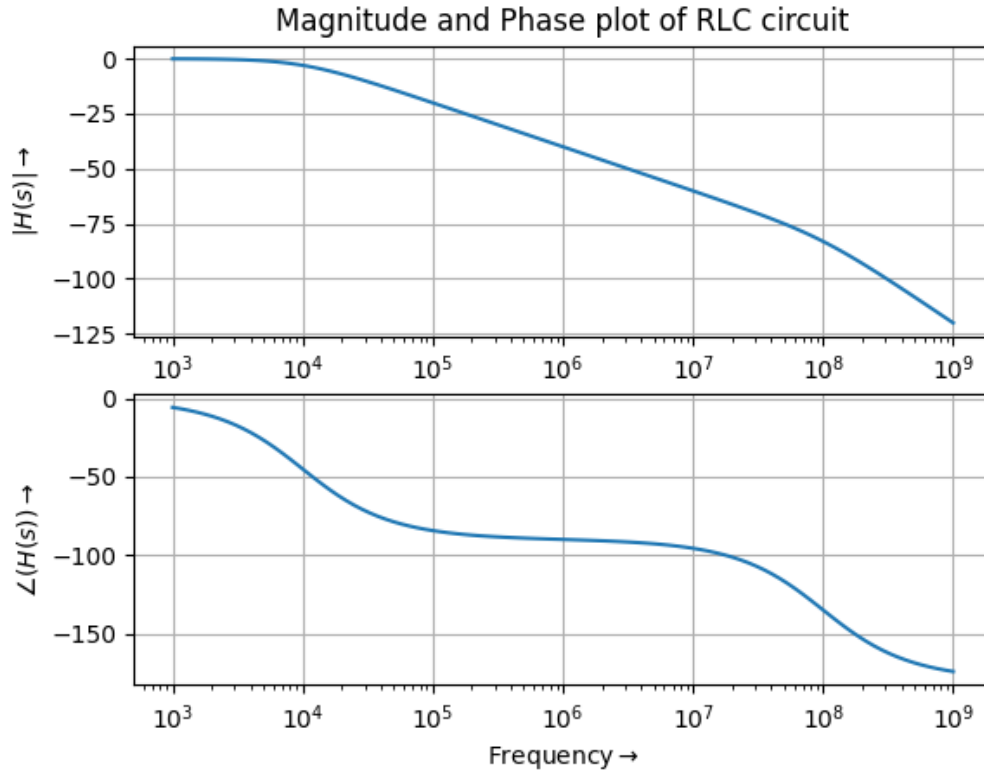


Figure 5: Bode Plots For RLC Low pass filter

6. Time Response with input signal

We know the response of the low pass filter to the input:

$$v_i(t) = (\cos(10^3 t) - \cos(10^6 t))u(t)$$

in the Laplace domain would be:

$$Vo(s) = H(s)Vi(s) \quad (11)$$

Solving for $0 < t < 30\mu s$ and $0 < t < 30ms$ using `sp.lsim` gives us the following plots:

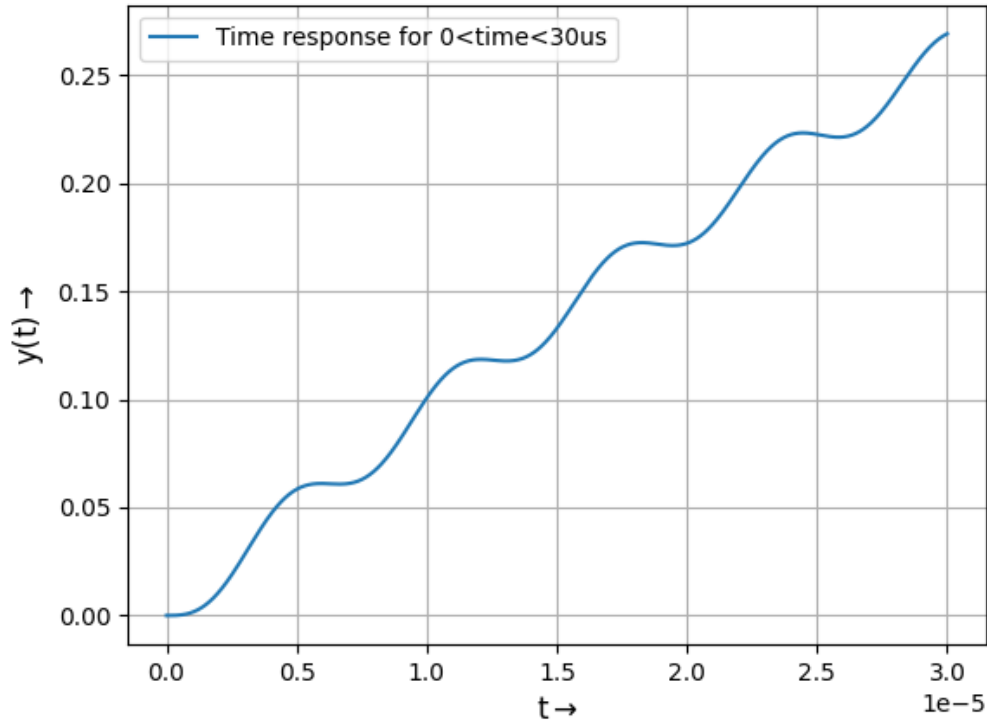


Figure 6: System response for $0 < t < 30\mu s$

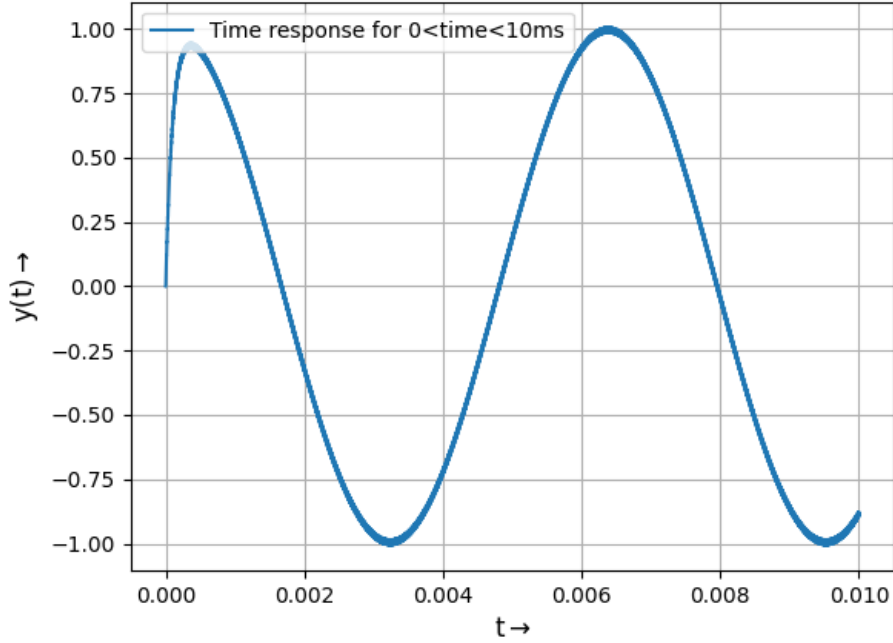


Figure 7: System response for $0 < t < 30ms$

From the Bode plots of a two-port network, we see that the transfer function $H(s)$ provides almost unity gain at frequencies of the order 10^3 , hence, preserving these components in the output.

On the other hand, at $\omega = 10^6$, magnitude of $H(s)$ almost drops to -40dB and hence, the peak to peak amplitude of oscillations at these frequencies is reduced by a factor of 1/100, explaining the graph for $0 < t < 30ms$, and making the two-port network essentially act as a low pass filter.

4. Conclusion

In this assignment, we have used scipy's signal processing library to analyze a wide range of LTI systems. To be precise, we analyzed the single spring system with change in the decay of oscillation and also varying frequency of the forcing function, a coupled spring system and transfer function and response of a two-port network functioning as low pass RLC filter.